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A Comparative Study of Sequential Feature Selection Methods for Support Vector Machine

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Abstract—In this paper we investigate existing feature selection algorithms combined with support vector machine (SBS). Two ranking-based algorithms, recursive feature elimination (RFE) and incremental regularized risk minimization (IRRM), and greedy sequential backward search (SBS) are tested by using biosignal dataset which contains 35 features per sample and a total of 25 samples labeled by four emotion classes. The performance of the selection algorithms are compared by considering recognition rates obtained by the leave-one-out validation.

I. INTRODUCTION

TOWDAYS in many pattern classification problems it is not uncommon that we are confronted with a very high dimensional variable space, with hundreds to tens of thousands of attributes or features. In this case, not only the "curse of dimensionality" caused by a very high ratio of number of features to number of data samples is problematic but also the irrelevant features in the feature set that undermine the performance of a given learning algorithm. The purpose of feature selection is to eliminate irrelevant and noisy features in the original feature set and to find a new feature subset which can improve computational and functional performance of a given classifier. Since most supervised learning algorithms such as support vector machine (SVM) do not offer the opportunity for automatically filtering the irrelevant and redundant features, feature selection/reduction as preprocessing plays an important role in pattern classification system. A well selected feature subset does help gain a deeper insight about the concept to be learned and generalize the performance of classifier with reduced computational cost.

There are a number of papers in this special issue. We refer to [1] and [2] for a comprehensive survey. In general, one can approach to feature selection through one of two ways: given a number of selected features $m \ll n$, where n is number of features, find the m features that give the smallest expected generalization error, or given a maximum allowable generalization error γ , find the smallest number m of features. Note that

choices of m in former case can usually be parameterized as choices of γ in latter case [3]. Based on the nature of algorithms, most methods for feature selection can be categorized to two types, i.e. the filter method and wrapper method. For filter approach one performs a feature selection with regard to some predefined relevance measure before applying a given induction algorithm, accordingly such methods evaluate a feature based on its marginal contribution to the class discrimination without considering its interaction with other features. Wrapper methods, on the other hand, use the learning algorithm, which is used for classification, as induction method for evaluation criterion. Hence designing of a wrapper method depends on the classifier.

In this paper, we present a comparative analysis of different wrapper feature selection methods which are adapted particularly to the SVM classifier. For validation of the selected features, we used the feature set that are extracted from biosignal dataset in our previous work on emotion recognition [4]. The performance of selection methods were compared with sequential backward selection (SBS) method.

II. FEATURE SELECTION METHODS FOR SVM

A. Support Vector Machine

The support vector machine is a binary classifier algorithm that looks for an optimal hyperplane (Fig. 1) as a decision function in a high-dimensional space [5], [6].

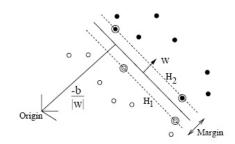


Fig. 1. Basic idea of the SVM algorithm

In supervised classification task we have a training dataset $\{\mathbf{x}_k, y_k\} \in \mathbb{R}^n \times \{-1, 1\}$, where \mathbf{x}_k are the training samples and y_k the class labels. Before of computing a decision function one needs to make a mapping \mathbf{x} into a high dimensional space using a function $\boldsymbol{\Phi}$. Different mappings $\mathbf{x} \mapsto \boldsymbol{\Phi}(\mathbf{x}) \in \mathcal{H}$ construct different SVMs. The following function describes an equation of separating the hyperplane:

$$f(\mathbf{x}) = \langle \mathbf{w}, \mathbf{\Phi}(\mathbf{x}) \rangle + b = \sum_{k} \alpha_{k}^{0} y_{k} K \langle \mathbf{x}_{k}, \mathbf{x} \rangle + b \quad (1)$$

where K is a kernel function defined as an inner product in \mathcal{H} . Thus, the goal of the SVM is to maximize the distance to the closest image $\Phi(\mathbf{x}_k)$ from the training samples. The optimization problem, where misclassified examples from the SVM classifier will be quadratically penalized, can be written as,

$$\min_{\mathbf{w},\xi} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{k=1}^m \xi_k^2 \tag{2}$$

under the constraint $\forall k, y_k f(\mathbf{x}_k) \ge 1 - \xi_k$. In Eq. 2, $\|\mathbf{w}\|$ is inverse to the margin size and $\|\cdot\|$ is the 2-norm and the regularization constant C > 0 determines the trade-off between the empirical error and the complexity term. The solution of Eq. 2 can be obtained by using the Lagrangian multipliers:

$$\mathbf{w} = \sum_{k=1}^{m} \alpha_k^* y_k \mathbf{\Phi}(\mathbf{x}_k) \tag{3}$$

where α_k^* is the solution of the following quadratic optimization problem:

$$\max_{\alpha} W(\alpha) = \sum_{k=1}^{m} \alpha_k - \frac{1}{2} \sum_{k,l}^{m} \alpha_k \alpha_l y_k y_l \Big(K(\mathbf{x}_k, \mathbf{x}_l) + \frac{1}{C} \delta_{k,l} \Big)$$
(4)

subject to $\sum_{k=1}^{m} y_k \alpha_k = 0$ and $\forall k, \alpha_k \ge 0$, where $\delta_{k,l}$ is the Kronecker delta and $K(\mathbf{x}_k, \mathbf{x}_l) = \langle \Phi(\mathbf{x}_k), \Phi(\mathbf{x}_l) \rangle$ is the Gram matrix of the training samples.

B. Ranking algorithms for SVM

In ranking algorithms for feature selection in literature, different criteria C_t and their combinations are used such as bounds which operate with weight vector $\|\mathbf{w}\|^2$, radius/margin bound $R^2 \|\mathbf{w}\|^2$, $R^2 W^2$ or span estimate. Also different variable space search algorithms are used like a greedy algorithm or gradient descent. Furthermore, for each criterion, two approaches similarly to neural network based variable selection are proposed in the work [7], zero-order method and firstorder method. Zero-order method uses the criterion C_t directly for variable ranking and identifies the variable that produces the smallest value of C_t when removed. Hence, the ranking criterion $R_c(i) = C_t^{(i)}$, where $C_t^{(i)}$ is the criterion value when variable *i* has been removed. In the latter method, derivatives of the criterion with regard to each variable are used. So one estimates the influence of the variable on the criterion which is calculated as an absolute value of the derivative. Ranking criterion is then $R_c(i) = |\nabla C_t^{(i)}|$.

1) SVM-Recursive Feature Elimination Algorithm: The most common feature selection algorithm for SVM is the recursive feature elimination (RFE) algorithm. This realizes an idea of sequential backward selection and is based on finding a subset, which supplies the best result. RFE begins with all the features and removes one feature at a time, which most completes an input dataset. As noted α_k^* is the solution of Eq. 4 and $\alpha_k^{*(i)}$ denotes the corresponding solution, when i-th feature is removed. Ranking criterion for a given variable *i* is then,

$$\left| \|\mathbf{w}\|^{2} - \|\mathbf{w}^{(i)}\|^{2} \right| = \frac{1}{2} \left| \sum_{k,j} \alpha_{k}^{*} \alpha_{j}^{*} y_{k} y_{j} K(\mathbf{x}_{k}, \mathbf{x}_{j}) - \sum_{k,j} \alpha_{k}^{*(i)} \alpha_{j}^{*(i)} y_{k} y_{j} K^{(i)}(\mathbf{x}_{k}, \mathbf{x}_{j}) \right|$$
(5)

where $K^{(i)}$ is the Gram matrix of the training data when variable *i* is removed. In this case each feature obtains its own ranking. For a given dataset with the size of *d*, the goal is to remove *r* features (r < d) based on the ranking value for which the result of Eq. 5 becomes minimal. The elimination procedure is repeated until the number of features has been reached. $\alpha_k^{*(i)}$ is supposed to be equal to α_k^* , even if a variable has been removed. Note that this algorithm is identical to the zero-order method with $\|\mathbf{w}\|^2$ criterion, since the first sum in Eq. 5 is constant during the evaluation of $R_c(i)$. Although the RFE algorithm provides a fast selection, it can lead to suboptimal solutions because it uses a greedy strategy to perform backward elimination.

2) SVM-IRRM Algorithm: Incremental regularized risk minimization (IRRM) algorithm proposed in [8] is based on the SVM-RFE approach. The basic idea of the algorithm is as follows: one calculates a ranking value for each feature and than divides all these features with regard to their ranking in sets S and R. Hence, given dfeatures, the set S constrains m features which are used for the classifier and the set R consists of d-m features which are the removed features. Since there might be features in R which are relevant to classification, one combines the features of set S with some features of set R in order to improve classification accuracy with reduced regularized risk. Table I shows the algorithm and we refer to [8] for more detailed description of algorithm. **IRRM** algorithm

```
perform RFE
S = set of selected feature
R = set of removed features (queue)
t = 0
repeat
  S_{old} = S
   repeat
     \vec{R}_{reg}^{old} = R_{reg}
     compute R_{reg} for feature in S
     if R_{reg}^{old} < R_{reg}
       restore old {\cal S}
     C = \eta highest ranked features
     {\tt from}\ R
     S \leftarrow S \cup C
     R \leftarrow R - C
     remove \eta features from S
     according to (5)
     put removed features at the end of
     queue R
   until convergence
   resort queue R by means of RFE
   t \leftarrow t + 1
until S == S_{old} AND t > 1
   return best solution S^*
```



For each feature in new set S obtained by combining S with the features in R, the regularized risk should be calculated,

$$R_{reg}[f] = R_{emp}[f] + \frac{1}{2} \|\mathbf{w}\|^2$$
(6)

where R_{emp} denotes the empirical risk (training error), i.e.

$$R_{emp}[f] = \frac{1}{n} \sum_{i=1}^{n} l(\mathbf{x}_i, y_i, f(\mathbf{x}_i))$$
(7)

The regularized risk in Eq. 6 is an upper bound on the expected generalization error (risk) over all possible patterns drawn from the unknown distribution $\mathcal{P}(\mathbf{x}, y)$, i.e.,

$$R[f] = \int_{\mathbf{x},y} l(\mathbf{x}, y, f(\mathbf{x})) d\mathcal{P}(\mathbf{x}, y)$$
(8)

If the regularized risk does not change significantly any more, one assumes that the algorithm is converged. Then one resorts the queue by means of RFE and restarts the whole algorithm.

3) Gradient methods: Main idea of gradient method is to estimate the sensitivity of a bound with respect to a variable. For example, one introduces a scaling factor and then computes the gradient of a criterion with respect to the scaling factor v. The computation of gradient can be performed by componentwise multiplication on the input variables and the kernel $k(\mathbf{x}, \mathbf{x}')$ becomes $k(v \cdot \mathbf{x}, v \cdot$ **x**'). As a result, for a Gaussian Kernel i.e., $k(v \cdot \mathbf{x}, v \cdot \mathbf{x}') = e^{-\frac{|v \cdot \mathbf{x} - v \cdot \mathbf{x}'|^2}{2\sigma^2}}$, one obtains following derivatives,

$$\frac{\partial k}{\partial v_i} = -\frac{1}{\sigma^2} (v_i \mathbf{x}_i - v_i \mathbf{x}'_i)^2 k(\mathbf{x}, \mathbf{x}')$$

$$= -\frac{1}{\sigma^2} (\mathbf{x}_i - \mathbf{x}'_i)^2 k(\mathbf{x}, \mathbf{x}')$$
(9)

assuming that $v_i = 1$. The ranking term for a given criterion C_t becomes then,

$$R_c(i) = \left| \frac{\partial C_t(\alpha, b)}{\partial v_i} \right| \tag{10}$$

where C_t is either $||\mathbf{w}||^2$, $R^2\mathbf{w}^2$ or $\sum_p \alpha_p^* S_p^2$ and depends on the solution of Eq. 4. and the bias b. Both criterions are based on radius/margin bound and are nearly. Four ranking terms obtained by using the results of [9][10] are as following:

• weight vector gradient:

$$R_c(i) = \left| \sum_{i,j} \alpha_k^* \alpha_j^* y_k y_j \frac{\partial k(\upsilon \cdot \mathbf{x}_k, \upsilon \cdot \mathbf{x}_j)}{\partial \upsilon_i} \right|$$

• radius/margin gradient:

$$\begin{split} R_{c}(i) &= \left| \|\mathbf{w}\|^{2} \sum_{k,j} (\beta_{k}\beta_{j} - \beta_{k}\delta_{k,j}) \frac{\partial k(\boldsymbol{\upsilon} \cdot \mathbf{x}_{k}, \boldsymbol{\upsilon} \cdot \mathbf{x}_{j})}{\partial \upsilon_{i}} + \right. \\ & \left. R^{2} \sum_{k,j} \alpha_{k}^{*} \alpha_{j}^{*} y_{k} y_{j} \frac{\partial k(\boldsymbol{\upsilon} \cdot \mathbf{x}_{k}, \boldsymbol{\upsilon} \cdot \mathbf{x}_{j})}{\partial \upsilon_{i}} \right| \end{split}$$

where R^2 is the optimal objective function of the following problem:

$$\max_{\beta} \sum_{k} \beta_k k(\upsilon \cdot \mathbf{x}_k, \upsilon \cdot \mathbf{x}_k) - \sum_{k,j} \beta_k \beta_j k(\upsilon \cdot \mathbf{x}_k, \upsilon \cdot \mathbf{x}_j)$$

where $\sum_k \beta_k$ and $\beta_k \ge 0, \forall k$.

span estimate gradient:

$$R_{c}(i) = \left| \sum_{p=1}^{l} 2 \left(-H^{-1} \frac{\partial H}{\partial v_{i}} \alpha^{*} \right)_{pp} S_{p}^{2} + \alpha_{p}^{*} S_{p}^{4} \left(\tilde{K}_{SV}^{-1} \frac{\partial \tilde{K}_{SV}}{\partial v_{i}} \tilde{K}_{SV}^{-1} \right)_{pp} \right|$$

where H is the matrix

$$H = \begin{pmatrix} K^Y & Y \\ Y^T & 0 \end{pmatrix}$$
 and $K^Y_{kj} = y_k y_j k(\upsilon\cdot\mathbf{x}_k,\upsilon\cdot\mathbf{x}_j)$

III. EXPERIMENT

In order to investigate the performance of the feature selection methods described above, we used biosignal dataset from our previous work on emotion recognition [4]. The feature set contains 25 samples and each sample consists of 35 features. It is labeled by four emotional classes, i.e., joy, anger, sad, and pleasure. The original biosignal dataset was recorded by using four channel biosensors, electromyogram (EMG), electrocardiogram (ECG), skin conductivity (SC), and respiration change (RSP) while the subject was listening to music songs which the subject carefully handpicked with regard to the four target emotions.

Each of the four emotions represents four quadrants of 2-D emotion model, respectively, which is spanned by two axes, arousal and valence [11]. For supporting more detailed insight into characteristics of the selection methods, we performed two cases of binary classification, instead of a direct four-class classification. For arousal classification, the samples of joy and anger were labeled as high arousal, and sad and pleasure as low arousal. For valence classification, the samples of anger and sad were labeled as negative valence, and joy and pleasure as positive valence.

We tested three feature selection methods, SVM-RFE, SVM-IRRM, and the common sequential backward search (SBS) by leave-one-out cross validation. For former two algorithms, the $\|\mathbf{w}\|^2$ criterion was used and the Gaussian-based radial basis function (RBF) kernel with fixed parameters, i.e. $\sigma = 0, 9, d = 5$, and hyper-parameter C = 500, was used for the SVM classifier. The leave-one-out validation is the most straightforward method but suffers from high computational cost. We chose this method, though, because the dataset contains relatively small number of samples.

	Number of features				
Methods	5	10	15	20	
$RFE- \mathbf{w} ^2$	82.38%	76.81%	76.93%	77.10 %	
IRRM- $\ \mathbf{w}\ ^2$	84.68%	78.23%	79.03%	79.32 %	
	Number of features		Rate of recognition		
SVM	35		83.00 %		
SVM-SBS	3		95.16%		

TABLE II RESULTS OF AROUSAL CLASSIFICATION

Table II and III show the results of the binary classifications. Overall it turned out that the arousal intensity of emotional states can be better classified than the valence classification, regardless which selection method is used. In fact, this is already proven in many previous works on automatic emotion recognition. Despite their adapted

	Number of features				
Methods	5	10	15	20	
$RFE- \mathbf{w} ^2$	52.62%	53.08%	56.01%	59.89%	
$\ \mathbf{RRM}\ ^2$	57.65%	59.45%	62.26%	66.21%	
	Number of features		Rate of recognition		
SVM	35		17.74 %		
SVM-SBS	8		79.84%		

TABLE III RESULTS OF VALENCE CLASSIFICATION

characteristic of the feature selection methods we tested, RFE and IRRM, the classification rates in tables show that the common SBS outperforms the other methods. Particularly, when comparing the number of selected features for each method, the superiority of the SBS method could be revealed more apparently. In the case of valence classification, we can see that the classification rate (79.84%) by using SBS differs extremely from the rate (17.74%) without selection method. This means that the more complex prediction problem such as valence classification, the more compact feature selection we need.

IV. CONCLUSION

In this paper, we tested different feature selection methods, SVM-RFE, SVM-IRRM, and the common SBS and compared the performance of the methods by recognition rates obtained from two binary emotion classifications, arousal and valence. It turned out that the SBS outperforms the other methods in both classification problems. Particularly, the work supports the general evidence that the arousal intensity of emotional states can be better classified than the valence classification, regardless which selection method is used.

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