

## A reduction-based cut-free Gentzen calculus for dynamic epistemic logic

Martin Wirsing, Alexander Knapp

### Angaben zur Veröffentlichung / Publication details:

Wirsing, Martin, and Alexander Knapp. 2023. "A reduction-based cut-free Gentzen calculus for dynamic epistemic logic." *Logic Journal of the IGPL* 31 (6): 1047–68.  
<https://doi.org/10.1093/jigpal/jzac078>.

### Nutzungsbedingungen / Terms of use:

licgercopyright

Dieses Dokument wird unter folgenden Bedingungen zur Verfügung gestellt: / This document is made available under these conditions:

**Deutsches Urheberrecht**

Weitere Informationen finden Sie unter: / For more information see:

<https://www.uni-augsburg.de/de/organisation/bibliothek/publizieren-zitieren-archivieren/publiz/>



# A Reduction-based Cut-free Gentzen Calculus for Dynamic Epistemic Logic<sup>1</sup>

MARTIN WIRSING\*, *Institut für Informatik, Ludwig-Maximilians-Universität München, 80538 München, Germany.*

ALEXANDER KNAPP, *Institut für Informatik, Universität Augsburg, 86159 Augsburg, Germany.*

## Abstract

Dynamic epistemic logic (DEL) is a multi-modal logic for reasoning about the change of knowledge in multi-agent systems. It extends epistemic logic by a modal operator for actions which announce logical formulas to other agents. In Hilbert-style proof calculi for DEL, modal action formulas are reduced to epistemic logic, whereas current sequent calculi for DEL are labelled systems which internalize the semantic accessibility relation of the modal operators, as well as the accessibility relation underlying the semantics of the actions. We present a novel cut-free ordinary sequent calculus, called  $\mathbf{G4}_{P,A}[]$ , for propositional DEL. In contrast to the known sequent calculi, our calculus does not internalize the accessibility relations, but—similar to Hilbert style proof calculi—action formulas are reduced to epistemic formulas. Since no ordinary sequent calculus for full  $\mathbf{S5}$  modal logic is known, the proof rules for the knowledge operator and the Boolean operators are those of an underlying  $\mathbf{S4}$  modal calculus. We show the soundness and completeness of  $\mathbf{G4}_{P,A}[]$  and prove also the admissibility of the cut-rule and of several other rules for introducing the action modality.

*Keywords:* Dynamic epistemic logic, sequent calculus, cut elimination.

## 1 Introduction

Dynamic epistemic logic (DEL) is a framework for reasoning about the change of knowledge in multi-agent systems. It is based on epistemic logic, a multi-modal logic in which the modal operators express the knowledge and the belief of the agents. The main additional feature of DEL is the communication of epistemic information. Using the so-called (epistemic) actions, agents can send public, private and semi-private announcements to one or more agents. In the logic this is expressed by a modal operator  $[u]$  for epistemic actions  $u$  and formulae of the form  $[u]\psi$  with the meaning that always after executing the action  $u$ , the formula  $\psi$  holds. Public announcement logic (PAL), a simplified variant of DEL, restricts actions to public announcements.

There exist several proof calculi for DEL and PAL. Sound and complete Hilbert-style axiomatizations are given for PAL by Plaza [37, 38] and for DEL by Baltag *et al.* [6] and Gerbrandy [17] (see [42] for an overview). These proof systems are based on Hilbert calculi for epistemic logic and translate modal formulae of the form  $[u]\psi$  into pure epistemic logic formulae without announcement actions. For PAL and DEL also tableaux and display calculi have been developed (Balbiani *et al.* [4], Hansen [19], Aucher *et al.* [1] and Frittella *et al.* [15]; for a comparison with other proof systems, see Frittella *et al.* [16]). A first sequent calculus for DEL has been presented by Baltag *et al.* [5]. Actions enjoy a quantal structure; propositions, actions and agents are resource-sensitive. The calculus is sound and complete but does not admit the elimination of cuts. Dyckhoff and Sadrzadeh [14] refine

---

\*E-mail: wirsing@ifi.lmu.de

<sup>1</sup>Dedicated to John N. Crossley

this proof calculus to a cut-free calculus. However, this calculus does not use ordinary sequents but more complex nested sequents.

This is similar to the situation in modal logic. Only for modal logic systems **S4** or smaller, ordinary sequent calculi are known which are sound, complete and cut-free. For modal logic **S5**, such proof systems need global side conditions (as in Braüner [8] or extend the sequence format by additional structure such as hypersequents (see, e.g. Poggiolesi [41]) and display systems (see, e.g. Dosen [13]); for an overview, cf. Wansing [43] and Negri [30]. Labelled sequent systems internalize the Kripke semantics of modal logic into the syntax of the proof system. Such calculi are ordinary sequent systems which contain not only modalities but also variables and the semantic accessibility relation (see, e.g. Brünnler [9]). Negri [29] presents a general method for generating contraction- and cut-free ordinary sequent calculi for a large family of normal modal logics. Her method has been applied by several authors for constructing labelled cut-free sequent calculi for PAL (see Maffezioli and Negri [26], Negri [30], Balbiani *et al.* [2], Nomura *et al.* [34] and Balbiani and Galmiche [3]). The cut-free sequent calculus of Nomura *et al.* [32, 33] for full DEL internalizes the semantic accessibility relation of the modal operators as well as the accessibility relation underlying the semantics of the actions.

We present a novel cut-free sequent calculus, called  $\mathbf{G4}_{P,A}[]$ , for propositional DEL. In contrast to the labelled sequent calculi, our calculus does not internalize the accessibility relations or does it contain labels, instead the rules for epistemic actions mirror the reduction rules of [7, 42]; these rules are invertible but do not enjoy the subterm property. As an underlying modal system, we choose an **S4** calculus, since no ordinary sequent calculus for full **S5** modal logic is not known. We show the soundness and completeness of  $\mathbf{G4}_{P,A}[]$  and prove also the admissibility of the cut-rule and of several rules for introducing the action modality. Neither for completeness nor for the cut, we apply the well-known translation of [42]; instead, we give direct proofs of the admissibility of cut and of all axioms and rules of the Hilbert calculus for  $\mathbf{DS4}_{P,A}$ . Closely related to our work is the independently developed labelled sequent calculus of Wu *et al.* [45] for PAL. Similar to our approach, the proof rules of [45] follow the structure of the goal and reduce (PAL) formulas to basic epistemic logic formulas. But in contrast to us, the semantic accessibility relation is internalized and the proofs of completeness and admissibility of cut use the translation to epistemic logic.

The paper is organized as follows: in Section 2, we recap the basics of epistemic logic and present the sequent calculus  $\mathbf{G4}_{P,A}$  together with some derived rules and the main theorems for soundness, completeness and admissibility of cut. Section 3 contains the main results: we present the ordinary sequent calculus  $\mathbf{G4}_{P,A}[]$  for DEL, show some derived rules including a particular kind of necessitation for dynamic modalities and prove soundness and completeness of  $\mathbf{G4}_{P,A}[]$  and the admissibility of cuts. Section 4 concludes with an outlook to future work.

**Personal note.** John, Martin and Alexander have known each other for many years. Alexander met John for the first time at the end of the 1990s in the Research Training Group ‘Logic in Computer Science’<sup>2</sup> when he was a PhD student in the group and John a guest researcher. Martin and John had met much earlier, in 1975 at a garden party of Martin’s doctoral supervisor Kurt Schütte. The day after the party, John, Martin and the logician Peter Pöppinghaus drove together in Martin’s car to the ‘Colloque International de Logique’ in Clermont-Ferrand. They became good friends, though communication was difficult. Although each of the three spoke two languages, there was no common language: John spoke English and French, Martin German and French and Peter German and English.

---

<sup>2</sup><https://gepris.dfg.de/gepris/projekt/271709?language=en>

About 10 years later, a close collaboration developed between John and Martin. John visited Martin regularly in Passau and later in Munich, Martin was twice in Melbourne with John in the late 1990s. Together with their students, they worked on two research topics, the development of constrained  $\lambda$ -calculi and program extraction from structured specifications. Four papers [11, 22, 23, 28] were written on the first topic, as well as the dissertations of Luis Mandel [27] and Matthias Hölzl [21]. Luis and Matthias were also jointly supervised by Martin and John. On the second topic, John and Martin wrote three papers [12, 39, 44] together with Hannes Peterreins and Iman Poernomo, a doctoral student of John. An important part of the joint monograph [40] also deals with this topic. At that time, Alexander worked on other topics including the semantics of Java [10] and formal approaches to mobile systems [25] and object-oriented software development [24].

Working and discussing with John is a very pleasant experience. He is not only an outstanding scientist; he is also a warm-hearted and kind friend and colleague. We are looking forward to many further inspiring exchanges with him.

## 2 Epistemic Logic

Propositional epistemic logic is a multi-modal logic. We briefly recall some basic definitions and results about Gentzen-type proof systems.

An *epistemic signature*  $(P, A)$  consists of a set  $P$  of *propositions* and a set  $A$  of *agents*. The set  $\Phi_{P,A}$  of *epistemic formulae*  $\varphi$  over  $(P, A)$  is defined by the following grammar:

$$\varphi ::= p \mid \text{false} \mid \varphi_1 \supset \varphi_2 \mid K_a \varphi,$$

where  $p \in P$  and  $a \in A$ . The epistemic formula  $K_a \varphi$  is to be read as ‘agent  $a$  knows  $\varphi$ ’. The usual propositional connectives can be added by defining  $\neg \varphi \equiv \varphi \supset \text{false}$ ,  $\varphi_1 \vee \varphi_2 \equiv (\neg \varphi_1) \supset \varphi_2$ ,  $\varphi_1 \wedge \varphi_2 \equiv \neg(\varphi \supset \neg \varphi_2)$  and  $\varphi_1 \leftrightarrow \varphi_2 \equiv (\varphi_1 \supset \varphi_2) \wedge (\varphi_2 \supset \varphi_1)$ .

An *epistemic (S4) structure*  $K = (W, E, L)$  over  $(P, A)$  consists of a set  $W$  of *worlds*, an  $A$ -indexed family  $E = (E_a \subseteq W \times W)_{a \in A}$  of *epistemic accessibility relations* and a *labelling*  $L : W \rightarrow \mathcal{P}(P)$  which determines for each world  $w \in W$  the set of propositions valid in  $w$ . The accessibility relations of epistemic structures are assumed to be reflexive and transitive (but not necessarily symmetric as in **S5**). For any  $a \in A$ ,  $(w, w') \in E_a$  models that agent  $a$  cannot distinguish the two worlds  $w$  and  $w'$ . An *epistemic (S4) state* over  $(P, A)$  is a pointed epistemic structure  $\mathfrak{K} = (K, w)$  where  $w \in W$  determines an actual world.

For any epistemic signature  $(P, A)$  and epistemic structure  $K = (W, E, L)$  over  $(P, A)$ , the *satisfaction* of an epistemic formula  $\varphi \in \Phi_{P,A}$  by  $K$  at a world  $w \in W$ , written  $K, w \models \varphi$ , is inductively defined as follows for any  $a \in A$ ,  $p \in P$  and  $\varphi, \varphi_1, \varphi_2 \in \Phi_{P,A}$ :

$$K, w \models p \iff p \in L(w)$$

$$K, w \not\models \text{false}$$

$$K, w \models \varphi_1 \supset \varphi_2 \iff K, w \not\models \varphi_1 \text{ or } K, w \models \varphi_2$$

$$K, w \models K_a \varphi \iff K, w' \models \varphi \text{ for all } w' \in W \text{ with } (w, w') \in E_a.$$

Hence, an agent  $a$  knows  $\varphi$  at world  $w$  if  $\varphi$  holds in all worlds  $w'$  which  $a$  cannot distinguish from  $w$ . For an epistemic state  $\mathfrak{K} = (K, w)$  and for  $\varphi \in \Phi_{P,A}$ ,  $\mathfrak{K} \models \varphi$  means  $K, w \models \varphi$ .

The epistemic logic **S4** consists of all epistemic formulae  $\varphi \in \Phi_{P,A}$  such that  $K, w \models \varphi$  for all epistemic structures  $K = (W, E, L)$  and all their states  $w \in W$ . This logic can be axiomatized in a Hilbert-calculus by the axioms and derivation rules of Table 1 (see, e.g. [42]) where axiom

#### 4 A Reduction-based Cut-free Gentzen Calculus for DEL

TABLE 1. Hilbert-style axiomatisation of  $\mathbf{S4}_{P,A}$ .

(taut) propositional tautologies	(K) $K_a(\varphi_1 \supset \varphi_2) \supset (K_a \varphi_1 \supset K_a \varphi_2)$
(T) $K_a \varphi \supset \varphi$	(4) $K_a \varphi \supset K_a K_a \varphi$
(MP) $\frac{\varphi_1 \quad \varphi_1 \supset \varphi_2}{\varphi_2}$	(GK) $\frac{\varphi}{K_a \varphi}$

TABLE 2. Modal Gentzen system  $\mathbf{G4}_{P,A}$  for epistemic logic  $\mathbf{S4}_{P,A}$ .

(pA) $\frac{}{p, \Gamma \Rightarrow p, \Delta}$	
(Lfalse) $\frac{}{\text{false}, \Gamma \Rightarrow \Delta}$	
(L $\supset$ ) $\frac{\Gamma \Rightarrow \varphi_1, \Delta \quad \varphi_2, \Gamma \Rightarrow \Delta}{\varphi_1 \supset \varphi_2, \Gamma \Rightarrow \Delta}$	(R $\supset$ ) $\frac{\varphi_1, \Gamma \Rightarrow \varphi_2, \Delta}{\Gamma \Rightarrow \varphi_1 \supset \varphi_2, \Delta}$
(LT) $\frac{\varphi, \Gamma \Rightarrow \Delta}{K_a \varphi, \Gamma \Rightarrow \Delta}$	(RK) $\frac{K_a \Gamma \Rightarrow \varphi}{K_a \Gamma, \Gamma' \Rightarrow K_a \varphi, \Delta'}$

TABLE 3. Structural rules and cut.

(Weak) $\frac{\Gamma \Rightarrow \Delta}{\Gamma, \Gamma' \Rightarrow \Delta, \Delta'}$	(Contr) $\frac{\Gamma, \Gamma, \Gamma' \Rightarrow \Delta, \Delta, \Delta'}{\Gamma, \Gamma' \Rightarrow \Delta, \Delta'}$
(Cut) $\frac{\Gamma \Rightarrow \Delta, \varphi \quad \varphi, \Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta}$	

(T), called *truth*, reflects the reflexivity of the accessibility relations and axiom (4), called *positive introspection*, their transitivity.

We use the modal Gentzen system  $\mathbf{G4}_{P,A}$  in Table 2 for the epistemic logic  $\mathbf{S4}_{P,A}$ . Our system builds on  $\mathbf{G3}_n\mathbf{K}$  for basic modal logic (Hakli and Negri [18]) and for the extension to  $\mathbf{S4}$  on the system  $\mathbf{S4}^*$  (Ohnishi and Matsumoto [35]) and the system  $\mathbf{GS4}$  (Ono [36]). In our rules,  $\varphi, \varphi_1, \varphi_2$  range over the formulae in  $\Phi_{P,A}$ ,  $p$  over the propositions in  $P$ ,  $a$  over the agents in  $A$  and  $\Gamma, \Gamma', \Delta, \Delta'$  over the multisets of formulae in  $\Phi_{P,A}$ . In particular,  $\Gamma$  can be empty in (RK), i.e. this multiset can be dropped; then, (RK) is a direct generalization of (GK).

##### LEMMA 2.1

All sequents of the form  $\varphi, \Gamma \Rightarrow \Delta, \varphi$  are derivable in  $\mathbf{G4}_{P,A}$ .

PROOF. By structural induction over  $\varphi$ , see, e.g. [18]. □

The structural rules, see Table 3, of *weakening* and *contraction* are admissible, and so is *cut*.

##### LEMMA 2.2

(Weak) and (Contr) are height-preservingly admissible for  $\mathbf{G4}_{P,A}$ .

TABLE 4. Additional rules for  $\mathbf{G4}_{P,A}$ .

$(L\neg) \frac{\Gamma \Rightarrow \varphi, \Delta}{\neg\varphi, \Gamma \Rightarrow \Delta}$	$(R\neg) \frac{\varphi, \Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \neg\varphi, \Delta}$
$(L\vee) \frac{\varphi_1, \Gamma \Rightarrow \Delta \quad \varphi_2, \Gamma \Rightarrow \Delta}{\varphi_1 \vee \varphi_2, \Gamma \Rightarrow \Delta}$	$(R\vee) \frac{\Gamma \Rightarrow \varphi_1, \varphi_2, \Delta}{\Gamma \Rightarrow \varphi_1 \vee \varphi_2, \Delta}$
$(L\wedge) \frac{\varphi_1, \varphi_2, \Gamma \Rightarrow \Delta}{\varphi_1 \wedge \varphi_2, \Gamma \Rightarrow \Delta}$	$(R\wedge) \frac{\Gamma \Rightarrow \varphi_1, \Delta \quad \Gamma \Rightarrow \varphi_2, \Delta}{\Gamma \Rightarrow \varphi_1 \wedge \varphi_2, \Delta}$
$(L\leftrightarrow) \frac{\varphi_1, \varphi_2, \Gamma \Rightarrow \Delta \quad \Gamma \Rightarrow \varphi_1, \varphi_2, \Delta}{\varphi_1 \leftrightarrow \varphi_2, \Gamma \Rightarrow \Delta}$	$(R\leftrightarrow) \frac{\varphi_1, \Gamma \Rightarrow \varphi_2, \Delta \quad \varphi_2, \Gamma \Rightarrow \varphi_1, \Delta}{\Gamma \Rightarrow \varphi_1 \leftrightarrow \varphi_2, \Delta}$
$(LK^2) \frac{K_a K_a \varphi, \Gamma \Rightarrow \Delta}{K_a \varphi, \Gamma \Rightarrow \Delta}$	$(RT) \frac{\Gamma \Rightarrow K_a \varphi, \Delta}{\Gamma \Rightarrow \varphi, \Delta}$
	$(RK^2) \frac{\Gamma \Rightarrow K_a \varphi, \Delta}{\Gamma \Rightarrow K_a K_a \varphi, \Delta}$
$(LRK) \frac{\Gamma \Rightarrow \varphi}{K_a \Gamma, \Gamma' \Rightarrow K_a \varphi, \Delta'}$	

PROOF. By induction on the height of the derivation (as in, e.g. [31]). □

THEOREM 2.3

(Cut) is admissible for  $\mathbf{G4}_{P,A}$ .

PROOF. As in, e.g. [36]. □

THEOREM 2.4

$\mathbf{G4}_{P,A}$  is sound and complete for  $\mathbf{S4}$ , i.e. for any  $\varphi \in \Phi_{P,A}$ ,  $\vdash_{\mathbf{G4}_{P,A}} \varphi$  if, and only if,  $\mathfrak{K} \models \varphi$  in all epistemic  $\mathbf{S4}$  states  $\mathfrak{K}$  over  $(P, A)$ .

PROOF. For soundness, it suffices to check that each rule of  $\mathbf{G4}_{P,A}$  is valid in  $\mathbf{S4}$ ; for completeness, that each axiom of the Hilbert-style axiomatization in Table 1 is derivable in  $\mathbf{G4}_{P,A}$  and that each rule is admissible. □

Table 4 contains derived rules for the other propositional connectives. Additionally, it shows admissible rules for truth, (RT) and positive introspection, (LK<sup>2</sup>) and (RK<sup>2</sup>).

LEMMA 2.5

For all  $a \in A$ , all  $\varphi \in \Phi_{P,A}$  and all multisets  $\Gamma, \Delta$  of formulæ the following statements hold.

- (a) If  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow K_a \varphi, \Delta$ , then  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow \varphi, \Delta$ .
- (b) If  $\vdash_{\mathbf{G4}_{P,A}} K_a K_a \varphi, \Gamma \Rightarrow \Delta$ , then  $\vdash_{\mathbf{G4}_{P,A}} K_a \varphi, \Gamma \Rightarrow \Delta$ .
- (c) If  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow K_a \varphi, \Delta$ , then  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow K_a K_a \varphi, \Delta$ .

PROOF. For all claims, we proceed by induction over the derivation of the premiss and consider the last rule applied. The cases ( $pA$ ), (Lfalse), (L $\supset$ ), (R $\supset$ ) are immediate since neither  $K_a \varphi$  in the

succedent nor  $K_a K_a \varphi$  in the antecedent is principal in these rules; the same holds for (a) and (c) with (LT), where  $K_a \varphi$  is in the succedent.

(a) We only consider (RK). Then  $\Gamma = K_{a'} \Gamma', \Gamma''$  and  $K_a \varphi, \Delta = K_{a'} \varphi', \Delta'$  for some  $a', \Gamma', \Gamma'', \varphi', \Delta'$  and  $\vdash_{\mathbf{G4}_{P,A}} K_{a'} \Gamma' \Rightarrow \varphi'$ . If  $K_a \varphi$  is principal, i.e.  $K_a \varphi = K_{a'} \varphi'$  and  $\Delta = \Delta'$ , then  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow \varphi, \Delta$  follows from weakening  $\vdash_{\mathbf{G4}_{P,A}} K_{a'} \Gamma' \Rightarrow \varphi$ . If  $K_a \varphi$  is not principal, i.e.  $\Delta = K_{a'} \varphi', \Delta''$ , then  $\vdash_{\mathbf{G4}_{P,A}} K_{a'} \Gamma', \Gamma'' \Rightarrow K_{a'} \varphi', \varphi, \Delta''$  by applying (RK) with premiss  $K_{a'} \Gamma' \Rightarrow \varphi'$ , i.e.  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow \varphi, \Delta$ .

(b) We only consider (LT) and (RK).

Case (LT): Then immediately  $\vdash_{\mathbf{G4}_{P,A}} K_a \varphi, \Gamma \Rightarrow \Delta$ .

Case (RK): Then  $K_a K_a \varphi, \Gamma = K_{a'} \Gamma', \Gamma''$  and  $\Delta = K_{a'} \varphi', \Delta'$  for some  $a', \Gamma', \Gamma'', \varphi', \Delta'$ . If  $a = a'$ , then  $\vdash_{\mathbf{G4}_{P,A}} K_a K_a \varphi, K_a \Gamma' \Rightarrow \varphi'$ ; thus,  $\vdash_{\mathbf{G4}_{P,A}} K_a \varphi, K_a \Gamma' \Rightarrow \varphi'$  by the induction hypothesis, and hence,  $\vdash_{\mathbf{G4}_{P,A}} K_a \varphi, K_a \Gamma', \Gamma'' \Rightarrow K_a \varphi', \Delta'$  using (RK). If  $a \neq a'$ , then  $\vdash_{\mathbf{G4}_{P,A}} K_{a'} \Gamma' \Rightarrow \varphi'$  and thus  $\vdash_{\mathbf{G4}_{P,A}} K_a \varphi, K_a \Gamma', \Gamma'' \Rightarrow K_a \varphi', \Delta'$  again by (RK).

(c) We only consider (RK). Then  $\Gamma = K_{a'} \Gamma', \Gamma''$  and  $K_a \varphi, \Delta = K_{a'} \varphi', \Delta'$  for some  $a', \Gamma', \Gamma'', \varphi', \Delta'$ , and  $\vdash_{\mathbf{G4}_{P,A}} K_{a'} \Gamma' \Rightarrow \varphi'$ . If  $K_a \varphi$  is principal, i.e.  $K_a \varphi = K_{a'} \varphi'$  and  $\Delta = \Delta'$ , then  $\vdash_{\mathbf{G4}_{P,A}} K_a \Gamma' \Rightarrow \varphi$ , such that  $\vdash_{\mathbf{G4}_{P,A}} K_a \Gamma' \Rightarrow K_a K_a \varphi$  by applying (RK) twice, which yields  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow K_a K_a \varphi, \Delta$  by weakening. If  $K_a \varphi$  is not principal, i.e.  $\Delta = K_{a'} \varphi', \Delta''$  for some  $\Delta''$ , then  $\vdash_{\mathbf{G4}_{P,A}} K_{a'} \Gamma', \Gamma'' \Rightarrow K_{a'} \varphi', K_a K_a \varphi, \Delta'$  by applying (RK) with premiss  $K_{a'} \Gamma' \Rightarrow \varphi'$ , i.e.  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow K_a K_a \varphi, \Delta$ .  $\square$

The asymmetric rule (RK) may be replaced by a more symmetric variant (LRK) if not only the truth rule (LT) but also the positive introspection rule (LK<sup>2</sup>) is present.

LEMMA 2.6

If  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow \varphi$ , then  $\vdash_{\mathbf{G4}_{P,A}} K_a \Gamma, \Gamma' \Rightarrow K_a \varphi, \Delta'$ . Conversely, replace (RK) by (LRK) and call the resulting system  $\mathbf{G4}'_{P,A}$ : if  $\vdash_{\mathbf{G4}'_{P,A}} K_a \Gamma \Rightarrow \varphi$ , then  $\vdash_{\mathbf{G4}'_{P,A}} K_a \Gamma, \Gamma' \Rightarrow K_a \varphi, \Delta'$ .

PROOF. In  $\mathbf{G4}_{P,A}$ , we have the following derivation to the left, for the converse direction using  $\mathbf{G4}'_{P,A}$  the derivation to the right, where (LT)\* and (LK<sup>2</sup>)\* mean an iterated rule application (including zero iterations).

$$\frac{\frac{\vdots}{\Gamma \Rightarrow \varphi} \text{ (LT)*}}{K_a \Gamma \Rightarrow \varphi} \text{ (RK)} \qquad \frac{\frac{\vdots}{K_a \Gamma \Rightarrow \varphi} \text{ (LRK)}}{K_a \Gamma, \Gamma' \Rightarrow K_a \varphi, \Delta'} \text{ (LK}^2\text{)*}$$

$\square$

### 3 Dynamic Epistemic Logic

We briefly summarize epistemic actions and DEL following van Ditmarsch *et al.* [42]. Based on this, we present our calculus  $\mathbf{G4}_{P,A}[]$  and prove the admissibility of cut as well as its soundness and completeness.

An *epistemic action structure*  $U = (Q, F, pre)$  over  $(P, A)$  and some logical language  $\mathcal{L}$  consists of a finite set of *action points*  $Q$ , an  $A$ -indexed family of epistemic *action accessibility relations*  $F = (F_a \subseteq Q \times Q)_{a \in A}$  and a *precondition* function  $pre : Q \rightarrow \mathcal{L}$ . We assume that the accessibility relations are reflexive and transitive. For any agent  $a$ ,  $(q, q') \in F_a$  models that agent  $a$  cannot distinguish between occurrences of  $q$  and  $q'$ . For  $q \in Q$ , the epistemic formula  $pre(q)$  determines a condition under which  $q$  can happen. An *epistemic action*  $u = (U, q)$  over  $(P, A)$  and  $\mathcal{L}$  is given by the epistemic action structure  $U = (Q, F, pre)$  and a designated point  $q \in Q$ .

The set  $\Psi_{P,A}$  of *dynamic epistemic formulae* over  $(P, A)$  is defined as  $\bigcup_{n \in \mathbb{N}} \Psi_{P,A}^{(n)}$  where  $\Psi_{P,A}^{(n)}$  are the dynamic epistemic formulae of *depth*  $n$ ; the set  $\mathfrak{U}$  of *epistemic actions* over  $(P, A)$  is defined as  $\bigcup_{n \in \mathbb{N}} \mathfrak{U}_{P,A}^{(n)}$  where  $\mathfrak{U}_{P,A}^{(n)}$  are the epistemic actions of *depth*  $n$ . The families  $(\Psi_{P,A}^{(n)})_{n \in \mathbb{N}}$  and  $(\mathfrak{U}_{P,A}^{(n)})_{n \in \mathbb{N}}$  are mutually recursively defined as follows:  $\Psi_{P,A}^{(0)}$  is just  $\Phi_{P,A}$  and the dynamic epistemic formulae  $\Psi_{P,A}^{(n+1)}$  are defined by the following grammar:

$$\psi ::= \text{false} \mid \psi_1 \supset \psi_2 \mid K_a \psi \mid [u]\psi,$$

where  $u \in \mathfrak{U}_{P,A}^{(n)}$  and  $\mathfrak{U}_{P,A}^{(n)}$  comprises the epistemic actions over  $(P, A)$  and  $\Psi_{P,A}^{(n)}$ . The formula  $[u]\psi$  is to be read as ‘the execution of the epistemic action  $u$  in the current epistemic state leads to an epistemic state where the formula  $\psi$  holds’. In the following,  $\psi$  (and its adorned variants) always ranges over  $\Psi_{P,A}$  and  $u$  over  $\mathfrak{U}$ .

The *product update* of an epistemic structure  $K = (W, E, L)$  over  $(P, A)$  and an epistemic action structure  $U = (Q, F, \text{pre})$  over  $(P, A)$  is the epistemic structure  $K \triangleleft U = (W', E', L')$  over  $(P, A)$  with

$$W' = \{(w, q) \in W \times Q \mid K, w \models \text{pre}(q)\}$$

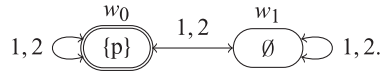
$$E'_a = \{((w, q), (w', q')) \in W' \times W' \mid (w, w') \in E_a, (q, q') \in F_a\} \text{ for all } a \in A,$$

$$L'(w, q) = L(w) \text{ for all } (w, q) \in W'.$$

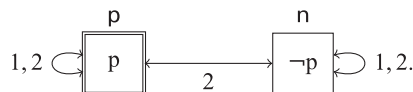
The product update for epistemic structures is well defined, since the relations  $E'_a$  are again reflexive and transitive.  $E'_a$  reflects that the uncertainty of an agent  $a$  in a world  $(w, q)$  is determined by the uncertainty of  $a$  about world  $w$  and its uncertainty about the occurrence of  $q$ . The *product update* of an epistemic state  $\mathfrak{K}$  and an epistemic action  $u = (U, q)$  over  $(P, A)$  is defined by the epistemic state  $(K, w) \triangleleft (U, q) = (K \triangleleft U, (w, q))$ , provided that  $K, w \models \text{pre}(q)$ . Note that all epistemic actions are deterministic.

### EXAMPLE 3.1

(see, e.g. [33]) Let  $P = \{p\}$  and  $A = \{1, 2\}$ . For the current epistemic state, assume that neither agent 1 nor agent 2 know whether proposition  $p$  holds. This situation can be represented by  $\mathfrak{K} = ((W, E, L), w_0)$  with  $W = \{w_0, w_1\}$ ,  $E_1 = W^2 = E_2$  and  $L(w_0) = \{p\}$ ,  $L(w_1) = \emptyset$ , as depicted below:



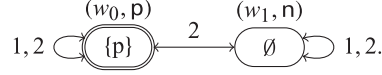
(Both accessibility relations are symmetric, as indicated by the arrows, but this is not required in **S4**). Now assume that only 1 reads a letter telling that  $p$ , such that 1 consequently knows  $p$ , but 2 does not. This reading is modelled by  $\mathfrak{r}\mathfrak{d} = ((Q, F, \text{pre}), p)$  with  $Q = \{p, n\}$ ,  $F_1 = \{(p, p), (n, n)\}$ ,  $F_2 = Q^2$ ,  $\text{pre}(p) = p$  and  $\text{pre}(n) = \neg p$ , graphically shown below:





## 8 A Reduction-based Cut-free Gentzen Calculus for DEL

The epistemic state resulting from executing  $\tau d$  in  $\mathfrak{K}$ , depicted below, is  $\mathfrak{K} \triangleleft \tau d = ((W', E', L'), (w_0, p))$  with  $W' = \{(w_0, p), (w_1, n)\}$ ,  $E'_1 = \{((w_0, p), (w_0, p)), ((w_1, n), (w_1, n))\}$ ,  $E'_2 = W'^2$ ,  $L'(w_0, p) = \{p\}$  and  $L'(w_1, n) = \emptyset$ :



Indeed, in this epistemic state  $\mathfrak{K} \triangleleft \tau d$  agent 1 knows  $p$ .

The *syntactic composition*  $U_1; U_2$  of two epistemic action structures  $U_i = (Q_i, F_i, pre_i)$ ,  $1 \leq i \leq 2$  is given by  $(Q, F, pre)$  with

$$Q = Q_1 \times Q_2 ,$$

$$F_a = \{((q_1, q_2), (q'_1, q'_2)) \mid (q_1, q'_1) \in F_{1,a}, (q_2, q'_2) \in F_{2,a}\} ,$$

$$pre(q_1, q_2) = pre_1(q_1) \wedge [(U_1, q_1)]pre_2(q_2) .$$

The syntactic composition  $u_1; u_2$  of two epistemic actions  $u_i = (U_i, q_i)$ ,  $1 \leq i \leq 2$ , is given by  $(U_1; U_2, (q_1, q_2))$ . The syntactic composition of epistemic actions is associative up to isomorphism [42, Prop. 6.9], i.e. it holds for all  $u_1, u_2, u_3 \in \mathfrak{U}_{P,A}$  that

$$u_1; (u_2; u_3) \cong (u_1; u_2); u_3 . \quad (A1)$$

In the following, we will identify isomorphic epistemic actions.

For an epistemic action  $u = ((Q, F, pre), q)$ , we write  $Q(u)$  for  $Q$ ,  $F(u)_a$  for  $\{q' \mid (q, q') \in F_a\}$ ,  $\cdot u$  for  $pre(q)$ ,  $q(u)$  for  $q$  and  $u \cdot q'$  for  $((Q, F, pre), q')$  whenever  $q' \in Q$ . It holds for all  $a \in A$ ,  $u_1, u_2 \in \mathfrak{U}_{P,A}$  and  $q_i \in Q(u_i)$ ,  $1 \leq i \leq 2$ , that

$$F(u_1; u_2)_a = F(u_1)_a \times F(u_2)_a \quad (A2)$$

$$(u_1; u_2) \cdot (q_1, q_2) = (u_1 \cdot q_1); (u_2 \cdot q_2) \quad (A3)$$

$$\cdot (u_1; u_2) = \cdot u_1 \wedge [u_1] \cdot u_2 \quad (A4)$$

The *satisfaction* of a dynamic epistemic formula  $\psi$  in an epistemic state  $\mathfrak{K}$  over the same epistemic signature  $(P, A)$ , written  $\mathfrak{K} \models \psi$ , extends the respective satisfaction of (pure) epistemic formulæ by

$$\mathfrak{K} \models [u]\psi \iff \mathfrak{K} \models \cdot u \text{ implies } \mathfrak{K} \triangleleft u \models \psi .$$

The DEL **DS** $_{P,A}$  consists of all dynamic epistemic formulæ  $\psi \in \Psi_{P,A}$  such that  $\mathfrak{K} \models \psi$  for all epistemic states  $\mathfrak{K}$ . This logic can be axiomatized in a Hilbert-calculus by the axioms and derivation rules for  $\cdot$ , see Table 1, together with the *reduction axioms* in Table 5, where  $\bigwedge$  abbreviates iterated conjunction.

TABLE 5. Reduction axioms for  $\mathbf{DS4}_{P,A}$ 

$(\text{red}p) [u]p \leftrightarrow \cdot u \supset p$	$(\text{redfalse}) [u]\text{false} \leftrightarrow \neg \cdot u$
$(\text{red}\supset) [u](\psi_1 \supset \psi_2) \leftrightarrow [u]\psi_1 \supset [u]\psi_2$	$(\text{red}K) [u]K_a \psi \leftrightarrow \cdot u \supset \bigwedge_{q \in F(u)_a} K_a[u \cdot q]\psi$
$(\text{red}\Box) [u_1][u_2]\psi \leftrightarrow [u_1; u_2]\psi$	

 TABLE 6. Modal Gentzen system  $\mathbf{G4}_{P,A}[\Box]$  for DEL.

$(L\Box p) \frac{\Gamma \Rightarrow \cdot u, \Delta \quad \Gamma, p \Rightarrow \Delta}{[u]p, \Gamma \Rightarrow \Delta}$	$(R\Box p) \frac{\cdot u, \Gamma \Rightarrow p, \Delta}{\Gamma \Rightarrow [u]p, \Delta}$
$(L\Box \text{false}) \frac{\Gamma \Rightarrow \cdot u, \Delta}{[u]\text{false}, \Gamma \Rightarrow \Delta}$	$(R\Box \text{false}) \frac{\cdot u, \Gamma \Rightarrow \Delta}{\Gamma \Rightarrow [u]\text{false}, \Delta}$
$(L\Box \supset) \frac{\Gamma \Rightarrow [u]\psi_1, \Delta \quad [u]\psi_2, \Gamma \Rightarrow \Delta}{[u](\psi_1 \supset \psi_2), \Gamma \Rightarrow \Delta}$	$(R\Box \supset) \frac{[u]\psi_1, \Gamma \Rightarrow [u]\psi_2, \Delta}{\Gamma \Rightarrow [u](\psi_1 \supset \psi_2), \Delta}$
$(L\Box K) \frac{\Gamma \Rightarrow \cdot u, \Delta \quad (K_a[u \cdot q']\psi)_{q' \in F(u)_a}, \Gamma \Rightarrow \Delta}{[u]K_a \psi, \Gamma \Rightarrow \Delta}$	$(R\Box K) \frac{(\cdot u, \Gamma \Rightarrow K_a[u \cdot q']\psi, \Delta)_{q' \in F(u)_a}}{\Gamma \Rightarrow [u]K_a \psi, \Delta}$
$(L\Box \Box) \frac{[u_1; u_2]\psi, \Gamma \Rightarrow \Delta}{[u_1][u_2]\psi, \Gamma \Rightarrow \Delta}$	$(R\Box \Box) \frac{\Gamma \Rightarrow [u_1; u_2]\psi, \Delta}{\Gamma \Rightarrow [u_1][u_2]\psi, \Delta}$

Our Gentzen-style calculus  $\mathbf{G4}_{P,A}[\Box]$  for epistemic dynamic logic extends the epistemic rules in Table 2 with the action rules in Table 6 where now  $\Gamma$  and  $\Delta$  always range over  $\Psi_{P,A}$ . Table 7 comprises some additional rules: on the one hand, the additional propositional connectives can be directly handled by corresponding derived rules; on the other hand, some admissible rules for handling actions are offered (see Lemmas 3.7 and 3.8).

### EXAMPLE 3.2

Consider the reading action of  $\tau d$  as introduced in Example 3.1.

$$\begin{array}{c}
 \vdots \quad \vdots \\
 \hline
 \neg p \Rightarrow \neg p \quad \neg p, p \Rightarrow \quad (L\Box p) \\
 \hline
 \neg p, [\tau d \cdot n]p \Rightarrow \quad (R\Box \neg) \\
 \hline
 \Rightarrow [\tau d \cdot n]\neg p \quad (RK) \\
 \hline
 \neg p \Rightarrow [\tau d \cdot n]K_1 p, K_1[\tau d \cdot n]\neg p \quad (R\Box K) \\
 \hline
 \Rightarrow [\tau d \cdot n]K_1 p, [\tau d \cdot n]K_1 \neg p \quad (R\Box \vee) \\
 \hline
 \Rightarrow [\tau d \cdot n](K_1 p \vee K_1 \neg p) \quad (RK) \\
 \hline
 p \Rightarrow K_2[\tau d \cdot n](K_1 p \vee K_1 \neg p) \quad \vdots \\
 \hline
 p \Rightarrow K_2[\tau d \cdot p](K_1 p \vee K_1 \neg p) \quad (R\Box K) \\
 \hline
 \Rightarrow [\tau d]K_2(K_1 p \vee K_1 \neg p)
 \end{array}$$

TABLE 7. Additional rules for  $\mathbf{G4}_{P,A}[\cdot]$ .

---

$(L[\cdot]\neg) \frac{\Gamma \Rightarrow \cdot u, \Delta \quad \Gamma \Rightarrow [u]\psi, \Delta}{[u]\neg\psi, \Gamma \Rightarrow \Delta}$	$(R[\cdot]\neg) \frac{\cdot u, [u]\psi, \Gamma \Rightarrow \Delta}{\Gamma \Rightarrow [u]\neg\psi, \Delta}$
$(L[\cdot]\wedge) \frac{[u]\psi_1, [u]\psi_2, \Gamma \Rightarrow \Delta}{[u](\psi_1 \wedge \psi_2), \Gamma \Rightarrow \Delta}$	$(R[\cdot]\wedge) \frac{\Gamma \Rightarrow [u]\psi_1, \Delta \quad \Gamma \Rightarrow [u]\psi_2, \Delta}{\Gamma \Rightarrow [u](\psi_1 \wedge \psi_2), \Delta}$
$(L[\cdot]\vee) \frac{[u]\psi_1, \Gamma \Rightarrow \Delta \quad [u]\psi_2, \Gamma \Rightarrow \Delta}{[u](\psi_1 \vee \psi_2), \Gamma \Rightarrow \Delta}$	$(R[\cdot]\vee) \frac{\Gamma \Rightarrow [u]\psi_1, [u]\psi_2, \Delta}{\Gamma \Rightarrow [u](\psi_1 \vee \psi_2), \Delta}$
$(LK[\cdot]) \frac{K_a[u_1; u_2]\psi, \Gamma \Rightarrow \Delta}{K_a[u_1][u_2]\psi, \Gamma \Rightarrow \Delta}$	$(RK[\cdot]) \frac{\Gamma \Rightarrow K_a[u_1; u_2]\psi, \Delta}{\Gamma \Rightarrow K_a[u_1][u_2]\psi, \Delta}$
$(LR[\cdot]) \frac{\Gamma \Rightarrow \Delta}{\cdot u, [u]\Gamma, \Gamma' \Rightarrow [u]\Delta, \Delta'}$	

---

The *rank* of a formula  $\psi$  and an action  $u$  is inductively defined as follows (see [42, Def. 7.38]):

$$\begin{aligned}
rk(\text{false}) &= 1 \\
rk(p) &= 1 \\
rk(\psi_1 \supset \psi_2) &= 1 + \max\{rk(\psi_1), rk(\psi_2)\} \\
rk(K_a\psi) &= 1 + rk(\psi) \\
rk([u]\psi) &= (4 + rk(u)) \cdot rk(\psi) \\
rk(u) &= \max\{rk(\cdot(u \cdot q)) \mid q \in \mathcal{Q}(u)\}.
\end{aligned}$$

It holds that  $rk([u]K_a\psi) > rk([u]\psi)$ ,  $rk([u]\psi) > rk(\cdot u)$ ,  $rk([u]\psi) > rk(\psi)$ ,  $rk([u]K_a\psi) > rk(K_a[u \cdot q]\psi)$  for all  $q \in \mathcal{Q}(u)$  and  $rk([u_1][u_2]\psi) > rk([u_1; u_2]\psi)$ .

The following lemmata hold for all  $\psi \in \Psi_{P,A}$ ,  $u, u_1, u_2 \in \mathcal{U}_{P,A}$ ,  $a \in A$  and  $\Psi_{P,A}$ -multisets  $\Gamma$  and  $\Delta$ . We first show that Lemma 2.1 generalizing the axiom rule ( $pA$ ) to arbitrary formulæ carries over from  $\mathbf{G4}_{P,A}$ .

LEMMA 3.3

$\vdash_{\mathbf{G4}_{P,A}[\cdot]} \psi, \Gamma \Rightarrow \Delta, \psi$ .

PROOF. We proceed by induction on the rank of  $\psi$ . For  $\psi \in \Phi_{P,A}$ , the claim already holds in  $\mathbf{G4}_{P,A}$  by Lemma 2.1. We only consider  $\psi = [u]p$  and  $\psi = [u]K_a\psi'$ ; the remaining cases are analogous.

Case  $\psi = [u]p$ : We have

$$\frac{\frac{\frac{\vdots \text{I. H.}}{\cdot u, \Gamma \Rightarrow \cdot u, p, \Delta} \quad \frac{\vdots \text{I. H.}}{\cdot u, p, \Gamma \Rightarrow p, \Delta}}{\cdot u, [u]p, \Gamma \Rightarrow p, \Delta} (L[\cdot]p)}{[u]p, \Gamma \Rightarrow [u]p, \Delta} (R[\cdot]p)$$

Case  $\psi = [u]K_a\psi'$ : We have

$$\frac{\frac{\frac{\vdots \text{I. H.}}{(\cdot u, \Gamma \Rightarrow \cdot u, [u \cdot q']K_a\psi', \Delta)_{q' \in F(u)_a}} \quad (\cdot u, ([u \cdot q'']K_a\psi')_{q'' \in F(u)}, \Gamma \Rightarrow [u \cdot q']K_a\psi', \Delta)_{q' \in F(u)_a}}{(\cdot u, [u]K_a\psi', \Gamma \Rightarrow [u \cdot q']K_a\psi', \Delta)_{q' \in F(u)_a}} \quad (\text{L}[\Box]K)} \quad (\text{R}[\Box]K)} \quad \frac{(\cdot u, [u]K_a\psi', \Gamma \Rightarrow [u \cdot q']K_a\psi', \Delta)_{q' \in F(u)_a}}{[u]K_a\psi', \Gamma \Rightarrow [u]K_a\psi', \Delta} \quad (\text{R}[\Box]K)}$$

□

Also, Lemma 2.2 showing the admissibility of (Weak) and (Contr) carries over from  $\mathbf{G4}_{P,A}$ .

LEMMA 3.4

(Weak) and (Contr) are height-preservingly admissible for  $\mathbf{G4}_{P,A}[\Box]$ .

□

PROOF. By induction on the height of the derivation.

LEMMA 3.5

If  $\vdash_{\mathbf{G4}_{P,A}[\Box]} \cdot u, \Gamma \Rightarrow [u]\psi, \Delta$ , then  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow [u]\psi, \Delta$ .

PROOF. We proceed by induction over the derivation of  $\vdash_{\mathbf{G4}_{P,A}[\Box]} \cdot u, \Gamma \Rightarrow [u]\psi, \Delta$  and consider the last rule applied. If therein  $[u]\psi$  is principal and  $\cdot u$  is added in the antecedent — as in  $(\text{R}[\Box]p)$ ,  $(\text{R}[\Box]\text{false})$  and  $(\text{R}[\Box]K)$  —, then (Contr) is applied. If, e.g.  $(\text{R}[\Box]p)$  is the last rule, then  $\psi = p$  and  $\vdash_{\mathbf{G4}_{P,A}[\Box]} \cdot u, \cdot u, \Gamma \Rightarrow p, \Delta$  and

$$\frac{\frac{\cdot u, \cdot u, \Gamma \Rightarrow p, \Delta}{\cdot u, \Gamma \Rightarrow p, \Delta} \quad (\text{Contr})}{\Gamma \Rightarrow [u]p, \Delta} \quad (\text{R}[\Box]p)$$

If  $[u]\psi$  is principal, but  $\cdot u$  is not added in the antecedent—as in  $(\text{R}[\Box]\supset)$  and  $(\text{R}[\Box]\Box)$ —then the claim follows directly from the induction hypothesis.

If  $[u]\psi$  is not principal and the rule for  $[u]\psi$  in the succedent adds  $\cdot u$  to the antecedent, we first (from bottom to top) duplicate  $[u]\psi$  in the succedent by (Contr), then apply the ‘box’-rule matching  $\psi$  for adding  $\cdot u$ , and finally apply (Weak).

$$\frac{\dots \quad \frac{\cdot u, \Gamma \Rightarrow [u]\psi, \Delta}{\cdot u, \Gamma, \Gamma' \Rightarrow [u]\psi, \Delta', \Delta} \quad (\text{Weak})}{\frac{\Gamma \Rightarrow [u]\psi, [u]\psi, \Delta}{\Gamma \Rightarrow [u]\psi, \Delta} \quad (\text{Contr})} \quad \text{R}[\Box] \dots$$

If  $[u]\psi$  is not principal and  $\cdot u$  is not added to the antecedent by the ‘box’-rule matching  $\psi$ , then the claim follows directly from the induction hypothesis. □

LEMMA 3.6

All of the ‘box’ rules in  $\mathbf{G4}_{P,A}[\Box]$  are invertible, i.e.: if  $\vdash_{\mathbf{G4}_{P,A}[\Box]} [u]p, \Gamma \Rightarrow \Delta$ , then  $\vdash_{\mathbf{G4}_{P,A}} \Gamma \Rightarrow \cdot u, \Delta$  and  $\vdash_{\mathbf{G4}_{P,A}} \Gamma, p \Rightarrow \Delta$ , &c.

PROOF. Only a single rule applies to each possible form of  $[u]\psi$  in the antecedent and the succedent. □

We append  $^{-1}$  to a rule name when applying it invertedly. The rules  $(\text{LK}[\Box])$  and  $(\text{RK}[\Box])$  for treating sequential composition of epistemic actions and repeated boxes equally are both admissible and invertible.

LEMMA 3.7

- (a)  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} K_a[u_1; u_2]\psi, \Gamma \Rightarrow \Delta$  if, and only if,  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} K_a[u_1][u_2]\psi, \Gamma \Rightarrow \Delta$ .  
 (b)  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \Gamma \Rightarrow K_a[u_1; u_2]\psi, \Delta$  if, and only if,  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \Gamma \Rightarrow K_a[u_1][u_2]\psi, \Delta$ .

PROOF. (a) The only applicable rule with  $K_a[u_1; u_2]\psi$  and  $K_a[u_1][u_2]\psi$  principal is (LT) where the claim follows immediately by  $(L[\Box])$  or  $(L[\Box])^{-1}$ .

(b) Only (RK) shows  $K_a[u_1; u_2]\psi$  or  $K_a[u_1][u_2]\psi$  principally. If the last rule for obtaining  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \Gamma \Rightarrow K_a[u_1; u_2]\psi, \Delta$  has been (RK), then  $\Gamma = K_a\Gamma', \Gamma''$  for some  $\Gamma', \Gamma''$  and  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} K_a\Gamma' \Rightarrow [u_1; u_2]\psi$ . We thus have

$$\frac{\frac{K_a\Gamma' \Rightarrow [u_1; u_2]\psi}{K_a\Gamma' \Rightarrow [u_1][u_2]\psi} (R[\Box])}{K_a\Gamma', \Gamma'' \Rightarrow K_a[u_1][u_2]\psi, \Delta} (RK)$$

The reverse direction uses  $(R[\Box])^{-1}$ . □

We show that the rule (LR $[\Box]$ ) is admissible. The rule always assumes the precondition of the contextual epistemic action to hold; without this precondition, the rule would not apply to an empty succedent (see Lemma 3.5): the sequent  $\text{false} \Rightarrow$  is derivable, but  $[\text{ff}]\text{false} \Rightarrow$  with  $\text{ff} = \text{false}$  must not be.

LEMMA 3.8

If  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \Gamma \Rightarrow \Delta$ , then  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \cdot u, [u]\Gamma, \Gamma' \Rightarrow [u]\Delta, \Delta'$  for all  $u, \Gamma'$  and  $\Delta'$ .

PROOF. We proceed by induction over the derivation of  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \Gamma \Rightarrow \Delta$  and consider the last rule applied.

*Case (pA):* Then  $\Gamma = p, \Gamma'$  and  $\Delta = p, \Delta'$  for some  $p, \Gamma', \Delta'$ . We have

$$\frac{\frac{\vdash_{\text{Lem. 5}} \cdot u, \cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot u, [u]\Delta', \Delta''}{\cdot u, \cdot u, [u]p, [u]\Gamma', \Gamma'' \Rightarrow p, [u]\Delta', \Delta''} (pA)}{\cdot u, [u]p, [u]\Gamma', \Gamma'' \Rightarrow [u]p, [u]\Delta', \Delta''} (L[p])$$

*Case (Lfalse):* Then  $\Gamma = \text{false}, \Gamma'$  for some  $\Gamma'$ . We have

$$\frac{\vdash_{\text{Lem. 5}} \cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot u, [u]\Delta', \Delta''}{\cdot u, [u]\text{false}, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} (L[\Box]\text{false})$$

*Case (R $\supset$ ):* Then  $\Gamma = \psi_1 \supset \psi_2, \Gamma'$  for some  $\psi_1, \psi_2, \Gamma'$  and  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \Gamma' \Rightarrow \psi_1, \Delta$ , as well as  $\vdash_{\mathbf{G4}_{p,\mathcal{A}}} \psi_2, \Gamma' \Rightarrow \Delta$ . We have

$$\frac{\frac{\vdash_{\text{I. H.}} \cdot u, [u]\Gamma', \Gamma'' \Rightarrow [u]\psi_1, [u]\Delta, \Delta'}{\cdot u, [u]\psi_1 \supset \psi_2, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} \quad \frac{\vdash_{\text{I. H.}} \cdot u, [u]\psi_2, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'}{\cdot u, [u]\psi_1 \supset \psi_2, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} (L[\supset])$$

Case (R $\supset$ ): Then  $\Delta = \psi_1 \supset \psi_2, \Delta'$ , for some  $\psi_1, \psi_2, \Delta'$  and  $\vdash_{\mathbf{G4}_{P,A}[]}\psi_1, \Gamma \Rightarrow \psi_2, \Delta'$ . We have

$$\frac{\begin{array}{c} \vdots \text{I. H.} \\ \cdot u, [u]\psi_1, [u]\Gamma, \Gamma' \Rightarrow [u]\psi_2, [u]\Delta', \Delta'' \end{array}}{\cdot u, [u]\Gamma, \Gamma' \Rightarrow [u]\psi_1 \supset \psi_2, [u]\Delta', \Delta''} \text{ (R}\square\supset\text{)}$$

Case (LT): Then  $\Gamma = K_a\psi, \Gamma'$  for some  $a, \psi, \Gamma'$  and  $\vdash_{\mathbf{G4}_{P,A}[]}\psi, \Gamma' \Rightarrow \Delta$ . We have

$$\frac{\begin{array}{c} \vdots \text{Lem. 5} \\ \cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot u, [u]\Delta, \Delta' \end{array} \quad \frac{\begin{array}{c} \vdots \text{I. H.} \\ \cdot u, [u]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta' \end{array} \text{ (LT)}}{\cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot u, [u]\Delta, \Delta'} \text{ (Weak)} \\ \frac{\cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot u, [u]\Delta, \Delta' \quad \cdot u, (K_a[u \cdot q']\psi)_{q' \in F(u)_a}, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'}{\cdot u, [u]K_a\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} \text{ (L}\square\text{K)}$$

where the step (Weak) is possible since  $q(u) \in F(u)_a$  by the reflexivity of  $F(u)$  and  $u \cdot q(u) = u$ .

Case (RK): Then  $\Gamma = K_a\Gamma', \Gamma''$  and  $\Delta = K_a\psi, \Delta'$  for some  $a, \Gamma', \Gamma'', \psi, \Delta'$  and  $\vdash_{\mathbf{G4}_{P,A}[]}K_a\Gamma' \Rightarrow \psi$ . We have

$$\frac{\begin{array}{c} \vdots \text{I. H.} \\ \cdot (u \cdot q'), ([u \cdot q']K_a\Gamma' \Rightarrow [u \cdot q']\psi)_{q' \in F(u)_a} \end{array} \text{ Lem. 7}}{([u \cdot q']K_a\Gamma' \Rightarrow [u \cdot q']\psi)_{q' \in F(u)_a}} \text{ (L}\square\text{K)}^{-1} \\ \frac{((K_a([u \cdot q'] \cdot q'')\Gamma')_{q' \in F(u)_a, q'' \in F(u \cdot q')_a} \Rightarrow [u \cdot q']\psi)_{q' \in F(u)_a}}{((K_a[u \cdot q'']\Gamma')_{q'' \in F(u)_a} \Rightarrow [u \cdot q']\psi)_{q' \in F(u)_a}} \text{ (Contr)} \\ \frac{\begin{array}{c} \vdots \text{Lem. 5} \\ \cdot u, [u]\Gamma'', \Gamma''' \Rightarrow \end{array} \quad \frac{(\cdot u, (K_a[u \cdot q']\Gamma')_{q'' \in F(u)_a}, [u]\Gamma'', \Gamma''' \Rightarrow K_a[u \cdot q']\psi, [u]\Delta', \Delta'')_{q' \in F(u)_a}}{\cdot u, [u]K_a\psi, [u]\Delta', \Delta''} \text{ (RK)}}{\cdot u, [u]K_a\Gamma', [u]\Gamma'', \Gamma''' \Rightarrow [u]K_a\psi, [u]\Delta', \Delta''} \text{ (L}\square\text{K)}$$

where  $((u \cdot q') \cdot q'')_{q' \in F(u)_a, q'' \in F(u \cdot q')_a} = (u \cdot q')_{q' \in F(u)_a}$  up to contraction by transitivity and reflexivity.

Case (L $\square p$ ): Then  $\Gamma = [u']p, \Gamma'$  for some  $u', p, \Gamma'$  and  $\vdash_{\mathbf{G4}_{P,A}[]} \Gamma' \Rightarrow \cdot u', \Delta$ , as well as  $\vdash_{\mathbf{G4}_{P,A}[]} \Gamma', p \Rightarrow \Delta$ .

$$\frac{\begin{array}{c} \vdots \text{I. H.} \\ \cdot u, [u]p, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta' \end{array} \text{ (L}\square p\text{)}^{-1}}{\cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot (u; u'), [u]\Delta, \Delta'} \text{ (L}\square p\text{)} \\ \frac{\cdot u, [u; u']p, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'}{\cdot u, [u][u']p, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} \text{ (L}\square\text{)}$$

where the derivation  $*_0$  is

$$\frac{\begin{array}{c} \vdots \text{Lem. 5} \\ \cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot u, [u]\Delta, \Delta' \end{array} \quad \begin{array}{c} \vdots \text{I. H.} \\ \cdot u, [u]\Gamma', \Gamma'' \Rightarrow [u]u', [u]\Delta, \Delta' \end{array}}{\cdot u, [u]\Gamma', \Gamma'' \Rightarrow \cdot (u; u'), [u]\Delta, \Delta'} \text{ (R}\wedge\text{)}$$

Case (R[]p): Then  $\Delta = [u']p, \Delta'$  for some  $u', p, \Delta'$  and  $\vdash_{\mathbf{G4}_{p,A}[]} \cdot u', \Gamma \Rightarrow p, \Delta'$ .

$$\frac{\frac{\frac{\frac{\vdots \text{I. H.}}{\cdot u, [u] \cdot u', [u] \Gamma, \Gamma' \Rightarrow [u] p, [u] \Delta', \Delta''} (R[]p)^{-1}}{\cdot u, \cdot u, [u] \cdot u', [u] \Gamma, \Gamma' \Rightarrow p, [u] \Delta', \Delta''} (L\wedge)}}{\cdot u, \cdot (u; u'), [u] \Gamma, \Gamma' \Rightarrow p, [u] \Delta', \Delta''} (R[]p)}{\cdot u, [u] \Gamma, \Gamma' \Rightarrow [u; u'] p, [u] \Delta', \Delta''} (R[]p)}{\cdot u, [u] \Gamma, \Gamma' \Rightarrow [u][u'] p, [u] \Delta', \Delta''} (R[]\Box)$$

Case (L[]false): Then  $\Gamma = [u']\text{false}, \Gamma'$  for some  $u', \Gamma'$  and  $\vdash_{\mathbf{G4}_{p,A}[]} \Gamma' \Rightarrow \cdot u', \Delta$ . We have

$$\frac{\frac{\frac{\vdots *_0}{\cdot u, [u] \Gamma', \Gamma'' \Rightarrow \cdot (u; u'), [u] \Delta, \Delta'} (L[]\text{false})}}{\cdot u, [u; u'] \text{false}, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\Box)}{\cdot u, [u][u'] \text{false}, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\Box)$$

where the derivation  $*_0$  is as in (L[]p).

Case (R[]false): Analogous to (L[]false).

Case (L[] $\supset$ ): Then  $\Gamma = [u']\psi_1 \supset \psi_2, \Gamma'$  for some  $u', \psi_1, \psi_2, \Gamma'$  and  $\vdash_{\mathbf{G4}_{p,A}[]} \Gamma' \Rightarrow [u']\psi_1, \Delta$  as well as  $\vdash_{\mathbf{G4}_{p,A}[]} [u']\psi_2, \Gamma' \Rightarrow \Delta$ . We have

$$\frac{\frac{\frac{\vdots \text{I. H.}}{\cdot u, [u] \Gamma', \Gamma'' \Rightarrow [u][u'] \psi_1, [u] \Delta, \Delta'} (R[]\Box)^{-1}}{\cdot u, [u] \Gamma', \Gamma'' \Rightarrow [u; u'] \psi_1, [u] \Delta, \Delta'} (L[]\Box)^{-1}}{\frac{\frac{\vdots \text{I. H.}}{\cdot u, [u][u'] \psi_2, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\Box)^{-1}}{\cdot u, [u; u'] \psi_2, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\supset)}}{\frac{\cdot u, [u; u'](\psi_1 \supset \psi_2), [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'}{\cdot u, [u][u'](\psi_1 \supset \psi_2), [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\Box)}$$

Case (R[] $\supset$ ): Analogous to (L[] $\supset$ ). Case (L[]K): Then  $\Gamma = [u']K_a \psi, \Gamma'$  for some  $u', a, \psi, \Gamma'$  and  $\vdash_{\mathbf{G4}_{p,A}[]} \Gamma' \Rightarrow \cdot u', \Delta$ , as well as  $\vdash_{\mathbf{G4}_{p,A}[]} (K_a[u' \cdot q']\psi)_{q' \in F(u')_a}, \Gamma' \Rightarrow \Delta$ . We have

$$\frac{\frac{\frac{\vdots *_0}{\cdot u, [u] \Gamma', \Gamma'' \Rightarrow \cdot (u; u'), [u] \Delta, \Delta'} (L[]\text{false})}}{\cdot u, (K_a[(u; u') \cdot q'']\psi)_{q'' \in F(u; u')_a}, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]K)}{\frac{\frac{\vdots *_1}{\cdot u, [u; u'] K_a \psi, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\Box)^{-1}}{\cdot u, [u][u'] K_a \psi, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\Box)}$$

where the derivation  $*_0$  is as in the case of (L[]p) and the derivation  $*_1$  is

$$\frac{\frac{\frac{\vdots \text{I. H.}}{\cdot u, ([u] K_a[u' \cdot q']\psi)_{q' \in F(u')_a}, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]K)^{-1}}{\cdot u, (K_a[u \cdot q][u' \cdot q']\psi)_{q \in F(u)_a, q' \in F(u')_a}, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[]\Box)^{-1}}{\cdot u, (K_a[(u; u') \cdot q'']\psi)_{q'' \in F(u; u')_a}, [u] \Gamma', \Gamma'' \Rightarrow [u] \Delta, \Delta'} (L[K[]\Box])^{-1}$$

Case (R[]K): Analogous to (L[]K).

Case (L $\square\square$ ): Then  $\Gamma = [u_1][u_2]K_a\psi, \Gamma'$  for some  $u_1, u_2, a, \psi$  and  $\vdash_{\mathbf{G4}_{P,A}[\square]} [u_1; u_2]\psi, \Gamma' \Rightarrow \Delta$ . We have

$$\begin{array}{c} \vdots \text{I. H.} \\ \frac{\cdot u, [u][u_1; u_2]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'}{\cdot u, [u; (u_1; u_2)]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} (\text{L}\square\square)^{-1} \\ \frac{\cdot u, [u; (u_1; u_2)]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'}{\cdot u, [(u; u_1); u_2]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} (\text{A1}) \\ \frac{\cdot u, [(u; u_1); u_2]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'}{\cdot u, [u; u_1][u_2]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} (\text{L}\square\square) \\ \frac{\cdot u, [u; u_1][u_2]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'}{\cdot u, [u][u_1][u_2]\psi, [u]\Gamma', \Gamma'' \Rightarrow [u]\Delta, \Delta'} (\text{L}\square\square) \end{array}$$

Case (R $\square\square$ ): Analogous to (L $\square\square$ ).  $\square$

We finally show that (Cut) is admissible for  $\mathbf{G4}_{P,A}[\square]$ . First, we prove the admissibility of the cut rule for independent contexts  $\Gamma_1, \Delta_1$  and  $\Gamma_2, \Delta_2$ .

LEMMA 3.9

For any  $\psi \in \Psi_{P,A}$  and any multisets  $\Gamma_1, \Gamma_2, \Delta_1, \Delta_2$  of  $\Psi_{P,A}$ -formulae it holds that  $\vdash_{\mathbf{G4}_{P,A}[\square]} \Gamma_1 \Rightarrow \Delta_1, \psi$  and  $\vdash_{\mathbf{G4}_{P,A}[\square]} \psi, \Gamma_2 \Rightarrow \Delta_2$  implies  $\vdash_{\mathbf{G4}_{P,A}[\square]} \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2$ .

PROOF. We proceed by a double induction over the rank  $rk(\psi)$  of  $\psi$  and the height of a deduction.

Case 1: At least one of the sequents of the hypothesis of the claim is an axiom. A proof of the form

$$\frac{\frac{\cdot p, \Gamma_1 \Rightarrow \Delta_1, p}{p, \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} (pA) \quad \frac{\vdots h}{p, \Gamma_2 \Rightarrow \Delta_2}}{p, \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} (\text{Cut})$$

is transformed into

$$\frac{\vdots h}{p, \Gamma_2 \Rightarrow \Delta_2}}{p, \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} (\text{Weak})$$

Case 2: The cut"-formula is a side formula  $\psi$ . We only give some illustrative cases, the transformations for all the other rules is analogous.

Case 2-(RK): Then

$$\frac{\frac{\vdots h_1}{K_a \Gamma' \Rightarrow \psi'} (RK) \quad \frac{\vdots h_2}{\psi, \Gamma_2 \Rightarrow \Delta_2}}{\frac{K_a \Gamma', \Gamma_1 \Rightarrow K_a \psi', \Delta_1, \psi}{K_a \Gamma', \Gamma_1, \Gamma_2 \Rightarrow K_a \psi', \Delta_1, \Delta_2}} (\text{Cut})$$

is transformed into

$$\frac{\vdots h_1}{K_a \Gamma' \Rightarrow \psi'} (RK)}{K_a \Gamma', \Gamma_1, \Gamma_2 \Rightarrow K_a \psi', \Delta_1, \Delta_2}$$



Case 2–(RK): Then

$$\frac{\frac{\frac{\vdots h_1}{\psi'_1, \Gamma_1 \Rightarrow \psi'_2, \Delta_1, \psi} \quad (\text{R}\supset) \quad \frac{\vdots h_2}{\psi, \Gamma_2 \Rightarrow \Delta_2}}{\Gamma_1 \Rightarrow \psi'_1 \supset \psi'_2, \Delta_1, \psi} \quad (\text{Cut})}{\Gamma_1, \Gamma_2 \Rightarrow \psi'_1 \supset \psi'_2, \Delta_1, \Delta_2} \quad (\text{Cut})$$

is transformed into

$$\frac{\frac{\frac{\vdots h_1}{\psi'_1, \Gamma_1 \Rightarrow \psi'_2, \Delta_1, \psi} \quad \frac{\vdots h_2}{\psi, \Gamma_2 \Rightarrow \Delta_2}}{\psi'_1, \Gamma_1, \Gamma_2 \Rightarrow \psi'_2, \Delta_1, \Delta_2} \quad (\text{Cut})}{\Gamma_1, \Gamma_2 \Rightarrow \psi'_1 \supset \psi'_2, \Delta_1, \Delta_2} \quad (\text{R}\supset)$$

Case 2–(R $\supset$ ): Then

$$\frac{\frac{\frac{\vdots h_{11}}{\Gamma_1 \Rightarrow \cdot u, \Delta_1, \psi} \quad (\text{K}_a[u \cdot q']\psi')_{q' \in F(u)_a}, \Gamma_1 \Rightarrow \Delta_1, \psi}{[u]\text{K}_a \psi', \Gamma_1 \Rightarrow \Delta_1, \psi} \quad (\text{L}\Box\text{K}) \quad \frac{\vdots h_{12}}{\psi, \Gamma_2 \Rightarrow \Delta_2}}{\frac{[u]\text{K}_a \psi', \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2}}{[u]\text{K}_a \psi', \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \quad (\text{Cut})$$

is transformed into

$$\frac{\frac{\frac{\vdots h_{11}}{\Gamma_1 \Rightarrow \cdot u, \Delta_1, \psi} \quad \frac{\vdots h_2}{\psi, \Gamma_2 \Rightarrow \Delta_2}}{\Gamma_1, \Gamma_2 \Rightarrow \cdot u, \Delta_1, \Delta_2} \quad (\text{Cut}) \quad \frac{\frac{\frac{\vdots h_{12}}{(\text{K}_a[u \cdot q']\psi')_{q' \in F(u)_a}, \Gamma_1 \Rightarrow \Delta_1, \psi} \quad \frac{\vdots h_2}{\psi, \Gamma_2 \Rightarrow \Delta_2}}{(\text{K}_a[u \cdot q']\psi')_{q' \in F(u)_a}, \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \quad (\text{Cut})}{[u]\text{K}_a \psi', \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \quad (\text{L}\Box\text{K})$$

Case 3: In the sequents of both premisses the cut-formula  $\psi$  is principal.

Case 3–S4: as for **G4**<sub>P,A</sub>, see Theorem 2.3.

Case 3–(L $\Box$ p)–(R $\Box$ p): Then

$$\frac{\frac{\frac{\vdots h_1}{\cdot u, \Gamma_1 \Rightarrow p, \Delta_1} \quad (\text{R}\Box p) \quad \frac{\frac{\vdots h_{21}}{\Gamma_2 \Rightarrow \cdot u, \Delta_2} \quad \frac{\vdots h_{22}}{p, \Gamma_2 \Rightarrow \Delta_2}}{[u]p, \Gamma_2 \Rightarrow \Delta_2} \quad (\text{L}\Box p)}{\Gamma_1 \Rightarrow \Delta_1, [u]p} \quad (\text{Cut})}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \quad (\text{Cut})$$

is transformed into

$$\frac{\frac{\frac{\vdots h_1}{\cdot u, \Gamma_1 \Rightarrow p, \Delta_1} \quad \frac{\vdots h_{21}}{\Gamma_2 \Rightarrow \cdot u, \Delta_2}}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2, p} \quad (\text{Cut}) \quad \frac{\vdots h_{22}}{p, \Gamma_2 \Rightarrow \Delta_2}}{\frac{\Gamma_1, \Gamma_2, \Gamma_2 \Rightarrow \Delta_1, \Delta_2, \Delta_2}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \quad (\text{Contr})} \quad (\text{Cut})$$

where  $rk(\cdot u) \leq rk(u) < rk([u]p)$  and  $rk(p) = 1 < rk([u]p)$ .

Case 3-(L[] $\supset$ )-(R[] $\supset$ ): Then

$$\frac{\frac{\frac{\vdots h_1}{[u]\psi_1, \Gamma_1 \Rightarrow [u]\psi_2, \Delta_1}}{\Gamma_1 \Rightarrow \Delta_1, [u](\psi_1 \supset \psi_2)} \text{ (R}\Box\text{)} \quad \frac{\frac{\frac{\vdots h_{21}}{\Gamma_2 \Rightarrow [u]\psi_1, \Delta_2} \quad \frac{\vdots h_{22}}{[u]\psi_2, \Gamma_2 \Rightarrow \Delta_2}}{[u](\psi_1 \supset \psi_2), \Gamma_2 \Rightarrow \Delta_2} \text{ (L}\Box\text{)}}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \text{ (Cut)}$$

is transformed into

$$\frac{\frac{\frac{\Gamma_2 \Rightarrow [\mathbf{u}]\psi_1, \Delta_2 \quad \Gamma_1, [\mathbf{u}]\psi_1 \Rightarrow \Delta_1, [\mathbf{u}]\psi_2}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2, [\mathbf{u}]\psi_2} \text{ (Cut)} \quad \frac{[\mathbf{u}]\psi_2, \Gamma_2 \Rightarrow \Delta_2}{\Gamma_1, \Gamma_2, \Gamma_2 \Rightarrow \Delta_1, \Delta_2, \Delta_2} \text{ (Cut)}}{\frac{\Gamma_1, \Gamma_2, \Gamma_2 \Rightarrow \Delta_1, \Delta_2, \Delta_2}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \text{ (Contr)}} \text{ (Cut)}$$

where  $rk(\cdot u) \leq rk(u) < rk([u](\psi_1 \supset \psi_2)) = (4 + rk(u)) \cdot (1 + \max\{rk(\psi_1), rk(\psi_2)\})$  and  $rk([u]\psi_1), rk([u]\psi_2) < rk([u](\psi_1 \supset \psi_2))$ .

*Case 3*—(L[]K)—(R[]K): Then

$$\frac{\frac{(\cdot u, \Gamma_1 \Rightarrow K_a[u \cdot q']\psi, \Delta_1)_{q' \in F(u)_a} \quad (\mathbf{R}[\Box]K) \quad \frac{\Gamma_2 \Rightarrow \cdot u, \Delta_2 \quad (K_a[u \cdot q']\psi)_{q' \in F(u)_a}, \Gamma_2 \Rightarrow \Delta_2}{[u]K_a\psi, \Gamma_2 \Rightarrow \Delta_2} \quad (\mathbf{L}[\Box]K)}{\Gamma_1 \Rightarrow \Delta_1, [u]K_a\psi} \quad (\mathbf{Cut})$$

is transformed into

$$\frac{\Gamma_2 \Rightarrow \Delta_2, \dot{u}}{\frac{\Gamma_1, \Gamma_2, \Gamma_2 \Rightarrow \Delta_1, \Delta_2, \Delta_2}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \text{ (Contr)}} \frac{\dot{h}_{21} \quad \frac{\dot{u}, \Gamma_1 \Rightarrow \Delta_1, K_a[\dot{u} \cdot q'_1]\psi}{\dot{u}, \Gamma_1, \dot{u}, \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_1, \Delta_2} \quad \frac{\dot{h}_{1q'_1} \quad \frac{\dot{u}, \Gamma_1 \Rightarrow \Delta_1, K_a[\dot{u} \cdot q'_1]\psi}{K_a[\dot{u} \cdot q'_1]\psi, \dot{u}, \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_1, \Delta_2} \quad \frac{\dot{h}_{1q'_2} \quad \frac{\dot{u}, \Gamma_1 \Rightarrow \Delta_1, K_a[\dot{u} \cdot q'_2]\psi}{K_a[\dot{u} \cdot q'_2]\psi, \dot{u}, \Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_1, \Delta_2} \quad \frac{\dot{h}_{22} \quad (K_a[\dot{u} \cdot q']\psi)_{q' \in F(u)_a}, \Gamma_2 \Rightarrow \Delta_2}{(\text{Contr}), (\text{Cut}), h_{1q'}}}{(\text{Cut})} \text{ (Cut)}$$

where the reasoning for  $h_{1q'}$  is iterated over all  $q' \in F(u)_a$  as exemplified for  $h_{1q_1'}$  and  $h_{1q_2'}$ . It holds that  $rk(\cdot u) \leq rk(u) < rk([u]K_a\psi) = (4 + rk(u)) \cdot (1 + rk(\psi))$  and  $rk(K_a[u \cdot q']\psi) = 1 + (4 + rk(u)) \cdot rk(\psi) < rk([u]K_a\psi)$ .

Case 3—(L[ ] [ ])—(R[ ] [ ]): Then

$$\frac{\frac{\frac{\vdots h_1}{\Gamma_1 \Rightarrow \Delta_1, [u_1; u_2]\psi} \quad \frac{[u_1; u_2]\psi, \Gamma_2 \Rightarrow \Delta_2}{[u_1][u_2]\psi, \Gamma_2 \Rightarrow \Delta_2} \quad (\mathbf{R}[\Box])}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \quad \frac{(\mathbf{L}[\Box])}{(\mathbf{Cut})}$$

is transformed into

$$\frac{\frac{\vdots h_1}{\Gamma_1 \Rightarrow \Delta_1, [u_1; u_2]\psi} \quad [u_1; u_2]\psi, \Gamma_2 \Rightarrow \Delta_2}{\Gamma_1, \Gamma_2 \Rightarrow \Delta_1, \Delta_2} \text{ (Cut)}$$

where  $rk([u_1; u_2]\psi) < rk([u_1][u_2]\psi)$ . □

By admissibility of (Contr), see Lemma 3.4, the admissibility of (Cut) is a direct consequence of Lemma 3.9.

**THEOREM 3.10**

(Cut) is admissible for  $\mathbf{G4}_{P,A}[]$ .

**PROOF.** We obtain  $\vdash_{\mathbf{G4}_{P,A}[]} \Gamma \Rightarrow \Delta$  from  $\vdash_{\mathbf{G4}_{P,A}[]} \Gamma \Rightarrow \Delta, \psi$  and  $\vdash_{\mathbf{G4}_{P,A}[]} \psi, \Gamma \Rightarrow \Delta$  as follows:

$$\frac{\frac{\Gamma \Rightarrow \Delta, \psi \quad \psi, \Gamma \Rightarrow \Delta}{\Gamma, \Gamma \Rightarrow \Delta, \Delta} \text{ Lem. 11}}{\Gamma \Rightarrow \Delta} \text{ (Contr)}$$
□

**THEOREM 4**

$\mathbf{G4}_{P,A}[]$  is sound and complete for  $\mathbf{DS4}_{P,A}$ .

**PROOF.** For soundness, it suffices to check that each rule of  $\mathbf{G4}_{P,A}[]$  is valid in  $\mathbf{DS4}_{P,A}$ ; for completeness, that each axiom of the Hilbert-style axiomatization Table 5 is derivable in  $\mathbf{G4}_{P,A}[]$  and that each rule is admissible. Modus ponens (MP) follows from Theorem 3.10. For the axioms, we only show the derivations of (red $\supset$ ) and (redK); all other case are analogous.

*Case (red $\supset$ ):* We have

$$\frac{\frac{\frac{\vdots \text{Lem. 5}}{\psi_1 \Rightarrow \psi_1, \psi_2} \quad \frac{\vdots \text{Lem. 5}}{\psi_1, \psi_2 \Rightarrow \psi_2}}{\psi_1 \supset \psi_2, \psi_1 \Rightarrow \psi_2} \text{ (L}\supset\text{)} \quad \frac{\frac{\frac{\vdots \text{Lem. 5}}{[u]\psi_1 \Rightarrow [u]\psi_1, [u]\psi_2} \quad \frac{\vdots \text{Lem. 5}}{[u]\psi_1, [u]\psi_2 \Rightarrow [u]\psi_2}}{[u]\psi_1, [u]\psi_1 \supset [u]\psi_2 \Rightarrow [u]\psi_2} \text{ (L}\supset\text{)}}{\frac{[u](\psi_1 \supset \psi_2), [u]\psi_1 \Rightarrow [u]\psi_2}{[u](\psi_1 \supset \psi_2) \Rightarrow [u]\psi_1 \supset [u]\psi_2} \text{ (LR[]), Lem. 7} \quad \frac{[u]\psi_1, [u]\psi_1 \supset [u]\psi_2 \Rightarrow [u]\psi_2}{[u]\psi_1 \supset [u]\psi_2 \Rightarrow [u](\psi_1 \supset \psi_2)} \text{ (R[]}\supset\text{)}}{\Rightarrow [u](\psi_1 \supset \psi_2) \leftrightarrow ([u]\psi_1 \supset [u]\psi_2)} \text{ (R}\leftrightarrow\text{)}$$

*Case (redK):* We have

$$\frac{\frac{\vdots *1}{[u]K_a \psi \Rightarrow \cdot u \supset \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi} \quad \frac{\vdots *2}{\cdot u \supset \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi \Rightarrow [u]K_a \psi}}{\Rightarrow [u]K_a \psi \leftrightarrow \cdot u \supset \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi} \text{ (R}\leftrightarrow\text{)}$$

with  $*_1$  given by

$$\frac{\frac{\frac{\vdots \text{Lem. 5}}{\cdot u \Rightarrow \cdot u, \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi} \quad \frac{\frac{\vdots \text{Lem. 5}}{(\cdot u, (K_a[u \cdot q']\psi)_{q' \in F(u)_a} \Rightarrow K_a[u \cdot q]\psi)_{q \in F(u)_a}} \quad (R\wedge)^+}{\cdot u, (K_a[u \cdot q']\psi)_{q' \in F(u)_a} \Rightarrow \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi} \quad (L\Box K)}{\frac{\cdot u, [u]K_a \psi \Rightarrow \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi}{[u]K_a \psi \Rightarrow \cdot u \supset \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi} \quad (R\supset)}$$

where  $(R\wedge)^+$  denotes iterated application of  $(R\wedge)$ , and  $*_2$  is given by

$$\frac{\frac{\frac{\vdots \text{Lem. 5}}{(\cdot u \Rightarrow \cdot u, K_a[u \cdot q]\psi)_{q \in F(u)_a}} \quad \frac{\frac{\vdots \text{Lem. 5}}{(\cdot u, (K_a[u \cdot q']\psi)_{q' \in F(u)_a} \Rightarrow K_a[u \cdot q]\psi)_{q \in F(u)_a}} \quad (L\wedge)^+}{(\cdot u, \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi \Rightarrow K_a[u \cdot q]\psi)_{q \in F(u)_a}} \quad (L\supset)}{\frac{(\cdot u, \cdot u \supset \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi \Rightarrow K_a[u \cdot q]\psi)_{q \in F(u)_a}}{\cdot u \supset \bigwedge_{q' \in F(u)_a} K_a[u \cdot q']\psi \Rightarrow [u]K_a \psi} \quad (R\Box K)}$$

where  $(L\wedge)^+$  denotes iterated application of  $(R\wedge)$ . □

## 4 Conclusions

We presented the novel ordinary Gentzen-type calculus  $\mathbf{G4}_{P,A}[]$  for DEL. The special feature of  $\mathbf{G4}_{P,A}[]$  is that—instead of internalizing the accessibility relation—the rules for the action modality correspond to the reduction rules in [7, 42]. The main results of this work are the admissibility of the cut rule and the completeness of the calculus.

Currently,  $\mathbf{G4}_{P,A}[]$  is based on  $\mathbf{S4}$  modal logic. In the future, we want to extend our calculus to  $\mathbf{S5}$  and to include rules for general knowledge and with further action combinators like selection and iteration. We also want to integrate the calculus into a systematic software development approach for collective adaptive systems [20].

## Acknowledgements

We thank the anonymous reviewers for their critical evaluations and their constructive comments. In particular, our thanks go to one of the reviewers for suggesting simplifications of some of our proof rules. We also thank Rolf Hennicker for constructive and helpful discussions on dynamic epistemic logic.

## References

- [1] G. Aucher, B. Maubert and F. Schwarzentruher. Generalized DEL-sequents. In *Proc. 13th Europ. Conf. Logics in Artificial Intelligence (JELIA)*, L. F. del Cerro, A. Herzig, and J. Mengin, eds. Vol. 7519 of *Lect. Notes Comp. Sci.*, pp. 54–66. Springer, 2012.
- [2] P. Balbiani, V. Demange and D. Galmiche. A sequent calculus with labels for PAL. In *10th Conf. Advances in Modal Logic (AiML 2014)*, 2014. <https://members.loria.fr/DGalmiche/files/publications.html>.

- [3] P. Balbiani and D. Galmiche. About intuitionistic public announcement logic. In *Advances in Modal Logic*, L. D. Beklemishev, S. Demri, and A. Maté, eds. Vol. 11, pp. 97–116. College Publ., 2016.
- [4] P. Balbiani, H. van Ditmarsch, A. Herzig and T. de Lima. Tableaux for public announcement logic. *Journal of Logic and Computation*, **20**, 55–76, 2010.
- [5] A. Baltag, B. Coecke and M. Sadrzadeh. Algebra and sequent calculus for epistemic actions. In *Proc. 2nd Int. Ws. Logic and Communication in Multi-Agent Systems 2004*, W. van der Hoek, A. Lomuscio, E. de Vink, and M. Wooldridge, eds. Vol. 126 of *Electron. Notes Theor. Comput. Sci.*, pp. 27–52. Elsevier, 2005.
- [6] A. Baltag, L. S. Moss and S. Solecki. The logic of public announcements and common knowledge and private suspicions. In *Proc. 7th Conf. Theoretical Aspects of Rationality and Knowledge (TARK 1998)*, I. Gilboa, ed., pp. 43–56. Morgan Kaufmann, 1998.
- [7] A. Baltag and B. Renne. Dynamic epistemic logic. In *The Stanford Encyclopedia of Philosophy*, E. N. Zalta, ed. Metaphysics Research Lab. Winter 2016 edition. Stanford University, 2016.
- [8] T. Bräuner. A cut-free Gentzen formulation of the modal logic S5. *Logic Journal of IGPL*, **8**, 629–643, 2000.
- [9] K. Brännler. Deep sequent systems for modal logic. *Archive for Mathematical Logic*, **48**, 551–577, 2009.
- [10] P. Cenciarelli, A. Knapp, B. Reus and M. Wirsing. From sequential to multi-threaded Java: An event-based operational semantics. In *Proc. 6th Int. Conf. Algebraic Methodology and Software Technology (AMAST 1997)*, M. Johnson, ed. Vol. 1349 of *Lect. Notes Comp. Sci.*, pp. 75–90. Springer, 1997.
- [11] J. N. Crossley, L. Mandel and M. Wirsing. First-order constrained lambda calculus. In *Proc. 1st Int. Ws. Frontiers of Combining Systems (FroCoS 1996)*, F. Baader and K. U. Schulz, eds. Vol. 3 of *Applied Logic Series*, pp. 339–356. Kluwer Academic Publishers, 1996.
- [12] J. N. Crossley, I. H. Poernomo and M. Wirsing. Extraction of structured programs from specification proofs. In *Sel. Papers 14th Int. Ws. Recent Trends in Algebraic Development Techniques (WADT 1999)*, D. Bert, C. Choppy, and P. D. Mosses, eds. Vol. 1827 of *Lect. Notes Comp. Sci.*, pp. 419–437. Springer, 1999.
- [13] K. Došen. Sequent-systems and groupoid models I. *Studia Logica*, **47**, 353–385, 1988.
- [14] R. Dyckhoff and M. Sadrzadeh. A cut-free sequent calculus for algebraic dynamic epistemic logic. *Technical Report CS-RR-10-11*. Oxford University Computing Laboratory, 2011.
- [15] S. Frittella, G. Greco, A. Kurz, A. Palmigiano and V. Sikimic. Multi-type display calculus for dynamic epistemic logic. *Journal of Logic and Computation*, **26**, 2017–2065, 2016.
- [16] S. Frittella, G. Greco, A. Kurz, A. Palmigiano and V. Sikimic. A proof-theoretic semantic analysis of dynamic epistemic logic. *Journal of Logic and Computation*, **26**, 1961–2015, 2016.
- [17] J. D. Gerbrandy. *Bisimulations on Planet Kripke*. PhD Thesis, University of Amsterdam, 1998.
- [18] R. Hakli and S. Negri. Does the deduction theorem fail for modal logic? *Synthese*, **187**, 849–867, 2012.
- [19] J. U. Hansen. Terminating tableaux for dynamic epistemic logics. In *Proc. 6th Ws. Methods for Modalities (M4M)*, T. Boland and T. Bräuner, eds. Vol. 262 of *Electron. Notes Theor. Comput. Sci.*, pp. 141–156. Elsevier, 2010.
- [20] R. Hennicker, A. Knapp and M. Wirsing. Epistemic ensembles. In *Proc. 11th Int. Symp. Leveraging Applications of Formal Methods, Verification and Validation (ISoLA 2022). Part III: Adaptation and Learning*, T. Margaria and B. Steffen, eds. Vol. 13703 of *Lect. Notes Comp. Sci.*, pp. 110–126. Springer, 2022.

- [21] M. M. Hölzl. *Constraint-Lambda Calculi: Theory and Applications*. PhD Thesis, Ludwig-Maximilians-Universität München, Germany, 2001.
- [22] M. M. Hölzl and J. N. Crossley. Constraint-lambda calculi. In *Proc. 4th Int. Ws. Frontiers of Combining Systems (FroCoS 2002)*, A. Armando, ed. Vol. 2309 of *Lect. Notes Comp. Sci.*, pp. 207–221. Springer, 2002.
- [23] M. M. Hölzl and J. N. Crossley. Disjunctive constraint lambda calculi. In *Proc. 12th Int. Conf. Logic for Programming, Artificial Intelligence, and Reasoning (LPAR 2005)*, G. Sutcliffe and A. Voronkov, eds. Vol. 3835 of *Lect. Notes Comp. Sci.*, pp. 64–78. Springer, 2005.
- [24] A. Knapp. *A Formal Approach to Object-Oriented Software Engineering*. PhD Thesis, Ludwig-Maximilians-Universität München, Germany, 2000.
- [25] A. Knapp, S. Merz, M. Wirsing and J. Zappe. Specification and refinement of mobile systems in MTLA and mobile UML. *Theoretical Computer Science*, **351**, 184–202, 2006.
- [26] P. Maffezoli and S. Negri. A proof-theoretical perspective on public announcement logic. *Logic & Philosophy of Science*, **IX**, 49–59, 2011.
- [27] L. Mandel. *Constrained Lambda Calculus*. PhD Thesis, Ludwig-Maximilians-Universität München, Germany, 1995.
- [28] L. Mandel, M. Wirsing and J. N. Crossley. Cálculo lambda de primer orden con constraints y la propiedad Church–Rosser. In *Proc. 2<sup>do</sup>. Ws. Aspectos Teóricos de la Inteligencia Artificial*, 1996.
- [29] S. Negri. Proof analysis in modal logic. *Journal of Philosophical Logic*, **34**, 507–544, 2005.
- [30] S. Negri. Proof theory for modal logic. *Philosophy Compass*, **6**, 523–538, 2011.
- [31] S. Negri and J. von Plato. *Structural Proof Theory*. Cambridge University Press, 2001.
- [32] S. Nomura, H. Ono and K. Sano. A cut-free labelled sequent calculus for dynamic epistemic logic. In *Proc. Int. Symp. Logical Foundations of Computer Science (LFCS 2016)*, S. N. Artëmov and A. Nerode, eds. Vol. 9537 of *Lect. Notes Comp. Sci.*, pp. 283–298. Springer, 2016.
- [33] S. Nomura, H. Ono and K. Sano. A cut-free labelled sequent calculus for dynamic epistemic logic. *Journal of Logic and Computation*, **30**, 321–348, 2020.
- [34] S. Nomura, K. Sano and S. Tojo. A labelled sequent calculus for intuitionistic public announcement logic. In *Proc. 20th Int. Conf. Logic for Programming, Artificial Intelligence, and Reasoning (LPAR-20)*, M. Davis, A. Fehnker, A. McIver, and A. Voronkov, eds. Vol. 9450 of *Lect. Notes Comp. Sci.*, pp. 187–202. Springer, 2015.
- [35] M. Ohnishi and K. Matsumoto. Gentzen method in modal calculi. *Osaka Journal of Mathematics*, **9**, 113–130, 1957.
- [36] H. Ono. Proof-theoretic methods in nonclassical logic—An introduction. In *Theories of Types and Proofs*, M. Takahashi, M. Okada, and M. Dezani-Ciancaglini, eds. Vol. 2 of *Math. Soc. Japan Memoirs*, pp. 207–254. Math. Soc. Japan, 1998.
- [37] J. Plaza. Logics of public communications. In *Proc. 4th Int. Symp. Methodologies for Intelligent Systems (ISMIS): Poster Session Program*, M. L. Emrich, M. S. Pfeifer, M. Hadzikadic, and Z. W. Ras, eds, pp. 201–216. Oak Ridge National Laboratory, ORNL/DSRD-24, 1989.
- [38] J. Plaza. Logics of public communications. *Synthese*, **158**, 165–179, 2007.
- [39] I. H. Poernomo, J. N. Crossley and M. Wirsing. Programs, proofs and parametrized specifications. In *Sel. Papers 15th Int. Ws. Recent Trends in Algebraic Development Techniques (WADT 2001)*, M. Cerioli and G. Reggio, eds. Vol. 2267 of *Lect. Notes Comp. Sci.*, pp. 280–304. Springer, 2001.
- [40] I. H. Poernomo, M. Wirsing and J. N. Crossley. *Adapting Proofs-as-Programs—The Curry–Howard Protocol*. Monographs in Computer Science. Springer, 2005.

- [41] F. Poggiolesi. A cut-free simple sequent calculus for modal logic S5. *The Review of Symbolic Logic*, **1**, 3–15, 2008.
- [42] H. van Ditmarsch, W. van der Hoek and B. Kooi. *Dynamic Epistemic Logic*. Vol. 337 of *Synthese Library*. Springer, 2008.
- [43] H. Wansing. Sequent systems for modal logics. In *Handbook of Philosophical Logic*, D. M. Gabbay and F. Guenther, eds. Vol. 8, pp. 61–145. Springer, 2002.
- [44] M. Wirsing, J. N. Crossley and H. Peterreins. Proof normalization of structured algebraic specifications is convergent. In *Sel. Papers 13th Int. Ws. Recent Trends in Algebraic Development Techniques (WADT 1998)*, J. L. Fiadeiro, ed. Vol. 1589 of *Lect. Notes Comp. Sci.*, pp. 326–340. Springer, 1998.
- [45] H. Wu, H. van Ditmarsch and J. Chen. A labelled sequent calculus for public announcement logic. *Presented at the 3rd Dynamic Logic Ws. (DaLi)*, 2022. <http://dali2022.campus.ciencias.ulisboa.pt/>.