

PROBABILITY DENSITIES FOR DISCRETE DYNAMICAL SYSTEMS  
WITH WEAK NOISE

P.Reimann, Institut für Physik, Klingelbergstr. 82, CH-4056 BASEL, Switzerland  
P.Talkner, Paul Scherrer Institut, CH-5232 VILLIGEN, Switzerland

Problem and Model

The determination of stationary probability densities in multidimensional non-equilibrium systems in the presence of weak noise is of great importance in many cases [1] but plagued by notorious difficulties. It is widely believed that often useful predictions for the full system can be obtained by the restriction on a stroboscopic time-discretization of a single state-variable. As a model system we consider the following Langevin equation in discrete time  $n$  for the single variable  $x$

$$x_{n+1} = f(x_n) + \xi_n = x_n + \frac{b}{2\pi} \sin(2\pi x_n) + \xi_n \quad (1)$$

where the noise term  $\xi_n$  represents an analogue of the random force in the time-continuous case. For the sake of simplicity  $\xi_n$  is assumed to be independent and identically Gaussian distributed:  $P(\xi_n \in [\xi, \xi + d\xi]) = (2\pi\epsilon)^{-1/2} \exp(-\xi^2/2\epsilon) d\xi$  with small noise strength  $\epsilon \ll 1$  [2]. Under these assumptions the stationary probability density  $W_\epsilon(x)$  satisfies the following integral equation [2]

$$W_\epsilon(x) = \frac{1}{\sqrt{2\pi\epsilon}} \int_{-\infty}^{+\infty} e^{-(x-f(y))^2/2\epsilon} W_\epsilon(y) dy \quad (2)$$

The usual analytic and numerical methods for solving integral equations fail to give the correct asymptotic behaviour for weak noise.

Results

By means of a new geometrically motivated concept we find for the stationary probability density a WKB-like result

$$W_\epsilon(x) = N_\epsilon Z_\epsilon(x) e^{-\phi(x)/\epsilon} \quad (3)$$

where the nonequilibrium potential  $\phi(x)$  is  $\epsilon$ -independent and  $Z_\epsilon(x)$  may depend on  $\epsilon$  algebraically at most.  $N_\epsilon$  represents a normalization factor. For  $b \leq 2$  the deterministic map  $f(x)$  in eq.(1) has stable fixed points at  $x = 0.5 \text{ mod } 1$  and unstable fixed points at  $x = 0 \text{ mod } 1$ . In the neighbourhood of the stable fixed points  $\phi(x)$  has a parabolic shape with curvature  $1 - f'(0.5)^2$  and thus in Gaussian approximation we have  $N_\epsilon = \sqrt{(1 - f'(0.5)^2)/2\pi\epsilon}$  if we choose  $Z_\epsilon(0.5) = 1$ . In the neighbourhood of unstable fixed points  $\phi(x)$  consists of straight lines whose slopes and matching points both geometrically converge to zero at the rate  $f'(0)^{-1}$  as an unstable fixed point is approached. Each straight piece touches an enveloping parabola

with curvature  $1 - f'(0)^2$  from above. Analogous results for continuous time systems in more than one dimension have been obtained previously [3]. The prefactor  $Z_\epsilon(x)$  in eq.(3) turns out to be  $\epsilon$ -independent for most  $x$ , except for those in the vicinity of the bends of  $\phi(x)$  where cusps occur with  $\epsilon$ -independent heights and widths proportional to  $\epsilon$ . Outside an  $\epsilon^{1/2}$ -neighbourhood of  $x = 0$  there are plateaus between two cusps. Their heights decrease geometrically with a rate  $f'(0)^{-1}$  if  $x = 0$  is approached. Within the  $\epsilon^{1/2}$ -neighbourhood cusps and plateaus merge and the value of the prefactor at  $x = 0$  becomes proportional to  $\epsilon^{1/2}$ . In the expression (3) for the stationary probability density the singularities of  $\phi(x)$  and  $Z_\epsilon(x)$  compensate each other resulting in a smooth behaviour of  $W_\epsilon(x)$  for all  $x$  and  $\epsilon$ . The Figure below shows  $\phi(x)$  and  $Z_\epsilon(x)$  for  $b = 1.4$  and  $\epsilon = 10^{-3}$ .

Details of the novel geometrical method will be published elsewhere. Within this concept generalisations to more complicated cases as e.g. maps with periodic or chaotic attractors and to non-Gaussian white noise are straightforward.

### References

- [1] R.Graham, Springer Tracts in Modern Physics 60, Springer Berlin (1973)
- [2] P.Talkner, P.Hänggi, E.Freidkin, D.Trautmann, J. Stat. Phys. 48, 231 (1987);  
P.Talkner, P.Hänggi in 'Noise in Nonlinear Dynamical Systems', Vol.2, edited by F.Moss and P.V.E.McClintock, Cambridge University Press (1989)
- [3] R.Graham and T.Tél, Phys. Rev. A 31, 1109 (1985)

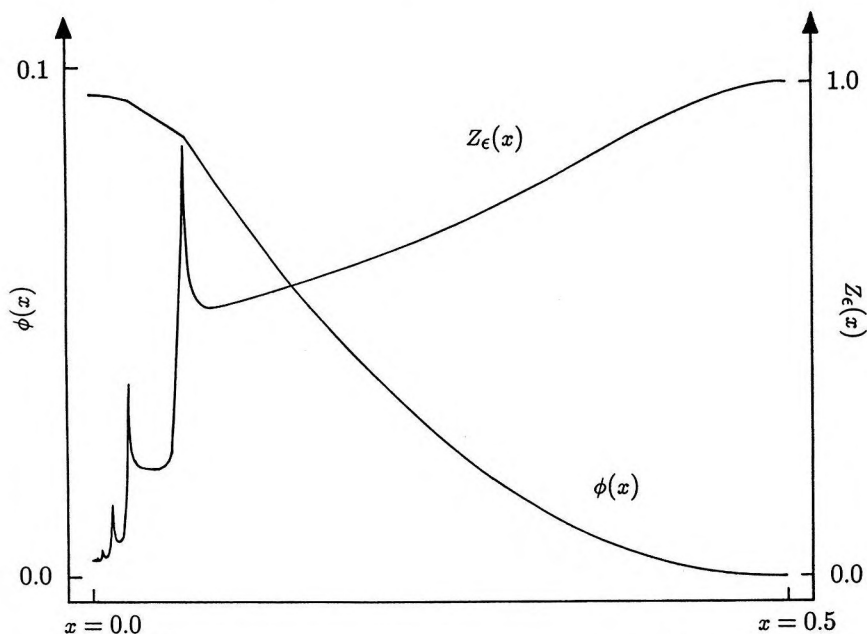


Figure: Nonequilibrium-potential  $\phi(x)$  and prefactor  $Z_\epsilon(x)$ . For further discussion see text.