# Equivariant symplectic homology, linearized contact homology and the Lagrangian capacity 

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Miguel Barbosa Pereira

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Betreuer: Prof. Dr. Kai Cieliebak, Universität Augsburg
Gutachter: Prof. Dr. Urs Frauenfelder, Universität Augsburg
Prof. Dr. Klaus Mohnke, Humboldt-Universität zu Berlin

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#### Abstract

We establish computational results concerning the Lagrangian capacity from [CM18]. More precisely, we show that the Lagrangian capacity of a 4-dimensional convex toric domain is equal to its diagonal. The proof involves comparisons between the Lagrangian capacity, the McDuff-Siegel capacities from [MS22], and the Gutt-Hutchings capacities from [GH18]. Working under the assumption that there is a suitable virtual perturbation scheme which defines the curve counts of linearized contact homology, we extend the previous result to toric domains which are convex or concave and of any dimension. For this, we use the higher symplectic capacities from [Sie20]. The key step is showing that moduli spaces of asymptotically cylindrical holomorphic curves in ellipsoids are transversely cut out.


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## Contents

1 Introduction ..... 1
1.1 Symplectic capacities and their uses ..... 1
1.2 Historical remarks ..... 4
1.3 Main results ..... 5
1.4 Proof sketches ..... 8
1.5 Outline of the thesis ..... 10
2 Symplectic and contact manifolds ..... 13
2.1 Symplectic manifolds ..... 13
2.2 Contact manifolds ..... 16
2.3 Liouville domains ..... 20
2.4 Symplectization of a contact manifold ..... 22
2.5 Completion of a Liouville domain ..... 24
3 Indices ..... 29
3.1 Maslov indices ..... 29
3.2 Conley-Zehnder index ..... 30
3.3 First Chern class ..... 31
3.4 Conley-Zehnder index of a periodic orbit ..... 33
3.5 Periodic Reeb orbits in a unit cotangent bundle ..... 37
4 Holomorphic curves ..... 43
4.1 Holomorphic curves ..... 43
4.2 Moduli spaces of Holomorphic curves ..... 48
4.3 SFT compactness ..... 52
4.4 Solutions of the parametrized Floer equation ..... 55
4.5 Compactness for solutions of the parametrized Floer equation ..... 62
4.6 Transversality for solutions of the parametrized Floer equation ..... 64
$5 \quad S^{1}$-equivariant Floer homology ..... 71
5.1 Categorical setup ..... 71
5.2 Action functional ..... 73
$5.3 \quad S^{1}$-equivariant Floer homology ..... 78
5.4 Viterbo transfer map of a Liouville embedding ..... 82
5.5 Viterbo transfer map of a generalized Liouville embedding ..... 89
$5.6 \delta$ map ..... 92
6 Symplectic capacities ..... 97
6.1 Symplectic capacities ..... 97
6.2 Lagrangian capacity ..... 102
6.3 Gutt-Hutchings capacities ..... 104
6.4 McDuff-Siegel capacities ..... 107
6.5 Computations not requiring contact homology ..... 110
7 Contact homology ..... 117
7.1 Assumptions on virtual perturbation scheme ..... 117
$7.2 \quad \mathcal{L}_{\infty}$-algebras ..... 118
7.3 Contact homology ..... 120
7.4 Higher symplectic capacities ..... 123
7.5 Cauchy-Riemann operators on bundles ..... 125
7.6 Cauchy-Riemann operators as sections ..... 130
7.7 Moduli spaces of curves in ellipsoids ..... 137
7.8 Computations using contact homology ..... 146
Bibliography ..... 149

## Chapter 1

## Introduction

### 1.1 Symplectic capacities and their uses

A symplectic manifold is a pair $(X, \omega)$, where $X$ is a manifold and $\omega \in \Omega^{2}(X)$ is a closed and nondegenerate 2-form on $X$. An example of a symplectic manifold is $\mathbb{C}^{n}$ with the canonical symplectic structure

$$
\omega_{0}:=\sum_{j=1}^{n} \mathrm{~d} x^{j} \wedge \mathrm{~d} y^{j}
$$

An embedding $\phi:\left(X, \omega_{X}\right) \longrightarrow\left(Y, \omega_{Y}\right)$ between symplectic manifolds is symplectic if $\phi^{*} \omega_{Y}=\omega_{X}$. A symplectomorphism is a symplectic diffeomorphism. Darboux' theorem implies that any symplectic manifold $(X, \omega)$ is locally symplectomorphic to $\left(\mathbb{C}^{n}, \omega_{0}\right)$. We point out that the analogue of this theorem in Riemannian geometry is clearly false: such a theorem would imply that every Riemannian manifold is flat. Conversely, Darboux' theorem also implies that it is not possible to define local invariants of symplectic manifolds that are analogues of the curvature of a Riemannian manifold.

There are, however, examples of global invariants of symplectic manifolds, for example symplectic capacities. A symplectic capacity is a function $c$ that assigns to every symplectic manifold ( $X, \omega$ ) (in a restricted subclass of all symplectic manifolds) a number $c(X, \omega) \in[0,+\infty]$, satisfying
(Monotonicity) If there exists a symplectic embedding (possibly in a restricted subset of all symplectic embeddings) $\left(X, \omega_{X}\right) \longrightarrow\left(Y, \omega_{Y}\right)$, then $c\left(X, \omega_{X}\right) \leq c\left(Y, \omega_{Y}\right)$;
(Conformality) If $\alpha>0$ then $c\left(X, \alpha \omega_{X}\right)=\alpha c\left(X, \omega_{X}\right)$.
By the monotonicity property, symplectic capacities are symplectomorphism invariants of symplectic manifolds. There are many examples of symplectic capacities, a simple one being the volume capacity $c_{\mathrm{vol}}$, defined as follows for a $2 n$-dimensional symplectic manifold $(X, \omega)$. Since $\omega$ is nondegenerate, $\omega^{n} / n$ ! is a volume form on $X$. Define

$$
\operatorname{vol}(X):=\int_{X} \frac{\omega^{n}}{n!}
$$

$$
c_{\mathrm{vol}}(X):=\left(\frac{\operatorname{vol}(X)}{\operatorname{vol}(B)}\right)^{1 / n},
$$

where $B=\left\{\left.z \in \mathbb{C}^{n}|\pi| z\right|^{2} \leq 1\right\}$. Symplectic capacities are especially relevant when discussing symplectic embedding problems. Notice that by the monotonicity property, a symplectic capacity can provide an obstruction to the existence of a symplectic embedding. We provide an example from physics. A classical mechanical system is a symplectic manifold $(X, \omega)$ together with a function $H$ called the Hamiltonian. The Hamiltonian vector field of $H$ is the unique vector field $X_{H}$ on $X$ such that

$$
\mathrm{d} H=-\iota_{X_{H}} \omega .
$$

Denote by $\phi_{H}^{t}$ the flow of $X_{H}$, which is a symplectomorphism. Liouville's theorem for a classical mechanical system says that for any subset $O \subset X$, the symplectic volume $c_{\mathrm{vol}}\left(\phi_{H}^{t}(O)\right)$ is independent of $t$. The proof of this statement works for any capacity $c$ replacing the volume capacity. So, for every symplectic capacity we get a theorem analogous to Liouville's theorem, giving restrictions on what regions of the phase space flow onto other regions.

In more generality, one could say that a symplectic capacity is a quantitative encoding of some specific property of symplectic manifolds. To make this statement less vague, let us mention some symplectic capacities we will be working with in this thesis.
(1) If $(X, \omega)$ is a $2 n$-dimensional symplectic manifold, a submanifold $L \subset(X, \omega)$ is Lagrangian if $\operatorname{dim} L=n$ and $\left.\omega\right|_{L}=0$. The minimal symplectic area of $L$ is given by

$$
A_{\min }(L):=\inf \left\{\omega(\sigma) \mid \sigma \in \pi_{2}(X, L), \omega(\sigma)>0\right\}
$$

Cieliebak-Mohnke [CM18, Section 1.2] define the Lagrangian capacity of ( $X, \omega$ ) by

$$
c_{L}(X, \omega):=\sup \left\{A_{\min }(L) \mid L \subset X \text { is an embedded Lagrangian torus }\right\} .
$$

(2) If $(X, \lambda)$ is a nondegenerate Liouville domain (this implies that $X$ is a compact manifold with boundary together with a 1 -form $\lambda$ such that $(X, \mathrm{~d} \lambda)$ is symplectic, see Definition 2.31), one can define its $S^{1}$-equivariant symplectic homology, denoted $S H^{S^{1}}(X, \lambda)$ (see Section 5.3). This is a $\mathbb{Q}$-module which comes equipped with a filtration, i.e. for every $a \in \mathbb{R}$ we have a $\mathbb{Q}$-module $S H^{S^{1}, a}(X, \lambda)$ and a map

$$
\iota^{a}: S H^{S^{1}, a}(X, \lambda) \longrightarrow S H^{S^{1}}(X, \lambda)
$$

In particular, we can define the $S^{1}$-equivariant symplectic homology associated to intervals $(a, b] \subset \mathbb{R}$ and $(a,+\infty) \subset \mathbb{R}$ by taking the quotient:

$$
\begin{aligned}
S H^{S^{1},(a, b]}(X, \lambda) & :=S H^{S^{1}, b}(X, \lambda) / \iota^{b, a}\left(S H^{S^{1}, a}(X, \lambda)\right), \\
S H^{S^{1},(a,+\infty)}(X, \lambda) & :=S H^{S^{1}}(X, \lambda) / \iota^{a}\left(S H^{S^{1}, a}(X, \lambda)\right) .
\end{aligned}
$$

The positive $S^{1}$-equivariant symplectic homology is given by $S H^{S^{1},+}(X, \lambda)=$ $S H^{S^{1},(\varepsilon,+\infty)}(X, \lambda)$, where $\varepsilon>$ is a small number. The $S^{1}$-equivariant symplectic homology also comes with maps $U$ and $\delta$, which can be composed to obtain the map

$$
\delta \circ U^{k-1} \circ \iota^{a}: S H^{S^{1},(\varepsilon, a]}(X) \longrightarrow H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q}) .
$$

The $k$ th Gutt-Hutchings capacity of $(X, \lambda)([G H 18$, Definition 4.1]) is given by

$$
c_{k}^{\mathrm{GH}}(X):=\inf \left\{a>0 \mid[\mathrm{pt}] \otimes[X] \in \operatorname{im}\left(\delta \circ U^{k-1} \circ \iota^{a}\right)\right\} .
$$

(3) Let $(X, \lambda)$ be a nondegenerate Liouville domain. There is a map

$$
\iota^{a, \varepsilon} \circ \alpha^{-1}: H \bullet\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q}) \longrightarrow S H^{S^{1}, a}(X) .
$$

The $k$ th $S^{1}$-equivariant symplectic homology capacity was defined by Irie in [Iri21, Section 2.5], and it is given by

$$
c_{k}^{S^{1}}(X):=\inf \left\{a>0 \mid \iota^{a, \varepsilon} \circ \alpha^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right)=0\right\} .
$$

(4) Let $(X, \lambda)$ be a nondegenerate Liouville domain. Choose a point $x \in \operatorname{int} X$ and a symplectic divisor (germ of a symplectic submanifold of codimension 2) $D \subset X$ through $x$. The boundary $\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ is a contact manifold (Definition 2.17) and therefore has a Reeb vector field (Definition 2.21). The completion of $(X, \lambda)$ (Definition 2.47) is the exact symplectic manifold

$$
(\hat{X}, \hat{\lambda}):=(X, \lambda) \cup_{\partial X}\left(\mathbb{R}_{\geq 0} \times \partial X,\left.e^{r} \lambda\right|_{\partial X}\right)
$$

Let $\mathcal{M}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle$ denote the moduli space of $J$-holomorphic curves in $\hat{X}$ which are positively asymptotic to the tuple of Reeb orbits $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ and which have contact order $k$ to $D$ at $x$. Finally, for $\ell, k \in \mathbb{Z}_{\geq 1}$, the McDuff-Siegel capacities of $(X, \lambda)([$ MS22, Definition 3.3.1]) are given by

$$
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X):=\sup _{J \in \mathcal{J}(X, D)} \inf _{\Gamma_{1}, \ldots, \Gamma_{p}} \sum_{i=1}^{p} \mathcal{A}\left(\Gamma_{i}\right),
$$

where $\mathcal{J}(X, D)$ is a set of almost complex structures on $\hat{X}$ which are cylindrical at infinity and compatible with $D$ (see Section 4.2) and the infimum is over tuples of Reeb orbits $\Gamma_{1}, \ldots, \Gamma_{p}$ such that there exist $k_{1}, \ldots, k_{p} \in \mathbb{Z}_{\geq 1}$ with

$$
\sum_{i=1}^{p} \# \Gamma_{i} \leq \ell, \quad \sum_{i=1}^{p} k_{i} \geq k, \quad \prod_{i=1}^{p} \mathcal{M}_{X}^{J}\left(\Gamma_{i}\right)\left\langle\mathcal{T}^{\left(k_{i}\right)} x\right\rangle \neq \varnothing .
$$

(5) Let $(X, \lambda)$ be a nondegenerate Liouville domain. If one assumes the existence of a suitable virtual perturbation scheme, one can define the linearized contact homology $\mathcal{L}_{\infty}$-algebra of $(X, \lambda)$, denoted $C C(X)[-1]$ (see Definitions 7.5, 7.11 and 7.12). We can then consider its bar complex $\mathcal{B}(C C(X)[-1])$ (see Definition 7.6) and the homology of the bar complex, $H(\mathcal{B}(C C(X)[-1]))$. There is an augmentation map (see Definition 7.16)

$$
\epsilon_{k}: \mathcal{B}(C C(X)[-1]) \longrightarrow \mathbb{Q}
$$

which counts $J$-holomorphic curves satisfying a tangency constraint. For $\ell, k \in$ $\mathbb{Z}_{\geq 1}$, Siegel [Sie20, Section 6.1] defines the higher symplectic capacities by ${ }^{1}$

$$
\mathfrak{g}_{k}^{\leq \ell}(X):=\inf \left\{a>0 \mid \epsilon_{k}: H\left(\mathcal{A}^{\leq a} \mathcal{B}^{\leq \ell}(C C(X)[-1])\right) \longrightarrow \mathbb{Q} \text { is nonzero }\right\},
$$

where $\mathcal{A}^{\leq a}$ denotes the action filtration (Definition 7.14) and $\mathcal{B} \leq \ell$ denotes the word length filtration (Definition 7.9).

The previous examples illustrate the fact that capacities can be defined using many tools that exist in symplectic geometry. If a capacity encodes a quantitative property between symplectic manifolds, then an inequality between two capacities encodes a relationship between said properties. So, capacities are also an efficient language to describe quantitative relations between properties of symplectic manifolds. Consider also that one can chain inequalities together to obtain new inequalities. In fact, one of the main goals of this thesis is to compute the Lagrangian capacity of convex or concave toric domains (a toric domain is a special type of Liouville domain, see Definition 2.35). We give two results in this direction (Theorems 6.41 and 7.65), and the proof of both results consists in composing together several inequalities between capacities (namely the capacities $c_{k}^{\mathrm{GH}}, \tilde{\mathfrak{g}}_{k}^{\leq 1}$ and $\mathfrak{g}_{k}^{\leq 1}$ which were defined above), where each of those inequalities is proven separately. Notice that in this case, we are able to compute the Lagrangian capacity of (some) toric domains, whose definition only concerns Lagrangian submanifolds, by considering other capacities whose definition concerns holomorphic curves in the toric domain.

### 1.2 Historical remarks

The first symplectic capacity, the Gromov width, was constructed by Gromov [Gro85], although at this time the nomenclature of "symplectic capacity" had not been introduced. The notion of symplectic capacity was first introduced by Ekeland-Hofer in [EH89]. In the sequel [EH90], the authors define the Ekeland-Hofer capacities $c_{k}^{\mathrm{EH}}$ (for every $k \in \mathbb{Z}_{\geq 1}$ ) using variational techniques for the symplectic action functional. The Hofer-Zehnder capacity [HZ90, HZ11] is another example of a capacity which can be defined by considering Hamiltonian systems. One can consider spectral capacities, which are generally defined as a minimal or maximal action of an orbit (Hamiltonian or Reeb) which is "topologically visible". The Gutt-Hutchings capacities [GH18], $S^{1}$-equivariant symplectic homology capacities [Iri21], and Siegel's higher symplectic capacities [Sie20] mentioned above are examples of this principle. Other authors have used constructions like this, namely Hofer [Hof93], Viterbo [Vit92, Vit99], Schwarz [Sch00], Oh [Oh02b, Oh02a, Oh05], Frauenfelder-Schlenk [FS07], Schlenk [Sch08] and GinzburgShon [GS18]. Using embedded contact homology (ECH), Hutchings [Hut11] defines the ECH capacities $c_{k}^{\mathrm{ECH}}$ (for every $k \in \mathbb{Z}_{\geq 1}$ ).

[^0]
### 1.3 Main results

As explained before, one of the main goals of this thesis is to compute the Lagrangian capacity of (some) toric domains. A toric domain is a Liouville domain of the form $X_{\Omega}:=\mu^{-1}(\Omega) \subset \mathbb{C}^{n}$, where $\Omega \subset \mathbb{R}_{\geq 0}^{n}$ and $\mu\left(z_{1}, \ldots, z_{n}\right)=\pi\left(\left|z_{1}\right|^{2}, \ldots,\left|z_{n}\right|^{2}\right)$. The ball, the cylinder and the ellipsoid, which are defined by

$$
\begin{aligned}
B^{2 n}(a) & :=\left\{z=\left.\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n}|\pi| z\right|^{2} \leq a\right\}, \\
Z^{2 n}(a) & :=\left\{z=\left.\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n}|\pi| z_{1}\right|^{2} \leq a\right\}, \\
E^{2 n}\left(a_{1}, \ldots, a_{n}\right) & :=\left\{z=\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n} \left\lvert\, \sum_{j=1}^{n} \frac{\pi\left|z_{j}\right|^{2}}{a_{j}} \leq 1\right.\right\},
\end{aligned}
$$

are examples of toric domains. ${ }^{2}$ The diagonal of a toric domain $X_{\Omega}$ is

$$
\delta_{\Omega}:=\max \{a \mid(a, \ldots, a) \in \Omega\} .
$$

It is easy to show (see Lemmas 6.19 and 6.20) that $c_{L}\left(X_{\Omega}\right) \geq \delta_{\Omega}$ for any convex or concave toric domain $X_{\Omega}$. Cieliebak-Mohnke give the following results for the Lagrangian capacity of the ball and the cylinder.

Proposition 6.21 ([CM18, Corollary 1.3]). The Lagrangian capacity of the ball is

$$
c_{L}\left(B^{2 n}(1)\right)=\frac{1}{n} .^{3}
$$

Proposition 6.22 ([CM18, p. 215-216]). The Lagrangian capacity of the cylinder is

$$
c_{L}\left(Z^{2 n}(1)\right)=1
$$

In other words, if $X_{\Omega}$ is the ball or the cylinder then $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$. This motivates the following conjecture by Cieliebak-Mohnke.

Conjecture 6.23 ([CM18, Conjecture 1.5]). The Lagrangian capacity of the ellipsoid is

$$
c_{L}\left(E\left(a_{1}, \ldots, a_{n}\right)\right)=\left(\frac{1}{a_{1}}+\cdots+\frac{1}{a_{n}}\right)^{-1} .
$$

A more general form of the previous conjecture is the following.
Conjecture 6.24. If $X_{\Omega}$ is a convex or concave toric domain then

$$
c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}
$$

The goal of this project is to prove Conjecture 6.24 . We will offer two main results in this direction.

[^1](1) In Theorem 6.41, we prove that $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$ whenever $X_{\Omega}$ is convex and 4dimensional.
(2) In Theorem 7.65, using techniques from contact homology we prove that $c_{L}\left(X_{\Omega}\right)=$ $\delta_{\Omega}$ for any convex or concave toric domain $X_{\Omega}$. More specifically, in this case we are working under the assumption that there is a virtual perturbation scheme such that the linearized contact homology of a nondegenerate Liouville domain can be defined (see Section 7.1).

Notice that by the previous discussion, we only need to prove the hard inequality $c_{L}\left(X_{\Omega}\right) \leq \delta_{\Omega}$. We now describe our results concerning the capacities mentioned so far. The key step in proving $c_{L}\left(X_{\Omega}\right) \leq \delta_{\Omega}$ is the following inequality between $c_{L}$ and $\tilde{\mathfrak{g}}_{k}^{\leq 1}$.

Theorem 6.40. If $(X, \lambda)$ is a Liouville domain then

$$
c_{L}(X) \leq \inf _{k} \frac{\tilde{\mathfrak{g}}_{k}^{\leq 1}(X)}{k}
$$

Indeed, this result can be combined with the following results from [MS22] and [GH18].
Proposition 6.37 ([MS22, Proposition 5.6.1]). If $X_{\Omega}$ is a 4-dimensional convex toric domain then

$$
\tilde{\mathfrak{g}}_{k}^{\leq 1}\left(X_{\Omega}\right)=c_{k}^{\mathrm{GH}}\left(X_{\Omega}\right)
$$

Lemma 6.28 ([GH18, Lemma 1.19]). $c_{k}^{\mathrm{GH}}\left(N^{2 n}(\delta)\right)=\delta(k+n-1)$.
Here,

$$
N^{2 n}(\delta):=\left\{\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n} \mid \exists j=1, \ldots, n: \frac{\pi\left|z_{j}\right|^{2}}{\delta} \leq 1\right\}
$$

is the nondisjoint union of cylinders. Combining the three previous results, we get the following particular case of Conjecture 6.24. Since the proof is short, we present it here as well.

Theorem 6.41. If $X_{\Omega}$ is a 4-dimensional convex toric domain then

$$
c_{L}\left(X_{\Omega}\right)=\delta_{\Omega} .
$$

Proof. For every $k \in \mathbb{Z}_{\geq 1}$,

$$
\begin{aligned}
\delta_{\Omega} & \leq c_{L}\left(X_{\Omega}\right) & & {[\text { by Lemmas } 6.19 \text { and } 6.20] } \\
& \leq \frac{\tilde{\mathfrak{g}}_{k}^{\leq 1}\left(X_{\Omega}\right)}{k} & & {[\text { by Theorem 6.40] }} \\
& =\frac{c_{k}^{\mathrm{GH}}\left(X_{\Omega}\right)}{k} & & {[\text { by Proposition 6.37] }} \\
& \leq \frac{c_{k}^{\mathrm{GH}}\left(N\left(\delta_{\Omega}\right)\right)}{k} & & {\left[X_{\Omega} \text { is convex, hence } X_{\Omega} \subset N\left(\delta_{\Omega}\right)\right] } \\
& =\frac{\delta_{\Omega}(k+1)}{k} & & {[\text { by Lemma } 6.28] . }
\end{aligned}
$$

The result follows by taking the infimum over $k$.

Notice that in the proof of this result, we used the Gutt-Hutchings capacities because the value $c_{k}^{\mathrm{GH}}\left(N^{2 n}(\delta)\right)$ is known and provides the desired upper bound for $c_{L}\left(X_{\Omega}\right)$. Notice also that the hypothesis of the toric domain being convex and 4 -dimensional is present because we wish to use Proposition 6.37 to compare $\tilde{\mathfrak{g}}_{k}^{\leq 1}$ and $c_{k}^{\mathrm{GH}}$. This suggests that we try to compare $c_{L}$ and $c_{k}^{\mathrm{GH}}$ directly.

Conjecture 6.42. If $X$ is a Liouville domain, $\pi_{1}(X)=0$ and $\left.c_{1}(T X)\right|_{\pi_{2}(X)}=0$, then

$$
c_{L}(X, \lambda) \leq \inf _{k} \frac{c_{k}^{\mathrm{GH}}(X, \lambda)}{k} .
$$

We will try to prove Conjecture 6.42 by mimicking the proof of Theorem 6.40. Unfortunately we will be unsuccessful, because we run into difficulties coming from the fact that in $S^{1}$-equivariant symplectic homology, the Hamiltonians and almost complex structures can depend on the domain and on a high dimensional sphere $S^{2 N+1}$. Before we move on to the discussion about computations using contact homology, we show one final result which uses only the properties of $S^{1}$-equivariant symplectic homology.

Theorem 6.31. If $(X, \lambda)$ is a Liouville domain, then
(1) $c_{k}^{\mathrm{GH}}(X) \leq c_{k}^{S^{1}}(X)$;
(2) $c_{k}^{\mathrm{GH}}(X)=c_{k}^{S^{1}}(X)$ provided that $X$ is star-shaped.

We now present another approach that can be used to compute $c_{L}$, using linearized contact homology. This has the disadvantage that at the time of writing, linearized contact homology has not yet been defined in the generality that we need (see Section 7.1 and more specifically Assumption 7.1). Using linearized contact homology, one can define the higher symplectic capacities $\mathfrak{g}_{k}^{\leq \ell}$. The definition of $\mathfrak{g}_{k}^{\leq \ell}$ for any $\ell \in \mathbb{Z}_{\geq 1}$ relies on the $\mathcal{L}_{\infty}$-algebra structure of the linearized contact homology chain complex, as well as an $\mathcal{L}_{\infty}$-augmentation map $\epsilon_{k}$. However, to prove that $c_{L}\left(X_{\Omega}\right) \leq \delta_{\Omega}$, we will only need the capacity $\mathfrak{g}_{k}^{\leq 1}$, and for this the $\mathcal{L}_{\infty}$-algebra structure is not necessary. The key idea is that the capacities $\mathfrak{g}_{k}^{\leq 1}$ can be compared to $\tilde{\mathfrak{g}}_{k}^{\leq 1}$ and $c_{k}^{\mathrm{GH}}$.

Theorem 7.63 ([MS22, Section 3.4]). If $X$ is a Liouville domain then

$$
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X) \leq \mathfrak{g}_{k}^{\leq \ell}(X)
$$

Theorem 7.64. If $X$ is a Liouville domain such that $\pi_{1}(X)=0$ and $2 c_{1}(T X)=0$ then

$$
\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X) .
$$

These two results show that $\tilde{\mathfrak{g}}_{k}^{\leq 1}\left(X_{\Omega}\right) \leq c_{k}^{\mathrm{GH}}\left(X_{\Omega}\right)$ (under Assumption 7.1). Using the same proof as before, we conclude that $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$.

Theorem 7.65. Under Assumption 7.1, if $X_{\Omega}$ is a convex or concave toric domain then

$$
c_{L}\left(X_{\Omega}\right)=\delta_{\Omega} .
$$

### 1.4 Proof sketches

In the last section, we explained our proof of $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$ (first in the case where $X_{\Omega}$ is convex and 4 -dimensional, and second assuming that Assumption 7.1 holds). In this section, we explain the proofs of the relations

$$
\begin{aligned}
c_{L}(X) & \leq \inf _{k} \frac{\tilde{\mathfrak{g}}_{k}^{\leq 1}(X)}{k}, \\
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X) & \leq \mathfrak{g}_{k}^{\leq \ell}(X), \\
\mathfrak{g}_{k}^{\leq 1}(X) & =c_{k}^{\text {GH }}(X),
\end{aligned}
$$

which were mentioned without proof in the last section. Each of these relations will be proved in the main text, so the proof sketches of this section act as a way of showcasing what technical tools will be required for our purposes. In Section 6.1, we study the question of extending the domain of a symplectic capacities from the class of nondegenerate Liouville domains to the class of Liouville domains which are possibly degenerate. By this discussion, it suffices to prove each theorem for nondegenerate Liouville domains only.

Theorem 6.40. If $(X, \lambda)$ is a Liouville domain then

$$
c_{L}(X) \leq \inf _{k} \frac{\tilde{\mathfrak{g}}_{k}^{\leq 1}(X)}{k}
$$

Proof sketch. Let $k \in \mathbb{Z}_{\geq 1}$ and $L \subset \operatorname{int} X$ be an embedded Lagrangian torus. Denote $a:=\tilde{\mathfrak{g}}_{k}^{\leq 1}(X)$. We wish to show that there exists $\sigma \in \pi_{2}(X, L)$ such that $0<\omega(\sigma) \leq a / k$. Choose a suitable Riemannian metric on $L$, given by Lemma 3.30 (which is a restatement of [CM18, Lemma 2.2]). Now, consider the unit cotangent bundle $S^{*} L$ of $L$. Choose a point $x$ inside the unit codisk bundle $D^{*} L$, a symplectic divisor $D$ through $x$, and a sequence $\left(J_{t}\right)_{t \in[0,1)}$ of almost complex structures on $\hat{X}$ realizing SFT neck stretching along $S^{*} L$.
By definition of $\tilde{\mathfrak{g}}_{k}^{\leq 1}(X)=: a$, there exists a Reeb orbit $\gamma_{0}$ together with a sequence $\left(u_{t}\right)_{t}$ of $J_{t}$-holomorphic curves $u_{t} \in \mathcal{M}_{X}^{J_{t}}\left(\gamma_{0}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$. By the SFT-compactness theorem, the sequence $\left(u_{t}\right)_{t}$ converges to a holomorphic building $F=\left(F^{1}, \ldots, F^{N}\right)$, where each $F^{\nu}$ is a holomorphic curve. Denote by $C$ the component of $F^{1} \subset T^{*} L$ which carries the tangency constraint. The choices of almost complex structures $J_{t}$ can be done in such a way that the simple curve corresponding to $C$ is regular, i.e. it is an element of a moduli space which is a manifold. Using the dimension formula for this moduli space, it is possible to conclude that $C$ must have at least $k+1$ punctures (see Theorem 4.15 and Lemmas 4.16 and 4.17). This implies that $C$ gives rise to at least $k>0$ disks $D_{1}, \ldots, D_{k}$ in $X$ with boundary on $L$. The total energy of the disks is less or equal to $a$. Therefore, one of the disks must have energy less or equal to $a / k$.

We now address a small imprecision in the proof we just described. We need to show that $\omega\left(D_{i}\right) \leq a$ for some $i=1, \ldots, k$. However, the above proof actually shows that $\tilde{\omega}\left(D_{i}\right) \leq a$, where $\tilde{\omega}$ is a piecewise smooth 2-form on $\hat{X} \backslash L$ given as in Definition 4.12. This form has the property that $\omega=\tilde{\omega}$ outside $S^{*} L$. The solution then is to neck stretch along $S_{\delta}^{*} L$ for some small $\delta>0$. In this case, one can bound $\omega\left(D_{i}\right)$ by $\tilde{\omega}\left(D_{i}\right)$ times a function of $\delta$ (see Lemma 4.14), and we can still obtain the desired bound for $\omega\left(D_{i}\right)$.

Theorem 7.63 ([MS22, Section 3.4]). If $X$ is a Liouville domain then

$$
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X) \leq \mathfrak{g}_{k}^{\leq \ell}(X) .
$$

Proof sketch. Choose a point $x \in \operatorname{int} X$ and a symplectic divisor $D$ through $x$. Let $J \in \mathcal{J}(X, D)$ and consider the bar complex $\mathcal{B}(C C(X)[-1])$, computed with respect to $J$. Suppose that $a>0$ and $\beta \in H\left(\mathcal{A}^{\leq a} \mathcal{B}^{\leq \ell}(C C(X)[-1])\right)$ is such that $\epsilon_{k}(\beta) \neq 0$. By Theorem 6.34,

$$
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X)=\sup _{J \in \mathcal{J}(X, D)} \inf _{\Gamma} \mathcal{A}(\Gamma)
$$

where the infimum is taken over tuples of Reeb orbits $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ such that $p \leq \ell$ and $\overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle \neq \varnothing$. The class $\beta$ is a linear combination of words of Reeb orbits $\Gamma$ such that $\# \Gamma \leq \ell$ and $\mathcal{A}(\Gamma) \leq a$. Since $\epsilon_{k}(\beta) \neq 0$, one of the words in this linear combination, say $\Gamma$, is such that the virtual count of $\overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle$ is nonzero. By assumption on the virtual perturbation scheme, $\overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle$ is nonempty, which is the condition in the definition of $\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X)$.

Theorem 7.64. If $X$ is a Liouville domain such that $\pi_{1}(X)=0$ and $2 c_{1}(T X)=0$ then

$$
\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X) .
$$

Proof sketch. Choose a small ellipsoid $E$ such that there exists a strict exact symplectic embedding $\phi: E \longrightarrow X$. There are associated Viterbo transfer maps (see Sections 5.4 and 5.5, where we define the Viterbo transfer map of $S^{1}$-equivariant symplectic homology)

$$
\begin{aligned}
\phi_{!}^{S^{1}}: S H^{S^{1}}(X) & \longrightarrow S H^{S^{1}}(E), \\
\quad \phi_{!}: C H(X) & \longrightarrow C H(E) .
\end{aligned}
$$

Because of the topological conditions on $X$, the $S^{1}$-equivariant symplectic homology and the linearized contact homology have $\mathbb{Z}$-gradings given by the Conley-Zehnder index. In this context, one can offer an alternative definition of the Gutt-Hutchings capacities via the Viterbo transfer map, namely $c_{k}^{\mathrm{GH}}(X)$ is the infimum over $a$ such that the map

$$
S H_{n-1+2 k}^{S^{1},(\varepsilon, a]}(X) \xrightarrow{\iota^{S^{1}, a}} S H_{n-1+2 k}^{S^{1},+}(X) \xrightarrow{\phi_{!}^{S^{1}}} S H_{n-1+2 k}^{S^{1},+}(E)
$$

is nonzero (see Lemma 6.27). Bourgeois-Oancea [BO16] define an isomorphism

$$
\Phi_{\mathrm{BO}}: S H^{S^{1},+}(X) \longrightarrow C H(X)
$$

between positive $S^{1}$-equivariant symplectic homology and linearized symplectic homology (whenever the latter is defined). All the maps we have just described assemble into
the following commutative diagram.


Here, the vertical arrows between the top two rows are the Bourgeois-Oancea isomorphism and the maps $\epsilon_{k}^{X}$ and $\epsilon_{k}^{E}$ are the augmentation maps of $X$ and $E$. Using this information, we can show that $c_{k}^{\mathrm{GH}}(X) \leq \mathfrak{g}_{k}^{\leq 1}(X)$ :

$$
\begin{aligned}
c_{k}^{\mathrm{GH}}(X) & =\inf \left\{a>0 \mid \phi_{!}^{S^{1}} \circ \iota^{S^{1}, a} \neq 0\right\} & & {\left[\text { by the alternative definition of } c_{k}^{\mathrm{GH}}\right] } \\
& \leq \inf \left\{a>0 \mid \epsilon_{k}^{X} \circ \iota^{a} \neq 0\right\} & & {[\text { since the diagram commutes }] } \\
& =\mathfrak{g}_{k}^{\leq 1}(X) & & {\left[\text { by definition of } \mathfrak{g}_{k}^{\leq 1}\right] . }
\end{aligned}
$$

In this computation, the inequality in the second line is an equality if $\epsilon_{k}^{E}$ is an isomorphism. The proof of this statement is done in Section 7.7, using the techniques from Sections 7.5 and 7.6. The key ideas are the following. One can show that $C H_{n-1+2 k}(E) \cong \mathbb{Q}$ (see Lemma 7.55), and therefore it is enough to show that $\epsilon_{k}^{E}$ is nonzero. Recall that $\epsilon_{k}^{E}$ is given by the virtual count of holomorphic curves in $X$ satisfying a tangency constraint. We count those curves explicitly in Proposition 7.60. Notice that here we need to justify that the virtual count of curves equals the usual signed count. This follows by assumption on the virtual perturbation scheme and because in Section 7.7, we also show that the moduli spaces are transversely cut out.

### 1.5 Outline of the thesis

We now give a chapter by chapter outline of this thesis.
In Chapter 2 we review the various types of manifolds that will show up in this thesis, i.e. symplectic manifolds and contact manifolds. We talk about the various types of vector fields in these manifolds (Hamiltonian vector field, Liouville vector field, Reeb vector field) and mention the properties of their flows. We give the definition of special types of symplectic manifolds, from less to more specific: Liouville domains, star-shaped domains, toric domains. Finally, we explain two constructions which will be present throughout: the symplectization of a contact manifold, and the completion of a Liouville domain.

In Chapter 3 we give a review of the Conley-Zehnder indices. In order to list the properties of the Conley-Zehnder index, one needs to mention the Maslov index and the first Chern class, so we offer a review of those as well. We explain how to define the Conley-Zehnder index of an orbit in a symplectic or contact manifold by defining an induced path of symplectic matrices via a trivialization. Finally, we study the ConleyZehnder index of a Reeb orbit in a unit cotangent bundle. The Conley-Zehnder index
is needed for our purposes because it provides the grading of $S^{1}$-equivariant symplectic homology and of linearized contact homology.

Chapter 4 is about the analytic properties of holomorphic curves and Floer trajectories. We define punctured Riemann surfaces as the domains for such curves, and symplectic cobordisms as the targets for such curves. We prove the energy identity for holomorphic curves, as well as the maximum principle. Then, we discuss the known compactness and transversality for moduli spaces of asymptotically cylindrical holomorphic curves (these are the moduli spaces which are considered in linearized contact homology). The second half of this chapter is about solutions of the "parametrized Floer equation" (solutions to this equation are the trajectories which are counted in the differential of $S^{1}$-equivariant Floer chain complex). We prove an energy inequality for Floer trajectories, as well as three "confinement lemmas": the maximum principle, the asymptotic behaviour lemma, and the no escape lemma. Finally, we prove compactness and transversality for moduli spaces of solutions of the parametrized Floer equation using the corresponding results for moduli spaces of solutions of the Floer equation.

In Chapter 5 we define the $S^{1}$-equivariant symplectic homology and establish its structural properties. First we define the $S^{1}$-equivariant Floer chain complex and its homology. The $S^{1}$-equivariant symplectic homology is then defined by taking the limit with respect to an increasing sequence of Hamiltonians of the $S^{1}$-equivariant Floer homology. We devote two sections to showing that $S^{1}$-equivariant symplectic homology is a functor, which amounts to defining the Viterbo transfer maps and proving their properties. Finally, we define a $\delta$ map, which enters the definition of the Gutt-Hutchings capacities.

Chapter 6 is about symplectic capacities. The first section is about generalities about symplectic capacities. We show how to extend a capacity of nondegenerate Liouville domains to a capacity of (possibly degenerate) Liouville domains. The next three sections are each devoted to defining and proving the properties of a specific capacity, namely the Lagrangian capacity $c_{L}$, the Gutt-Hutchings capacities $c_{k}^{\mathrm{GH}}$ and the $S^{1}$-equivariant symplectic homology capacities $c_{k}^{S^{1}}$, and finally the McDuff-Siegel capacities $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$. In the section about the Lagrangian capacity, we also state the conjecture that we will try to solve in the remainder of the thesis, i.e. $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$ for a convex or concave toric domain $X_{\Omega}$. The final section is devoted to computations. We show that $c_{L}(X) \leq \inf _{k} \tilde{\mathfrak{g}}_{k}^{\leq 1}(X) / k$. We use this result to prove the conjecture in the case where $X_{\Omega}$ is 4 -dimensional and convex.

Chapter 7 introduces the linearized contact homology of a nondegenerate Liouville domain. The idea is that using the linearized contact homology, one can define the higher symplectic capacities, which will allow us to prove $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$ for any convex or concave toric domain $X_{\Omega}$ (but under the assumption that linearized contact homology and the augmentation map are well-defined). We give a review of real linear CauchyRiemann operators on complex vector bundles, with a special emphasis on criteria for surjectivity in the case where the bundle has complex rank 1 . We use this theory to prove that moduli spaces of curves in ellipsoids are transversely cut out and in particular that the augmentation map of an ellipsoid is an isomorphism. The final section is devoted to computations. We show that $\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)$, and use this result to prove our conjecture (again, under Assumption 7.1).

## Chapter 2

## Symplectic and contact manifolds

### 2.1 Symplectic manifolds

In this section, we recall some basics about symplectic manifolds.
Definition 2.1. A symplectic manifold is a manifold $X$ together with a 2 -form $\omega$ which is closed and nondegenerate. In this case we say that $\omega$ is a symplectic form. An exact symplectic manifold is a manifold $X$ together with a 1 -form $\lambda$ such that $\omega=\mathrm{d} \lambda$ is a symplectic form. In this case we call $\lambda$ a symplectic potential for $\omega$.

Example 2.2. Consider $\mathbb{C}^{n}$ with coordinates $\left(x^{1}, \ldots, x^{n}, y^{1}, \ldots, y^{n}\right)$, where $z^{j}=x^{j}+i y^{j}$ for every $j=1, \ldots, n$. We define

$$
\begin{aligned}
& \lambda:=\frac{1}{2} \sum_{j=1}^{n}\left(x^{j} \mathrm{~d} y^{j}-y^{j} \mathrm{~d} x^{j}\right), \\
& \omega:=\mathrm{d} \lambda=\sum_{j=1}^{n} \mathrm{~d} x^{j} \wedge \mathrm{~d} y^{j}
\end{aligned}
$$

Then, $\left(\mathbb{C}^{n}, \lambda\right)$ is an exact symplectic manifold.
Example 2.3. Let $L$ be a manifold and consider the cotangent bundle of $L$, which is a vector bundle $\pi: T^{*} L \longrightarrow L$. As a set, $T^{*} L=\bigcup_{q \in L} T_{q}^{*} L$. As a vector bundle, $T^{*} L$ is given as follows. For each coordinate chart $\left(U, q^{1}, \ldots, q^{n}\right)$ on $L$, there is a coordinate chart $\left(\pi^{-1}(U), q^{1} \circ \pi, \ldots, q^{n} \circ \pi, p_{1}, \ldots, p_{n}\right)$ on $T^{*} L$, where the $p_{i}$ are given by

$$
p_{i}(u):=u\left(\left.\frac{\partial}{\partial q^{i}}\right|_{\pi(u)}\right)
$$

for $u \in T^{*} L$. For simplicity, denote $q^{i}=q^{i} \circ \pi$. Define a 1-form $\lambda$ on $T^{*} L$, called the canonical symplectic potential or Liouville 1-form, as follows. For each $u \in T^{*} L$, the linear map $\lambda_{u}: T_{u} T^{*} L \longrightarrow \mathbb{R}$ is given by $\lambda_{u}:=u \circ \mathrm{D} \pi(u)$. The form $\omega:=\mathrm{d} \lambda$ is the canonical symplectic form. In coordinates,

$$
\lambda=\sum_{i=1}^{n} p_{i} \mathrm{~d} q^{i}
$$

$$
\omega=\sum_{i=1}^{n} \mathrm{~d} p_{i} \wedge \mathrm{~d} q^{i}
$$

Then, $\left(T^{*} L, \lambda\right)$ is an exact symplectic manifold.
If $(X, \omega)$ is a symplectic manifold, then using symplectic linear algebra we conclude that $X$ must be even dimensional, i.e. $\operatorname{dim} X=2 n$ for some $n$ (see for example [dS08, Theorem 1.1]). In particular, $\omega^{n}$ is a volume form on $X$.
Definition 2.4. Let $\left(X, \omega_{X}\right),\left(Y, \omega_{Y}\right)$ be symplectic manifolds and $\varphi: X \longrightarrow Y$ be an embedding. Then, $\varphi$ is symplectic if $\varphi^{*} \omega_{Y}=\omega_{X}$. A symplectomorphism is a symplectic embedding which is a diffeomorphism. We say that $\varphi$ is strict if $\varphi(X) \subset$ int $Y$. If $\left(X, \lambda_{X}\right),\left(Y, \lambda_{Y}\right)$ are exact, then we say that $\varphi$ is:
(1) symplectic if $\varphi^{*} \lambda_{Y}-\lambda_{X}$ is closed (this is equivalent to the previous definition);
(2) generalized Liouville if $\varphi^{*} \lambda_{Y}-\lambda_{X}$ is closed and $\left.\left(\varphi^{*} \lambda_{Y}-\lambda_{X}\right)\right|_{\partial X}$ is exact;
(3) exact symplectic if $\varphi^{*} \lambda_{Y}-\lambda_{X}$ is exact;
(4) Liouville if $\varphi^{*} \lambda_{Y}-\lambda_{X}=0$.

Remark 2.5. In the context of Definition 2.4, if $H_{\mathrm{dR}}^{1}(X)=0$ then $(1) \Longleftrightarrow(2) \Longleftrightarrow(3)$.
Remark 2.6. The composition of generalized Liouville embeddings is not necessarily a generalized Liouville embedding. This means that exact symplectic manifolds together with generalized Liouville embeddings do not form a category.

Definition 2.7. Let $(X, \omega)$ be a symplectic manifold of dimension $2 n$ and $\iota: L \longrightarrow X$ be an immersed submanifold of dimension $n$. Then, $L$ is Lagrangian if $\iota^{*} \omega=0$. If $(X, \lambda)$ is exact, then we say that $L$ is:
(1) Lagrangian if $\iota^{*} \lambda$ is closed (this is equivalent to the previous definition);
(2) exact Lagrangian if $\iota^{*} \lambda$ is exact.

Example 2.8. Let $L$ be a manifold and consider its cotangent bundle, $T^{*} L$. Then, the zero section $z: L \longrightarrow T^{*} L$ is an exact Lagrangian. In fact, $z^{*} \lambda=0$.

Lemma 2.9 (Moser's trick). Let $X$ be a manifold, $\alpha_{t}$ be a smooth 1-parameter family of forms on $X$ and $Y_{t}$ be a complete time dependent vector field on $X$ with flow $\phi_{t}$. Then,

$$
\phi_{t}^{*} \alpha_{t}-\alpha_{0}=\int_{0}^{t} \phi_{s}^{*}\left(\dot{\alpha}_{s}+L_{Y_{s}} \alpha_{s}\right) \mathrm{d} s=\int_{0}^{t} \phi_{s}^{*}\left(\dot{\alpha}_{s}+\mathrm{d} \iota_{Y_{s}} \alpha_{s}+\iota_{Y_{s}} \mathrm{~d} \alpha_{s}\right) \mathrm{d} s .
$$

Proof.

$$
\begin{aligned}
\phi_{t}^{*} & \alpha_{t}-\alpha_{0} & & \\
& =\phi_{t}^{*} \alpha_{t}-\phi_{0}^{*} \alpha_{0} & & \text { since } \left.\phi_{0}=\mathrm{id}\right] \\
& =\int_{0}^{t} \frac{\mathrm{~d}}{\mathrm{~d} s} \phi_{s}^{*} \alpha_{s} \mathrm{~d} s & & \text { by the fundamental theorem of calculus }] \\
& =\int_{0}^{t} \phi_{s}^{*}\left(\dot{\alpha}_{s}+L_{Y_{s}} \alpha_{s}\right) \mathrm{d} s & & \text { [by definition of Lie derivative }] \\
& =\int_{0}^{t} \phi_{s}^{*}\left(\dot{\alpha}_{s}+\mathrm{d} \iota_{Y_{s}} \alpha_{s}+\iota_{Y_{s}} \mathrm{~d} \alpha_{s}\right) \mathrm{d} s & & \text { [by the Cartan magic formula]. }
\end{aligned}
$$

Theorem 2.10 (Darboux). Let $(X, \omega)$ be a symplectic manifold. Then, for every $p \in X$, there exists a coordinate neighbourhood $\left(U, x^{1}, \ldots, x^{n}, y^{1}, \ldots, y^{n}\right)$ of $p$ such that

$$
\omega=\sum_{i=1}^{n} \mathrm{~d} x^{i} \wedge \mathrm{~d} y^{i}
$$

Proof. Taking a coordinate chart on $X$, it is enough to assume that $\omega_{0}, \omega_{1}$ are symplectic forms on a neighbourhood of 0 in $\mathbb{C}^{n}$ and to prove that there exists a local diffeomorphism $\phi$ of $\mathbb{C}^{n}$ such that $\phi^{*} \omega_{1}=\omega_{0}$. Choosing the initial coordinate chart carefully, we may assume in addition that $\omega_{j}$ has a primitive $\lambda_{j}$, i.e. $\omega_{j}=\mathrm{d} \lambda_{j}$, for $j=0,1$, and also that $\omega_{0}$ and $\omega_{1}$ are equal at $0 \in \mathbb{C}$, i.e. $\left.\omega_{0}\right|_{0}=\left.\omega_{1}\right|_{0}$. Let

$$
\begin{aligned}
& \lambda_{t}:=\lambda_{0}+t\left(\lambda_{1}-\lambda_{0}\right), \\
& \omega_{t}:=\mathrm{d} \omega_{t}=\omega_{0}+t\left(\omega_{1}-\omega_{0}\right) .
\end{aligned}
$$

Since $\left.\omega_{t}\right|_{0}=\left.\omega_{0}\right|_{0}$ is symplectic, possibly after passing to a smaller neighbourhood of 0 we may assume that $\omega_{t}$ is symplectic. Let $Y_{t}$ be the unique time-dependent vector field such that $\dot{\lambda}_{t}+\iota_{Y_{t}} \omega_{t}=0$ and denote by $\phi_{t}$ the flow of $Y_{t}$. Then,

$$
\begin{aligned}
\phi_{t}^{*} \omega_{t}-\omega_{0} & =\int_{0}^{t} \phi_{s}^{*}\left(\dot{\omega}_{s}+\mathrm{d} \iota_{Y_{s}} \omega_{s}+\iota_{Y_{s}} \mathrm{~d} \omega_{s}\right) \mathrm{d} s & & {[\text { by Moser's trick (Lemma 2.9) }] } \\
& =\int_{0}^{t} \phi_{s}^{*} \mathrm{~d}\left(\dot{\lambda}_{s}+\mathrm{d} \iota_{Y_{s}} \omega_{s}\right) \mathrm{d} s & & {\left[\text { since } \omega_{t}=\mathrm{d} \lambda_{t}\right] } \\
& =0 & & {\left[\text { by definition of } Y_{t}\right] }
\end{aligned}
$$

which shows that $\phi_{1}$ is the desired local diffeomorphism.
Definition 2.11. If $(X, \lambda)$ is an exact symplectic manifold, then the Liouville vector field of $(X, \lambda)$ is the unique vector field $Z$ such that

$$
\lambda=\iota_{Z} \omega
$$

Lemma 2.12. The Liouville vector field satisfies

$$
L_{Z} \lambda=\lambda
$$

Proof.

$$
\begin{aligned}
L_{Z} \lambda & =\mathrm{d} \iota_{Z} \lambda+\iota_{Z} \mathrm{~d} \lambda & & {[\text { by the Cartan magic formula }] } \\
& =\mathrm{d} \iota_{Z} \lambda+\iota_{Z} \omega & & {[\text { since } \omega=\mathrm{d} \lambda] } \\
& =\mathrm{d} \iota_{Z} \iota_{Z} \omega+\lambda & & {\left[\text { by definition of Liouville vector field, } \lambda=\iota_{Z} \omega\right] } \\
& =\lambda & & {\left[\text { since } \omega \text { is antisymmetric, } \iota_{Z} \iota_{Z} \omega=0\right] . }
\end{aligned}
$$

Definition 2.13. Let $H \in C^{\infty}(X, \mathbb{R})$ be a function on $X$. The Hamiltonian vector field of $H$, denoted $X_{H}$, is the unique vector field on $X$ satisfying

$$
\mathrm{d} H=-\iota_{X_{H}} \omega .
$$

Proposition 2.14. The Hamiltonian vector field preserves the symplectic form, i.e.

$$
L_{X_{H}} \omega=0 .
$$

Proof.

$$
\begin{aligned}
L_{X_{H}} \omega & =\mathrm{d} \iota_{X_{H}} \omega+\iota_{X_{H}} \mathrm{~d} \omega & & {[\text { by the Cartan magic formula }] } \\
& =\mathrm{d} \iota_{X_{H}} \omega & & {[\text { since } \omega \text { is closed }] } \\
& =-\mathrm{d}^{2} H & & {\left[\text { by definition of } X_{H}\right] } \\
& =0 & & {\left[\text { since } \mathrm{d}^{2}=0\right] . }
\end{aligned}
$$

Proposition 2.15 (Liouville's theorem). The Hamiltonian vector field preserves the symplectic volume form, i.e.

$$
L_{X_{H}}\left(\frac{\omega^{n}}{n!}\right)=0 .
$$

Proof. By Proposition 2.14 and the fact that Lie derivatives obey the Leibniz rule.
Proposition 2.16 (conservation of energy). The Hamiltonian is constant along the Hamiltonian vector field, i.e.

$$
X_{H}(H)=0
$$

Proof.

$$
\begin{aligned}
X_{H}(H) & =\mathrm{d} H\left(X_{H}\right) & & {[\text { by definition of exterior derivative }] } \\
& =-\iota_{X_{H}} \omega\left(X_{H}\right) & & {\left[\text { by definition of } X_{H}\right] } \\
& =-\omega\left(X_{H}, X_{H}\right) & & {[\text { by definition of interior product }] } \\
& =0 & & {[\text { since } \omega \text { is a form }] . }
\end{aligned}
$$

### 2.2 Contact manifolds

In this section, we recall some basics about contact manifolds.
Definition 2.17. A contact manifold is a pair $(M, \xi)$, where $M$ is a smooth manifold and $\xi$ is a distribution on $M$ of codimension 1, called the contact structure, such that for all locally defining forms $\alpha \in \Omega^{1}(U)$ for $\xi$ (i.e. such that $\xi=\operatorname{ker} \alpha$ ), $\left.\mathrm{d} \alpha\right|_{\xi}$ is nondegenerate. In this case we call $\alpha$ a local contact form for $M$. In the case where $\alpha \in \Omega^{1}(M)$ we say that $\alpha$ is a global contact form for $M$. A strict contact manifold is a pair $(M, \alpha)$ such that $(M, \operatorname{ker} \alpha)$ is a contact manifold.

The following lemma characterizes the linear algebra of contact manifolds.
Lemma 2.18. Let $M$ be an m-dimensional manifold, $\alpha \in \Omega^{1}(M)$ be nonvanishing and $\xi=\operatorname{ker} \alpha$. Then, the following are equivalent:
(1) The form $\left.\mathrm{d} \alpha\right|_{\xi}$ is nondegenerate, i.e. $(M, \alpha)$ is a contact manifold;
(2) The tangent bundle of $M$ decomposes as $T M=\operatorname{ker} \mathrm{d} \alpha \oplus \operatorname{ker} \alpha$;
(3) There exists an $n \in \mathbb{Z}_{\geq 0}$ such that $m=2 n+1$ and $\alpha \wedge(\mathrm{d} \alpha)^{n}$ is a volume form.

Proof. (1) $\Longrightarrow(2)$ : We show that $\operatorname{ker} \mathrm{d} \alpha \cap \operatorname{ker} \alpha=0$. For this, it suffices to assume that $v \in \operatorname{ker} \mathrm{~d} \alpha \cap \operatorname{ker} \alpha$ and to prove that $v=0$. Since $\left.\mathrm{d} \alpha\right|_{\operatorname{ker} \alpha}(v)=0$ and $\left.\mathrm{d} \alpha\right|_{\operatorname{ker} \alpha}$ is nondegenerate we conclude that $v=0$.

We show that $\operatorname{dim} T M=\operatorname{dim} \operatorname{ker} \mathrm{d} \alpha+\operatorname{dim} \operatorname{ker} \alpha$. Since $\alpha$ is nonvanishing, $\operatorname{dim} \operatorname{ker} \alpha=$ $\operatorname{dim} T M-1$. Since $\operatorname{ker} \mathrm{d} \alpha \cap \operatorname{ker} \alpha=0$, this implies that $\operatorname{dim} \operatorname{ker} \mathrm{d} \alpha \in\{0,1\}$. Considering that $\left.\mathrm{d} \alpha\right|_{\operatorname{ker} \alpha}$ is nondegenerate and that $\operatorname{dim} T M=\operatorname{dim} \operatorname{ker} \alpha+1$, we conclude that $\left.\mathrm{d} \alpha\right|_{T M}$ is degenerate. Therefore, $\operatorname{dim} \operatorname{ker} \mathrm{d} \alpha=1$.
$(2) \Longrightarrow(3):$ Since $T M=\operatorname{ker} \mathrm{d} \alpha \oplus \operatorname{ker} \alpha$, we conclude that the forms $\left.\alpha\right|_{\operatorname{ker} d \alpha}$ and $\left.\mathrm{d} \alpha\right|_{\operatorname{ker} \alpha}$ are nondegenerate. In particular, $\operatorname{ker} \alpha$ is even dimensional, i.e. $\operatorname{dim} \operatorname{ker} \alpha=2 n$ for some $n$, and $\left(\left.\mathrm{d} \alpha\right|_{\operatorname{ker} \alpha}\right)^{n}$ is a volume form on $\operatorname{ker} \alpha$. So, $\alpha \wedge(\mathrm{d} \alpha)^{n}$ is a volume form on $M$.
$(3) \Longrightarrow(1):$ If $v \in \xi=\operatorname{ker} \alpha$ is such that $\left.v \in \operatorname{ker} \mathrm{~d} \alpha\right|_{\xi}$, then $\iota_{v}\left(\alpha \wedge(\mathrm{~d} \alpha)^{n}\right)=0$, which implies that $v=0$.

Definition 2.19. Let $\left(M, \xi_{M}\right),\left(N, \xi_{N}\right)$ be contact manifolds. A contactomorphism from $M$ to $N$ is a diffeomorphism $\phi: M \longrightarrow N$ such that $T \phi\left(\xi_{M}\right)=\xi_{N}$. If ( $M, \alpha_{M}$ ), $\left(N, \alpha_{N}\right)$ are strict contact manifolds, a strict contactomorphism from $M$ to $N$ is a diffeomorphism $\phi: M \longrightarrow N$ such that $\phi^{*} \alpha_{N}=\alpha_{M}$.
Remark 2.20. We will consider only strict contact manifolds and strict contactomorphisms, and for simplicity we will drop the word "strict" from our nomenclature.

Definition 2.21. The Reeb vector field of ( $M, \alpha$ ) is the unique vector field $R$ satisfying

$$
\begin{aligned}
\iota_{R} \mathrm{~d} \alpha & =0, \\
\iota_{R} \alpha & =1 .
\end{aligned}
$$

Remark 2.22. Lemma 2.18 (2) can also be written as $T M=\langle R\rangle \oplus \xi$.
Lemma 2.23. The Reeb vector field preserves the contact form, i.e.

$$
L_{R} \alpha=0 .
$$

Proof.

$$
\begin{aligned}
L_{R} \alpha & =\iota_{R} \mathrm{~d} \alpha+\mathrm{d} \iota_{R} \alpha & & {[\text { by the Cartan magic formula] }} \\
& =0+\mathrm{d} 1 & & \text { [by definition of } R] \\
& =0 . & &
\end{aligned}
$$

We now consider contact manifolds which are hypersurfaces of symplectic manifolds.
Definition 2.24. Let $(X, \omega)$ be a symplectic manifold of dimension $2 n,(M, \alpha)$ be a contact manifold of dimension $2 n-1$ such that $M \subset X$, and denote by $\iota: M \longrightarrow X$ the inclusion. We say that $M$ is a hypersurface of contact type if $\mathrm{d} \alpha=\iota^{*} \omega$. In this case, the Liouville vector field is the unique vector field $Z \in C^{\infty}\left(\iota^{*} T X\right)$ such that

$$
\iota_{Z} \omega=\alpha
$$

Example 2.25. Let $(L, g)$ be a Riemannian manifold. Recall that $\left(T^{*} L, \lambda\right)$ is an exact symplectic manifold. Consider the unit cotangent bundle

$$
S^{*} L:=\left\{u \in T^{*} L \mid\|u\|=1\right\}
$$

The form $\alpha:=\left.\lambda\right|_{S^{*} L}$ is a contact form on $S^{*} L$. Therefore, $\left(S^{*} L, \alpha\right) \subset\left(T^{*} L, \lambda\right)$ is a hypersurface of contact type. More generally, we can also define the cotangent bundle of radius $r>0$ by $S_{r}^{*} L:=\left\{u \in T^{*} L \mid\|u\|=r\right\}$, which is also a hypersurface of contact type.

Lemma 2.26. We have the decompositions

$$
\begin{aligned}
\iota^{*} T X & =\langle Z\rangle \oplus\langle R\rangle \oplus \xi, \\
T M & =\langle R\rangle \oplus \xi \\
\xi^{\perp} & =\langle Z\rangle \oplus\langle R\rangle .
\end{aligned}
$$

Proof. By Lemma 2.18, we have that $T M=\langle R\rangle \oplus \xi$. To show that $\xi^{\perp}=\langle Z\rangle \oplus\langle R\rangle$, by considering the rank of the vector bundles it suffices to show that $\langle Z\rangle \oplus\langle R\rangle \subset \xi^{\perp}$. Let $v \in \xi_{p}=\operatorname{ker} \alpha_{p}$. We wish to show that $\omega\left(Z_{p}, v\right)=0$ and $\omega\left(R_{p}, v\right)=0$.

$$
\begin{aligned}
\omega\left(Z_{p}, v\right) & =\alpha(v) & & {[\text { by definition of } Z] } \\
& =0 & & {\left[\text { since } v \in \operatorname{ker} \alpha_{p}\right], } \\
\omega\left(R_{p}, v\right) & =\mathrm{d} \alpha\left(R_{p}, v\right) & & {[\text { by definition of hypersurface of contact type }] } \\
& =0 & & {[\text { by definition of Reeb vector field }] . }
\end{aligned}
$$

Then, as oriented vector bundles, $\iota^{*} T X=\xi^{\perp} \oplus \xi=\langle Z\rangle \oplus\langle R\rangle \oplus \xi$.
Lemma 2.27. Let $H: X \longrightarrow \mathbb{R}$ and assume that $M$ is the preimage of $H$ under a regular value $c \in \mathbb{R}$, i.e. $M=H^{-1}(c)$. Then, there exists a unique vector field $X_{H}^{M}$ on $M$ which is $\iota$-related to $X_{H}$. In addition, $X_{H}^{M}=\alpha\left(X_{H}^{M}\right) R$.

Proof. To prove the first statement, it suffices to show that $\left.X_{H}\right|_{p} \in T_{p} M$ for every $p \in M$. By conservation of energy (Proposition 2.16), we have that

$$
\begin{aligned}
\left.X_{H}\right|_{p} & \in \operatorname{kerd} H(p) \\
& =T_{p}\left(H^{-1}(c)\right) \\
& =T_{p} M .
\end{aligned}
$$

We now show that $\iota_{X_{H}^{M}} \mathrm{~d} \alpha=0$.

$$
\begin{aligned}
\iota_{X_{H}^{M}} \mathrm{~d} & =\iota_{X_{H}^{M}} \iota^{*} \omega & & {[\text { by definition of hypersurface of contact type }] } \\
& =\iota^{*} \iota_{X_{H}} \omega & & {\left[\text { since } X_{H}^{M} \text { is } \iota \text {-related to } X_{H}\right] } \\
& =-\iota^{*} \mathrm{~d} H & & {[\text { by definition of Hamiltonian vector field }] } \\
& =-\mathrm{d} \iota^{*} H & & {[\text { by naturality of d }] } \\
& =0 & & {[\text { since } H \text { is constant equal to } c \text { on } M] . }
\end{aligned}
$$

By definition of Reeb vector field, we conclude that $X_{H}^{M}$ and $R$ are collinear, and in particular $X_{H}^{M}=\alpha\left(X_{H}^{M}\right) R$.

We now compare the dynamics from the points of view of Riemannian, symplectic and contact geometry. Let $(L, g)$ be a Riemannian manifold of dimension $n$. The manifold $L$ has a tangent bundle $T L$ and a cotangent bundle $T^{*} L$, and the map $\tilde{g}: T L \longrightarrow T^{*} L$ given by $\tilde{g}(v)=g(v, \cdot)$ is a vector bundle isomorphism. Consider the unit cotangent bundle $\iota: S^{*} L \longrightarrow T^{*} L$, which has a Reeb vector field $R$, and the function

$$
\begin{aligned}
H: T^{*} L & \longrightarrow \mathbb{R} \\
u & \longmapsto \frac{1}{2}\|u\|^{2} .
\end{aligned}
$$

Definition 2.28. We define a vector field $G$ on $T L$, called the geodesic field, as follows. At $v \in T L, G_{v}$ is given by

$$
G_{v}:=\left.\frac{\mathrm{d}}{\mathrm{~d} t}\right|_{t=0} \dot{\gamma}(t),
$$

where $\gamma: I \longrightarrow L$ is the unique geodesic with $\dot{\gamma}(0)=v$ and $\dot{\gamma}: I \longrightarrow T L$ is the lift of $\gamma$. A curve $\gamma$ in $L$ is a geodesic if and only if its lift $\dot{\gamma}$ to $T L$ is a flow line of $G$.

Theorem 2.29. The vector field $G$ is $\tilde{g}$-related to $X_{H}$.
Proof. See for example [Gei08, Theorem 1.5.2] or [Fv18, Theorem 2.3.1].
Theorem 2.30. The vector field $R$ is $\iota$-related to $X_{H}$.
Proof. Notice that $S^{*} L=H^{-1}(2)$. By Lemma 2.27, it suffices to show that $\lambda\left(X_{H}\right) \circ \iota=1$. Let $\left(q^{1}, \ldots, q^{n}\right)$ be coordinates on $L$, with induced coordinates $\left(q^{1}, \ldots, q^{n}, p_{1}, \ldots, p_{n}\right)$ on $T^{*} L$. With respect to these coordinates, $X_{H}$ can be written as

$$
\begin{align*}
X_{H} & =\sum_{i=1}^{n}\left(\frac{\partial H}{\partial p_{i}} \frac{\partial}{\partial q^{i}}-\frac{\partial H}{\partial q^{i}} \frac{\partial}{\partial p_{i}}\right) \\
& =\sum_{i=1}^{n}\left(\sum_{j=1}^{n} g^{i j} p_{j} \frac{\partial}{\partial q^{i}}-\sum_{j, k=1}^{n} \frac{\partial g^{j k}}{\partial q^{i}} p_{j} p_{k} \frac{\partial}{\partial p_{i}}\right) . \tag{2.1}
\end{align*}
$$

We show that $\left\langle\left.\mathrm{D} \pi(u) X_{H}\right|_{u}, \cdot\right\rangle=u$.

$$
\begin{aligned}
\left\langle\left.\mathrm{D} \pi(u) X_{H}\right|_{u}, v\right\rangle & =\sum_{i, j=1}^{n} g_{i j}\left(\left.\mathrm{D} \pi(u) X_{H}\right|_{u}\right)^{i} v^{j} \\
& =\sum_{i, j, k=1}^{n} g_{i j} g^{i k} p_{k} v^{j} \\
& =\sum_{j, k=1}^{n} \delta_{j}^{k} p_{k} v^{j} \\
& =\sum_{j=1}^{n} p_{j} v^{j} \\
& =\sum_{i=1}^{n} p_{i} \mathrm{~d} q^{i}\left(\sum_{j=1}^{n} v^{j} \frac{\partial}{\partial q^{j}}\right) \\
& =u(v) .
\end{aligned}
$$

We show that $\lambda\left(X_{H}\right)=2 H$ :

$$
\begin{aligned}
\left.\lambda\left(X_{H}\right)\right|_{u} & =u\left(\left.\mathrm{D} \pi(u) X_{H}\right|_{u}\right) & & {[\text { by definition of } \lambda] } \\
& =\left\langle\left.\mathrm{D} \pi(u) X_{H}\right|_{u},\left.\mathrm{D} \pi(u) X_{H}\right|_{u}\right\rangle & & {\left[\text { since } u=\left\langle\left.\mathrm{D} \pi(u) X_{H}\right|_{u}, \cdot\right\rangle\right] } \\
& =\left\|\left.\mathrm{D} \pi(u) X_{H}\right|_{u}\right\|^{2} & & {[\text { by definition of the norm }] } \\
& =\|u\|^{2} & & {\left[\text { since } u=\left\langle\left.\mathrm{D} \pi(u) X_{H}\right|_{u}, \cdot\right\rangle\right] } \\
& =2 H(u) & & {[\text { by definition of } H] . }
\end{aligned}
$$

By definition of $H$, this implies that $\lambda\left(X_{H}\right) \circ \iota=1$, as desired.

### 2.3 Liouville domains

In this section we introduce Liouville domains, which are going to be the main type of symplectic manifold we will work with.

Definition 2.31. A Liouville domain is a pair $(X, \lambda)$, where $X$ is a compact, connected smooth manifold with boundary $\partial X$ and $\lambda \in \Omega^{1}(X)$ is such that $\mathrm{d} \lambda \in \Omega^{2}(X)$ is symplectic, $\left.\lambda\right|_{\partial X}$ is contact and the orientations on $\partial X$ coming from $(X, \mathrm{~d} \lambda)$ and coming from $\left.\lambda\right|_{\partial X}$ are equal.

Example 2.32. Let $(L, g)$ be a Riemannian manifold. The unit codisk bundle,

$$
D^{*} L:=\left\{u \in T^{*} L \mid\|u\| \leq 1\right\},
$$

is a Liouville domain. More generally, we can define the codisk bundle of radius $r>0$ by $D_{r}^{*} L:=\left\{u \in T^{*} L \mid\|u\| \leq r\right\}$, which is also a Liouville domain.

Definition 2.33. A star-shaped domain is a compact, connected $2 n$-dimensional submanifold $X$ of $\mathbb{C}^{n}$ with boundary $\partial X$ such that $(X, \lambda)$ is a Liouville domain, where $\lambda$ is the symplectic potential of Example 2.2.

Definition 2.34. The moment map is the map $\mu: \mathbb{C}^{n} \longrightarrow \mathbb{R}_{\geq 0}^{n}$ given by

$$
\mu\left(z_{1}, \ldots, z_{n}\right):=\pi\left(\left|z_{1}\right|^{2}, \ldots,\left|z_{n}\right|^{2}\right) .
$$

Define also

$$
\begin{array}{rlrl}
\Omega_{X} & :=\Omega(X) & :=\mu(X) \subset \mathbb{R}_{\geq 0}^{n}, & \\
X_{\Omega} & :=X(\Omega) & :=\mu^{-1}(\Omega) \subset \mathbb{C}^{n}, & \\
\delta_{\Omega} & :=\delta(\Omega) & :=\sup \text { every } X \subset \sup ^{n}\{a \mid(a, \ldots, a) \in \Omega\}, & \\
\text { for every } \Omega \subset \mathbb{R}_{\geq 0}^{n}, \\
\Omega \subset \mathbb{R}_{\geq 0}^{n}
\end{array}
$$

We call $\delta_{\Omega}$ the diagonal of $\Omega$.
Definition 2.35. A toric domain is a star-shaped domain $X$ such that $X=X(\Omega(X))$. A toric domain $X=X_{\Omega}$ is
(1) convex if $\hat{\Omega}:=\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}^{n} \mid\left(\left|x_{1}\right|, \ldots,\left|x_{n}\right|\right) \in \Omega\right\}$ is convex;
(2) concave if $\mathbb{R}_{\geq 0}^{n} \backslash \Omega$ is convex.

Example 2.36. Here we give some examples of toric domains. See Fig. 2.1 for a picture of the examples given below.
(1) The ellipsoid is the convex and concave toric domain given by

$$
\begin{aligned}
E\left(a_{1}, \ldots, a_{n}\right) & :=\left\{\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n} \left\lvert\, \sum_{j=1}^{n} \frac{\pi\left|z_{j}\right|^{2}}{a_{j}} \leq 1\right.\right\} \\
\Omega_{E}\left(a_{1}, \ldots, a_{n}\right) & :=\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}_{\geq 0}^{n} \left\lvert\, \sum_{j=1}^{n} \frac{x_{j}}{a_{j}} \leq 1\right.\right\} .
\end{aligned}
$$

Its limit shape, the ball, is $B^{2 n}(a):=B(a):=E(a, \ldots, a)$.
(2) The polydisk is the convex "toric domain with corners" given by

$$
\begin{aligned}
P\left(a_{1}, \ldots, a_{n}\right) & :=\left\{\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n} \mid \forall j=1, \ldots, n: \frac{\pi\left|z_{j}\right|^{2}}{a_{j}} \leq 1\right\} \\
\Omega_{P}\left(a_{1}, \ldots, a_{n}\right) & :=\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}_{\geq 0}^{n} \mid \forall j=1, \ldots, n: \frac{x_{j}}{a_{j}} \leq 1\right\} .
\end{aligned}
$$

Its limit shape, the cube, is $P^{2 n}(a):=P(a):=P(a, \ldots, a)$.
(3) The nondisjoint union of cylinders is the concave "noncompact toric domain with corners" given by

$$
\begin{aligned}
& N\left(a_{1}, \ldots, a_{n}\right): \\
& \Omega_{N}\left(a_{1}, \ldots, a_{n}\right):=\left\{\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n} \mid \exists j=1, \ldots, n: \frac{\pi\left|z_{j}\right|^{2}}{a_{j}} \leq 1\right\} \\
&\left.\left.x_{1}, \ldots, x_{n}\right) \in \mathbb{R}_{\geq 0}^{n} \mid \exists j=1, \ldots, n: \frac{x_{j}}{a_{j}} \leq 1\right\} .
\end{aligned}
$$

Its limit shape is denoted $N^{2 n}(a):=N(a):=N(a, \ldots, a)$.
(4) The cylinder is the convex and concave "noncompact toric domain" given by

$$
\begin{aligned}
Z(a) & :=\left\{\left(z_{1}, \ldots, z_{n}\right) \in \mathbb{C}^{n} \left\lvert\, \frac{\pi\left|z_{1}\right|^{2}}{a_{1}} \leq 1\right.\right\} \\
\Omega_{Z}(a) & :=\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}_{\geq 0}^{n} \left\lvert\, \frac{x_{1}}{a_{1}} \leq 1\right.\right\} .
\end{aligned}
$$

Note that $Z^{2 n}(a):=Z(a)=E(a, \infty, \ldots, \infty)=P(a, \infty, \ldots, \infty)$.


Figure 2.1: Toric domains

### 2.4 Symplectization of a contact manifold

Let $(M, \alpha)$ be a contact $(2 n-1)$-dimensional manifold.
Definition 2.37. The symplectization of $(M, \alpha)$ is the exact symplectic manifold $\left(\mathbb{R} \times M, e^{r} \alpha\right.$ ), where $r$ is the coordinate on $\mathbb{R}$.

Lemma 2.38. The form $\mathrm{d}\left(e^{r} \alpha\right)$ is symplectic.
Proof. The form $\mathrm{d}\left(e^{r} \alpha\right)$ is exact, so it is closed. We show that $\mathrm{d}\left(e^{r} \alpha\right)$ is nondegenerate.

$$
\begin{array}{rlrl}
\left(\mathrm{d}\left(e^{r} \alpha\right)\right)^{n} & & \\
\quad & =\left(e^{r} \mathrm{~d} r \wedge \alpha+e^{r} \mathrm{~d} \alpha\right)^{n} & & {[\text { by the Leibniz rule }]} \\
& =e^{n r} \sum_{k=0}^{n}\binom{n}{k}(\mathrm{~d} r \wedge \alpha)^{k} \wedge(\mathrm{~d} \alpha)^{n-k} & & {[\text { by the binomial theorem }]} \\
& =e^{n r} \mathrm{~d} r \wedge \alpha \wedge(\mathrm{~d} \alpha)^{n-1} & & {\left[\text { since } \alpha^{2}=0 \text { and }(\mathrm{d} \alpha)^{n}=0\right]} \\
& \neq 0 & & {\left[\text { since } \alpha \wedge(\mathrm{d} \alpha)^{n-1} \text { is a volume form on } M\right] .}
\end{array}
$$

Lemma 2.39. The Liouville vector field of $\left(\mathbb{R} \times M, e^{r} \alpha\right)$ is $Z=\partial_{r}$.
Proof. By definition of Liouville vector field, we need to show that $\iota_{\partial_{r}} \mathrm{~d}\left(e^{r} \alpha\right)=e^{r} \alpha$.

$$
\begin{aligned}
\iota_{\partial_{r}} \mathrm{~d}\left(e^{r} \alpha\right) & =\iota_{\partial_{r}}\left(e^{r} \mathrm{~d} r \wedge \alpha+e^{r} \mathrm{~d} \alpha\right) & & \text { [by the Leibniz rule] } \\
& =e^{r}\left(\mathrm{~d} r\left(\partial_{r}\right) \alpha-\alpha\left(\partial_{r}\right) \mathrm{d} r+\iota_{\partial_{r}} \mathrm{~d} \alpha\right) & & {\left[\text { since } \iota_{Z}\right. \text { is a derivation] }} \\
& =e^{r} \alpha & & {[\text { since } \alpha \text { is a form on } M] . }
\end{aligned}
$$

Example 2.40. Let $(L, g)$ be a Riemannian manifold. Recall that $\left(T^{*} L, \lambda\right)$ is an exact symplectic manifold and that ( $S^{*} L, \alpha$ ) is a hypersurface of contact type. Consider the symplectization of $S^{*} L$, which is ( $\mathbb{R} \times S^{*} L, e^{r} \alpha$ ). Then, the map $\mathbb{R} \times S^{*} L \longrightarrow T^{*} L \backslash L$ given by $(r, u) \longmapsto e^{r} u$ is a Liouville diffeomorphism.

Defining $R_{(r, x)}=R_{x}$ we can view the Reeb vector field of $M$ as a vector field in $\mathbb{R} \times M$. Analogously, we define a distribution $\xi$ on $\mathbb{R} \times M$ by $\xi_{(r, x)}=\xi_{x}$. Then, $T(\mathbb{R} \times M)=$ $\langle Z\rangle \oplus\langle R\rangle \oplus \xi$. Let $H: \mathbb{R} \times M \longrightarrow \mathbb{R}$ be a function which only depends on $\mathbb{R}$, (i.e. $H(r, x)=H(r))$. Define $h:=H \circ \exp ^{-1}: \mathbb{R}_{>0} \longrightarrow \mathbb{R}$ and $T(r):=H^{\prime}(r) / e^{r}=h^{\prime}\left(e^{r}\right)$.
Lemma 2.41. The Hamiltonian vector field of $H$ satisfies $\alpha\left(X_{H}\right)=T$ and $X_{H}=T R$.
Proof. By Lemma 2.27, $X_{H}$ and $R$ are collinear. By definition of Reeb vector field, this implies that $X_{H}=\alpha\left(X_{H}\right) R$. It remains to show that $\alpha\left(X_{H}\right)=T$. For this, we compute

$$
\begin{aligned}
H^{\prime} \mathrm{d} r & =\mathrm{d} H & & \text { [by definition of exterior derivative] } \\
& =-\iota_{X_{H}} \mathrm{~d}\left(e^{r} \alpha\right) & & \text { [by definition of Hamiltonian v.f.] } \\
& =-\iota_{X_{H}}\left(e^{r} \mathrm{~d} r \wedge \alpha+e^{r} \mathrm{~d} \alpha\right) & & \text { [Leibniz rule for exterior derivative] } \\
& =-e^{r}\left(\mathrm{~d} r\left(X_{H}\right) \alpha-\alpha\left(X_{H}\right) \mathrm{d} r+\iota_{X_{H}} \mathrm{~d} \alpha\right) & & \text { [interior product is a derivation]. }
\end{aligned}
$$

Therefore, $H^{\prime} \mathrm{d} r=e^{r} \alpha\left(X_{H}\right) \mathrm{d} r$, which implies that $\alpha\left(X_{H}\right)=H^{\prime} / \exp =T$.

Corollary 2.42. Suppose that $\gamma=(r, \rho): S^{1} \longrightarrow \mathbb{R} \times M$ is a 1-periodic orbit of $X_{H}$, i.e. $\dot{\gamma}(t)=X_{H}(\gamma(t))$. Then:
(1) $r: S^{1} \longrightarrow \mathbb{R}$ is constant;
(2) $\rho: S^{1} \longrightarrow M$ is a $T(r)$-periodic orbit of $R$, i.e. $\dot{\rho}(t)=T(r) R(\rho(t))$.

Proof. The function $r: S^{1} \longrightarrow \mathbb{R}$ is constant because $X_{H}$ is tangent to $\{r\} \times M$. Since $\dot{\gamma}(t)=X_{H}(\gamma(t))$ and by Lemma 2.41, we conclude that $\dot{\rho}(t)=T(r) R(\rho(t))$.

Lemma 2.43. Let $\gamma=(r, \rho): S^{1} \longrightarrow \mathbb{R} \times M$ be a 1-periodic orbit of $X_{H}$ and consider its action, given by

$$
\mathcal{A}_{H}(\gamma)=\int_{S^{1}} \gamma^{*}\left(e^{r} \alpha\right)-\int_{S^{1}} H(\gamma(t)) \mathrm{d} t .
$$

Then, $\mathcal{A}_{H}(\gamma)=: \mathcal{A}_{H}(r)$ only depends on $r$, and we have the following formulas for $\mathcal{A}_{H}$ and $\mathcal{A}_{H}^{\prime}$ (as functions of $r$ ):

$$
\begin{aligned}
& \mathcal{A}_{H}(r)=H^{\prime}(r)-H(r)=e^{r} h^{\prime}\left(e^{r}\right)-h\left(e^{r}\right), \\
& \mathcal{A}_{H}^{\prime}(r)=H^{\prime \prime}(r)-H^{\prime}(r)=e^{2 r} h^{\prime \prime}\left(e^{r}\right) .
\end{aligned}
$$

Proof. We show only that $\mathcal{A}_{H}(\gamma)=H^{\prime}(r)-H(r)$, since the other formulas follow from this one by elementary calculus.

$$
\begin{aligned}
\mathcal{A}_{H}(\gamma) & =\int_{S^{1}} \gamma^{*}\left(e^{r} \alpha\right)-\int_{S^{1}} H(\gamma(t)) \mathrm{d} t & & {[\text { by definition of action }] } \\
& =\int_{S^{1}} e^{r} \rho^{*} \alpha-\int_{0}^{1} H(r, \rho(t)) \mathrm{d} t & & {[\text { since } \gamma(t)=(r, \rho(t))] } \\
& =e^{r} \int_{S^{1}} \rho^{*} \alpha-\int_{0}^{1} H(r) \mathrm{d} t & & {[\text { since } H=H(r)] } \\
& =e^{r} T(\rho)-H(r) & & {[\text { by Corollary } 2.42] } \\
& =H^{\prime}(r)-H(r) & & {[\text { by definition of } T] . }
\end{aligned}
$$

Definition 2.44. Let $J$ be an almost complex structure on $\left(\mathbb{R} \times M, e^{r} \alpha\right)$. We say that $J$ is cylindrical if $J\left(\partial_{r}\right)=R$, if $J(\xi) \subset \xi$, and if the almost complex structure $J: \xi \longrightarrow \xi$ is compatible with $\mathrm{d} \alpha$ and independent of $r$. We denote by $\mathcal{J}(M)$ the set of such $J$.

Lemma 2.45. If $J$ is cylindrical then $\alpha \circ J=\mathrm{d} r$.

Proof. It suffices to show that $\alpha \circ J=\mathrm{d} r$ on $\partial_{r}, R$ and $V \in \xi$.

$$
\begin{aligned}
& \alpha \circ J\left(\partial_{r}\right)=\alpha(R)=1=\mathrm{d} r\left(\partial_{r}\right) \\
& \alpha \circ J(R)=-\alpha\left(\partial_{r}\right)=0=\mathrm{d} r(R) \\
& \alpha \circ J(V)=\alpha(J(V))=0=\mathrm{d} r(V) \text {. }
\end{aligned}
$$

### 2.5 Completion of a Liouville domain

Let $(X, \lambda)$ be a Liouville domain and $\omega=\mathrm{d} \lambda$. Our goal in this section is to define the completion of $(X, \lambda)$, which is an exact symplectic manifold denoted by $(\hat{X}, \hat{\lambda})$. Recall that $\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ is contact. Consider the symplectization $\left(\mathbb{R} \times \partial X,\left.e^{r} \lambda\right|_{\partial X}\right)$ of $\left(\partial X,\left.\lambda\right|_{\partial X}\right)$. Let $Z$ be the Liouville vector field of $(X, \lambda)$, which is given by $\lambda=\iota_{Z} \omega$. Denote the flow of $Z$ by

$$
\begin{aligned}
\Phi_{Z}: \mathbb{R}_{\leq 0} \times \partial X & \longrightarrow X \\
(t, x) & \longmapsto \phi_{Z}^{t}(x) .
\end{aligned}
$$

Since the vector field $Z$ is outward pointing at $\partial X$, the map $\Phi_{Z}$ is well-defined. Also, since $\Phi_{Z}$ is given by flowing along the vector field $Z$, it is an embedding.

Lemma 2.46. The map $\Phi_{Z}$ is a Liouville embedding, i.e. $\Phi_{Z}^{*} \lambda=\left.e^{r} \lambda\right|_{\partial X}$.
Proof. If $(t, x) \in \mathbb{R}_{\leq 0} \times \partial X$ and $(u, v) \in T_{(t, x)}\left(\mathbb{R}_{\leq 0} \times \partial X\right)=\mathbb{R} \oplus T_{x} \partial X$, then

$$
\begin{array}{rlrl}
\left(\Phi_{Z}^{*} \lambda\right)(u, v) & & \\
& =\lambda\left(\mathrm{D} \Phi_{Z}(t, x)(u, v)\right) & & \text { [by definition of pullback] } \\
=\lambda\left(\mathrm{D} \Phi_{Z}(t, x)(0, v)\right)+\lambda\left(\mathrm{D} \Phi_{Z}(t, x)(u, 0)\right) & \text { [by linearity of the derivative] } \\
=\lambda\left(\mathrm{D} \phi_{Z}^{t}(x)(v)\right)+u \lambda\left(Z_{\phi_{Z}^{t}(x)}\right) & & \text { [by definition of } \Phi_{Z} \text { ] } \\
=\lambda\left(\mathrm{D} \phi_{Z}^{t}(x)(v)\right)+u \omega\left(Z_{\phi_{Z}^{t}(x)}, Z_{\phi_{Z}^{t}(x)}\right) & & \text { [by definition of } Z] \\
=\lambda\left(\mathrm{D} \phi_{Z}^{t}(x)(v)\right) & & \text { [since } \omega \text { is antisymmetric] } \\
=\left(\left(\phi_{Z}^{t}\right)^{*} \lambda\right)(v) & & \text { [by definition of pullback] } \\
=e^{t} \lambda(v) & & \text { [by Lemmas 2.9 and 2.12]. }
\end{array}
$$

Definition 2.47. We define an exact symplectic manifold ( $\hat{X}, \hat{\lambda}$ ) called the completion of $(X, \lambda)$, as follows. As a smooth manifold, $\hat{X}$ is the gluing of $X$ and $\mathbb{R} \times \partial X$ along the map $\Phi_{Z}: \mathbb{R}_{\leq 0} \times \partial X \longrightarrow \Phi_{Z}\left(\mathbb{R}_{\leq 0} \times \partial X\right)$. This gluing comes with embeddings

$$
\begin{array}{r}
\iota_{X}: X \longrightarrow \hat{X} \\
\iota_{\mathbb{R} \times \partial X}: \mathbb{R} \times \partial X
\end{array}
$$

The form $\hat{\lambda}$ is the unique 1 -form on $\hat{X}$ such that

$$
\begin{aligned}
\iota_{X}^{*} \hat{\lambda} & =\lambda, \\
\iota_{\mathbb{R} \times \partial X}^{*} \hat{\lambda} & =\left.e^{r} \lambda\right|_{\partial X}
\end{aligned}
$$

The symplectic form of $\hat{X}$ is given by $\hat{\omega}:=d \hat{\lambda}$, which satisfies

$$
\begin{aligned}
\iota_{X}^{*} \hat{\omega} & =\omega, \\
\iota_{\mathbb{R} \times \partial X}^{*} \hat{\omega} & =\mathrm{d}\left(\left.e^{r} \lambda\right|_{\partial X}\right) .
\end{aligned}
$$

The Liouville vector field of $\hat{X}$ is the unique vector field $\hat{Z}$ such that $\iota_{\hat{Z}} \hat{\omega}=\hat{\lambda}$, which satisfies
$Z \quad$ is $\iota_{X}$-related to $\hat{Z}$, $\partial_{r}$ is $\iota_{\mathbb{R} \times \partial X}$-related to $\hat{Z}$.

Example 2.48. Let $(L, g)$ be a Riemannian manifold. Recall that $T^{*} L$ is an exact symplectic manifold, $S^{*} L$ is a hypersurface of contact type and that $D^{*} L$ is a Liouville domain. Also recall that there is a Liouville embedding $\varphi: \mathbb{R} \times S^{*} L \longrightarrow T^{*} L$ given by $\varphi(r, u)=e^{r} u$. Then, we can define a Liouville diffeomorphism $\hat{\varphi}: \widehat{D^{*} L} \longrightarrow T^{*} L$ as the unique map such that the following diagram commutes:


Lemma 2.49. The diagram

commutes.
Proof. The left square commutes by definition of $\hat{X}$. To prove that the right square commutes, let $(t, x) \in \mathbb{R} \times \partial X$. We wish to show that $\Phi_{\hat{Z}}(t, x)=\iota_{\mathbb{R} \times \partial X}(t, x)$.

$$
\begin{aligned}
\iota_{\mathbb{R} \times \partial X}(t, x) & =\iota_{\mathbb{R} \times \partial X} \circ \phi_{\partial_{r}}^{t}(0, x) & & {\left[\text { by definition of flow of } \partial_{r}\right] } \\
& =\phi_{\hat{Z}}^{t} \circ \iota_{\mathbb{R} \times \partial X}(0, x) & & {\left[\text { since } \partial_{r} \text { is } \iota_{\mathbb{R} \times \partial X} \text {-related to } \hat{Z}\right] } \\
& =\phi_{\hat{Z}}^{t} \circ \iota_{X}(x) & & {[\text { by definition of completion }] } \\
& =\Phi_{\hat{Z}}(t, x) & & {\left[\text { by definition of } \Phi_{\hat{Z}}\right] . }
\end{aligned}
$$

Lemma 2.50. If $\left(X, \lambda_{X}\right)$ and $\left(Y, \lambda_{Y}\right)$ are Liouville domains and $\varphi: X \longrightarrow Y$ is a Liouville embedding of codimension 0 then $Z_{X}$ is $\varphi$-related to $Z_{Y}$.

Proof. For any $x \in X$ and $v \in T_{x} X$,

$$
\begin{array}{rlrl}
\omega_{Y}\left(\mathrm{D} \varphi(x)\left(\left.Z_{X}\right|_{x}\right)-\left.Z_{Y}\right|_{\varphi(x)}, \mathrm{D} \varphi(x)(v)\right) & & \\
& =\left(\iota_{Z_{X}} \varphi^{*} \omega_{Y}-\varphi^{*} \iota_{Z_{Y}} \omega_{Y}\right)(v) & & \text { [by the definitions of } \left.\iota_{Z_{X}}, \iota_{Z_{Y}}, \text { and } \varphi^{*}\right] \\
=\left(\iota_{Z_{X}} \omega_{X}-\varphi^{*} \iota_{Z_{Y}} \omega_{Y}\right)(v) & & \text { [since } \varphi \text { is a Liouville embedding] } \\
=\left(\lambda_{X}-\varphi^{*} \lambda_{X}\right)(v) & & \text { [by definition of Liouville vector field] } \\
& =0 & & \text { [since } \varphi \text { is a Liouville embedding]. }
\end{array}
$$

Since $\omega_{Y}$ is nondegenerate and $\varphi$ is a 0 -codimensional embedding, the result follows.
We will now explain how to view the construction of taking the completion of a Liouville domain as a functor. Let $\left(X, \lambda_{X}\right),\left(Y, \lambda_{Y}\right)$ be Liouville domains and $\varphi: X \longrightarrow Y$ be a Liouville embedding such that $Z_{X}$ is $\varphi$-related to $Z_{Y}$ (by Lemma 2.50, this is true whenever $\varphi$ is 0 -codimensional, although here we assume only that the Liouville vector
fields are related). We wish to define an embedding $\varphi: \hat{X} \longrightarrow \hat{Y}$, using the following diagram as a guide (we will show that this diagram commutes in Lemma 2.55):


Definition 2.51. We define an embedding $\hat{\varphi}: \hat{X} \longrightarrow \hat{Y}$ by

$$
\begin{aligned}
\hat{\varphi} \circ \iota_{X} & :=\iota_{Y} \circ \varphi, \\
\hat{\varphi} \circ \iota_{\mathbb{R} \times \partial X} & :=\Phi_{\hat{Z}_{Y}} \circ\left(\operatorname{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ \varphi \circ \iota_{\partial X}\right)\right) .
\end{aligned}
$$

For $\hat{\varphi}$ to be well-defined, we need to check that the definitions of $\varphi$ on each region agree on the overlap.

Lemma 2.52. The map $\hat{\varphi}$ is well-defined, i.e.

$$
\iota_{Y} \circ \varphi \circ \Phi_{Z_{X}}=\Phi_{\hat{Z}_{Y}} \circ\left(\operatorname{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ \varphi \circ \iota_{\partial X}\right)\right) \circ\left(\iota_{\mathbb{R}_{\leq 0}} \times \operatorname{id}_{\partial X}\right) .
$$

Proof. It suffices to assume that $(t, x) \in \mathbb{R}_{\leq 0} \times \partial X$ and to prove that $\iota_{Y} \circ \varphi \circ \Phi_{Z_{X}}(t, x)=$ $\Phi_{\hat{Z}_{Y}}\left(t, \iota_{Y}(\varphi(x))\right)$.

$$
\begin{aligned}
\iota_{Y} \circ \varphi \circ \Phi_{Z_{X}}(t, x) & =\iota_{Y} \circ \varphi \circ \phi_{Z_{X}}^{t}(x) & & {\left[\text { by definition of } \Phi_{Z_{X}}\right] } \\
& =\iota_{Y} \circ \phi_{Z_{Y}}^{t} \circ \varphi(x) & & {\left[\text { since } Z_{X} \text { is } \varphi \text {-related to } Z_{Y}\right] } \\
& =\phi_{\hat{Z}_{Y}}^{t} \circ \iota_{Y} \circ \varphi(x) & & {\left[\text { since } Z_{Y} \text { is } \iota_{Y} \text {-related to } \hat{Z}_{Y}\right] } \\
& =\Phi_{\hat{Z}_{Y}}\left(t, \iota_{Y}(\varphi(x))\right) & & {\left[\text { by definition of } \Phi_{\hat{Z}_{Y}}\right] . }
\end{aligned}
$$

Lemma 2.53. The map $\hat{\varphi}$ is a Liouville embedding, i.e. $\hat{\varphi}^{*} \hat{\lambda}_{Y}=\hat{\lambda}_{X}$.
Proof. We need to show that $\hat{\varphi}^{*} \hat{\lambda}_{Y}=\hat{\lambda}_{X}$, which is equivalent to

$$
\begin{align*}
\iota_{X}^{*} \hat{\varphi}^{*} \hat{\lambda}_{Y} & =\iota_{X}^{*} \hat{\lambda}_{X},  \tag{2.3}\\
\iota_{\mathbb{R} \times \partial X}^{*} \hat{\varphi}^{*} \hat{\lambda}_{Y} & =\iota_{\mathbb{R} \times \partial X}^{*} \hat{\lambda}_{X} . \tag{2.4}
\end{align*}
$$

We prove Equation (2.3).

$$
\begin{aligned}
\iota_{X}^{*} \hat{\varphi}^{*} \hat{\lambda}_{Y} & =\left(\hat{\varphi} \circ \iota_{X}\right)^{*} \hat{\lambda}_{Y} & & {[\text { by functoriality of pullbacks }] } \\
& =\left(\iota_{Y} \circ \varphi\right)^{*} \hat{\lambda}_{Y} & & {[\text { by definition of } \hat{\varphi}] } \\
& =\varphi^{*} \iota_{Y}^{*} \hat{\lambda}_{Y} & & {[\text { by functoriality of pullbacks }] }
\end{aligned}
$$

$$
\begin{array}{ll}
=\varphi^{*} \lambda_{Y} & \\
\text { [by definition of } \left.\hat{\lambda}_{Y}\right] \\
=\lambda_{X} & \\
=\iota_{X}^{*} \hat{\lambda}_{X} & \\
\text { [since } \varphi \text { is a Liouville embedding] } \\
\text { [by definition of } \left.\hat{\lambda}_{X}\right] .
\end{array}
$$

We prove Equation (2.4).

$$
\begin{array}{rlrl}
\iota_{\mathbb{R} \times}^{*} & =\left(\hat{\varphi}^{*} \hat{\lambda}_{Y}\right. & & \\
& =\left(\hat{\varphi}^{\circ} \circ \iota_{\mathbb{R} \times \partial X}\right)^{*} \hat{\lambda}_{Y} & & \text { [by functoriality of pullbacks] } \\
& =\left(\Phi_{\hat{Z}_{Y}} \circ\left(\mathrm{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ \varphi \circ \iota_{\partial X}\right)\right)\right)^{*} \hat{\lambda}_{Y} & \text { [by definition of } \hat{\varphi} \text { ] } \\
& =\left(\operatorname{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ \varphi \circ \iota_{\partial X}\right)\right)^{*} \Phi_{\hat{Z}_{Y}}^{*} \hat{\lambda}_{Y} & & \text { [by functoriality of pullbacks] } \\
& =\left(\operatorname{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ \varphi \circ \iota_{\partial X}\right)\right)^{*} e^{r} \hat{\lambda}_{Y} & & \text { [by Lemmas 2.9 and 2.12] } \\
& =e^{r} \iota_{\partial X}^{*} \varphi^{*} \iota_{Y}^{*} \hat{\lambda}_{Y} & & \text { [by functoriality of pullbacks] } \\
& =e^{r} \iota_{\partial X}^{*} \varphi^{*} \lambda_{Y} & & \text { [by definition of } \hat{\lambda}_{Y} \text { ] } \\
& =e^{r} \iota_{\partial X}^{*} \lambda_{X} & & \text { [since } \varphi \text { is a Liouville embedding] } \\
& =\iota_{\mathbb{R} \times \partial X}^{*} \hat{\lambda}_{X} & & \text { [by definition of } \hat{\lambda}_{X} \text { ]. }
\end{array}
$$

Lemma 2.54. The Liouville vector fields $\hat{Z}_{X}$ and $\hat{Z}_{Y}$ are $\hat{\varphi}$-related.
Proof. We need to show that

$$
\begin{array}{r}
Z_{X} \text { is }\left(\iota_{Y} \circ \varphi\right) \text {-related to } \hat{Z}_{Y}, \\
\partial_{r} \text { is }\left(\Phi_{\hat{Z}_{Y}} \circ\left(\mathrm{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ \varphi \circ \iota_{\partial X}\right)\right)\right) \text {-related to } \hat{Z}_{Y} . \tag{2.6}
\end{array}
$$

Here, (2.5), follows because $Z_{X}$ is $\varphi$-related to $Z_{Y}$. To prove (2.6), notice that for every $(t, x) \in \mathbb{R} \times \partial X$, we have $\partial_{r}=(1,0) \in \mathbb{R} \oplus T_{x} \partial X$ and therefore

$$
\begin{aligned}
\mathrm{D} & \left(\Phi_{\hat{Z}_{Y}} \circ\left(\mathrm{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ \varphi \circ \iota_{\partial X}\right)\right)\right)(t, x)(1,0) & & \\
& =\mathrm{D} \Phi_{\hat{Z}_{Y}}(t, \varphi(x))(1,0) & & \text { [by the chain rule] } \\
& =\hat{Z}_{Y}(t, \varphi(x)) & & \text { [by definition of } \left.\Phi_{\hat{Z}_{Y}}\right] .
\end{aligned}
$$

Lemma 2.55. Diagram (2.2) commutes.
Proof. We have already proven in Lemma 2.49 that the squares on the front and back commute. The first square on the bottom commutes by definition of $\hat{\varphi}$. The other two squares on the bottom commute trivially. The top square commutes because $\hat{\varphi} \circ \iota_{X}=$ $\iota_{Y} \circ \varphi$ by definition of $\hat{\varphi}$. We prove that the right square commutes. For $(t, x) \in \mathbb{R} \times \hat{X}$,

$$
\begin{aligned}
\hat{\varphi} \circ \Phi_{\hat{Z}_{X}}(t, x) & =\hat{\varphi} \circ \phi_{\hat{Z}_{X}}^{t}(x) & & {\left[\text { by definition of } \Phi_{\hat{Z}_{X}}\right] } \\
& =\phi_{\hat{Z}_{Y}}^{t} \circ \hat{\varphi}(x) & & {[\text { by Lemma } 2.54] } \\
& =\Phi_{\hat{Z}_{Y}}(t, \hat{\varphi}(x)) & & {\left[\text { by definition of } \Phi_{\hat{Z}_{Y}}\right] } \\
& =\Phi_{\hat{Z}_{Y}} \circ\left(\operatorname{id}_{\mathbb{R}} \times \hat{\varphi}\right)(x) & & {\left[\text { by definition of } \mathrm{id}_{\mathbb{R}} \times \hat{\varphi}\right] . }
\end{aligned}
$$

Finally, we check that the induced maps on the completions behave nicely with respect to compositions.

Proposition 2.56. The operation of taking the completion is a functor.
Proof. We show that identities are preserved. Let $(X, \lambda)$ be a Liouville domain. We wish to prove that $\widehat{\mathrm{id}_{X}}=\mathrm{id}_{\hat{X}}: \hat{X} \longrightarrow \hat{X}$, which is equivalent to

$$
\begin{align*}
\widehat{\operatorname{id}_{X}} \circ \iota_{X} & =\operatorname{id}_{\hat{X}}^{\circ} \iota_{X},  \tag{2.7}\\
\hat{\mathrm{id}_{X}} \circ \iota_{\mathbb{R} \times \partial X} & =\operatorname{id}_{\hat{X}} \circ \iota_{\mathbb{R} \times \partial X} . \tag{2.8}
\end{align*}
$$

We prove Equation (2.7).

$$
\begin{aligned}
\widehat{\mathrm{id} \mathrm{X}_{X}} \circ \iota_{X} & =\iota_{X} \circ \operatorname{id}_{X} & & {[\text { by definition of } \widehat{\mathrm{id}}] } \\
& =\iota_{X} & & {\left[\text { since id }{ }_{X} \text { is the identity map }\right] } \\
& =\operatorname{id}_{\hat{X}} \circ \iota_{X} & & {[\text { since id } \hat{X} \text { is the identity map }] . }
\end{aligned}
$$

We prove Equation (2.8).

$$
\begin{aligned}
\widehat{\operatorname{id}_{X}} \circ \iota_{\mathbb{R} \times \partial X} & =\Phi_{\hat{Z}} \circ\left(\mathrm{id}_{\mathbb{R}} \times\left(\iota_{X} \circ \operatorname{id}_{X} \circ \iota_{\partial X}\right)\right) & & {[\text { by definition of id } \widehat{X}] } \\
& =\operatorname{id}_{\hat{X}} \circ \iota_{\mathbb{R} \times \partial X} & & {[\text { by Lemma } 2.49] . }
\end{aligned}
$$

Now, we prove that compositions are preserved. Let $\left(X, \lambda_{X}\right),\left(Y, \lambda_{Y}\right)$ and $\left(W, \lambda_{W}\right)$ be Liouville domains and $f: X \longrightarrow Y$ and $g: Y \longrightarrow W$ be Liouville embeddings. We wish to prove that $\widehat{g \circ f}=\hat{g} \circ \hat{f}$, which is equivalent to

$$
\begin{align*}
\widehat{g \circ f} \circ \iota_{X} & =\hat{g} \circ \hat{f} \circ \iota_{X},  \tag{2.9}\\
\widehat{g \circ f} \circ \iota_{\mathbb{R} \times \partial X} & =\hat{g} \circ \hat{f} \circ \iota_{\mathbb{R} \times \partial X} .
\end{align*}
$$

We prove Equation (2.9).

$$
\begin{aligned}
\widehat{g \circ f} \circ \iota_{X} & =\iota_{W} \circ g \circ f & & {[\text { by definition of } \widehat{g \circ f}] } \\
& =\hat{g} \circ \iota_{Y} \circ f & & {[\text { by definition of } \hat{g}] } \\
& =\hat{g} \circ \hat{f} \circ \iota_{X} & & {[\text { by definition of } \hat{f}] . }
\end{aligned}
$$

We prove Equation (2.10).

$$
\begin{array}{rlrl}
\widehat{g \circ f} \circ \iota_{\mathbb{R} \times \partial X} & & \\
& =\Phi_{\hat{Z}_{W}} \circ\left(\operatorname{id}_{\mathbb{R}} \times\left(\iota_{W} \circ g \circ f \circ \iota_{\partial X}\right)\right) & & {[\text { by definition of } \widehat{g \circ f}]} \\
& =\Phi_{\hat{Z}_{W}} \circ\left(\operatorname{id}_{\mathbb{R}} \times\left(\hat{g} \circ \iota_{Y} \circ f \circ \iota_{\partial X}\right)\right) & & {[\text { by definition of } \hat{g}]} \\
& =\Phi_{\hat{Z}_{W}} \circ\left(\operatorname{id}_{\mathbb{R}} \times \hat{g}\right) \circ\left(\operatorname{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ f \circ \iota_{\partial X}\right)\right) & & \\
& =\hat{g} \circ \Phi_{\hat{Z}_{Y}} \circ\left(\operatorname{id}_{\mathbb{R}} \times\left(\iota_{Y} \circ f \circ \iota_{\partial X}\right)\right) & & {[\text { by diagram }(2.2)]} \\
& =\hat{g} \circ \hat{f} \circ \iota_{\mathbb{R} \times \partial X} & & {[\text { by definition of } \hat{f}] .}
\end{array}
$$

## Chapter 3

## Indices

### 3.1 Maslov indices

In this section, our goal is to define the Maslov index of a loop of symplectic matrices and the Maslov index of a loop of Lagrangian subspaces. Our presentation is based on [MS17]. We start by recalling relevant facts and notation about symplectic linear algebra. Let $V$ be a finite dimensional vector space. The vector spaces $V \oplus V^{*}$ and $V^{*} \oplus V$ admit symplectic structures given by

$$
\begin{aligned}
& \omega_{V \oplus V^{*}}((a, \alpha),(b, \beta))=\beta(a)-\alpha(b), \\
& \omega_{V^{*} \oplus V}((\alpha, a),(\beta, b))=\alpha(b)-\beta(a) .
\end{aligned}
$$

If $V$ has an inner product $\langle\cdot, \cdot\rangle$, then we define a symplectic structure on $V \oplus V$ by

$$
\begin{equation*}
\omega_{V \oplus V}((u, v),(x, y))=\langle u, y\rangle-\langle v, x\rangle . \tag{3.1}
\end{equation*}
$$

In this case, the maps

$$
\begin{aligned}
\phi: V \oplus V & \longrightarrow V \oplus V^{*} & \psi: V \oplus V & \longrightarrow V^{*} \oplus V \\
(x, y) & \longmapsto(x,\langle y, \cdot\rangle), & (x, y) & \longmapsto(\langle x, \cdot\rangle, y)
\end{aligned}
$$

are isomorphisms of symplectic vector spaces. For each $n$, define the $2 n \times 2 n$ matrices

$$
J_{0}=\left[\begin{array}{cc}
0 & -I \\
I & 0
\end{array}\right], \quad \Omega_{0}=\left[\begin{array}{cc}
0 & I \\
-I & 0
\end{array}\right] .
$$

The canonical symplectic structure of $\mathbb{R}^{2 n}=\mathbb{R}^{n} \oplus \mathbb{R}^{n}$, denoted $\omega_{0}$, is defined as in Equation (3.1) (where we use the Euclidean inner product). For $\mathbf{u}=(u, v) \in \mathbb{R}^{2 n}$ and $\mathbf{x}=(x, y) \in \mathbb{R}^{2 n}, \omega_{0}(\mathbf{u}, \mathbf{v})$ is given by

$$
\begin{aligned}
\omega_{0}((u, v),(x, y)) & =\langle u, y\rangle-\langle v, x\rangle \\
& =\mathbf{u}^{T} \Omega_{0} \mathbf{v} .
\end{aligned}
$$

The symplectic group is given by

$$
\mathrm{Sp}(2 n):=\left\{A \in \mathrm{GL}(2 n, \mathbb{R}) \mid A^{T} \Omega_{0} A=\Omega_{0}\right\}
$$

Denote by $C\left(S^{1}, \mathrm{Sp}(2 n)\right)$ the set of continuous maps from $S^{1}$ to $\operatorname{Sp}(2 n)$, i.e. the set of loops of symplectic matrices.

Theorem 3.1 ([MS17, Theorem 2.2.12]). There exists a unique function

$$
\mu: C\left(S^{1}, \operatorname{Sp}(2 n)\right) \longrightarrow \mathbb{Z}
$$

called the Maslov index, which satisfies the following properties:
(Homotopy) The Maslov index descends to an isomorphism $\mu: \pi_{1}(\operatorname{Sp}(2 n)) \longrightarrow \mathbb{Z}$.
(Product) If $A_{1}, A_{2} \in C\left(S^{1}, \mathrm{Sp}(2 n)\right)$ then $\mu\left(A_{1} A_{2}\right)=\mu\left(A_{1}\right)+\mu\left(A_{2}\right)$.
(Direct sum) If $A_{i} \in C\left(S^{1}, \operatorname{Sp}\left(2 n_{i}\right)\right)$ for $i=1,2$ then $\mu\left(A_{1} \oplus A_{2}\right)=\mu\left(A_{1}\right)+\mu\left(A_{2}\right)$.
(Normalization) If $A \in C\left(S^{1}, \mathrm{Sp}(2)\right)$ is given by

$$
A(t)=\left[\begin{array}{cc}
\cos (2 \pi t) & -\sin (2 \pi t) \\
\sin (2 \pi t) & \cos (2 \pi t)
\end{array}\right]
$$

then $\mu(A)=1$.
Let $(V, \omega)$ be a symplectic vector space. A subspace $W$ of $V$ is Lagrangian if $\operatorname{dim} W=$ $1 / 2 \operatorname{dim} V$ and $\left.\omega\right|_{W}=0$. The Lagrangian Grassmannian of $(V, \omega)$, denoted $\mathcal{L}(V, \omega)$, is the set of Lagrangian subspaces of $(V, \omega)$. Denote $\mathcal{L}(n)=\mathcal{L}\left(\mathbb{R}^{2 n}, \omega_{0}\right)$.
Theorem 3.2 ([MS17, Theorem 2.3.7]). There exists a unique function

$$
\mu: C\left(S^{1}, \mathcal{L}(n)\right) \longrightarrow \mathbb{Z}
$$

called the Maslov index, which satisfies the following properties:
(Homotopy) The Maslov index descends to an isomorphism $\mu: \pi_{1}(\mathcal{L}(n)) \longrightarrow \mathbb{Z}$.
(Product) If $W \in C\left(S^{1}, \mathcal{L}(n)\right)$ and $A \in C\left(S^{1}, \operatorname{Sp}(2 n)\right)$ then $\mu(A W)=\mu(W)+2 \mu(A)$.
(Direct sum) If $W_{i} \in C\left(S^{1}, \mathcal{L}\left(n_{i}\right)\right)$ for $i=1,2$ then $\mu\left(W_{1} \oplus W_{2}\right)=\mu\left(W_{1}\right)+\mu\left(W_{2}\right)$.
(Normalization) If $W \in C\left(S^{1}, \mathcal{L}(n)\right)$ is given by $W(t)=e^{\pi i t} \mathbb{R} \subset \mathbb{C}$ then $\mu(W)=1$.
(Zero) A constant loop has Maslov index zero.

### 3.2 Conley-Zehnder index

In this section we define the Conley-Zehnder index of a path of symplectic matrices. We define

$$
\left.\begin{array}{rl}
\mathrm{Sp}^{\star}(2 n) & :=\{A \in \operatorname{Sp}(2 n) \mid \operatorname{det}(A-I) \neq 0\}, \\
\mathrm{SP}(n) & :=\left\{A:[0,1] \longrightarrow \operatorname{Sp}(2 n) \left\lvert\, \begin{array}{l}
A \text { is continuous, } \\
A(0)=I \\
A(1) \in \mathrm{Sp}^{\star}(2 n)
\end{array}\right.\right.
\end{array}\right\} .
$$

The following theorem characterizes the Conley-Zehnder index of a path of symplectic matrices. Originally, this result has appeared in [SZ92] and [Sal99]. However, we will use a restatement from [Gut12]. Recall that if $S$ is a symmetric matrix, its signature, denoted by $\operatorname{sign} S$, is the number of positive eigenvalues of $S$ minus the number of negative eigenvalues of $S$.

Theorem 3.3 ([Gut12, Propositions 35 and 37]). There exists a unique function

$$
\mu_{\mathrm{CZ}}: \mathrm{SP}(n) \longrightarrow \mathbb{Z},
$$

called the Conley-Zehnder index, which satisfies the following properties:
(Naturality) If $B:[0,1] \longrightarrow \mathrm{Sp}(2 n)$ is a continuous path, then $\mu_{\mathrm{CZ}}\left(B A B^{-1}\right)=\mu_{\mathrm{CZ}}(A)$;
(Homotopy) $\mu_{\mathrm{CZ}}$ is constant on each component of $\mathrm{SP}(n)$;
(Zero) If $A(s)$ has no eigenvalue on the unit circle for $s>0$ then $\mu_{\mathrm{CZ}}(A)=0$;
(Product) If $A_{i} \in \operatorname{SP}\left(n_{i}\right)$ for $i=1,2$ then $\mu_{\mathrm{CZ}}\left(A_{1} \oplus A_{2}\right)=\mu_{\mathrm{CZ}}\left(A_{1}\right)+\mu_{\mathrm{CZ}}\left(A_{2}\right)$;
(Loop) If $B \in C\left(S^{1}, \operatorname{Sp}(2 n)\right)$ and $B(0)=B(1)=I$ then $\mu_{\mathrm{CZ}}(B A)=\mu_{\mathrm{CZ}}(A)+2 \mu(B)$.
(Signature) If $S$ is a symmetric nondegenerate $2 n \times 2 n$-matrix with operator norm $\|S\|<$ $2 \pi$ and $A(t)=\exp \left(J_{0} S t\right)$, then $\mu_{\mathrm{CZ}}(A)=\frac{1}{2} \operatorname{sign}(S)$;
(Determinant) $n-\mu_{\mathrm{CZ}}(A)$ is even if and only if $\operatorname{det}(I-A(1))>0$;
(Inverse) $\mu_{\mathrm{CZ}}\left(A^{-1}\right)=\mu_{\mathrm{CZ}}\left(A^{T}\right)=-\mu_{\mathrm{CZ}}(A)$.
Remark 3.4. By [Gut12, Proposition 37], the homotopy, loop and signature properties are enough to determine the Conley-Zehnder index uniquely.

We finish this section with a result which we will use later on to compute a ConleyZehnder index.

Proposition 3.5 ([Gut12, Proposition 41]). Let $S$ be a symmetric, nondegenerate $2 \times 2$ matrix and $T>0$ be such that $\exp \left(T J_{0} S\right) \neq I$. Consider the path of symplectic matrices $A:[0, T] \longrightarrow \mathrm{Sp}(2)$ given by

$$
A(t):=\exp \left(t J_{0} S\right)
$$

Let $a_{1}$ and $a_{2}$ be the eigenvalues of $S$ and $\operatorname{sign} S$ be its signature. Then,

$$
\mu_{\mathrm{CZ}}(A)= \begin{cases}\left(\frac{1}{2}+\left\lfloor\frac{\sqrt{a_{1} a_{2}} T}{2 \pi}\right\rfloor\right) \operatorname{sign} S & \text { if } \operatorname{sign} S \neq 0 \\ 0 & \text { if } \operatorname{sign} S=0\end{cases}
$$

### 3.3 First Chern class

Denote by Man ${ }^{2}$ the category of manifolds which are 2-dimensional, connected, compact, oriented and with empty boundary. We will give a definition of the first Chern class of a symplectic vector bundle $E \longrightarrow \Sigma$ where $\Sigma \in \operatorname{Man}^{2}$. Our presentation is based on [MS17]. We will start by setting up some categorical language. Define a contravariant functor Man $^{2} \longrightarrow$ Set:

$$
\begin{aligned}
\mathcal{E}: \operatorname{Man}^{2} & \longrightarrow \text { Set } \\
\Sigma & \longmapsto \mathcal{E}(\Sigma):=\{\text { symplectic vector bundles with base } \Sigma\} / \sim \\
f \downarrow & \longmapsto f^{*} \\
\Sigma^{\prime} & \longmapsto \mathcal{E}\left(\Sigma^{\prime}\right):=\left\{\text { symplectic vector bundles with base } \Sigma^{\prime}\right\} / \sim,
\end{aligned}
$$

where $\sim$ is the equivalence relation coming from isomorphisms of symplectic vector bundles. Define also the following contravariant functors Man $^{2} \longrightarrow$ Set:

$$
\begin{aligned}
H^{2}:=H^{2}(-; \mathbb{Z}): \operatorname{Man}^{2} & \longrightarrow \text { Set }, \\
H_{2}^{*}:=\operatorname{Hom}\left(H_{2}(-; \mathbb{Z}), \mathbb{Z}\right): \operatorname{Man}^{2} & \longrightarrow \text { Set }, \\
\mathcal{Z}: \operatorname{Man}^{2} & \longrightarrow \text { Set } \\
\Sigma & \longmapsto \mathcal{Z}(\Sigma):=\mathbb{Z} \\
f \downarrow & \longmapsto \uparrow \times \operatorname{deg} f \\
\Sigma^{\prime} & \longmapsto \mathcal{Z}\left(\Sigma^{\prime}\right):=\mathbb{Z} .
\end{aligned}
$$

We have a natural transformation $\alpha: H^{2} \longrightarrow H_{2}^{*}$ which is given by

$$
\begin{aligned}
\alpha_{\Sigma}: H^{2}(\Sigma ; \mathbb{Z}) & \longrightarrow \operatorname{Hom}\left(H_{2}(\Sigma ; \mathbb{Z}), \mathbb{Z}\right) \\
{[\omega] } & \alpha_{\Sigma}([\omega]),
\end{aligned}
$$

where $\alpha_{\Sigma}([\omega])([\sigma])=[\omega(\sigma)]$. By the universal coefficient theorem for cohomology (see for example [Rot09]), $\alpha_{\Sigma}$ is surjective. Both $H^{2}(\Sigma ; \mathbb{Z})$ and $\operatorname{Hom}\left(H_{2}(\Sigma ; \mathbb{Z}), \mathbb{Z}\right)$ are isomorphic to $\mathbb{Z}$, since $\Sigma \in \operatorname{Man}^{2}$. Therefore, $\alpha$ is a natural isomorphism. We also have a natural isomorphism ev: $H_{2}^{*} \longrightarrow \mathcal{Z}$, given by

$$
\begin{aligned}
\mathrm{ev}_{\Sigma}: \operatorname{Hom}\left(H_{2}(\Sigma ; \mathbb{Z}), \mathbb{Z}\right) & \longrightarrow \mathbb{Z} \\
\phi & \longmapsto \phi([\Sigma]) .
\end{aligned}
$$

As we will see, the first Chern class is a natural transformation $c_{1}: \mathcal{E} \longrightarrow H^{2}$ and the first Chern number is a natural transformation (which we denote by the same symbol) $c_{1}: \mathcal{E} \longrightarrow \mathcal{Z}$. These functors and natural transformations will all fit into the following commutative diagram:


Therefore, the first Chern class determines and is determined by the first Chern number. More precisely, if $E \longrightarrow \Sigma$ is a symplectic vector bundle then the first Chern number of $E$ equals the first Chern class of $E$ evaluated on $\Sigma$ :

$$
\begin{equation*}
c_{1}(E)=c_{1}(E)[\Sigma] \tag{3.2}
\end{equation*}
$$

Definition 3.6 ([MS17, Section 2.7]). Let $\Sigma \in \operatorname{Man}^{2}$ (i.e. $\Sigma$ is 2-dimensional, connected, compact, oriented, with empty boundary) and $E \longrightarrow \Sigma$ be a symplectic vector bundle. We define the first Chern number of $E, c_{1}(E) \in \mathbb{Z}$, as follows. Choose embedded 0 -codimensional manifolds $\Sigma_{1}$ and $\Sigma_{2}$ of $\Sigma$ such that

$$
S:=\partial \Sigma_{1}=\partial \Sigma_{2}=\Sigma_{1} \cap \Sigma_{2}
$$

and $\Sigma$ is the gluing of $\Sigma_{1}$ and $\Sigma_{2}$ along $S$. Orient $S$ as the boundary of $\Sigma_{1}$. For $i=1,2$, denote by $\iota_{i}: \Sigma_{i} \longrightarrow \Sigma$ the inclusion and choose a symplectic trivialization

$$
\tau^{i}: \iota_{i}^{*} E \longrightarrow \Sigma_{i} \times \mathbb{R}^{2 n}
$$

Define the overlap map $A: S \longrightarrow \operatorname{Sp}(2 n)$ by $A(x)=\tau_{x}^{1} \circ\left(\tau_{x}^{2}\right)^{-1}$. Denote by $S_{1}, \ldots, S_{k}$ the connected components of $S$ and parametrize each component by a loop $\gamma_{i}: S^{1} \longrightarrow S_{i}$ such that $\dot{\gamma}_{i}(t)$ is positively oriented. Finally, let

$$
c_{1}(E):=\sum_{i=1}^{k} \mu\left(A \circ \gamma_{i}\right),
$$

where $\mu$ is the Maslov index as in Theorem 3.1.
Theorem 3.7 ([MS17, Theorem 2.7.1]). The first Chern number is well-defined and it is the unique natural transformation $c_{1}: \mathcal{E} \longrightarrow \mathcal{Z}$ which satisfies the following properties:
(Classification) If $E, E^{\prime} \in \mathcal{E}(\Sigma)$ then $E$ and $E^{\prime}$ are isomorphic if and only if $\operatorname{rank} E=$ $\operatorname{rank} E^{\prime}$ and $c_{1}(E)=c_{1}\left(E^{\prime}\right)$.
(Naturality) If $f: \Sigma \longrightarrow \Sigma^{\prime}$ is a smooth map and $E \in \mathcal{E}(\Sigma)$ then $c_{1}\left(f^{*} E\right)=\operatorname{deg}(f) c_{1}(E)$. (Additivity) If $E, E^{\prime} \in \mathcal{E}(\Sigma)$ then $c_{1}\left(E \oplus E^{\prime}\right)=c_{1}(E)+c_{1}\left(E^{\prime}\right)$.
(Normalization) The first Chern number of $T \Sigma$ is $c_{1}(T \Sigma)=2-2 g$.

### 3.4 Conley-Zehnder index of a periodic orbit

Let $(X, \omega)$ be a symplectic manifold of dimension $2 n$ and $H: S^{1} \times X \longrightarrow \mathbb{R}$ be a timedependent Hamiltonian. For each $t \in S^{1}$ we denote by $H_{t}$ the map $H_{t}=H(t, \cdot): X \longrightarrow$ $\mathbb{R}$. The Hamiltonian $H$ has a corresponding time-dependent Hamiltonian vector field $X_{H}$ which is uniquely determined by

$$
\mathrm{d} H_{t}=-\iota_{X_{H_{t}}} \omega
$$

We denote by $\phi_{X_{H}}^{t}$ the time-dependent flow of $X_{H}$.
Definition 3.8. A 1-periodic orbit of $H$ is a map $\gamma: S^{1} \longrightarrow X$ such that

$$
\dot{\gamma}(t)=X_{H_{t}}(\gamma(t))
$$

for every $t \in S^{1}$. If $\lambda$ is a symplectic potential for $(X, \omega)$, then the action of $\gamma$ is

$$
\mathcal{A}_{H}(\gamma):=\int_{S^{1}} \gamma^{*} \lambda-\int_{S^{1}} H(t, \gamma(t)) \mathrm{d} t
$$

Definition 3.9. Let $\gamma$ be a 1-periodic orbit of $H$. We say that $\gamma$ is nondegenerate if the linear map

$$
\mathrm{D} \phi_{X_{H}}^{1}: T_{\gamma(0)} X \longrightarrow T_{\gamma(1)} X=T_{\gamma(0)} X
$$

does not have 1 as an eigenvalue. We say that the Hamiltonian $H$ is nondegenerate if every 1-periodic orbit of $H$ is nondegenerate.

Definition 3.10. Let $\gamma$ be a 1-periodic orbit of $H$ and $\tau$ be a symplectic trivialization of $\gamma^{*} T X$. We define the Conley-Zehnder index of $\gamma$ with respect to $\tau$, denoted $\mu_{\mathrm{CZ}}^{\tau}(\gamma)$, as follows. First, define a path of symplectic matrices $A^{\gamma, \tau}:[0,1] \longrightarrow \operatorname{Sp}(2 n)$ by the equation $A^{\gamma, \tau}(t):=\tau_{t} \circ \mathrm{D} \phi_{X_{H}}^{t}(\gamma(0)) \circ \tau_{0}^{-1}$. In other words, $A^{\gamma, \tau}(t)$ is the unique linear map such that the diagram

$$
\begin{aligned}
& T_{\gamma(0)} X \xrightarrow{\tau_{0}} \\
& \mathrm{D}_{X_{H}}^{t}(\gamma(0)) \\
& \mathbb{R}^{2 n} \\
& T_{\gamma(t)} \xrightarrow[\tau_{t}]{ }{ }_{\mathbb{R}^{2 n}}{ }^{2 \gamma, \tau(t)} \\
& \mathbb{R}^{\gamma}
\end{aligned}
$$

commutes. Notice that since $\gamma$ is nondegenerate, $A^{\gamma, \tau} \in \operatorname{SP}(n)$. Then, define

$$
\mu_{\mathrm{CZ}}^{\tau}(\gamma):=\mu_{\mathrm{CZ}}\left(A^{\gamma, \tau}\right)
$$

Let $D=\{z \in \mathbb{C}| | z \mid \leq 1\}$ be the disk and denote by $\iota_{D, S^{1}}: S^{1} \longrightarrow D$ the inclusion on the boundary, i.e. $\iota_{D, S^{1}}(t)=e^{2 \pi i t}$.

Lemma 3.11. Let $\gamma$ be a 1-periodic orbit of $H$. For $i=1,2$, let $u_{i}: D \longrightarrow X$ be $a$ filling disk for $\gamma$ (i.e. $\gamma=u_{i} \circ \iota_{D, S^{1}}$ ) and $\tau^{i}$ be a symplectic trivialization of $u_{i}^{*} T X$. If $\left.c_{1}(T X)\right|_{\pi_{2}(X)}=0$, then

$$
\mu_{\mathrm{CZ}}^{\tau^{1}}(\gamma)=\mu_{\mathrm{CZ}}^{\tau^{2}}(\gamma) .
$$

Proof. Consider the diagram

where we have defined $B(t):=\tau_{t}^{1} \circ\left(\tau_{t}^{2}\right)^{-1}$. Let $\sigma: S^{2} \longrightarrow X$ be the gluing of the disks $u_{1}$ and $u_{2}$ along their common boundary $\gamma$. Then,

$$
\begin{array}{rlrl}
\mu_{\mathrm{CZ}}^{\tau^{1}}(\gamma)-\mu_{\mathrm{CZ}}^{\tau^{2}}(\gamma) & & \\
& =\mu_{\mathrm{CZ}}\left(A^{\gamma, \tau^{1}}\right)-\mu_{\mathrm{CZ}}\left(A^{\gamma, \tau^{2}}\right) & & \text { by Definition 3.10] } \\
=\mu_{\mathrm{CZ}}\left(B A^{\gamma, \tau^{2}} B(0)^{-1}\right)-\mu_{\mathrm{CZ}}\left(A^{\gamma, \tau^{2}}\right) & & \text { [by diagram (3.3)] } \\
=\mu_{\mathrm{CZ}}\left(B(0)^{-1} B A^{\gamma, \tau^{2}}\right)-\mu_{\mathrm{CZ}}\left(A^{\gamma, \tau^{2}}\right) & & \text { [by naturality of } \left.\mu_{\mathrm{CZ}}\right] \\
=2 \mu\left(B(0)^{-1} B\right) & & \text { [by the loop property of } \left.\mu_{\mathrm{CZ}}\right] \\
=2 \mu(B) & & \text { [by homotopy invariance of } \mu] \\
=2 c_{1}\left(\sigma^{*} T X\right) & & \text { [by definition of the first Chern numberion }(3.2)] \\
=2 c_{1}(T X)([\sigma]) & & \text { [by assumption]. }
\end{array}
$$

Let $(M, \alpha)$ be a contact manifold of dimension $2 n+1$ with Reeb vector field $R$. Our goal is to repeat the discussion of the first part of this section in the context of periodic orbits of $R$.

Definition 3.12. A Reeb orbit is a map $\gamma: \mathbb{R} / T \mathbb{Z} \longrightarrow M$ such that

$$
\dot{\gamma}(t)=R(\gamma(t))
$$

for every $t \in S^{1}$. In this case, we call $T$ the period of $\gamma$. The multiplicity of $\gamma$, which we will usually denote by $m$, is the degree of the map $\gamma: \mathbb{R} / T \mathbb{Z} \longrightarrow \operatorname{im} \gamma$. The action of $\gamma$ is

$$
\mathcal{A}(\gamma):=\int_{0}^{T} \gamma^{*} \lambda=T
$$

Remark 3.13. Alternatively, a $T$-periodic Reeb orbit can be seen as a map $\gamma: S^{1} \longrightarrow M$ such that $\dot{\gamma}(t)=T R(\gamma(t))$. We will use the two possible descriptions interchangeably.
Since $L_{R} \alpha=0$ (by Lemma 2.23) and using Lemma 2.9, we conclude that $\left(\phi_{R}^{t}\right)^{*} \alpha=\alpha$. In particular, $\mathrm{D} \phi_{R}^{t}(p)\left(\xi_{p}\right) \subset \xi_{\phi_{R}^{t}(p)}$ and

$$
\mathrm{D} \phi_{R}^{t}(p): \xi_{p} \longrightarrow \xi_{\phi_{R}^{t}(p)}
$$

is a symplectic linear map.
Definition 3.14. A Reeb orbit $\gamma$ of $M$ is nondegenerate if the linear map

$$
\mathrm{D} \phi_{R}^{1}(\gamma(0)): \xi_{\gamma(0)} \longrightarrow \xi_{\gamma(1)}=\xi_{\gamma(0)}
$$

does not have 1 as an eigenvalue. We say that $(M, \alpha)$ is nondegenerate if every Reeb orbit in $M$ is nondegenerate. If $(X, \lambda)$ is a Liouville domain, then $(X, \lambda)$ is nondegenerate if $\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ is nondegenerate.
Definition 3.15. Let $\gamma$ be a periodic orbit of $R$ and $\tau$ be a symplectic trivialization of $\gamma^{*} \xi$. The Conley-Zehnder index of $\gamma$ is given by

$$
\mu_{\mathrm{CZ}}^{\tau}(\gamma):=\mu_{\mathrm{CZ}}\left(A^{\gamma, \tau}\right),
$$

where $A^{\gamma, \tau}:[0,1] \longrightarrow \operatorname{Sp}(2 n)$ is the path of symplectic matrices given by the equation $A^{\gamma, \tau}(t):=\tau_{t} \circ \mathrm{D} \phi_{R}^{t}(\gamma(0)) \circ \tau_{0}^{-1}$.
Lemma 3.16. Let $(X, \lambda)$ be a Liouville domain and $\gamma: S^{1} \longrightarrow \partial X$ be a Reeb orbit. For $i=1,2$, let $u_{i}: D \longrightarrow X$ be a filling disk for $\gamma\left(\right.$ i.e. $\iota_{X, \partial X} \circ \gamma=u_{i} \circ \iota_{D, S^{1}}$ ). Let $\tau^{i}$ be a symplectic trivialization of $u_{i}^{*} T X$ and denote also by $\tau^{i}$ the induced trivialization of $\left(\iota_{X, \partial X} \circ \gamma\right)^{*} T X$. Assume that

$$
\begin{aligned}
& \tau_{t}^{i}\left(Z_{\gamma(t)}\right)=e_{1} \quad \in \mathbb{R}^{2 n} \\
& \tau_{t}^{i}\left(R_{\gamma(t)}\right)=e_{n+1} \in \mathbb{R}^{2 n}
\end{aligned}
$$

for every $t \in S^{1}$. If $2 c_{1}(T X)=0$, then

$$
\mu_{\mathrm{CZ}}^{\tau^{1}}(\gamma)=\mu_{\mathrm{CZ}}^{\tau^{2}}(\gamma) .
$$

Proof. By the assumptions on $\tau^{i}$, the diagram

commutes, where

$$
\begin{aligned}
\iota_{\mathbb{R}^{2 n-2}}\left(x^{2}, \ldots, x^{n}, y^{2}, \ldots, y^{n}\right) & =\left(0, x^{2}, \ldots, x^{n}, 0, y^{2}, \ldots, y^{n}\right), \\
\iota_{\mathbb{R}^{2}}(x, y) & =(x, 0, \ldots, 0, y, 0, \ldots, 0) .
\end{aligned}
$$

Define

$$
\begin{aligned}
B^{2 n}(t) & :=\tau_{t}^{1} \circ\left(\tau_{t}^{2}\right)^{-1}: \quad \mathbb{R}^{2 n} \longrightarrow \mathbb{R}^{2 n}, \\
B^{2 n-2}(t) & :=\tau_{t}^{1} \circ\left(\tau_{t}^{2}\right)^{-1}: \mathbb{R}^{2 n-2} \longrightarrow \mathbb{R}^{2 n-2},
\end{aligned}
$$

By the assumptions on $\tau^{i}$, and diagram (3.4),

$$
B^{2 n}(t)=\left[\begin{array}{cc}
\mathrm{id}_{\mathbb{R}^{2}} & 0  \tag{3.5}\\
0 & B^{2 n-2}
\end{array}\right]
$$

Let $\sigma: S^{2} \longrightarrow X$ be the gluing of the disks $u_{1}$ and $u_{2}$ along their common boundary $\gamma$. Finally, we compute

$$
\begin{aligned}
\mu_{\mathrm{CZ}}^{\tau^{1}}(\gamma)-\mu_{\mathrm{CZ}}^{\tau^{2}}(\gamma) & =2 \mu\left(B^{2 n-2}\right) & & \\
& =2 \mu\left(B^{2 n}\right) & & \text { [by the same compuatation as in Lemma 3.11] } \\
& =2 c_{1}\left(\sigma^{*} T X\right) & & \text { [by definition of first Chern class] } \\
& =0 & & \text { [by assumption]. }
\end{aligned}
$$

Remark 3.17. Suppose that $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ is a tuple of (Hamiltonian or Reeb) orbits and $\tau$ is a trivialization of the relevant symplectic vector bundle over each orbit. We will frequently use the following notation:

$$
\begin{aligned}
\mathcal{A}(\Gamma) & :=\sum_{i=1}^{p} \mathcal{A}\left(\gamma_{i}\right), \\
\mu_{\mathrm{CZ}}^{\tau}(\Gamma) & :=\sum_{i=1}^{p} \mu_{\mathrm{CZ}}^{\tau}\left(\gamma_{i}\right) .
\end{aligned}
$$

If $\beta=\sum_{i=1}^{m} a_{i} \Gamma_{i}$ is a formal linear combination of tuples of orbits, then we denote

$$
\mathcal{A}(\beta):=\max _{i=1, \ldots, m} \mathcal{A}\left(\Gamma_{i}\right) .
$$

The action of a formal linear combination is going to be relevant only in Chapter 7, where we will consider the action filtration on linearized contact homology.

### 3.5 Periodic Reeb orbits in a unit cotangent bundle

Let $(L, g)$ be an orientable Riemannian manifold of dimension $n$. Recall that $L$ has a cotangent bundle $\pi: T^{*} L \longrightarrow L$, which is an exact symplectic manifold with symplectic potential $\lambda \in \Omega^{1}\left(T^{*} L\right)$, symplectic form $\omega:=\mathrm{d} \lambda$ and Liouville vector field $Z$ given by $\iota_{Z} \omega=\lambda$. We will denote by $z: L \longrightarrow T^{*} L$ the zero section. Consider the unit cotangent bundle $\pi: S^{*} L \longrightarrow L$ and denote by $\iota: S^{*} L \longrightarrow L$ the inclusion. Then, $\alpha:=\iota^{*} \lambda$ is a contact form on $S^{*} L$, with associated contact distribution $\xi=\operatorname{ker} \alpha \subset T S^{*} L$ and Reeb vector field $R \in \mathfrak{X}\left(S^{*} L\right)$. The Riemannian metric $g$ defines a vector bundle isomorphism $\tilde{g}: T L \longrightarrow T^{*} L$ given by $\tilde{g}(v)=g(v, \cdot)$.
Let $\ell>0$ and $c: \mathbb{R} / \ell \mathbb{Z} \longrightarrow L$ be a curve which is parametrized by arclength. Define $\gamma:=\tilde{g} \circ \dot{c}: \mathbb{R} / \ell \mathbb{Z} \longrightarrow S^{*} L$. Then, by Theorems 2.29 and 2.30, the curve $c$ is a geodesic (of length $\ell$ ) if and only if $\gamma$ is a Reeb orbit (of period $\ell$ ). We will assume that this is the case. The goal of this section is to study specific sets of trivializations and maps between these sets (see diagram (3.14)), which can be used to define the Conley-Zehnder index of $\gamma$ (see Theorem 3.29).
Since $T^{*} L$ is a symplectic manifold, $T T^{*} L \longrightarrow T^{*} L$ is a symplectic vector bundle. The hyperplane distribution $\xi$ is a symplectic subbundle of $\iota^{*} T T^{*} L \longrightarrow S^{*} L$. We can consider the symplectic complement of $\xi$, which by Lemma 2.26 is given by

$$
\xi_{u}^{\perp}=\left\langle Z_{u}\right\rangle \oplus\left\langle R_{u}\right\rangle
$$

for every $u \in S^{*} L$. Finally, $T^{*} L \oplus T L \longrightarrow L$ is a symplectic vector bundle, with symplectic structure given by

$$
\omega_{T^{*} L \oplus T L}((u, v),(x, y))=u(y)-x(v) .
$$

Remark 3.18. Let $\pi: E \longrightarrow B$ be a vector bundle. Consider the vector bundles $\pi^{*} E$, $T E$ and $\pi^{*} T B$ over $E$. There is a short exact sequence

$$
0 \longrightarrow \pi^{*} E \xrightarrow{I^{V}} T E \xrightarrow{P^{H}} \pi^{*} T B \longrightarrow 0
$$

of vector bundles over $E$, where

$$
\begin{aligned}
I_{e}^{V} & :=\mathrm{D} \iota_{e}(e): E_{\pi(e)} \longrightarrow T_{e} E, \quad \text { where } \iota_{e}: E_{\pi(e)} \longrightarrow E \text { is the inclusion, } \\
P_{e}^{H}: & =\mathrm{D} \pi(e): T_{e} E \longrightarrow T_{\pi(e)} B,
\end{aligned}
$$

for every $e \in E$. Recall that a Koszul connection on $E$ is a map

$$
\nabla: \mathfrak{X}(B) \times \Gamma(E) \longrightarrow \Gamma(E)
$$

which is $C^{\infty}$-linear on $\mathfrak{X}(B)$ and satisfies the Leibniz rule on $\Gamma(E)$. A linear Ehresmann connection on $E$ is a vector bundle map $P^{V}: T E \longrightarrow \pi^{*} E$ such that $P^{V} \circ I^{V}=\mathrm{id}_{\pi^{*} T B}$ and $P^{V} \circ T m_{\lambda}=m_{\lambda} \circ P^{V}$ for every $\lambda \in \mathbb{R}$, where $m_{\lambda}: E \longrightarrow E$ is the map which multiplies by $\lambda$. The sets of Koszul connections on $E$ and of linear Ehresmann connections on $E$ are in bijection. If $\nabla$ is a Koszul connection on $E$, the corresponding linear Ehresmann connection is given as follows. Let $I^{H}: \pi^{*} T B \longrightarrow T E$ be the map which is given by

$$
I_{e}^{H}(u):=\mathrm{D} s(\pi(e)) u-I_{e}^{V}\left(\nabla_{u} s\right)
$$

for every $e \in E$ and $u \in T_{\pi(e)} B$, where $s$ in any choice of section of $\pi: E \longrightarrow B$ such that $s(\pi(e))=e$. The map $I^{H}$ is independent of the choice of section $s$ and satisfies $P^{H} \circ I^{H}=\operatorname{id}_{\pi^{*} T B}$. Let $P^{V}: T E \longrightarrow \pi^{*} E$ be the map which is given by

$$
P_{e}^{V}(w):=\left(I_{e}^{V}\right)^{-1}\left(w-I_{e}^{H} \circ P_{e}^{H}(w)\right)
$$

for every $e \in E$ and $w \in T_{e} E$. We point out that this definition is well-posed, since $w-I_{e}^{H} \circ P_{e}^{H}(w) \in \operatorname{ker} P_{e}^{H}=\operatorname{im} I_{e}^{V}$. As before, $P^{V} \circ I^{V}=\operatorname{id}_{\pi^{*} E}$. Finally, the maps

$$
\begin{aligned}
I & :=I^{V} \oplus I^{H}: \pi^{*} E \oplus \pi^{*} T B \longrightarrow T E, \\
P & :=P^{V} \times P^{H}: T E \longrightarrow \pi^{*} E \oplus \pi^{*} T B,
\end{aligned}
$$

are isomorphisms and inverses of one another.
Consider the Levi-Civita connection on $L$, which is a Koszul connection on $T L$. There is an induced Koszul connection on $T^{*} L$ given by

$$
\left(\nabla_{X} \beta\right)(Y):=X(\beta(Y))-\beta\left(\nabla_{X} Y\right)
$$

for every $X, Y \in \mathfrak{X}(L)$ and $\beta \in \Gamma\left(T^{*} L\right)=\Omega^{1}(L)$. By Remark 3.18 (with $B=L$ and $E=T^{*} L$ ), there is an induced linear Ehresmann connection on $\pi: T^{*} L \longrightarrow L$ which is given by maps

$$
\begin{aligned}
I & :=I^{V} \oplus I^{H}: \pi^{*} T^{*} L \oplus \pi^{*} T L \longrightarrow T T^{*} L \\
P & :=P^{V} \times P^{H}: T T^{*} L \longrightarrow \pi^{*} T^{*} L \oplus \pi^{*} T L
\end{aligned}
$$

Lemma 3.19. The maps I and $P$ are isomorphisms of symplectic vector bundles. Moreover,

$$
\begin{array}{ll}
P\left(Z_{u}\right)=(u, 0), & \text { for every } u \in T^{*} L, \\
P\left(R_{u}\right)=\left(0, \tilde{g}^{-1}(u)\right), & \text { for every } u \in S^{*} L . \tag{3.7}
\end{array}
$$

Proof. Let $q:=\pi(u)$ and choose normal coordinates $\left(q^{1}, \ldots, q^{n}\right)$ on $L$ centred at $q$ (this means that with respect to these coordinates, $g_{i j}(q)=\delta_{i j}$ and $\partial_{k} g_{i j}(q)=0$ ). Let $\left(q^{1}, \ldots, q^{n}, p_{1}, \ldots, p_{n}\right)$ be the induced coordinates on $T^{*} L$. Then, the vector spaces $T_{u} T^{*} L$ and $T_{q}^{*} L \oplus T_{q} L$ have the following symplectic bases:

$$
\begin{align*}
T_{u} T^{*} L & =\operatorname{span}\left\{\left.\frac{\partial}{\partial p_{1}}\right|_{u}, \cdots,\left.\frac{\partial}{\partial p_{n}}\right|_{u},\left.\frac{\partial}{\partial q^{1}}\right|_{u}, \cdots,\left.\frac{\partial}{\partial q^{n}}\right|_{u}\right\},  \tag{3.8}\\
T_{q}^{*} L \oplus T_{q} L & =\operatorname{span}\left\{\left.\mathrm{d} q^{1}\right|_{q}, \ldots,\left.\mathrm{~d} q^{n}\right|_{q}\right\} \oplus \operatorname{span}\left\{\left.\frac{\partial}{\partial q^{1}}\right|_{q}, \cdots,\left.\frac{\partial}{\partial q^{n}}\right|_{q}\right\} . \tag{3.9}
\end{align*}
$$

By the definitions of $P$ and $I$ in Remark 3.18, we have

$$
\begin{align*}
I_{u}^{V}\left(\left.\mathrm{~d} q^{i}\right|_{q}\right) & =\left.\frac{\partial}{\partial p_{i}}\right|_{u}, \\
P_{u}^{H}\left(\left.\frac{\partial}{\partial q^{i}}\right|_{u}\right) & =\left.\frac{\partial}{\partial q^{i}}\right|_{q} ^{\prime}  \tag{3.10}\\
P_{u}^{V}\left(\left.\frac{\partial}{\partial p_{i}}\right|_{u}\right) & =P_{u}^{V} \circ I_{u}^{V}\left(\left.\mathrm{~d} q^{i}\right|_{q}\right)=\left.\mathrm{d} q^{i}\right|_{q}, \tag{3.11}
\end{align*}
$$

which implies that $P$ is the identity matrix when written with respect to the bases (3.8) and (3.9). Since these bases are symplectic, $P$ is a symplectic linear map. With respect to the coordinates $\left(q^{1}, \ldots, q^{n}, p_{1}, \ldots, p_{n}\right)$, the Liouville vector field is given by

$$
\begin{equation*}
Z=\sum_{i=1}^{n} p_{i} \frac{\partial}{\partial p_{i}} \tag{3.12}
\end{equation*}
$$

By Theorem 2.30 and Equation (2.1), and since the coordinates are normal, the Reeb vector field is given by

$$
\begin{equation*}
R_{u}=\left.\sum_{i=1}^{n} p_{i}(u) \frac{\partial}{\partial q^{i}}\right|_{u} . \tag{3.13}
\end{equation*}
$$

Equations (3.12) and (3.13) together with equations (3.10) and (3.11) imply Equations (3.6) and (3.7).

Define

$$
\begin{aligned}
\mathcal{T}\left(c^{*} T L\right) & :=\left\{\kappa \left\lvert\, \begin{array}{l}
\kappa \text { is an isometric trivialization of } c^{*} T L \\
\text { such that } \kappa_{t}(\dot{c}(t))=e_{1} \in \mathbb{R}^{n} \text { for every } t \in \mathbb{R} / \ell \mathbb{Z}
\end{array}\right.\right\}, \\
\mathcal{T}\left(\gamma^{*} \xi\right) & :=\left\{\tau \mid \tau \text { is a symplectic trivialization of } \gamma^{*} \xi\right\}
\end{aligned},
$$

We will define maps $\tau, \sigma_{0}$ and $\sigma$ (see Definitions 3.20 to 3.22 ) which fit into the following diagram.

$$
\begin{equation*}
\underset{\sim}{\mathcal{T}\left(\gamma^{*} \xi\right) \xrightarrow[\sigma_{0}]{\mathcal{T}\left(c^{*} T L\right)}} \underset{\mathcal{T}\left((z \circ c)^{*} T T^{*} L\right)}{\sigma} \tag{3.14}
\end{equation*}
$$

We will check that this diagram commutes in Lemma 3.24. Consider the following diagram of symplectic vector spaces and symplectic linear maps.

$$
\xi_{\gamma(t)} \xrightarrow{\iota_{\gamma(t)}} \xi_{\gamma(t)}^{\perp} \oplus \xi_{\gamma(t)}=T_{\gamma(t)} T^{*} L \xrightarrow{P_{\gamma(t)}} T_{c(t)}^{*} L \oplus T_{c(t)} L \stackrel{P_{z o c(t)}}{\rightleftarrows} T_{z o c(t)} T^{*} L
$$

We now define the maps $\tau, \sigma_{0}$ and $\sigma$.
Definition 3.20. For every $\kappa \in \mathcal{T}\left(c^{*} T L\right)$, we define $\tau(\kappa) \in \mathcal{T}\left(\gamma^{*} \xi\right)$ by

$$
\tau(\kappa)_{t}:=\pi_{\mathbb{R}^{2 n-2}} \circ \tilde{\kappa}_{t} \circ P_{\gamma(t)} \circ \iota_{\xi_{\gamma(t)}},
$$

where $\tilde{\kappa}_{t}: T_{c(t)}^{*} L \oplus T_{c(t)} L \longrightarrow \mathbb{R}^{n} \oplus \mathbb{R}^{n}$ and $\pi_{\mathbb{R}^{2 n-2}}: \mathbb{R}^{2 n} \longrightarrow \mathbb{R}^{2 n-2}$ are given by

$$
\begin{aligned}
\tilde{\kappa}_{t}(u, v) & :=\left(\kappa_{t} \circ \tilde{g}_{c(t)}^{-1}(u), \kappa_{t}(v)\right), \\
\pi_{\mathbb{R}^{2 n-2}}\left(x^{1}, \ldots, x^{n}, y^{1}, \ldots, y^{n}\right) & :=\left(x^{2}, \ldots, x^{n}, y^{2}, \ldots, y^{n}\right) .
\end{aligned}
$$

For Definition 3.20 to be well-posed, we need $\tilde{\kappa}_{t}$ to be a symplectic linear map. We check this in Lemma 3.23 below.

Definition 3.21. For every $\tau \in \mathcal{T}\left(\gamma^{*} \xi\right)$, we define $\sigma_{0}(\tau) \in \mathcal{T}\left((z \circ c)^{*} T T^{*} L\right)$ by

$$
\sigma_{0}(\tau)_{t}:=\tilde{\tau}_{t} \circ P_{\gamma(t)}^{-1} \circ P_{z \circ c(t)},
$$

where $\tilde{\tau}_{t}: \xi_{\gamma(t)}^{\perp} \oplus \xi_{\gamma(t)} \longrightarrow \mathbb{R}^{2 n}$ is the symplectic linear map given by

$$
\begin{aligned}
\tilde{\tau}_{t}\left(Z_{\gamma(t)}\right) & =e_{1}, \\
\tilde{\tau}_{t}\left(R_{\gamma(t)}\right) & =e_{n+1}, \\
\tilde{\tau}_{t}(v) & =\iota_{\mathbb{R}^{2 n-2}} \circ \tau_{t}(v), \quad \text { for every } v \in \xi_{\gamma(t)},
\end{aligned}
$$

and $\iota_{\mathbb{R}^{2 n-2}}: \mathbb{R}^{2 n-2} \longrightarrow \mathbb{R}^{2 n}$ is given by

$$
\iota_{\mathbb{R}^{2 n-2}}\left(x^{2}, \ldots, x^{n}, y^{2}, \ldots, y^{n}\right)=\left(0, x^{2}, \ldots, x^{n}, 0, y^{2}, \ldots, y^{n}\right) .
$$

Definition 3.22. For every $\kappa \in \mathcal{T}\left(c^{*} T L\right)$, we define $\sigma(\kappa) \in \mathcal{T}\left((z \circ c)^{*} T T^{*} L\right)$ by

$$
\sigma(\kappa)_{t}:=\tilde{\kappa}_{t} \circ P_{z \circ c(t)} .
$$

Lemma 3.23. The map $\tilde{\kappa}_{t}$ from Definitions 3.20 and 3.22 is symplectic.
Proof. For $(u, v),(x, y) \in T_{c(t)}^{*} L \oplus T_{c(t)} L$, we have

$$
\begin{aligned}
\omega_{\mathbb{R}^{n} \oplus \mathbb{R}^{n}}\left(\tilde{\kappa}_{t}(u, v), \tilde{\kappa}_{t}(x, y)\right) & & \\
=\omega_{\mathbb{R}^{n} \oplus \mathbb{R}^{n}}\left(\left(\kappa_{t} \circ \tilde{g}_{c(t)}^{-1}(u), \kappa_{t}(v)\right),\left(\kappa_{t} \circ \tilde{g}_{c(t)}^{-1}(x), \kappa_{t}(y)\right)\right) & & {\left[\text { by definition of } \tilde{\kappa}_{t}\right] } \\
=\left\langle\kappa_{t} \circ \tilde{g}_{c(t)}^{-1}(u), \kappa_{t}(y)\right\rangle_{\mathbb{R}^{n}}-\left\langle\kappa_{t} \circ \tilde{g}_{c(t)}^{-1}(x), \kappa_{t}(v)\right\rangle_{\mathbb{R}^{n}} & & {\left[\text { by definition of } \omega_{\mathbb{R}^{n} \oplus \mathbb{R}^{n}}\right] } \\
=\left\langle\tilde{g}_{c(t)}^{-1}(u), y\right\rangle_{T L}-\left\langle\tilde{g}_{c(t)}^{-1}(x), v\right\rangle_{T L} & & \text { [since } \kappa_{t} \text { is an isometry] } \\
=u(y)-x(v) & & \text { [by definition of } \tilde{g}] \\
=\omega_{T^{*} L \oplus T L}((u, v),(x, y)) & & \text { [by definition of } \left.\omega_{T^{*} L \oplus T L}\right] .
\end{aligned}
$$

Lemma 3.24. Diagram (3.14) commutes, i.e. $\sigma=\sigma_{0} \circ \tau$.
Proof. By Definitions 3.20 to 3.22,

$$
\begin{aligned}
\sigma(\kappa)_{t} & =\tilde{\kappa}_{t} \circ P_{z \circ c(t)}, \\
\sigma_{0}(\tau(\kappa)) & =\tau(\kappa)_{t} \circ P_{\gamma(t)}^{-1} \circ P_{z \circ c(t)} .
\end{aligned}
$$

Therefore, it is enough to show that $\tilde{\kappa}_{t} \circ P_{\gamma(t)}=\widetilde{\tau(\kappa)_{t}}: T_{\gamma(t)} T^{*} L \longrightarrow \mathbb{R}^{2 n}$. We show that $\tilde{\kappa}_{t} \circ P_{\gamma(t)}\left(Z_{\gamma(t)}\right)=\widetilde{\tau(\kappa)_{t}}\left(Z_{\gamma(t)}\right)$.

$$
\begin{aligned}
\tilde{\kappa}_{t} \circ P_{\gamma(t)}\left(Z_{\gamma(t)}\right) & =\tilde{\kappa}_{t}(\gamma(t), 0) & & {[\text { by Lemma 3.19] }} \\
& =\left(\kappa_{t} \circ \tilde{g}_{c(t)}^{-1}(\gamma(t)), 0\right) & & {\left[\text { by definition of } \tilde{\kappa}_{t}\right] } \\
& =\left(\kappa_{t}(\dot{c}(t)), 0\right) & & {[\text { by definition of } \gamma] } \\
& =\left(e_{1}, 0\right) & & {\left[\text { since } \kappa \in \mathcal{T}\left(c^{*} T L\right)\right] } \\
& =\widetilde{\tau(\kappa)_{t}\left(Z_{\gamma(t)}\right)} & & {\left[\text { by definition of } \tau(\kappa)_{t}\right] . }
\end{aligned}
$$

We show that $\tilde{\kappa}_{t} \circ P_{\gamma(t)}\left(R_{\gamma(t)}\right)=\widetilde{\tau(\kappa)_{t}}\left(R_{\gamma(t)}\right)$.

$$
\begin{aligned}
\tilde{\kappa}_{t} \circ P_{\gamma(t)}\left(R_{\gamma(t)}\right) & =\tilde{\kappa}_{t}\left(0, \tilde{g}_{c(t)}^{-1}(\gamma(t))\right) & & {[\text { by Lemma 3.19] }} \\
& =\left(0, \kappa_{t} \circ \tilde{g}_{c(t)}^{-1}(\gamma(t))\right) & & {\left[\text { by definition of } \tilde{\kappa}_{t}\right] } \\
& =\left(0, \kappa_{t}(\dot{c}(t))\right) & & {[\text { by definition of } \gamma] } \\
& =\left(0, e_{1}\right) & & {\left[\text { since } \kappa \in \mathcal{T}\left(c^{*} T L\right)\right] } \\
& =\widetilde{\tau(\kappa)_{t}\left(R_{\gamma(t)}\right)} & & {\left[\text { by definition of } \widetilde{\tau(\kappa)_{t}}\right] . }
\end{aligned}
$$

The previous computations show that

$$
P_{\gamma(t)} \circ \tilde{\kappa}_{t}\left(\xi_{\gamma(t)}^{\perp}\right)=\operatorname{ker} \pi_{\mathbb{R}^{2 n-2}}
$$

which in turn implies that

$$
\begin{equation*}
P_{\gamma(t)} \circ \tilde{\kappa}_{t}\left(\xi_{\gamma(t)}\right)=\left(\operatorname{ker} \pi_{\mathbb{R}^{2 n-2}}\right)^{\perp}=\operatorname{im} \iota_{\mathbb{R}^{2 n-2}} . \tag{3.15}
\end{equation*}
$$

Finally, we show that $\left.\tilde{\kappa}_{t} \circ P_{\gamma(t)}(v)=\widetilde{\tau(\kappa)}\right)_{t}(v)$ for every $v \in \xi_{\gamma(t)}$.

$$
\begin{aligned}
\widetilde{\tau(\kappa)_{t}}(v) & =\iota_{\mathbb{R}^{2 n-2}} \circ \tau(\kappa)_{t}(v) & & {\left.[\text { by definition of } \widetilde{\tau(\kappa)})_{t}\right] } \\
& =\iota_{\mathbb{R}^{2 n-2}} \circ \pi_{\mathbb{R}^{2 n-2}} \circ \tilde{\kappa}_{t} \circ P_{\gamma(t)} \circ \iota_{\xi_{\gamma(t)}}(v) & & {[\text { by definition of } \tau] } \\
& =\tilde{\kappa}_{t} \circ P_{\gamma(t)}(v) & & {[\text { by Equation }(3.15)] . }
\end{aligned}
$$

This finishes the "construction" of diagram (3.14). Our goal is to show that $\mu_{\text {CZ }}^{\tau(\kappa)}(\gamma)$ is independent of the choice of $\kappa \in \mathcal{T}\left(c^{*} T L\right)$ (see Theorem 3.29). Indeed, we will actually show that $\mu_{\mathrm{CZ}}^{\tau(\kappa)}(\gamma)=\mu_{\mathrm{M}}(c)$. To make sense of this statement, we start by explaining the meaning of the Morse index of a geodesic.
Remark 3.25. Define $X:=W^{1,2}(\mathbb{R} / \ell \mathbb{Z}, L)$ (maps from $\mathbb{R} / \ell \mathbb{Z}$ to $L$ of Sobolev class $W^{1,2}$ ). Then, $X$ is a Hilbert manifold. At $c \in X$, the tangent space of $X$ is

$$
T_{c} X=W^{1,2}\left(\mathbb{R} / \ell \mathbb{Z}, c^{*} T L\right)
$$

which is a Hilbert space. We can define the Energy functional by

$$
\begin{aligned}
& E: X \longrightarrow \mathbb{R} \\
& c \longmapsto \frac{1}{2} \int_{\mathbb{R} / \ell \mathbb{Z}}\|\dot{c}(t)\|^{2} \mathrm{~d} t .
\end{aligned}
$$

Then, $c \in X$ is a critical point of $E$ if and only if $c$ is smooth and a geodesic in $L$. We say that $c$ is nondegenerate if the kernel of the map

$$
\text { Hess } E(c): T_{c} X \longrightarrow T_{c}^{*} X
$$

is ker Hess $E(c)=\langle\dot{c}\rangle$. If $c$ is a critical point of $E$, i.e. a geodesic, then we define the Morse index of $c$ by

$$
\mu_{\mathrm{M}}(c)=\sup \left\{\begin{array}{l|l}
\operatorname{dim} V & \begin{array}{l}
V \text { is a subspace of } T_{c} X, \\
\text { Hess }\left.E(c)\right|_{V}: V \times V \longrightarrow \mathbb{R} \text { is negative definite }
\end{array}
\end{array}\right\} .
$$

Recall that $c$ is a geodesic if and only if $\gamma:=\tilde{g} \circ \dot{c}$ is a Reeb orbit. In this case, $c$ is a nondegenerate critical point of $E$ if and only if $\gamma$ is a nondegenerate Reeb orbit.

Definition 3.26. For $\sigma \in \mathcal{T}\left((z \circ c)^{*} T T^{*} L\right)$, we define the Maslov index of $c$ with respect to $\sigma$, denoted $\mu^{\sigma}(c)$, as follows. First, let $W^{c, \sigma}$ be the loop of Lagrangian subspaces of $\mathbb{R}^{2 n}$ given by

$$
W^{c, \sigma}(t):=\sigma_{t} \circ \mathrm{D} z(c(t))\left(T_{c(t)} L\right)
$$

Then, define $\mu^{\sigma}(c)$ to be the Maslov index of $W^{c, \sigma}$ in the sense of Theorem 3.2.
Lemma 3.27. For any $\kappa \in \mathcal{T}\left(c^{*} T L\right)$,

$$
\mu^{\sigma(\kappa)}(c)=0
$$

Proof. We will show that $W^{c, \sigma(\kappa)}=\{0\} \oplus \mathbb{R}^{n}$. By the zero property of the Maslov index for a path of Lagrangian subspaces, this implies the result. We start by showing that $P_{z(x)}^{V} \circ \mathrm{D} z(x)=0$ for any $x \in L$. For any $w \in T_{x} L$,
$P_{z(x)}^{V} \circ \mathrm{D} z(x) w$

$$
\begin{array}{ll}
=\left(I_{z(x)}^{V}\right)^{-1}\left(\mathrm{D} z(x) w-I_{z(x)}^{H} \circ P_{z(x)}^{H}(\mathrm{D} z(x) w)\right) & {\left[\text { by definition of } P^{V}\right]} \\
=\left(I_{z(x)}^{V}\right)^{-1}(\mathrm{D} z(x) w-\mathrm{D} z(x) \circ \mathrm{D} \pi(z(x)) \circ \mathrm{D} z(x) w) & {\left[\text { by definition of } I^{H} \text { and } P^{H}\right]} \\
=0 & {\left[\text { since } \pi \circ z=\operatorname{id}_{L}\right] .}
\end{array}
$$

We compute $W^{c, \sigma(\kappa)}$.

$$
\begin{aligned}
W^{c, \sigma(\kappa)} & =\sigma(\kappa)_{t} \circ \mathrm{D} z(c(t))\left(T_{c(t)} L\right) & & {\left[\text { by definition of } W^{c, \sigma(\kappa)}\right] } \\
& =\tilde{\kappa}_{t} \circ P_{z \circ c(t)} \circ \mathrm{D} z(c(t))\left(T_{c(t)} L\right) & & {[\text { by definition of } \sigma(\kappa)] } \\
& =\tilde{\kappa}_{t}\left(0, P_{z \circ c(t)}^{H} \circ \mathrm{D} z(c(t))\left(T_{c(t)} L\right)\right) & & {\left[\text { since } P_{z(c(t))}^{V} \circ \mathrm{D} z(c(t))=0\right] } \\
& =\left(0, \kappa_{t} \circ P_{z \circ c(t)}^{H} \circ \mathrm{D} z(c(t))\left(T_{c(t)} L\right)\right) & & {\left[\text { by definition of } \tilde{\kappa}_{t}\right] } \\
& =\left(0, \kappa_{t}\left(T_{c(t)} L\right)\right) & & {\left[\text { since } P_{z \circ c(t)}^{H}=\mathrm{D} \pi(z \circ c(t))\right] } \\
& =\{0\} \oplus \mathbb{R}^{n} & & \text { [since } \left.\kappa_{t} \text { is an isomorphism }\right] .
\end{aligned}
$$

The following theorem was originally proven in [Vit90], but we will use a restatement of it from [CM18].
Theorem 3.28 ([CM18, Lemma 2.1]). For any $\tau \in \mathcal{T}\left(\gamma^{*} \xi\right)$,

$$
\mu_{\mathrm{CZ}}^{\tau}(\gamma)+\mu^{\sigma_{0}(\tau)}(c)=\mu_{\mathrm{M}}(c)
$$

Theorem 3.29. For any $\kappa \in \mathcal{T}\left(c^{*} T L\right)$,

$$
\mu_{\mathrm{CZ}}^{\tau(\kappa)}(\gamma)=\mu_{\mathrm{M}}(c) .
$$

Proof. By Lemmas 3.24 and 3.27 and Theorem 3.28.
Finally, we state a result which will be necessary to prove Theorem 6.40.
Lemma 3.30 ([CM18, Lemma 2.2]). Let L be a compact n-dimensional manifold without boundary. Let Riem $(L)$ be the set of Riemannian metrics on L, equipped with the $C^{2}$ topology. If $g_{0} \in \operatorname{Riem}(L)$ is a Riemannian metric of nonpositive sectional curvature and $\mathcal{U} \subset \operatorname{Riem}(L)$ is an open neighbourhood of $g_{0}$, then for all $\ell_{0}>0$ there exists a Riemannian metric $g \in \mathcal{U}$ on $L$ such that with respect to $g$, any closed geodesic $c$ in $L$ of length $\ell(c) \leq \ell_{0}$ is noncontractible, nondegenerate, and such that $0 \leq \mu_{\mathrm{M}}(c) \leq n-1$.

## Chapter 4

## Holomorphic curves

### 4.1 Holomorphic curves

In this section we define asymptotically cylindrical holomorphic curves (see Definition 4.7). The domain of such a curve is a punctured Riemann surface (see Definition 4.1), and the target is a symplectic cobordism (see Definition 4.2).

Definition 4.1. Let $(\Sigma, j)$ be a Riemann surface. A puncture on $\Sigma$ is a point $z \in \Sigma$. Denote by $D$ the closed unit disk in $\mathbb{C}$ and by $Z^{ \pm}$the positive or negative half-cylinders:

$$
\begin{aligned}
Z^{+} & :=\mathbb{R}_{\geq 0} \times S^{1} \\
Z^{-} & :=\mathbb{R}_{\leq 0} \times S^{1}
\end{aligned}
$$

with coordinates $(s, t) \in Z^{ \pm}$and complex structure $j$ given by $j\left(\partial_{s}\right)=\partial_{t}$. Consider the holomorphic maps

$$
\psi^{ \pm}: Z^{ \pm} \longrightarrow D \backslash\{0\}, \quad \psi^{ \pm}(s, t)=\exp (\mp 2 \pi(s+i t))
$$

A positive or negative cylindrical end near $z$ is a holomorphic embedding $\phi^{ \pm}: Z^{ \pm} \longrightarrow$ $\Sigma \backslash\{z\}$ of the form $\phi^{ \pm}:=\varphi \circ \psi^{ \pm}$, where $\varphi: D \longrightarrow \Sigma$ is a holomorphic embedding such that $\varphi(0)=z$. In this case, we say that $(s, t)$ are cylindrical coordinates near $z$. A punctured Riemann surface is a Riemann surface $(\Sigma, j)$ together with sets

$$
\mathbf{z}=\mathbf{z}^{+} \cup \mathbf{z}^{-}, \quad \mathbf{z}^{ \pm}=\left\{z_{1}^{ \pm}, \ldots, z_{p^{ \pm}}^{ \pm}\right\} \subset \Sigma, \quad \mathbf{z}^{+} \cap \mathbf{z}^{-}=\varnothing
$$

of positive and negative punctures. In this case, we denote $\dot{\Sigma}:=\Sigma \backslash \mathbf{z}$. Whenever we talk about cylindrical coordinates near a puncture, it is implicit that we mean the cylindrical coordinates induced from a positive of negative cylindrical end, in accordance to whether the puncture is positive or negative.

Definition 4.2. A symplectic cobordism is a compact symplectic manifold ( $X, \omega$ ) with boundary $\partial X$, together with a 1 -form $\lambda$ defined on an open neighbourhood of $\partial X$, such that $\mathrm{d} \lambda=\omega$ and the restriction of $\lambda$ to $\partial X$ is a contact form. Let $\partial^{+} X$ (respectively $\left.\partial^{-} X\right)$ be the subset of $\partial X$ where the orientation defined by $\left.\lambda\right|_{\partial X}$ as a contact form agrees with the boundary orientation (respectively negative boundary orientation).

Definition 4.3. A Liouville cobordism is a symplectic cobordism $(X, \omega, \lambda)$ such that $\lambda$ is defined on $X$.

Example 4.4. A Liouville domain is a Liouville cobordism whose negative boundary is empty.
Remark 4.5. We can define the completion of a symplectic cobordism $(X, \omega, \lambda)$ like in Section 2.5 , with the difference that now we attach half-symplectizations to the negative and positive boundaries:

$$
\hat{X}:=\mathbb{R}_{\leq 0} \times \partial^{-} X \cup_{\partial^{-} X} X \cup_{\partial^{+} X} \mathbb{R}_{\geq 0} \times \partial^{+} X
$$

Definition 4.6. Let $(X, \omega, \lambda)$ be a symplectic cobordism and consider its completion $\hat{X}$. An almost complex structure $J$ on $\hat{X}$ is cylindrical if $J$ is compatible with $\hat{\omega}$ and $J$ is cylindrical on $\mathbb{R}_{\geq 0} \times \partial^{+} X$ and $\mathbb{R}_{\leq 0} \times \partial^{-} X$. Denote by $\mathcal{J}(X)$ the set of such $J$.
Definition 4.7. Let $(X, \omega, \lambda)$ be a symplectic cobordism, $J \in \mathcal{J}(X)$ be a cylindrical almost complex structure on $\hat{X}$ and $\Gamma^{ \pm}=\left(\gamma_{1}^{ \pm}, \ldots, \gamma_{p^{ \pm}}^{ \pm}\right)$be tuples of Reeb orbits in $\partial^{ \pm} X$. Let $T_{i}^{ \pm}$denote the period of $\gamma_{i}^{ \pm}$. An asymptotically cylindrical holomorphic curve in $\hat{X}$ from $\Gamma^{-}$to $\Gamma^{+}$is given by a Riemann surface $(\hat{\lambda}, j)$ with punctures $\mathbf{z}^{ \pm}=$ $\left\{z_{1}^{ \pm}, \ldots, z_{p^{ \pm}}^{ \pm}\right\}$together with a $J$-holomorphic map $u: \dot{\Sigma} \longrightarrow \hat{X}$, such that:
(1) $u$ is positively asymptotic to $\gamma_{i}^{+}$at $z_{i}^{+}$, i.e. there exist cylindrical coordinates $(s, t)$ near $z_{i}^{+}$such that $u(s, t) \in \mathbb{R}_{\geq 0} \times \partial^{+} X$ for $s$ big enough and

$$
\begin{aligned}
\lim _{s \rightarrow+\infty} \pi_{\mathbb{R}} \circ u(s, t) & =+\infty \\
\lim _{s \rightarrow+\infty} \pi_{\partial^{+} X} \circ u(s, t) & =\gamma_{i}^{+}\left(t T_{i}^{+}\right)
\end{aligned}
$$

(2) $u$ is negatively asymptotic to $\gamma_{i}^{-}$at $z_{i}^{-}$, i.e. there exist cylindrical coordinates $(s, t)$ near $z_{i}^{-}$such that $u(s, t) \in \mathbb{R}_{\leq 0} \times \partial^{-} X$ for $s$ small enough and

$$
\begin{aligned}
\lim _{s \rightarrow-\infty} \pi_{\mathbb{R}} \circ u(s, t) & =-\infty \\
\lim _{s \rightarrow-\infty} \pi_{\partial^{-} X} \circ u(s, t) & =\gamma_{i}^{-}\left(t T_{i}^{-}\right) .
\end{aligned}
$$

We now explain some analytical properties of asymptotically cylindrical holomorphic curves. The key results are the maximum principle (Lemma 4.10) and a lemma comparing the energy of such a curve and the action of the asymptotic Reeb orbits (Lemma 4.13). The following lemma is an auxiliary result which will allow us to prove that the energy (see Definition 4.12) is a nonnegative number.

Lemma 4.8. Let $(M, \alpha)$ be a contact manifold and $J$ be a cylindrical almost complex structure on $\mathbb{R} \times M$. If $u=(a, f): \dot{\Sigma} \longrightarrow \mathbb{R} \times M$ is a holomorphic curve, then $f^{*} \mathrm{~d} \alpha \geq 0$ and

$$
\begin{align*}
-\mathrm{d} a \circ j & =f^{*} \alpha  \tag{4.1}\\
\pi_{\xi} \circ \mathrm{D} f \circ j & =J_{\xi}(f) \circ \pi_{\xi} \circ \mathrm{D} f . \tag{4.2}
\end{align*}
$$

Proof. We prove equation (4.1):

$$
\begin{aligned}
-\mathrm{d} a \circ j & =-\mathrm{d} r \circ \mathrm{D} u \circ j & & {[\text { by definition of } a] } \\
& =-\mathrm{d} r \circ J(u) \circ \mathrm{D} u & & {[u \text { is holomorphic }] } \\
& =\alpha \circ \mathrm{D} u & & {[\text { by Lemma 2.45] }} \\
& =f^{*} \alpha & & {[\text { by definition of pullback }] . }
\end{aligned}
$$

Equation (4.2) follows by applying $\pi_{\xi}: T(\mathbb{R} \times M) \longrightarrow \xi$ to the equation $J \circ T u=T u \circ j$. We show that $f^{*} \mathrm{~d} \alpha \geq 0$ :

$$
\begin{aligned}
f^{*} \mathrm{~d} & \alpha(S, j(S)) & & \\
& =\mathrm{d} \alpha(\mathrm{D} f(S), \mathrm{D} f \circ j(S)) & & {[\text { by definition of pullback }] } \\
& =\mathrm{d} \alpha\left(\pi_{\xi} \circ \mathrm{D} f(S), \pi_{\xi} \circ \mathrm{D} f \circ j(S)\right) & & {[T M=\langle R\rangle \oplus \xi=\operatorname{ker} \mathrm{d} \alpha \oplus \operatorname{ker} \alpha] } \\
& =\mathrm{d} \alpha\left(\pi_{\xi} \circ \mathrm{D} f(S), J_{\xi}(f) \circ \pi_{\xi} \circ \mathrm{D} f(S)\right) & & {[\text { by Equation }(4.2)] } \\
& =\left\|\pi_{\xi} \circ \mathrm{D} f(S)\right\|_{J_{\xi}(f), \mathrm{d} \alpha}^{2} & & {[\text { since } J \text { is cylindrical }] } \\
& \geq 0 . & &
\end{aligned}
$$

Lemma 4.9. Let $\omega_{\dot{\Sigma}}$ be a symplectic form on $\dot{\Sigma}$ such that $g_{\dot{\Sigma}}:=\omega_{\dot{\Sigma}}(\cdot, j \cdot)$ is a Riemannian metric. Denote by $\mathrm{dvol}_{\dot{\Sigma}}$ the Riemannian volume element of $\dot{\Sigma}$. Let a be a function on $\dot{\Sigma}$ and consider the Laplacian of $a, \Delta a:=\operatorname{div}(\nabla a)$. Then, $\omega_{\dot{\Sigma}}=\operatorname{dvol}_{\dot{\Sigma}}$ and

$$
\Delta a \omega_{\dot{\Sigma}}=-\mathrm{d}(\mathrm{~d} a \circ j) .
$$

Proof. For any unit vector $S \in T \dot{\Sigma}$, if we define $T:=j(S)$ then $\{S, T\}$ is an orthonormal basis of $T \dot{\Sigma}$ and $\omega_{\dot{\Sigma}}(S, T)=1$, which implies $\omega_{\dot{\Sigma}}=\operatorname{dvol}_{\dot{\Sigma}}$. We now prove the formula for the Laplacian.

$$
\begin{aligned}
\Delta a \omega_{\dot{\Sigma}} & =\operatorname{div}(\nabla a) \omega_{\dot{\Sigma}} & & {[\text { by definition of Laplacian }] } \\
& =L_{\nabla a} \omega_{\dot{\Sigma}} & & {\left[\text { by definition of divergence and } \omega_{\dot{\Sigma}}=\mathrm{dvol}_{\dot{\Sigma}}\right] } \\
& =\mathrm{d} \iota_{\nabla a} \omega_{\dot{\Sigma}} & & {[\text { by the Cartan magic formula]. }}
\end{aligned}
$$

It remains to show that $\iota_{\nabla a} \omega_{\dot{\Sigma}}=-\mathrm{d} a \circ j$.

$$
\begin{aligned}
{ }^{{ }_{\nabla a} \omega_{\dot{\Sigma}}(S)} & =\omega_{\dot{\Sigma}}(\nabla a, S) & & \text { [by definition of interior product] } \\
& =-\omega_{\dot{\Sigma}}(\nabla a, j \circ j(S)) & & {[\text { by definition of almost complex structure] }} \\
& =-g_{\dot{\Sigma}}(\nabla a, j(S)) & & \text { [by definition of } \left.g_{\dot{\Sigma}}\right] \\
& =-\mathrm{d} a \circ j(S) & & {[\text { by definition of gradient }] . }
\end{aligned}
$$

Lemma 4.10 (maximum principle). Assume that $\dot{\Sigma}$ is connected. Let ( $M, \alpha$ ) be a contact manifold and $J$ be a cylindrical almost complex structure on $\mathbb{R} \times M$. If

$$
u=(a, f): \dot{\Sigma} \longrightarrow \mathbb{R} \times M
$$

is a holomorphic curve and $a: \dot{\Sigma} \longrightarrow \mathbb{R}$ has a local maximum then a is constant.

Proof. Define $L=-\Delta$. The operator $L$ is a linear elliptic partial differential operator (as in [Eva10, p. 312]). We show that $L a \leq 0$. For this, choose $\omega_{\Sigma}$ a symplectic structure on $\dot{\Sigma}$ such that $g_{\dot{\Sigma}}:=\omega_{\dot{\Sigma}}(\cdot, j \cdot)$ is a Riemannian metric.

$$
\begin{aligned}
L a \omega_{\dot{\Sigma}} & =-\Delta a \omega_{\dot{\Sigma}} & & {[\text { by definition of } L] } \\
& =\mathrm{d}(\mathrm{~d} a \circ j) & & {[\text { by Lemma } 4.9] } \\
& =-\mathrm{d} f^{*} \alpha & & {[\text { by Lemma 4.8] }} \\
& =-f^{*} \mathrm{~d} \alpha & & {[\text { by naturality of exterior derivative }] } \\
& \leq 0 & & {[\text { by Lemma } 4.8] . }
\end{aligned}
$$

This shows that $L a \leq 0$. By the strong maximum principle for elliptic partial differential operators in [Eva10, p. 349-350], if $a$ has a local maximum then $a$ is constant.

Lemma 4.11. Let $(V, j)$ be a complex vector space of real dimension $2,(W, J, \omega, g)$ be a complex vector space with a symplectic form $\omega$ and inner product $g=\omega(\cdot, J \cdot)$, and $\phi: V \longrightarrow W$ be a linear map. For each choice of $s \in V$, define

$$
\begin{aligned}
t & :=j s, \\
\{\sigma, \tau\} & :=\text { basis of } V^{*} \text { dual to }\{s, t\} \\
\omega_{V} & :=\sigma \wedge \tau \\
\|\phi\|^{2} & :=\|\phi s\|^{2}+\|\phi t\|^{2} .
\end{aligned}
$$

Then,

$$
\frac{1}{2}\|\phi\|^{2} \omega_{V}=\left(\phi^{1,0}\right)^{*} \omega-\left(\phi^{0,1}\right)^{*} \omega
$$

which is independent of the choice of $s$.
Proof. Recall the definitions of $\phi^{1,0}$ and $\phi^{0,1}$ :

$$
\begin{aligned}
\phi^{1,0} & :=\frac{1}{2}(\phi-J \circ \phi \circ j), \\
\phi^{0,1} & :=\frac{1}{2}(\phi+J \circ \phi \circ j) .
\end{aligned}
$$

These equations imply that $\phi^{1,0}$ is holomorphic, while $\phi^{0,1}$ is anti-holomorphic:

$$
\begin{equation*}
\phi^{1,0} \circ j=J \circ \phi^{1,0}, \quad \phi^{0,1} \circ j=-J \circ \phi^{0,1} . \tag{4.3}
\end{equation*}
$$

Finally, we compute

$$
\begin{array}{rlrl}
\|\phi\|^{2} \omega_{V}(s, j s) & & \\
\quad=\|\phi(s)\|^{2}+\|\phi \circ j(s)\|^{2} & & {\left[\text { definitions of }\|\phi\|, \omega_{V}\right]} \\
& =\left\|\phi^{1,0}(s)+\phi^{0,1}(s)\right\|^{2}+\left\|\phi^{1,0} \circ j(s)+\phi^{0,1} \circ j(s)\right\|^{2} & & {\left[\text { since } \phi=\phi^{1,0}+\phi^{0,1}\right]} \\
& =\left\|\phi^{1,0}(s)+\phi^{0,1}(s)\right\|^{2}+\left\|J \circ \phi^{1,0}(s)-J \circ \phi^{0,1}(s)\right\|^{2} & & {[\text { by }(4.3)]} \\
& =\left\|\phi^{1,0}(s)+\phi^{0,1}(s)\right\|^{2}+\left\|\phi^{1,0}(s)-\phi^{0,1}(s)\right\|^{2} & & {[\text { since } g=\omega(\cdot, J \cdot)]} \\
& =2\left\|\phi^{1,0}(s)\right\|^{2}+2\left\|\phi^{0,1}(s)\right\|^{2} & & {[\text { by the parallelogram law] }} \\
& =2 \omega\left(\phi^{1,0}(s), J \circ \phi^{1,0}(s)\right)+2 \omega\left(\phi^{0,1}(s), J \circ \phi^{0,1}(s)\right) & & {[\text { since } g=\omega(\cdot, J \cdot)]} \\
& =2 \omega\left(\phi^{1,0}(s), \phi^{1,0} \circ j(s)\right)-2 \omega\left(\phi^{0,1}(s), \phi^{0,1} \circ j(s)\right) & & {[\text { by }(4.3)]} \\
& =2\left(\phi^{1,0}\right)^{*} \omega(s, j s)-2\left(\phi^{0,1}\right)^{*} \omega(s, j s) & & \text { [by definition of pullback]. }
\end{array}
$$

Definition 4.12. Define a piecewise smooth 2-form $\tilde{\omega} \in \Omega^{2}(\hat{X})$ by

$$
\tilde{\omega}:= \begin{cases}\left.\mathrm{d} \lambda\right|_{\partial^{+} X} & \text { on } \mathbb{R}_{\geq 0} \times \partial^{+} X \\ \omega & \text { on } X \\ \left.\mathrm{~d} \lambda\right|_{\partial^{-} X} & \text { on } \mathbb{R}_{\leq 0} \times \partial^{-} X\end{cases}
$$

If $u$ is an asymptotically cylindrical holomorphic curve, its energies are given by

$$
\begin{aligned}
& E_{\hat{\omega}}(u):=\int_{\dot{\Sigma}} u^{*} \hat{\omega}, \\
& E_{\tilde{\omega}}(u):=\int_{\dot{\Sigma}} u^{*} \tilde{\omega} .
\end{aligned}
$$

We point out that if $u$ has positive punctures, then $E_{\hat{\omega}}(u)=+\infty$. Whenever we talk about the energy of an asymptotically cylindrical holomorphic curve, we mean the $E_{\tilde{\omega}}$ energy, unless otherwise specified. We included $E_{\hat{\omega}}$ in the definition above because we will need to use it in Theorem 6.40 to compare the Lagrangian and the McDuff-Siegel capacities. In Lemma 4.14, we compare $E_{\hat{\omega}}$ and $E_{\tilde{\omega}}$.

Lemma 4.13. If $(X, \omega, \lambda)$ is a Liouville cobordism then

$$
0 \leq E_{\tilde{\omega}}(u)=\mathcal{A}\left(\Gamma^{+}\right)-\mathcal{A}\left(\Gamma^{-}\right)
$$

Proof. Since $(X, \omega, \lambda)$ is a Liouville cobordism, $E_{\tilde{\omega}}(u)$ is given by

$$
\begin{aligned}
E_{\tilde{\omega}}(u) & =\int_{\dot{\Sigma}} u^{*} \tilde{\omega} \\
& =\left.\int_{u^{-1}\left(\mathbb{R}_{\leq 0} \times \partial^{-} X\right)} u^{*} \mathrm{~d} \lambda\right|_{\partial^{-} X}+\int_{u^{-1}(X)} u^{*} \mathrm{~d} \lambda+\left.\int_{u^{-1}\left(\mathbb{R}_{\geq 0} \times \partial^{+} X\right)} u^{*} \mathrm{~d} \lambda\right|_{\partial^{+} X} .
\end{aligned}
$$

Here, the first and third terms are nonnegative by Lemma 4.8, while the second term is nonnegative by Lemma 4.11. This shows that $E_{\tilde{\omega}}(u) \geq 0$. Since $u$ is asymptotic to $\Gamma^{ \pm}$ and by Stokes' theorem, $E_{\tilde{\omega}}(u)=\mathcal{A}\left(\Gamma^{+}\right)-\mathcal{A}\left(\Gamma^{-}\right)$.

Lemma 4.14. Assume that $\Sigma$ has no positive punctures. Let $(X, \omega, \lambda)$ be a symplectic cobordism, and $J \in \mathcal{J}(X)$ be a cylindrical almost complex structure on $\hat{X}$. Assume that the canonical symplectic embedding

$$
\left(\mathbb{R}_{\leq 0} \times \partial^{-} X, \mathrm{~d}\left(\left.e^{r} \lambda\right|_{\partial^{-} X}\right)\right) \longrightarrow(\hat{X}, \hat{\omega})
$$

can be extended to a symplectic embedding

$$
\left(\mathbb{R}_{\leq K} \times \partial^{-} X, \mathrm{~d}\left(\left.e^{r} \lambda\right|_{\partial^{-} X}\right)\right) \longrightarrow(\hat{X}, \hat{\omega})
$$

for some $K>0$. Let $u: \dot{\Sigma} \longrightarrow \hat{X}$ be a J-holomorphic curve which is negatively asymptotic to a tuple of Reeb orbits $\Gamma$ of $\partial^{-} X$. Consider the energies $E_{\hat{\omega}}(u)$ and $E_{\hat{\omega}}(u)$ of Definition 4.12. Then,

$$
\begin{align*}
\mathcal{A}(\Gamma) & \leq \frac{1}{e^{K}-1} E_{\tilde{\omega}}(u)  \tag{4.4}\\
E_{\hat{\omega}}(u) & \leq \frac{e^{K}}{e^{K}-1} E_{\tilde{\omega}}(u) \tag{4.5}
\end{align*}
$$

Proof. It is enough to show that

$$
\begin{align*}
E_{\hat{\omega}}(u)-E_{\tilde{\omega}}(u) & =\mathcal{A}(\Gamma)  \tag{4.6}\\
E_{\hat{\omega}}(u) & \geq e^{K} \mathcal{A}(\Gamma) \tag{4.7}
\end{align*}
$$

since these equations imply Equations (4.4) and (4.5). Since $u$ has no positive punctures, the maximum principle (Lemma 4.10) implies that $u$ is contained in $\mathbb{R}_{\leq 0} \times \partial^{-} X \cup X$. We prove Equation (4.6). For simplicity, denote $M=\partial^{-} X$ and $\alpha=\left.\lambda\right|_{\partial^{-} X}$.

$$
\begin{aligned}
E_{\hat{\omega}}(u)-E_{\tilde{\omega}}(u) & =\int_{\dot{\Sigma}} u^{*}(\hat{\omega}-\tilde{\omega}) & & {\left[\text { by definition of } E_{\hat{\omega}} \text { and } E_{\tilde{\omega}}\right] } \\
& =\int_{u^{-1}\left(\mathbb{R}_{\leq 0} \times M\right)} u^{*} \mathrm{~d}\left(\left(e^{r}-1\right) \alpha\right) & & {[\text { by definition of } \hat{\omega} \text { and } \tilde{\omega}] } \\
& =\mathcal{A}(\Gamma) & & {[\text { by Stokes' theorem }] . }
\end{aligned}
$$

We prove Equation (4.7).

$$
\begin{aligned}
E_{\hat{\omega}}(u) & =\int_{\dot{\Sigma}} u^{*} \hat{\omega} & & {\left[\text { by definition of } E_{\hat{\omega}}\right] } \\
& \geq \int_{u^{-1}\left(\mathbb{R}_{\leq K} \times M\right)} u^{*} \mathrm{~d}\left(e^{r} \alpha\right) & & {\left[\text { by definition of } \hat{\omega} \text { and } u^{*} \hat{\omega} \geq 0\right] } \\
& =e^{K} \int_{u^{-1}(\{K\} \times M)} u^{*} \alpha & & {[\text { by Stokes' theorem }] } \\
& =e^{K} \int_{u^{-1}\left(\mathbb{R}_{\leq K} \times M\right)} u^{*} \mathrm{~d} \alpha+e^{K} \mathcal{A}(\Gamma) & & {[\text { by Stokes' theorem }] } \\
& \geq e^{K} \mathcal{A}(\Gamma) & & {[\text { by Lemma } 4.8] . }
\end{aligned}
$$

### 4.2 Moduli spaces of Holomorphic curves

If $(M, \alpha)$ is a contact manifold, we denote by $\mathcal{J}(M)$ the set of cylindrical almost complex structures on $\mathbb{R} \times M$ (see Definition 2.44). If $(X, \omega, \lambda)$ is a symplectic cobordism, we denote by $\mathcal{J}(X)$ the set of cylindrical almost complex structures on $\hat{X}$ (see Definition 4.6). If $J^{ \pm} \in \mathcal{J}\left(\partial^{ \pm} X\right)$ is a cylindrical almost complex structure on $\mathbb{R} \times \partial^{ \pm} X$, then we define the following subsets of $\mathcal{J}(X)$ :

$$
\begin{aligned}
\mathcal{J}^{J^{+}}(X) & :=\left\{J \in \mathcal{J}(X) \mid J=J^{+} \text {on } \mathbb{R}_{\geq 0} \times \partial^{+} X\right\}, \\
\mathcal{J}_{J^{-}}(X) & :=\left\{J \in \mathcal{J}(X) \mid J=J^{-} \text {on } \mathbb{R}_{\leq 0} \times \partial^{-} X\right\}, \\
\mathcal{J}_{J^{-}}^{J^{+}}(X) & :=\left\{J \in \mathcal{J}(X) \mid J=J^{+} \text {on } \mathbb{R}_{\geq 0} \times \partial^{+} X \text { and } J=J^{-} \text {on } \mathbb{R}_{\leq 0} \times \partial^{-} X\right\} .
\end{aligned}
$$

Let $\Gamma^{ \pm}=\left(\gamma_{1}^{ \pm}, \ldots, \gamma_{p^{ \pm}}^{ \pm}\right)$be a tuple of Reeb orbits in $\partial^{ \pm} X$ and $J \in \mathcal{J}(X)$ be a cylindrical almost complex structure on $\hat{X}$. Define a moduli space

$$
\mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right):=\left\{\begin{array}{l|l}
(\Sigma, u) & \begin{array}{l}
\Sigma \text { is a connected closed Riemann surface } \\
\text { of genus } 0 \text { with punctures } \mathbf{z}^{ \pm}=\left\{z_{1}^{ \pm}, \ldots, z_{p^{ \pm}}^{ \pm}\right. \\
u: \dot{\Sigma} \longrightarrow \hat{X} \text { is as in Definition } 4.7
\end{array}
\end{array}\right\} / \sim,
$$

where $\left(\Sigma_{0}, u_{0}\right) \sim\left(\Sigma_{1}, u_{1}\right)$ if and only if there exists a biholomorphism $\phi: \Sigma_{0} \longrightarrow \Sigma_{1}$ such that $u_{1} \circ \phi=u_{0}$ and $\phi\left(z_{0, i}^{ \pm}\right)=z_{1, i}^{ \pm}$for every $i=1, \ldots, p^{ \pm}$. If $\Gamma^{ \pm}=\left(\gamma_{1}^{ \pm}, \ldots, \gamma_{p^{ \pm}}^{ \pm}\right)$
is a tuple of Reeb orbits on a contact manifold $M$ and $J \in \mathcal{J}(M)$, we define a moduli space $\mathcal{M}_{M}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$of holomorphic curves in $\mathbb{R} \times M$ analogously. Since $J$ is invariant with respect to translations in the $\mathbb{R}$ direction, $\mathcal{M}_{M}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$admits an action of $\mathbb{R}$ by composition on the target by a translation.
One can try to show that the moduli space $\mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$is transversely cut out by showing that the relevant linearized Cauchy-Riemann operator is surjective at every point of the moduli space. In this case, the moduli space is an orbifold whose dimension is given by the Fredholm index of the linearized Cauchy-Riemann operator. However, since the curves in $\mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$are not necessarily simple, this proof will in general not work, and we cannot say that the moduli space is an orbifold. However, the Fredholm theory part of the proof still works, which means that we still have a dimension formula. In this case the expected dimension given by the Fredholm theory is usually called a virtual dimension. For the moduli space above, the virtual dimension at a point $u$ is given by (see [BM04, Section 4])

$$
\operatorname{virdim}_{u} \mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)=(n-3)\left(2-p^{+}-p^{-}\right)+c_{1}^{\tau}\left(u^{*} T \hat{X}\right)+\mu_{\mathrm{CZ}}^{\tau}\left(\Gamma^{+}\right)-\mu_{\mathrm{CZ}}^{\tau}\left(\Gamma^{-}\right)
$$

where $\tau$ is a unitary trivialization of the contact distribution over each Reeb orbit.
We now discuss curves satisfying a tangency constraint. Our presentation is based on [MS22, Section 2.2] and [CM18, Section 3]. Let $(X, \omega, \lambda)$ be a symplectic cobordism and $x \in \operatorname{int} X$. A symplectic divisor through $x$ is a germ of a 2 -codimensional symplectic submanifold $D \subset X$ containing $x$. A cylindrical almost complex structure $J \in \mathcal{J}(X)$ is compatible with $D$ if $J$ is integrable near $x$ and $D$ is holomorphic with respect to $J$. We denote by $\mathcal{J}(X, D)$ the set of such almost complex structures. In this case, there are complex coordinates $\left(z^{1}, \ldots, z^{n}\right)$ near $x$ such that $D$ is given by $h\left(z_{1}, \ldots, z_{n}\right)=0$, where $h\left(z_{1}, \ldots, z_{n}\right)=z_{1}$. Let $u: \Sigma \longrightarrow X$ be a $J$-holomorphic curve together with a marked point $w \in \Sigma$. For $k \geq 1$, we say that $u$ has contact order $k$ to $D$ at $x$ if $u(w)=x$ and

$$
(h \circ u \circ \varphi)^{(1)}(0)=\cdots=(h \circ u \circ \varphi)^{(k-1)}(0)=0,
$$

for some local biholomorphism $\varphi:(\mathbb{C}, 0) \longrightarrow(\Sigma, w)$. We point out that the condition of having "contact order $k$ " as written above is equal to the condition of being "tangent of order $k-1$ " as defined in [CM18, Section 3]. Following [MS22], we will use the notation $\left\langle\mathcal{T}^{(k)} x\right\rangle$ to denote moduli spaces of curves which have contact order $k$, i.e. we will denote them by $\mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ and $\mathcal{M}_{M}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$. The virtual dimension is given by (see [MS22, Equation (2.2.1)])

$$
\begin{aligned}
& \operatorname{virdim}_{u} \mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle \\
& \quad=(n-3)\left(2-p^{+}-p^{-}\right)+c_{1}^{\tau}\left(u^{*} T \hat{X}\right)+\mu_{\mathrm{CZ}}^{\tau}\left(\Gamma^{+}\right)-\mu_{\mathrm{CZ}}^{\tau}\left(\Gamma^{-}\right)-2 n-2 k+4 .
\end{aligned}
$$

The following theorem says that moduli spaces of simple, asymptotically cylindrical holomorphic curves are transversely cut out.
Theorem 4.15 ([CM07, Proposition 6.9]). Let $(X, \omega, \lambda)$ be a symplectic cobordism, $x \in$ int $X$ and $D$ be a symplectic divisor at $x$. There exists a comeagre set $\mathcal{J}_{\text {reg }}(X, D) \subset$ $\mathcal{J}(X, D)$ with the following property. If $J \in \mathcal{J}_{\text {reg }}(X, D)$ is a regular almost complex structure, $\Gamma^{ \pm}=\left(\gamma_{1}^{ \pm}, \ldots, \gamma_{p^{ \pm}}^{ \pm}\right)$is a tuple of Reeb orbits of $\partial^{ \pm} X$ and $A \in H_{2}\left(X, \Gamma^{+} \cup \Gamma^{-}\right)$,
then the moduli space $\mathcal{M}_{X, A, s}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle \subset \mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ of simple curves representing the homology class $A$ is a manifold of dimension

$$
\begin{aligned}
& \operatorname{dim} \mathcal{M}_{X, A, s}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle \\
& \quad=(n-3)\left(2-p^{+}-p^{-}\right)+2 c_{1}^{\tau}(T X) \cdot A+\mu_{\mathrm{CZ}}^{\tau}\left(\Gamma^{+}\right)-\mu_{\mathrm{CZ}}^{\tau}\left(\Gamma^{-}\right)-2 n-2 k+4 .
\end{aligned}
$$

We will now use this transversality result to state two lemmas from [CM18], namely Lemmas 4.16 and 4.17, which we will use in the proof of Theorem 6.40. For the sake of completeness, we will also give proofs of the results. We point out that in order to achieve the conditions in the statement of the lemmas, we can use a metric as in Lemma 3.30. Finally, notice that Lemma 4.17 generalizes Lemma 4.16 to the case where the curve is not necessarily simple.

Lemma 4.16 ([CM18, Lemma 3.2]). Let ( $L, g$ ) be an n-dimensional Riemannian manifold with the property that for some $\ell_{0}>0$, all closed geodesics $\gamma$ of length $\ell(\gamma) \leq \ell_{0}$ are noncontractible and nondegenerate and have Morse index $\mu_{\mathrm{M}}(\gamma) \leq n-1$. Let $x \in T^{*} L$ and $D$ be a symplectic divisor through $x$. For generic $J$ every simple punctured $J$ holomorphic sphere $C$ in $T^{*} L$ which is asymptotic at the punctures to geodesics of length $\leq \ell_{0}$ and which has contact order $k$ to $D$ at $x$ must have at least $k+1$ punctures.

Proof. Let $\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ be the tuple of asymptotic Reeb orbits of $C$, which have corresponding geodesics also denoted by $\left(\gamma_{1}, \ldots, \gamma_{p}\right)$. By assumption, $\mu_{\mathrm{M}}\left(\gamma_{i}\right) \leq n-1$ for every $i=1, \ldots, p$. Choose a trivialization $\tau$ of $C^{*} T T^{*} L$ such that the induced trivialization over the asymptotic Reeb orbits is as in Theorem 3.29. We show that $p \geq k+1$.

$$
\begin{aligned}
0 & \leq \operatorname{dim}_{C} \mathcal{M}_{X, s}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle \\
& =(n-3)(2-p)+2 c_{1}^{\tau}(T X) \cdot[C]+\sum_{i=1}^{p} \mu_{\mathrm{CZ}}^{\tau}\left(\gamma_{i}\right)-2 n-2 k+4 \\
& =(n-3)(2-p)+\sum_{i=1}^{p} \mu_{\mathrm{M}}\left(\gamma_{i}\right)-2 n-2 k+4 \\
& \leq(n-3)(2-p)+\sum_{i=1}^{p}(n-1)-2 n-2 k+4 \\
& =2(p-1-k) .
\end{aligned}
$$

Lemma 4.17 ([CM18, Corollary 3.3]). Let ( $L, g$ ) be an n-dimensional Riemannian manifold with the property that for some $\ell_{0}>0$, all closed geodesics $\gamma$ of length $\ell(\gamma) \leq \ell_{0}$ are noncontractible and nondegenerate and have Morse index $\mu_{\mathrm{M}}(\gamma) \leq n-1$. Let $x \in T^{*} L$ and $D$ be a symplectic divisor through $x$. For generic $J$ every (not necessarily simple) punctured J-holomorphic sphere $\tilde{C}$ in $T^{*} L$ which is asymptotic at the punctures to geodesics of length $\leq \ell_{0}$ and which has contact order $\tilde{k}$ to $D$ at $x$ must have at least $\tilde{k}+1$ punctures.

Proof. Let $\tilde{z}_{1}, \ldots, \tilde{z}_{\tilde{p}}$ be the punctures of $\tilde{C}$. Then $\tilde{C}$ is a map $\tilde{C}: S^{2} \backslash\left\{\tilde{z}_{1}, \ldots, \tilde{z}_{\tilde{p}}\right\} \longrightarrow T^{*} L$ which has contact order $\tilde{k}$ at $\tilde{z}_{0}$ to $D$, for some $\tilde{z}_{0} \in S^{2} \backslash\left\{\tilde{z}_{1}, \ldots, \tilde{z}_{\tilde{p}}\right\}$. There exists a $d$-fold branched cover $\phi: S^{2} \longrightarrow S^{2}$ and a simple punctured $J$-holomorphic sphere $C$
with $p$ punctures $\left\{z_{1}, \ldots, z_{p}\right\}$ which has contact order $k$ at $z_{0}=\phi\left(\tilde{z}_{0}\right)$ to $D$, such that the following diagram commutes:


Define $b=\operatorname{ord}\left(\tilde{z}_{0}\right)$. Since the asymptotic Reeb orbits of $\tilde{C}$ are multiples of the asymptotic Reeb orbits of $C$, we have that the Reeb orbits of $C$ all have period less or equal to $\ell_{0}$. Therefore, applying Lemma 4.16 to $C$ we conclude that $p-1 \geq k$.
We show that $k b \geq \tilde{k}$. For this, choose holomorphic coordinates centred at $z_{0} \in S^{2}$, $\tilde{z}_{0} \in S^{2}$, and $x \in X$ such that $D$ is given by $h\left(z_{1}, \ldots, z_{n}\right)=0$, where $h\left(z_{1}, \ldots, z_{n}\right)=z_{1}$. Then, with respect to these coordinates

$$
\begin{aligned}
\phi(z) & =z^{b}, \\
h \circ C(z) & =\sum_{j=1}^{+\infty} a_{j} z^{j},
\end{aligned}
$$

and therefore

$$
h \circ \tilde{C}(z)=h \circ C \circ \phi(z)=\sum_{j=1}^{+\infty} a_{j} z^{b j} .
$$

Since $\tilde{C}$ has contact order $\tilde{k}$ to $D$,

$$
0=(h \circ \tilde{C})^{(r)}(0)=\left.\sum_{j=1}^{+\infty} a_{j}(b j)^{r} z^{b j-r}\right|_{z=0}
$$

for every $r=1, \ldots, \tilde{k}-1$. Therefore, for every $j \in \mathbb{Z}_{\geq 1}$ if there exists $r=1, \ldots, \tilde{k}-1$ such that if $b j-r=0$, then $a_{j}=0$. In other words $a_{1}=\cdots=a_{\ell}=0$, where

$$
\begin{aligned}
\ell & =\max \left\{j \in \mathbb{Z}_{\geq 1} \mid b j \leq \tilde{k}-1\right\} \\
& =\min \left\{j \in \mathbb{Z}_{\geq 1} \mid b(j+1) \geq \tilde{k}\right\} .
\end{aligned}
$$

So, we conclude that $b k \geq b(\ell+1) \geq \tilde{k}$.
We show that $\tilde{p} \geq(p-2) d+b+1$.

$$
\begin{aligned}
2 d-2 & =\sum_{\tilde{z} \in S^{2}}(\operatorname{ord}(\tilde{z})-1) & & \text { [by the Riemann-Hurwitz formula] } \\
& \geq \sum_{i=1}^{\tilde{p}}\left(\operatorname{ord}\left(\tilde{z}_{i}\right)-1\right)+\operatorname{ord}\left(\tilde{z}_{0}\right)-1 & & {\left[\text { since } \operatorname{ord}(z) \geq 1 \text { for every } z \in S^{2}\right] } \\
& =p d-\tilde{p}+\operatorname{ord}\left(\tilde{z}_{0}\right)-1 & & {\left[\text { since } \phi\left(\left\{\tilde{z}_{1}, \ldots, \tilde{z}_{\tilde{p}}\right\}\right)=\left\{z_{1}, \ldots, z_{p}\right\}\right] } \\
& =p d-\tilde{p}+b-1 & & {[\text { by definition of } b] . }
\end{aligned}
$$

Since $\phi$ is a $d$-fold covering, $d \geq b$. Combining all the facts which we have proven, we conclude that

$$
\begin{array}{rlrl}
\tilde{p} & \geq(p-2) d+b+1 & & {[\text { by the last computation }]} \\
& \geq(k-1) d+b+1 & & {[\text { since } p-1 \geq k]} \\
& \geq k b+1 & & {[\text { since } d \geq b]} \\
\geq \tilde{k}+1 & & {[\text { since } k b \geq \tilde{k}] .}
\end{array}
$$

### 4.3 SFT compactness

In this section we present the SFT compactness theorem, which describes the compactifications of the moduli spaces of the previous section. This theorem was first proven by Bourgeois-Eliashberg-Hofer-Wysocki-Zehnder [ $\mathrm{BEH}^{+}$03]. Cieliebak-Mohnke [CM05] have given a proof of this theorem using different methods. Our presentation is based primarily on [CM18] and [MS22].

Definition 4.18. A nodal Riemann surface is a Riemann surface $(\Sigma, j)$ together with a set $\mathbf{n}$ of nodes of the form $\mathbf{n}=\left\{n_{1}^{+}, n_{1}^{-}, \ldots, n_{k}^{+}, n_{k}^{-}\right\}$.
Definition 4.19. Let $(\Sigma, j)$ be a Riemann surface with a set $\mathbf{n}=\left\{n_{1}^{+}, n_{1}^{-}, \ldots, n_{k}^{+}, n_{k}^{-}\right\}$of nodes and $(X, J)$ be an almost complex manifold. A nodal $J$-holomorphic curve is a $J$-holomorphic curve $u:(\Sigma, j) \longrightarrow(X, J)$ such that $u\left(n_{i}^{+}\right)=u\left(n_{i}^{-}\right)$for every $i=1, \ldots, k$. Let $(X, \omega, \lambda)$ be a symplectic cobordism and choose almost complex structures $J^{ \pm} \in$ $\mathcal{J}\left(\partial^{ \pm} X\right)$ and $J \in \mathcal{J}_{J^{-}}^{J^{+}}(X)$. Let $\Gamma^{ \pm}=\left(\gamma_{1}^{ \pm}, \ldots, \gamma_{p^{ \pm}}^{ \pm}\right)$be a tuple of Reeb orbits in $\partial^{ \pm} X$.
Definition 4.20. For $1 \leq L \leq N$, let $\alpha^{ \pm}:=\left.\lambda\right|_{\partial^{ \pm} X}$ and define

$$
\begin{aligned}
& \left(X^{\nu}, \omega^{\nu}, \tilde{\omega}^{\nu}, J^{\nu}\right):= \begin{cases}\left(\mathbb{R} \times \partial^{-} X, \mathrm{~d}\left(e^{r} \alpha^{-}\right), \mathrm{d} \alpha^{-}, J^{-}\right) & \text {if } \nu=1, \ldots, L-1, \\
(\hat{X}, \hat{\omega}, \tilde{\omega}, J) & \text { if } \nu=L, \\
\left(\mathbb{R} \times \partial^{+} X, \mathrm{~d}\left(e^{r} \alpha^{+}\right), \mathrm{d} \alpha^{+}, J^{+}\right) & \text {if } \nu=L+1, \ldots, N,\end{cases} \\
& \left(X^{*}, \omega^{*}, \tilde{\omega}^{*}, J^{*}\right):=\coprod_{\nu=1}^{N}\left(X^{\nu}, \omega^{\nu}, \tilde{\omega}^{\nu}, J^{\nu}\right) .
\end{aligned}
$$

The moduli space of holomorphic buildings, denoted $\overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$, is the set of tuples $F=\left(F^{1}, \ldots, F^{N}\right)$, where $F^{\nu}: \dot{\Sigma}^{\nu} \longrightarrow X^{\nu}$ is an asymptotically cylindrical nodal $J^{\nu_{-}}$ holomorphic curve in $X^{\nu}$ with sets of asymptotic Reeb orbits $\Gamma_{\nu}^{ \pm}$. Here, each $F^{\nu}$ is possibly disconnected and if $X^{\nu}$ is a symplectization then $F^{\nu}$ is only defined up to translation in the $\mathbb{R}$ direction. We assume in addition that $F$ satisfies the following conditions.
(1) The sets of asymptotic Reeb orbits $\Gamma_{\nu}^{ \pm}$are such that

$$
\begin{aligned}
\Gamma_{\nu}^{+} & =\Gamma_{\nu+1}^{-} \quad \text { for every } \nu=1, \ldots, N-1 \\
\Gamma_{1}^{-} & =\Gamma^{-} \\
\Gamma_{N}^{+} & =\Gamma^{+}
\end{aligned}
$$

(2) Define the graph of $F$ to be the graph whose vertices are the components of $F^{1}, \ldots, F^{N}$ and whose edges are determined by the asymptotic Reeb orbits. Then the graph of $F$ is a tree.
(3) The building $F$ has no symplectization levels consisting entirely of trivial cylinders, and any constant component of $F$ has negative Euler characteristic after removing all special points.

Definition 4.21. The energy of a holomorphic building $F=\left(F^{1}, \ldots, F^{N}\right)$ is

$$
E_{\tilde{\omega}^{*}}(F):=\sum_{\nu=1}^{N} E_{\tilde{\omega}^{\nu}}\left(F^{\nu}\right),
$$

where $E_{\tilde{\omega}^{\nu}}\left(F^{\nu}\right)$ is given as in Definition 4.12.
The moduli space $\overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$admits a metrizable topology (see [BO16, Appendix B]). With this language, the SFT compactness theorem can be stated as follows.
Theorem 4.22 (SFT compactness). The moduli space $\overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$is compact.
We now consider the case where the almost complex structure on $\hat{X}$ is replaced by a family of almost complex structures obtained via neck stretching. Let ( $X^{ \pm}, \omega^{ \pm}, \lambda^{ \pm}$) be symplectic cobordisms with common boundary

$$
(M, \alpha)=\left(\partial^{-} X^{+},\left.\lambda^{+}\right|_{\partial^{-} X^{+}}\right)=\left(\partial^{+} X^{-},\left.\lambda^{-}\right|_{\partial^{+} X^{-}}\right) .
$$

Choose almost complex structures

$$
\begin{aligned}
J_{M} & \in \mathcal{J}(M), \\
J_{+} & \in \mathcal{J}_{J_{M}}\left(X^{+}\right), \\
J_{-} & \in \mathcal{J}^{J_{M}}\left(X^{-}\right),
\end{aligned}
$$

and denote by $J_{\partial^{ \pm} X^{ \pm}} \in \mathcal{J}\left(\partial^{ \pm} X^{ \pm}\right)$the induced cylindrical almost complex structure on $\mathbb{R} \times \partial^{ \pm} X^{ \pm}$. Let $(X, \omega, \lambda):=\left(X^{-}, \omega^{-}, \lambda^{-}\right) \odot\left(X^{+}, \omega^{+}, \lambda^{+}\right)$be the gluing of $X^{-}$and $X^{+}$ along $M$. We wish to define a family of almost complex structures $\left(J_{t}\right)_{t \in \mathbb{R} \geq 0} \subset \mathcal{J}(X)$. For every $t \geq 0$, let

$$
X_{t}:=X^{-} \cup_{M}[-t, 0] \times M \cup_{M} X^{+}
$$

There exists a canonical diffeomorphism $\phi_{t}: X \longrightarrow X_{t}$. Define an almost complex structure $J_{t}$ on $X_{t}$ by

$$
J_{t}:= \begin{cases}J^{ \pm} & \text {on } X^{ \pm} \\ J_{M} & \text { on }[-t, 0] \times M\end{cases}
$$

Denote also by $J_{t}$ the pullback of $J_{t}$ to $X$, as well as the induced almost complex structure on the completion $\hat{X}$. Finally, consider the moduli space

$$
\mathcal{M}_{X}^{\left(J_{t}\right)_{t}}\left(\Gamma^{+}, \Gamma^{-}\right):=\coprod_{t \in \mathbb{R}_{\geq 0}} \mathcal{M}_{X}^{J_{t}}\left(\Gamma^{+}, \Gamma^{-}\right) .
$$

Definition 4.23. For $1 \leq L^{-}<L^{+} \leq N$, let $\alpha^{ \pm}:=\left.\lambda^{ \pm}\right|_{\partial^{ \pm} X^{ \pm}}$and define

$$
\begin{aligned}
& \left(X^{\nu}, \omega^{\nu}, \tilde{\omega}^{\nu}, J^{\nu}\right):= \begin{cases}\left(\mathbb{R} \times \partial^{-} X^{-}, \mathrm{d}\left(e^{r} \alpha^{-}\right), \mathrm{d} \alpha^{-}, J_{\partial^{-} X^{-}}\right) & \text {if } \nu=1, \ldots, L^{-}-1, \\
\left(X^{-}, \omega^{-}, \tilde{\omega}^{-}, J^{-}\right) & \text {if } \nu=L^{-}, \\
\left(\mathbb{R} \times M, \mathrm{~d}\left(e^{r} \alpha\right), \mathrm{d} \alpha, J_{M}\right) & \text { if } \nu=L^{-}+1, \ldots, L^{+}-1, \\
\left(X^{+}, \omega^{+}, \tilde{\omega}^{+}, J^{+}\right) & \text {if } \nu=L^{+}, \\
\left(\mathbb{R} \times \partial^{+} X^{+}, \mathrm{d}\left(e^{r} \alpha^{+}\right), \mathrm{d} \alpha^{+}, J_{\partial^{+} X^{+}}\right) & \text {if } \nu=L^{+}+1, \ldots, N, \\
\left(X^{*}, \omega^{*}, \tilde{\omega}^{*}, J^{*}\right):=\coprod_{\nu=1}^{N}\left(X^{\nu}, \omega^{\nu}, \tilde{\omega}^{\nu}, J^{\nu}\right) .\end{cases}
\end{aligned}
$$

Define $\overline{\mathcal{M}}_{X}^{\left(J_{t}\right)_{t}}\left(\Gamma^{+}, \Gamma^{-}\right)$to be the set of tuples $F=\left(F^{1}, \ldots, F^{N}\right)$, where $F^{\nu}: \dot{\Sigma}^{\nu} \longrightarrow X^{\nu}$ is an asymptotically cylindrical nodal $J^{\nu}$-holomorphic curve in $X^{\nu}$ with sets of asymptotic Reeb orbits $\Gamma_{\nu}^{ \pm}$, such that $F$ satisfies conditions analogous to those of Definition 4.20.

Theorem 4.24 (SFT compactness). The moduli space $\overline{\mathcal{M}}_{X}^{\left(J_{t}\right) t}\left(\Gamma^{+}, \Gamma^{-}\right)$is compact.
Remark 4.25. The discussion above also applies to compactifications of moduli spaces of curves satisfying tangency constraints. The compactification $\overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ consists of buildings $F=\left(F^{1}, \ldots, F^{N}\right) \in \overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$such that exactly one component $C$ of $F$ inherits the tangency constraint $\left\langle\mathcal{T}^{(k)} x\right\rangle$, and which satisfy the following additional condition. Consider the graph obtained from the graph of $F$ by collapsing adjacent constant components to a point. Let $C_{1}, \ldots, C_{p}$ be the (necessarily nonconstant) components of $F$ which are adjacent to $C$ in the new graph. Then we require that there exist $k_{1}, \ldots, k_{p} \in \mathbb{Z}_{\geq 1}$ such that $k_{1}+\cdots+k_{p} \geq k$ and $C_{i}$ satisfies the constraint $\left\langle\mathcal{T}^{\left(k_{i}\right)} x\right\rangle$ for every $i=1, \ldots, p$. This definition is natural to consider by [CM07, Lemma 7.2]. We can define $\overline{\mathcal{M}}_{X}^{\left(J_{t}\right)_{t}}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ analogously.

Remark 4.26. We point out that in [MS22, Definition 2.2.1], the compactification of Remark 4.25 is denoted by $\overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$, while the notation $\overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ is used to denote the moduli space of buildings $F=\left(F^{1}, \ldots, F^{N}\right) \in \overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$such that exactly one component $C$ of $F$ inherits the tangency constraint $\left\langle\mathcal{T}^{(k)} x\right\rangle$, but which do not necessarily satisfy the additional condition of Remark 4.25.

Lemma 4.27. Suppose that $\Gamma^{-}=\varnothing$ and $\Gamma^{+}=(\gamma)$ consists of a single Reeb orbit. Let $F$ be a holomorphic building of genus 0 in any of the following compactified moduli spaces:

$$
\begin{array}{ll}
\overline{\mathcal{M}}_{X}^{J}(\gamma), & \overline{\mathcal{M}}_{X}^{J}(\gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle, \\
\overline{\mathcal{M}}_{X}^{\left(J_{t}\right) t}(\gamma), & \overline{\mathcal{M}}_{X}^{\left(J_{t}\right)_{t}}(\gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle .
\end{array}
$$

Then $F$ has no nodes.
Proof. Assume by contradiction that $F$ has a node. Let $\bar{\Sigma}$ be the topological space obtained by gluing the $\Sigma^{\nu}$ along the matching punctures. Let $\bar{X}$ be the topological space obtained by gluing the $X^{\nu}$ along the matching ends. The space $\bar{X}$ is homeomorphic to $\hat{X}$, and therefore we can identify homology classes in $\bar{X}$ and $\hat{X}$. The holomorphic building $F$ defines a continuous map $\bar{F}: \bar{\Sigma} \longrightarrow \bar{X}$ (for more details on the definitions
of $\bar{F}: \bar{\Sigma} \longrightarrow \bar{X}$, see [CM18, Section 2.6]). By the assumptions on $F$ and since $F$ has a node, it is possible to decompose $\bar{F}$ along the node into two continuous maps

$$
\begin{aligned}
& \bar{F}_{0}: \bar{\Sigma}_{0} \longrightarrow \bar{X}, \\
& \bar{F}_{1}: \bar{\Sigma}_{1} \longrightarrow \bar{X},
\end{aligned}
$$

where $\bar{F}_{0}$ is a plane and $\bar{F}_{1}$ is a sphere. Since $\bar{F}_{1}$ is a sphere, it defines a homology class $\left[\bar{F}_{1}\right] \in H_{2}(\hat{X} ; \mathbb{Z})$. Then,

$$
\begin{aligned}
0 & =\mathrm{d} \hat{\lambda}\left(\left[\bar{F}_{1}\right]\right) & & {\left[\text { since } \mathrm{d} \hat{\lambda}=0 \in H_{\mathrm{dR}}^{2}(\hat{X})\right] } \\
& >0 & & {[\text { by [CM18, Lemma 2.8]], }}
\end{aligned}
$$

which gives the desired contradiction.

### 4.4 Solutions of the parametrized Floer equation

The goal of this section is to introduce the trajectories that appear in $S^{1}$-equivariant symplectic homology (see Definition 4.32). We will write these trajectories as maps whose domain is any punctured Riemann surface, but we point out that in Chapter 5, where we discuss $S^{1}$-equivariant symplectic homology, all trajectories have as domain the cylinder $\mathbb{R} \times S^{1}$. Let $(\Sigma, j)$ be a Riemann surface with punctures

$$
\mathbf{z}=\mathbf{z}^{+} \cup \mathbf{z}^{-}, \quad \mathbf{z}^{ \pm}=\left\{z_{1}^{ \pm}, \ldots, z_{p^{ \pm}}^{ \pm}\right\} .
$$

We assume that near every puncture $z$, there are cylindrical coordinates $(s, t)$ as in Definition 4.1. Let $\sigma, \tau \in \Omega^{1}(\dot{\Sigma})$ be 1 -forms such that for every (positive or negative) puncture $z$, if we denote by $(s, t)$ the coordinates on the cylindrical end of $\dot{\Sigma}$ near $z$, then

$$
\begin{aligned}
& \sigma=A \mathrm{~d} s \\
& \tau=B \mathrm{~d} t
\end{aligned}
$$

for some $A, B>0$. Finally, we assume that there is an action

$$
S^{1} \times \dot{\Sigma} \longrightarrow \dot{\Sigma}
$$

of $S^{1}$ on $\dot{\Sigma}$ which preserves $j, \sigma$ and $\tau$ and such that if $t^{\prime} \in S^{1}$ and $(s, t)$ belongs to any cylindrical coordinate neighbourhood, then

$$
t^{\prime} \cdot(s, t)=\left(s, t+t^{\prime}\right)
$$

Example 4.28. Consider the cylinder $\mathbb{R} \times S^{1}$ with coordinates $(s, t)$ and almost complex structure given by $j\left(\partial_{s}\right)=\partial_{t}$. We have the 1 -forms $\sigma:=\mathrm{d} s$ and $\tau:=\mathrm{d} t$. The cylinder is biholomorphic to the sphere $S^{2}$ with the north and south poles removed. There is an action of $S^{1}$ on $\mathbb{R} \times S^{1}$ given by $t^{\prime} \cdot(s, t)=\left(s, t+t^{\prime}\right)$. Therefore, $\mathbb{R} \times S^{1}$ can be seen as a special case of the assumptions above. In this case, we will typically denote $\dot{\Sigma}=\mathbb{R} \times S^{1}$ and $\Sigma=S^{2}$.

Let $\left(S, g^{S}\right)$ be a Riemannian manifold together with an action $S^{1} \times S \longrightarrow S$ which is free, proper and by isometries. Define $C=S / S^{1}$ and denote the projection by $\pi: S \longrightarrow C$. Since the action is by isometries, there exists a unique Riemannian metric $g^{C}$ on $C$ such that $\pi: S \longrightarrow C$ is a Riemannian submersion. Let $f: C \longrightarrow \mathbb{R}$ be a Morse function and define $\tilde{f}:=f \circ \pi: S \longrightarrow \mathbb{R}$, which is Morse-Bott.

Example 4.29. For $N \in \mathbb{Z}_{\geq 1}$, let

$$
\begin{aligned}
S & :=S^{2 N+1}, \\
C & :=\mathbb{C} P^{N}, \\
f & :=f_{N},
\end{aligned}
$$

where

$$
f_{N}\left(\left[w_{0}: \cdots: w_{N}\right]\right):=\frac{\sum_{j=0}^{N} j\left|w_{j}\right|^{2}}{\sum_{j=0}^{N}\left|w_{j}\right|^{2}}
$$

As we will discuss in Section 5.2, $S, C$ and $f$ given above are as in the previous paragraph. Finally, let $(X, \lambda)$ be a Liouville domain.
Definition 4.30. An admissible Hamiltonian is a map $H: \dot{\Sigma} \times S \times \hat{X} \longrightarrow \mathbb{R}$ such that:
(1) For every puncture $z$, the restriction of $H$ to the cylindrical end near $z$ is independent of $s$ for $s$ large enough. In other words, there is a map $H_{z}: S^{1} \times S \times \hat{X} \longrightarrow \mathbb{R}$ such that $H(s, t, w, x)=H_{z}(t, w, x)$ for $s$ large enough.
(2) For every critical point $w$ of $\tilde{f}$, there exists a neighbourhood $V$ of $w$ in $S$ such that the restriction $H: \dot{\Sigma} \times V \times \hat{X} \longrightarrow \mathbb{R}$ is independent of $V$.
(3) Consider the action of $S^{1}$ on $\dot{\Sigma} \times S \times \hat{X}$ given by $t \cdot(z, w, x)=(t \cdot z, t \cdot w, x)$. Then, the Hamiltonian $H$ is invariant under the action of $S^{1}$.
(4) For every puncture $z$, there exist $D \in \mathbb{R}, C \in \mathbb{R}_{>0} \backslash \operatorname{Spec}\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ and $\delta>0$ such that on $S^{1} \times S \times[\delta,+\infty) \times \partial X$, we have that $H_{z}(t, w, r, x)=C e^{r}+D$.
(5) For every puncture $z$ and critical point $w$ of $\tilde{f}$ the Hamiltonian $H_{z, w}: S^{1} \times \hat{X} \longrightarrow \mathbb{R}$ is nondegenerate.
(6) For every $(z, w, x) \in \dot{\Sigma} \times S \times \hat{X}$ we have

$$
\begin{aligned}
& H_{w, x} \mathrm{~d} \tau \leq 0, \\
& \mathrm{~d}_{\dot{\Sigma}} H_{w, x} \wedge \tau \leq 0, \\
& \left\langle\nabla_{S} H_{z, x}(w), \nabla \tilde{f}(w)\right\rangle \sigma_{z} \wedge \tau_{z} \leq 0 .
\end{aligned}
$$

Definition 4.31. An admissible almost complex structure on $\hat{X}$ is a section $J: \dot{\Sigma} \times$ $S \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ such that $J^{2}=-\mathrm{id}_{T X}$ and:
(1) For every puncture $z$, the restriction of $J$ to the cylindrical end near $z$ is independent of $s$ for $s$ large enough. In other words, there is a function $J_{z}: S^{1} \times S \times \hat{X} \longrightarrow$ $\operatorname{End}(T \hat{X})$ such that $J(s, t, w, x)=J_{z}(t, w, x)$ for $s$ large enough.
(2) For every critical point $w$ of $\tilde{f}$, there exists a neighbourhood $V$ of $w$ in $S$ such that the restriction $J: \dot{\Sigma} \times V \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ is independent of $V$.
(3) The almost complex structure $J$ is $S^{1}$-invariant.
(4) $J$ is compatible, i.e. $g:=\omega(\cdot, J \cdot): \dot{\Sigma} \times S \times \hat{X} \longrightarrow T^{*} \hat{X} \otimes T^{*} \hat{X}$ is a Riemannian metric on $X$ parametrized by $\dot{\Sigma} \times S$.
(5) $J$ is cylindrical, i.e. if $(z, w) \in \dot{\Sigma} \times S$ then $J_{z, w}$ is cylindrical on $\mathbb{R}_{\geq 0} \times \partial X$.

Definition 4.32. Let $w: \dot{\Sigma} \longrightarrow S$ and $u: \dot{\Sigma} \longrightarrow \hat{X}$ be maps. We will denote by u the map $\mathbf{u}:=\left(\operatorname{id}_{\dot{\Sigma}}, w, u\right): \dot{\Sigma} \longrightarrow \dot{\Sigma} \times S \times \hat{X}$. We say that $(w, u)$ is a solution of the parametrized Floer equation if

$$
\begin{align*}
\mathrm{D} w-\nabla \tilde{f}(w) \otimes \sigma & =0,  \tag{4.8}\\
\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right)_{J(\mathbf{u}), j}^{0,} & =0 . \tag{4.9}
\end{align*}
$$

Example 4.33. Suppose that $(\dot{\Sigma}, j, \sigma, \tau)=\left(\mathbb{R} \times S^{1}, j, \mathrm{~d} s, \mathrm{~d} t\right)$ is the cylinder from Example 4.28. Then, $(w, u)$ is a solution of the parametrized Floer equation if and only if $w: \mathbb{R} \times S^{1} \longrightarrow S$ is independent of $t \in S^{1}$, thus defining a map $w: \mathbb{R} \longrightarrow S$, and

$$
\begin{aligned}
\frac{\partial w}{\partial s}(s) & =\nabla \tilde{f}(w(s)) \\
\frac{\partial u}{\partial s}(s, t) & =-J(s, t, w(s), u(s, t))\left(\frac{\partial u}{\partial t}(s, t)-X_{H}(s, t, w(s), u(s, t))\right) .
\end{aligned}
$$

Definition 4.34. Let $z$ be a puncture and $B>0$ be such that $\tau=B \mathrm{~d} t$, where $(s, t)$ are the cylindrical coordinates near $z$. A 1-periodic orbit of $H$ at $z$ is a pair $(w, \gamma)$ such that $w \in S$ is a critical point of $\tilde{f}$ and $\gamma$ is a 1-periodic orbit of $H_{z, w}: S^{1} \times \hat{X} \longrightarrow \mathbb{R}$. Denote by $\mathcal{P}(H, z)$ the set of such pairs. The action of $(w, \gamma)$ is

$$
\mathcal{A}_{H}(w, \gamma):=\mathcal{A}_{B H_{z, w}}(\gamma)=\int_{S^{1}} \gamma^{*} \hat{\lambda}-B \int_{S^{1}} H_{z, w}(t, \gamma(t)) \mathrm{d} t .
$$

Definition 4.35. Let $(w, u)$ be a solution of the parametrized Floer equation. We say that $(w, u)$ is asymptotic at $z_{i}^{ \pm}$to $\left(w_{i}^{ \pm}, \gamma_{i}^{ \pm}\right) \in \mathcal{P}\left(H, z_{i}^{ \pm}\right)$if

$$
\begin{aligned}
\lim _{s \rightarrow \pm \infty} w(s) & =w_{i}^{ \pm} \\
\lim _{s \rightarrow \pm \infty} u(s, t) & =\gamma_{i}^{ \pm}
\end{aligned}
$$

where $(s, t)$ are the cylindrical coordinates near $z_{i}^{ \pm}$.
Definition 4.36. The energy of $(w, u)$ is

$$
E(u):=\frac{1}{2} \int_{\dot{\Sigma}}\left\|\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right\|_{J(\mathbf{u}), \hat{\omega}}^{2} \omega_{\Sigma} .
$$

We will now state the analytical results about solutions of the parametrized Floer equation. Some results we will state are analogous to previous results about solutions of a pseudoholomorphic curve equation. Namely, in Lemma 4.37 we compare the energy of a solution with the action at the asymptotes, and in Lemma 4.39 we show that solutions satisfy a maximum principle.

Lemma 4.37. If $(w, u)$ is a solution of the parametrized Floer equation which is asymptotic at $z_{i}^{ \pm}$to $\left(w_{i}^{ \pm}, \gamma_{i}^{ \pm}\right) \in \mathcal{P}\left(H, z_{i}^{ \pm}\right)$, then

$$
0 \leq E(u) \leq \sum_{i=1}^{p^{+}} \mathcal{A}_{H}\left(w_{i}^{+}, \gamma_{i}^{+}\right)-\sum_{i=1}^{p^{-}} \mathcal{A}_{H}\left(w_{i}^{-}, \gamma_{i}^{-}\right)
$$

Proof. We show that $1 / 2\left\|\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right\|_{J(\mathbf{u}), j}^{2} \omega_{\dot{\Sigma}}=u^{*} \hat{\omega}-u^{*} \mathrm{~d}_{\hat{X}} H(\mathbf{u}) \wedge \tau$.

$$
\begin{aligned}
& \frac{1}{2}\left\|\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right\|_{J(\mathbf{u}), \hat{\omega}}^{2} \omega_{\dot{\Sigma}}(S, T) \\
& \quad=\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right)^{*} \hat{\omega}(S, T) \\
& \quad=\hat{\omega}\left(\mathrm{D} u(S)-X_{H}(\mathbf{u}) \tau(S), \mathrm{D} u(T)-X_{H}(\mathbf{u}) \tau(T)\right) \\
& \quad=\hat{\omega}(\mathrm{D} u(S), \mathrm{D} u(T))-\hat{\omega}\left(\mathrm{D} u(S), X_{H}(\mathbf{u})\right) \tau(T)-\hat{\omega}\left(X_{H}(\mathbf{u}), \mathrm{D} u(T)\right) \tau(S) \\
& \quad=u^{*} \hat{\omega}(S, T)+u^{*} \iota_{X_{H}(\mathbf{u})} \hat{\omega} \wedge \tau(S, T) \\
& \quad=u^{*} \hat{\omega}(S, T)-u^{*} \mathrm{~d}_{\hat{X}} H(\mathbf{u}) \wedge \tau(S, T),
\end{aligned}
$$

Where in the first equality we used Lemma 4.11 and the fact that $\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau$ is holomorphic, and in the last equality we used the definition of Hamiltonian vector field. We show that $u^{*} \hat{\omega}-u^{*} \mathrm{~d}_{\hat{X}} H(\mathbf{u}) \wedge \tau \leq u^{*} \hat{\omega}-\mathrm{d}\left(\mathbf{u}^{*} H \wedge \tau\right)$.

$$
\begin{aligned}
\mathrm{d}\left(\mathbf{u}^{*} H \wedge \tau\right) & =\mathbf{u}^{*} H \wedge \mathrm{~d} \tau+\mathbf{u}^{*} \mathrm{~d} H \wedge \tau \\
& =\mathbf{u}^{*} H \wedge \mathrm{~d} \tau+\mathrm{d}_{\dot{\Sigma}} H(\mathbf{u}) \wedge \tau+w^{*} \mathrm{~d}_{S} H(\mathbf{u}) \wedge \tau+u^{*} \mathrm{~d}_{\hat{X}} H(\mathbf{u}) \wedge \tau \\
& =\mathbf{u}^{*} H \wedge \mathrm{~d} \tau+\mathrm{d}_{\dot{\Sigma}} H(\mathbf{u}) \wedge \tau+\left\langle\nabla_{S} H(\mathbf{u}), \nabla \tilde{f}(w)\right\rangle \sigma \wedge \tau+u^{*} \mathrm{~d}_{\hat{X}} H(\mathbf{u}) \wedge \tau \\
& \leq u^{*} \mathrm{~d}_{\hat{X}} H(\mathbf{u}) \wedge \tau
\end{aligned}
$$

Here, in the third equality we used Equation (4.8) and in the last line of the computation we used the fact that $H$ is admissible. Combining these results,

$$
\begin{aligned}
0 & \leq E(u) \\
& \leq \int_{\dot{\Sigma}} u^{*} \mathrm{~d} \hat{\lambda}-\int_{\dot{\Sigma}} \mathrm{d}\left(\mathbf{u}^{*} H \wedge \tau\right) \\
& =\sum_{i=1}^{p^{+}} \mathcal{A}_{H}\left(w_{i}^{+}, \gamma_{i}^{+}\right)-\sum_{i=1}^{p^{-}} \mathcal{A}_{H}\left(w_{i}^{-}, \gamma_{i}^{-}\right),
\end{aligned}
$$

where in the last line we used Stokes' theorem.
Lemma 4.38. Suppose that $(M, \alpha)$ is a contact manifold, $H: \dot{\Sigma} \times S \times \mathbb{R} \times M \longrightarrow \mathbb{R}$ is a Hamiltonian which is independent of $M$ and $J: \dot{\Sigma} \times S \times \mathbb{R} \times M \longrightarrow \operatorname{End}(T(\mathbb{R} \times M))$ is a cylindrical almost complex structure. If

$$
\mathbf{u}=\left(\mathrm{id}_{\dot{\Sigma}}, w, u\right)=\left(\mathrm{id}_{\dot{\Sigma}}, w,(a, f)\right): \dot{\Sigma} \longrightarrow \dot{\Sigma} \times S \times \mathbb{R} \times M
$$

is a solution of the parametrized Floer equation, then $f^{*} \mathrm{~d} \alpha \geq 0$ and

$$
\begin{align*}
-\mathrm{d} a \circ j & =f^{*} \alpha-\alpha\left(X_{H}(\mathbf{u})\right) \tau  \tag{4.10}\\
\pi_{\xi} \circ \mathrm{D} f \circ j & =J_{\xi}(\mathbf{u}) \circ \pi_{\xi} \circ \mathrm{D} f . \tag{4.11}
\end{align*}
$$

Proof. We prove equation (4.10):

$$
\begin{aligned}
-\mathrm{d} a \circ j & =-\mathrm{d} r \circ \mathrm{D} u \circ j & & \text { [by definition of } a] \\
& =-\mathrm{d} r \circ\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right) \circ j & & {[H \text { is independent of } M] } \\
& =-\mathrm{d} r \circ J(\mathbf{u}) \circ\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right) & & {\left[\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right. \text { is holomorphic] }} \\
& =\alpha \circ\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right) & & {[\text { by Lemma 2.45] }} \\
& =f^{*} \alpha-\alpha\left(X_{H}(\mathbf{u})\right) \tau & & \text { [by definition of pullback]. }
\end{aligned}
$$

Equation (4.11) follows by applying $\pi_{\xi}: T(\mathbb{R} \times M) \longrightarrow \xi$ to $\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right)_{J(\mathbf{u}), j}^{0,1}=0$. The proof of $f^{*} \mathrm{~d} \alpha \geq 0$ is equal to the one presented in Lemma 4.8.

The following is an adaptation to solutions of the parametrized Floer equation of the maximum principle from Lemma 4.10. Other authors have proven similar results about solutions of a Floer equation satisfying a maximum principle, namely Viterbo [Vit99, Lemma 1.8], Oancea [Oan04, Lemma 1.5], Seidel [Sei08, Section 3] and Ritter [Rit13, Lemma D.1].

Lemma 4.39 (maximum principle). Under the assumptions of Lemma 4.38, define

$$
\begin{array}{rlrl}
h: \dot{\Sigma} \times S \times \mathbb{R} & \longrightarrow \mathbb{R}, & h(z, w, \rho) & =H(z, w, \ln (\rho)), \\
\rho: \dot{\Sigma} \longrightarrow \mathbb{R}, & \rho & =\exp \circ a .
\end{array}
$$

If

$$
\begin{array}{r}
\partial_{\rho} h(z, w, \rho) \mathrm{d} \tau \leq 0, \\
\mathrm{~d}_{\Sigma}\left(\partial_{\rho} h(z, w, \rho)\right) \wedge \tau \leq 0 \\
\left\langle\nabla_{S} \partial_{\rho} h(z, w, \rho), \nabla \tilde{f}(w)\right\rangle \sigma \wedge \tau \leq 0 \tag{4.14}
\end{array}
$$

and $a: \dot{\Sigma} \longrightarrow \mathbb{R}$ has a local maximum then $a$ is constant.
Proof. Choose a symplectic structure $\omega_{\dot{\Sigma}}$ on $\dot{\Sigma}$ such that $g_{\dot{\Sigma}}:=\omega_{\dot{\Sigma}}(\cdot, j \cdot)$ is a Riemannian metric. Define $L: C^{\infty}(\dot{\Sigma}, \mathbb{R}) \longrightarrow C^{\infty}(\dot{\Sigma}, \mathbb{R})$ by

$$
L \nu=-\Delta \nu-\rho \partial_{\rho}^{2} h(z, w, \rho) \frac{\mathrm{d} \nu \wedge \tau}{\omega_{\dot{\Sigma}}}
$$

for every $\nu \in C^{\infty}(\dot{\Sigma}, \mathbb{R})$. The map $L$ is a linear elliptic partial differential operator (as in [Eva10, p. 312]). We wish to show that $L \rho \leq 0$. For this, we start by computing $\Delta \rho \omega_{\dot{\Sigma}}$.

\[

\]

By Equation (4.12), the last term on the right is nonnegative. We show that the sum of the first two terms on the right is nonnegative.

$$
\begin{array}{rlrl}
- & u^{*} \mathrm{~d}\left(e^{r} \alpha\right)+\partial_{\rho} h(z, w, \rho) \mathrm{d} \rho \wedge \tau & \\
& =-u^{*} \mathrm{~d}\left(e^{r} \alpha\right)+u^{*} \mathrm{~d}_{\mathbb{R} \times M} H(\mathbf{u}) \wedge \tau & & \text { [by definition of } h] \\
& =-\frac{1}{2}\left\|\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right\|_{J(\mathbf{u}), \mathrm{d}\left(e^{r} \alpha\right)}^{2} \omega_{\dot{\Sigma}} & & \text { [by the computation in Lemma 4.37] } \\
& \leq 0
\end{array}
$$

Finally, we show that $\rho \mathrm{d}\left(\partial_{\rho} h(z, w, \rho)\right) \wedge \tau \leq \rho \partial_{\rho}^{2} h(z, w, \rho) \mathrm{d} \rho \wedge \tau$ :

$$
\begin{aligned}
& \rho \mathrm{d}\left(\partial_{\rho} h(z, w, \rho)\right) \wedge \tau \\
& \quad=\rho \mathrm{d}_{\dot{\Sigma}} \partial_{\rho} h(z, w, \rho) \wedge \tau+\rho\left\langle\nabla_{S} \partial_{\rho} h(z, w, \rho), \nabla \tilde{f}(w)\right\rangle \sigma \wedge \tau+\rho \partial_{\rho}^{2} h(z, w, \rho) \mathrm{d} \rho \wedge \tau \\
& \quad \leq \rho \partial_{\rho}^{2} h(z, w, \rho) \mathrm{d} \rho \wedge \tau
\end{aligned}
$$

where in the last line we used Equations (4.13) and (4.14). This shows that $L \rho \leq 0$. By the strong maximum principle in [Eva10, p. 349-350], if $\rho$ has a local maximum then $\rho$ is constant. Since $\rho=\exp \circ a$, the same is true for $a$.

The next lemma is an adaptation to our setup of an argument by Bourgeois-Oancea which first appeared in [BO09, p. 654-655]. The same argument was also used by Cieliebak-Oancea [CO18, Lemma 2.3] in a different setup.
Lemma 4.40 (asymptotic behaviour). Consider the half-cylinder $Z^{ \pm}$of Definition 4.1, with 1 -forms $\sigma:=\mathrm{d} s$ and $\tau:=\mathrm{d}$. Assume the same conditions as in Lemma 4.38, but with $\dot{\Sigma}$ replaced by $Z^{ \pm}$. Suppose that $\mathbf{u}$ is asymptotic at $\pm \infty$ to a 1-periodic orbit $\left(z_{ \pm}, \gamma_{ \pm}\right)$of $H_{ \pm \infty}$ of the form $\gamma_{ \pm}(t)=\left(r_{ \pm}, \rho_{ \pm}(t)\right)$, where $z_{ \pm}$is a critical point of $\tilde{f}$, $r_{ \pm} \in \mathbb{R}$ and $\rho_{ \pm}: S^{1} \longrightarrow M$ is a periodic Reeb orbit in $M$. Define $h: Z^{ \pm} \times S \times \mathbb{R} \longrightarrow \mathbb{R}$ by $h(s, t, z, r)=H(s, t, z, \ln (r))$ (recall that $H$ is independent of $M$ ). If

$$
\begin{align*}
\pm \partial_{r}^{2} h\left(s, t, z_{ \pm}, e^{r_{ \pm}}\right) & <0  \tag{4.15}\\
\left\langle\nabla_{S} \partial_{r} h\left(s, t, z_{ \pm}, e^{r_{ \pm}}\right), \nabla \tilde{f}\left(z_{ \pm}\right)\right\rangle & <0  \tag{4.16}\\
\partial_{s} \partial_{r} h\left(s, t, z_{ \pm}, e^{r_{ \pm}}\right) & \leq 0, \tag{4.17}
\end{align*}
$$

then either there exists $\left(s_{0}, t_{0}\right) \in Z^{ \pm}$such that $a\left(s_{0}, t_{0}\right)>r_{ \pm}$or $\mathbf{u}$ is of the form $\mathbf{u}(s, t)=$ $\left(s, t, w(s), r_{ \pm}, \rho_{ \pm}(t)\right)$.

Proof. It suffices to assume that $a(s, t) \leq r_{ \pm}$for all $(s, t) \in Z^{ \pm}$and to prove that $a(s, t)=r_{ \pm}$and $f(s, t)=\rho_{ \pm}(t)$ for all $(s, t) \in Z^{ \pm}$. After replacing $Z^{ \pm}$by a smaller half-cylinder we may assume the following analogues of (4.15) and (4.16):

$$
\begin{align*}
\pm \partial_{r}^{2} h\left(s, t, w(s), e^{a(s, t)}\right) & \leq 0,  \tag{4.18}\\
\left\langle\nabla_{S} \partial_{r} h\left(s, t, w(s), e^{r_{ \pm}}\right), \nabla \tilde{f}(w(s))\right\rangle & \leq 0 . \tag{4.19}
\end{align*}
$$

Define the average of $a$, which we denote by $\bar{a}: \mathbb{R}_{0}^{ \pm} \longrightarrow \mathbb{R}$, by

$$
\bar{a}(s):=\int_{0}^{1} a(s, t) \mathrm{d} t .
$$

Then,

$$
\begin{array}{rlrl} 
\pm \partial_{s} \bar{a}(s) & & \\
& = \pm \int_{0}^{1} \partial_{s} a(s, t) \mathrm{d} t & & {[\text { by definition of } \bar{a}]} \\
& = \pm \int_{0}^{1} f_{s}^{*} \alpha \mp \int_{0}^{1} \alpha\left(X_{H}(\mathbf{u}(s, t))\right) \mathrm{d} t & & {[\text { by Lemma } 4.38]} \\
& = \pm \int_{0}^{1} \rho_{ \pm}^{*} \alpha \mp \int_{s}^{ \pm \infty} \int_{0}^{1} f^{*} \mathrm{~d} \alpha \mp \int_{0}^{1} \alpha\left(X_{H}(\mathbf{u}(s, t))\right) \mathrm{d} t & & {[\text { by Stokes' theorem] }} \\
& \leq \pm \int_{0}^{1} \rho_{ \pm}^{*} \alpha \mp \int_{0}^{1} \alpha\left(X_{H}(\mathbf{u}(s, t))\right) \mathrm{d} t & & {\left[\text { since } f^{*} \mathrm{~d} \alpha \geq 0\right]} \\
& = \pm \int_{0}^{1} \partial_{r} h\left( \pm \infty, t, z_{ \pm}, e^{r_{ \pm}}\right) \mathrm{d} t \mp \int_{0}^{1} \partial_{r} h\left(s, t, w(s), e^{a(s, t)}\right) \mathrm{d} t & & {[\text { by Lemma 2.41] }} \\
& \leq \pm \int_{0}^{1} \partial_{r} h\left( \pm \infty, t, z_{ \pm}, e^{r_{ \pm}}\right) \mathrm{d} t \mp \int_{0}^{1} \partial_{r} h\left(s, t, w(s), e^{r_{ \pm}}\right) \mathrm{d} t & & {[\text { by Equation }(4.18)]} \\
& \leq \pm \int_{0}^{1} \partial_{r} h\left( \pm \infty, t, z_{ \pm}, e^{r_{ \pm}}\right) \mathrm{d} t \mp \int_{0}^{1} \partial_{r} h\left(s, t, z_{ \pm}, e^{r_{ \pm}}\right) \mathrm{d} t & & \text { [by Equation }(4.19)] \\
& \leq 0 & & {[\text { by Equation }(4.17)] .}
\end{array}
$$

Since $\pm \partial_{s} \bar{a}(s) \leq 0$ and $\bar{a}( \pm \infty)=r_{ \pm}$, we have that $\bar{a}(s) \geq r_{ \pm}$for all $s$. By assumption, $a(s, t) \leq r_{ \pm}$, and therefore $a(s, t)=r_{ \pm}$for all $(s, t) \in Z^{ \pm}$. This implies that every inequality in the previous computation is an equality, and in particular $f^{*} \mathrm{~d} \alpha=0$. Therefore, $f$ is independent of $s$ and $f(s, t)=\rho_{ \pm}(t)$ for all $(s, t) \in Z^{ \pm}$.

The following lemma is an adaptation of a result originally proven by Abouzaid-Seidel [AS10, Lemma 7.2]. Other authors have proven variations of this result, namely Ritter [Rit13, Lemma D.3], Gutt [Gut14, Theorem 3.1.6] and Cieliebak-Oancea [CO18, Lemma 2.2].

Lemma 4.41 (no escape). Let $V \subset(X, \lambda)$ be a Liouville domain such that $\iota: V \longrightarrow$ $(X, \lambda)$ is a strict Liouville embedding, $H: \dot{\Sigma} \times S \times \hat{X} \longrightarrow \mathbb{R}$ be an admissible Hamiltonian, $J: \dot{\Sigma} \times S \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ be a compatible almost complex structure and $\mathbf{u}=\left(\operatorname{id}_{\dot{\Sigma}}, w, u\right): \dot{\Sigma} \longrightarrow \dot{\Sigma} \times S \times \hat{X}$ be a solution of the parametrized Floer equation such that all the asymptotic 1-periodic orbits of $\mathbf{u}$ are inside $V$. Assume that there exists $\varepsilon>0$ such that:
(1) The restriction of $H$ to $\dot{\Sigma} \times S \times(-\varepsilon, \varepsilon) \times \partial V$ is independent of $\partial V$.
(2) The restriction of $J$ to $\dot{\Sigma} \times S \times(-\varepsilon, \varepsilon) \times \partial V$ is cylindrical.
(3) If $\mathcal{A}_{H}: \dot{\Sigma} \times S \times(-\varepsilon, \varepsilon) \longrightarrow \mathbb{R}$ is given by $\mathcal{A}_{H}(z, w, r):=\lambda\left(X_{H}\right)(z, w, r)-H(z, w, r)$, then for every $(z, w, r) \in \dot{\Sigma} \times S \times(-\varepsilon, \varepsilon)$,

$$
\begin{array}{r}
\mathcal{A}_{H}(z, w, r) \mathrm{d} \tau \leq 0, \\
\mathrm{~d}_{\Sigma} \mathcal{A}_{H}(z, w, r) \wedge \tau \leq 0, \\
\left\langle\nabla_{S} \mathcal{A}_{H}(z, w, r), \nabla \tilde{f}(w)\right\rangle \sigma \wedge \tau \leq 0 .
\end{array}
$$

Then, $\operatorname{im} u \subset V$.

Proof. Assume by contradiction that $\operatorname{im} u$ is not contained in $V$. After changing $V$ to $\hat{V} \backslash\left\{(r, x) \in \mathbb{R} \times \partial V \mid r>r_{0}\right\}$, for some $r_{0} \in(-\varepsilon, \varepsilon)$, we may assume without loss of generality that im $u$ is not contained in $V$ and that $u$ is transverse to $\partial V$. Then, $\Sigma_{V}:=u^{-1}(\hat{X} \backslash \operatorname{int} V)$ is a compact surface with boundary. We show that $E\left(\left.u\right|_{\Sigma_{V}}\right)=0$.

$$
\begin{array}{rlrl}
0 & \leq \frac{1}{2} \int_{\Sigma_{V}}\left\|\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right\|_{J(\mathbf{u}), \mathrm{d} \lambda}^{2} \omega_{\Sigma_{V}} & & \text { [by positivity of norms] } \\
& \leq \int_{\Sigma_{V}} \mathrm{~d}\left(u^{*} \lambda-H(\mathbf{u}) \tau\right) & & {[\text { by the computation in Lemma 4.37] }} \\
& =\int_{\partial \Sigma_{V}} u^{*} \lambda-H(\mathbf{u}) \tau & & {[\text { by Stokes' theorem] }} \\
& \leq \int_{\partial \Sigma_{V}} u^{*} \lambda-\lambda\left(X_{H}(\mathbf{u})\right) \tau & & {[(\mathrm{a}), \text { proven below] }} \\
& =\int_{\partial \Sigma_{V}} \lambda \circ\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right) & & {[\text { by definition of pullback] }} \\
& =-\int_{\partial \Sigma_{V}} \lambda \circ J(\mathbf{u}) \circ\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right) \circ j & {\left[\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau \text { is holomorphic }\right]} \\
& =-\int_{\partial \Sigma_{V}} \mathrm{~d} \exp \circ\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right) \circ j & & {\left[J \text { is cylindrical near } u\left(\partial \Sigma_{V}\right) \subset \partial V\right]} \\
& =-\int_{\partial \Sigma_{V}} \mathrm{~d} \exp \circ \mathrm{D} u \circ j & & {[H \text { is independent of } \partial V]} \\
& \leq 0 & & {[(\mathrm{~b}), \text { proven below]. }}
\end{array}
$$

The proof of (a) is the computation

$$
\begin{array}{rll}
\int_{\partial \Sigma_{V}}\left(\lambda\left(X_{H}(\mathbf{u})\right)-H(\mathbf{u})\right) \tau & \\
\quad=\int_{\partial \Sigma_{V}} \mathcal{A}_{H}\left(z, w, r_{0}\right) \tau & {\left[\text { by definition of } \mathcal{A}_{H} \text { and } u\left(\partial \Sigma_{V}\right) \subset \partial V\right]} \\
=\int_{\Sigma_{V}} \mathrm{~d}_{\Sigma_{V}}\left(\mathcal{A}_{H}\left(z, w, r_{0}\right) \tau\right) & {[\text { by Stokes' theorem }]} \\
\leq 0 & & {\left[\text { by the assumptions on } \mathcal{A}_{H}\right] .}
\end{array}
$$

Statement (b) is true because if $\xi$ is a vector tangent to $\partial \Sigma_{V}$ giving the boundary orientation, then $j(\xi)$ points into $\Sigma_{V}$, therefore $\mathrm{D} u \circ j(\xi)$ points out of $V$. Then, we conclude that $E\left(\left.u\right|_{\Sigma_{V}}\right)=0$ and that $\mathrm{D} u=X_{H}(\mathbf{u}) \otimes \tau$, and since $X_{H}(\mathbf{u})$ is tangent to $\partial V$ it follows that im $u \subset \partial V$. This contradicts the fact that $u$ is not contained in $V$.

### 4.5 Compactness for solutions of the parametrized Floer equation

In this section, we assume that $(\dot{\Sigma}, j, \sigma, \tau)=\left(\mathbb{R} \times S^{1}, j, \mathrm{~d} s, \mathrm{~d} t\right)$ is the cylinder from Example 4.28. Suppose that $H: \dot{\Sigma} \times S \times \hat{X} \longrightarrow \mathbb{R}$ is an admissible Hamiltonian as in Definition 4.30. In this case, there exist Hamiltonians $H^{ \pm}: S^{1} \times S \times \hat{X} \longrightarrow \mathbb{R}$ such that $H(s, t, w, x)=H^{ \pm}(t, w, x)$ for $\pm s \geq s_{0}$. Assume also that $J: \dot{\Sigma} \times S \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ is an admissible almost complex structure as in Definition 4.31, which has associated limit almost complex structures $J^{ \pm}: S^{1} \times S \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$. Note that since $\dot{\Sigma}=\mathbb{R} \times S^{1}$, we
can also view $H^{ \pm}$and $J^{ \pm}$as maps whose domain is $\dot{\Sigma}$. For $N \in \mathbb{Z}_{\geq 1}$ and $L, \nu=1, \ldots, N$, define

$$
H^{L, \nu}:=\left\{\begin{array}{ll}
H^{+} & \text {if } \nu>L, \\
H & \text { if } \nu=L, \\
H^{-} & \text {if } \nu<L,
\end{array} \quad J^{L, \nu}:= \begin{cases}J^{+} & \text {if } \nu>L \\
J & \text { if } \nu=L, \\
J^{-} & \text {if } \nu<L\end{cases}\right.
$$

Finally, let $\left(H_{m}\right)_{m}$ be a sequence of admissible Hamiltonians converging to $H$, $\left(J_{m}\right)_{m}$ be a sequence of admissible almost complex structures converging to $J$, and for every $m \in \mathbb{Z}_{\geq 1}$ let $\left(w_{m}, u_{m}\right)$ be a solution of the parametrized Floer equation with respect to $H_{m}, J_{m}$ with asymptotes $\left(z_{m}^{ \pm}, \gamma_{m}^{ \pm}\right)$.
Definition 4.42. Let $\left(z^{ \pm}, \gamma^{ \pm}\right)$be Hamiltonian 1-periodic orbits of $H^{ \pm}$. A broken Floer trajectory from $\left(z^{-}, \gamma^{-}\right)$to $\left(z^{+}, \gamma^{+}\right)$is given by:
(1) Numbers $N \in \mathbb{Z}_{\geq 1}$ and $L=1, \ldots, N$;
(2) Hamiltonian 1-periodic orbits $\left(z^{-}, \gamma^{-}\right)=\left(z^{1}, \gamma^{1}\right), \ldots,\left(z^{L}, \gamma^{L}\right)$ of $H^{-}$and Hamiltonian 1-periodic orbits $\left(z^{L+1}, \gamma^{L+1}\right), \ldots,\left(z^{N+1}, \gamma^{N+1}\right)=\left(z^{+}, \gamma^{+}\right)$of $H^{+}$;
(3) For every $\nu=1, \ldots, N$, a Floer trajectory ( $w^{\nu}, u^{\nu}$ ) with respect to $H^{L, \nu}, J^{L, \nu}$ with negative asymptote $\left(z^{\nu}, \gamma^{\nu}\right)$ and positive asymptote $\left(z^{\nu+1}, \gamma^{\nu+1}\right)$.

Definition 4.43. We say that $\left(w_{m}, u_{m}\right)_{m}$ converges to $\left(w^{\nu}, u^{\nu}\right)_{\nu}$ if there exist numbers $s_{m}^{1} \leq \cdots \leq s_{m}^{N}$ such that

$$
\begin{aligned}
\lim _{m \rightarrow+\infty} s_{m}^{L} & \in \mathbb{R} \\
\lim _{m \rightarrow+\infty}\left(s_{m}^{\nu+1}-s_{m}^{\nu}\right) & =+\infty \\
\lim _{m \rightarrow+\infty} w_{m}\left(\cdot+s_{m}^{\nu}\right) & =w_{m}^{\nu} \\
\lim _{m \rightarrow+\infty} u_{m}\left(\cdot+s_{m}^{\nu}, \cdot\right) & =u_{m}^{\nu}
\end{aligned}
$$

Theorem 4.44. There exists a subsequence (whose index we still denote by m) and a broken Floer trajectory $\left(w^{\nu}, u^{\nu}\right)_{\nu}$ such that $\left(w_{m}, u_{m}\right)_{m}$ converges to $\left(w^{\nu}, u^{\nu}\right)_{\nu}$.

Proof. Since $f: C \longrightarrow \mathbb{R}$ is Morse and $H_{z, w}: S^{1} \times \hat{X} \longrightarrow \mathbb{R}$ is nondegenerate for every puncture $z$ and critical point $w$ of $\tilde{f}$, we conclude that we can pass to a subsequence such that $\left(z_{m}^{ \pm}, \gamma_{m}^{ \pm}\right)$converges to $\left(z^{ \pm}, \gamma^{ \pm}\right)$. By compactness in Morse theory, there exists a further subsequence and a broken Morse trajectory $\left(w^{\nu}\right)_{\nu=1, \ldots, N}$, where $w^{\nu}: \mathbb{R} \longrightarrow S$ is a Morse trajectory from $z^{\nu}$ to $z^{\nu+1}, z^{1}=z^{-}$and $z^{N+1}=z^{+}$, such that $\left(w_{m}\right)_{m}$ converges in the sense of Morse theory to $\left(w^{\nu}\right)_{\nu}$. More precisely, this means that there exist numbers $s_{m}^{1} \leq \cdots \leq s_{m}^{N}$ and $L \leq N$ such that

$$
\begin{aligned}
\lim _{m \rightarrow+\infty} s_{m}^{L} & \in \mathbb{R} \\
\lim _{m \rightarrow+\infty}\left(s_{m}^{\nu+1}-s_{m}^{\nu}\right) & =+\infty \\
\lim _{m \rightarrow+\infty} w_{m}\left(\cdot+s_{m}^{\nu}\right) & =w^{\nu}
\end{aligned}
$$

Possibly after reparametrizing the $w^{\nu}$, we may assume that $s_{m}^{L}=0$ for every $m$. Now, for $\nu=1, \ldots, N$, define

$$
\begin{aligned}
u_{m}^{\nu}: \mathbb{R} \times S^{1} \longrightarrow \hat{X}, & u_{m}^{\nu}(s, t) & =u_{m}\left(s+s_{m}^{\nu}, t\right), \\
H_{m}^{\nu}: \mathbb{R} \times S^{1} \times \hat{X} \longrightarrow \mathbb{R}, & H_{m}^{\nu}(s, t, x) & =H_{m}\left(s+s_{m}^{\nu}, t, w_{m}\left(s+s_{m}^{\nu}\right), x\right), \\
H^{\nu}: \mathbb{R} \times S^{1} \times \hat{X} \longrightarrow \mathbb{R}, & H^{\nu}(s, t, x) & =H^{L, \nu}\left(s, t, w^{\nu}(s), x\right), \\
J_{m}^{\nu}: \mathbb{R} \times S^{1} \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X}), & J_{m}^{\nu}(s, t, x) & =J_{m}\left(s+s_{m}^{\nu}, t, w_{m}\left(s+s_{m}^{\nu}\right), x\right), \\
J^{\nu}: \mathbb{R} \times S^{1} \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X}), & J^{\nu}(s, t, x) & =J^{L, \nu}\left(s, t, w^{\nu}(s), x\right) .
\end{aligned}
$$

Then, $u_{m}^{\nu}$ is a solution of the equation

$$
\frac{\partial u_{m}^{\nu}}{\partial s}=-J_{m}^{\nu}\left(s, t, u_{m}^{\nu}\right)\left(\frac{\partial u_{m}^{\nu}}{\partial t}-X_{H_{m}^{\nu}}\left(s, t, u_{m}^{\nu}\right)\right),
$$

and

$$
\begin{aligned}
\lim _{m \rightarrow+\infty} H_{m}^{\nu} & =H^{\nu}, \\
\lim _{m \rightarrow+\infty} J_{m}^{\nu} & =J^{\nu} .
\end{aligned}
$$

By compactness in Floer theory, there exists a further subsequence such that for every $\nu=1, \ldots, N$ there exists a broken Floer trajectory $\left(u^{\nu, \mu}\right)_{\mu=1, \ldots, M_{\nu}}$ from $\gamma^{\nu, \mu}$ to $\gamma^{\nu, \mu+1}$ with respect to $\left(H^{\nu}, J^{\nu}\right)$, such that

$$
\begin{aligned}
\gamma^{1,1} & =\gamma^{-}, \\
\gamma^{N, M_{N}} & =\gamma^{+},
\end{aligned}
$$

and $\left(u_{m}^{\nu}\right)_{m}$ converges to $\left(u^{\nu, \mu}\right)_{\mu}$. More precisely, this means that there exist $L_{\nu}=$ $1, \ldots, N_{\nu}$ and numbers $s_{m}^{\nu, 1} \leq \cdots \leq s_{m}^{\nu, M_{\nu}}$ such that

$$
\begin{aligned}
\lim _{m \rightarrow+\infty} s_{m}^{\nu, L_{\nu}} & \in \mathbb{R}, \\
\lim _{m \rightarrow+\infty}\left(s_{m}^{\nu, \mu+1}-s_{m}^{\nu, \mu}\right) & =+\infty, \\
\lim _{m \rightarrow+\infty} u_{m}^{\nu}\left(\cdot+s_{m}^{\nu, \mu}, \cdot\right) & =u^{\nu, \mu} .
\end{aligned}
$$

Consider the list $\left(w^{\nu}, u^{\nu, \mu}\right)_{\nu, \mu}$ ordered according to the dictionary order of the indices $\nu, \mu$. In this list, if two elements $\left(w^{\nu}, u^{\nu, \mu}\right),\left(w^{\nu^{\prime}}, u^{\nu^{\prime}, \mu^{\prime}}\right)$ are equal then they must be adjacent. The list obtained from $\left(w^{\nu}, u^{\nu, \mu}\right)_{\nu, \mu}$ by removing duplicate elements is the desired broken Floer trajectory.

### 4.6 Transversality for solutions of the parametrized Floer equation

In this section, let $(\dot{\Sigma}, j, \sigma, \tau)=\left(\mathbb{R} \times S^{1}, j, \mathrm{~d} s, \mathrm{~d} t\right)$ be the cylinder from Example 4.28 and $(X, \lambda)$ be a nondegenerate Liouville domain. Let $H: S^{1} \times S \times \hat{X} \longrightarrow \mathbb{R}$ be a function such that the pullback $H: \mathbb{R} \times S^{1} \times S \times \hat{X} \longrightarrow \mathbb{R}$ is as in Definition 4.30. Define $\mathcal{J}$ to be the set of almost complex structures $J: S^{1} \times S \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ such that the
pullback $J: \mathbb{R} \times S^{1} \times S \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ is as in Definition 4.31. The set $\mathcal{J}$ admits the structure of a smooth Fréchet manifold, and therefore the tangent space $T_{J} \mathcal{J}$ at $J$ is a Fréchet space. Let $\left(z^{ \pm}, \gamma^{ \pm}\right)$be 1-periodic orbits of $H$, i.e. $z^{ \pm} \in S$ is a critical point of $\tilde{f}$ and $\gamma^{ \pm}$is a 1-periodic orbit of $H_{z^{ \pm}}: S^{1} \times \hat{X} \longrightarrow \mathbb{R}$.
If $w: \mathbb{R} \longrightarrow S$ and $u: \mathbb{R} \times S^{1} \longrightarrow \hat{X}$ are maps, we will denote by $\mathbf{u}$ the map

$$
\mathbf{u}: \mathbb{R} \times S^{1} \longrightarrow S^{1} \times S \times \hat{X}, \quad \mathbf{u}(s, t):=(t, w(s), u(s, t))
$$

The pair $(w, u)$ is a solution of the parametrized Floer equation if

$$
\begin{aligned}
\partial_{s} w-\nabla \tilde{f}(w) & =0, \\
\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right)_{J(\mathbf{u}), j}^{0,1} & =0 .
\end{aligned}
$$

Define $\left[z^{ \pm}, \gamma^{ \pm}\right]$to be the equivalence class

$$
\begin{aligned}
{\left[z^{ \pm}, \gamma^{ \pm}\right] } & :=\left\{t \cdot\left(z^{ \pm}, \gamma^{ \pm}\right) \mid t \in S^{1}\right\} \\
& =\left\{\left(t \cdot z^{ \pm}, \gamma^{ \pm}(\cdot+t)\right) \mid t \in S^{1}\right\},
\end{aligned}
$$

and denote by $\hat{\mathcal{M}}\left(X, H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$the moduli space of solutions $(w, u) \in$ $C^{\infty}(\mathbb{R}, S) \times C^{\infty}\left(\mathbb{R} \times S^{1}, \hat{X}\right)$ of the parametrized Floer equation such that

$$
\lim _{s \rightarrow \pm \infty}(w(s), u(s, \cdot)) \in\left[z^{ \pm}, \gamma^{ \pm}\right]
$$

Denote by $\mathcal{M}$ the moduli space of gradient flow lines $w: \mathbb{R} \longrightarrow S$ of $\tilde{f}$ such that

$$
\lim _{s \rightarrow \pm \infty} w(s) \in\left[z^{ \pm}\right] .
$$

By the assumptions on $\left(S, g^{S}, \tilde{f}\right)$ explained in Section 4.4 and [AB95, Section 3.2], the space $\mathcal{M}$ is a smooth finite dimensional manifold. Moreover,

$$
\begin{equation*}
\operatorname{dim} \mathcal{M}=\mu_{\mathrm{M}}\left(z^{+}\right)+\mu_{\mathrm{M}}\left(z^{-}\right)+1 \tag{4.20}
\end{equation*}
$$

Let $\varepsilon=\left(\varepsilon_{\ell}\right)_{\ell \in \mathbb{Z}_{\geq 0}}$ be a sequence of positive numbers $\varepsilon_{\ell}$ such that $\lim _{\ell \rightarrow+\infty} \varepsilon_{\ell}=0$. Define a function

$$
\begin{aligned}
\|\cdot\|^{\varepsilon}: T_{J_{\mathrm{ref}}} \mathcal{J} & \longrightarrow[0,+\infty] \\
Y & \longmapsto \sum_{\ell=0}^{+\infty} \varepsilon_{\ell}\|Y\|_{C^{\ell}\left(S^{1} \times S \times X\right)},
\end{aligned}
$$

where $\|\cdot\|_{C^{\ell}\left(S^{1} \times S \times X\right)}$ is the $C^{\ell}$-norm which is determined by some finite covering of $T X \longrightarrow S^{1} \times S \times X$ by coordinate charts and local trivializations. Define

$$
T_{J_{\mathrm{ref}}}^{\varepsilon} \mathcal{J}:=\left\{Y \in T_{J_{\mathrm{ref}}} \mathcal{J} \mid\|Y\|^{\varepsilon}<+\infty\right\}
$$

By [Flo88, Lemma 5.1], $\left(T_{J_{\text {ref }}}^{\varepsilon} \mathcal{J},\|\cdot\|^{\varepsilon}\right)$ is a Banach space consisting of smooth sections and containing sections with support in arbitrarily small sets. For every $Y \in T_{J_{\text {ref }}}^{\varepsilon} \mathcal{J}$, define

$$
\exp _{J_{\mathrm{ref}}}(Y):=J_{Y}:=\left(1+\frac{1}{2} J_{\mathrm{ref}} Y\right) J_{\mathrm{ref}}\left(1+\frac{1}{2} J_{\mathrm{ref}} Y\right)^{-1}
$$

There exists a neighbourhood $\mathcal{O} \subset T_{J_{\text {ref }}}^{\varepsilon} \mathcal{J}$ of 0 such that $\exp _{J_{J_{\text {ref }}}}: \mathcal{O} \longrightarrow \mathcal{J}$ is injective. Define $\mathcal{J}^{\mathcal{E}}:=\exp _{J_{\text {ref }}}(\mathcal{O})$, which is automatically a Banach manifold with one global parametrization $\exp _{J_{\text {ref }}}: \mathcal{O} \longrightarrow \mathcal{J}^{\varepsilon}$. The tangent space of $\mathcal{J}^{\varepsilon}$ at $J_{\text {ref }}$ is given by

$$
T_{J_{\mathrm{ref}}} \mathcal{J}^{\varepsilon}=T_{J_{\mathrm{ref}}}^{\varepsilon} \mathcal{J}
$$

Notice that the definition of $\mathcal{J}^{\varepsilon}$ involved making several choices, namely the sequence $\varepsilon$, the choices necessary to define the $C^{\ell}$-norm, and a reference almost complex structure $J_{\text {ref }}$.
Definition 4.45. For $w \in \mathcal{M}$, let $\mathcal{F}_{w}$ be the Banach manifold of maps $u: \mathbb{R} \times S^{1} \longrightarrow \hat{X}$ of the form

$$
u(s, t)=\exp _{u_{0}(s, t)} \xi(s, t),
$$

where

$$
\begin{aligned}
u_{0} & \in C^{\infty}\left(\mathbb{R} \times S^{1}, \hat{X}\right) \text { is such that } \lim _{s \rightarrow \pm \infty}\left(w(s), u_{0}(s, \cdot)\right) \in\left[z^{ \pm}, \gamma^{ \pm}\right] \\
\xi & \in W^{1, p}\left(\mathbb{R} \times S^{1}, u_{0}^{*} T \hat{X}\right) .
\end{aligned}
$$

Definition 4.46. For $J \in \mathcal{J}^{\varepsilon}$, we define a bundle $\pi^{J}: \mathcal{E}^{J} \longrightarrow \mathcal{B}$ as follows. The base, fibre and total space are given by

$$
\begin{aligned}
\mathcal{B} & :=\left\{(w, u) \mid w \in \mathcal{M}, u \in \mathcal{F}_{w}\right\}, \\
\mathcal{E}_{(w, u)}^{J} & :=L^{p}\left(\operatorname{Hom}_{J(\mathbf{u}), j}^{0,1}\left(T \dot{\Sigma}, u^{*} T \hat{X}\right)\right), \\
\mathcal{E}^{J} & :=\left\{(w, u, \xi) \mid(w, u) \in \mathcal{B}, \xi \in \mathcal{E}_{(w, u)}^{J}\right\} .
\end{aligned}
$$

The projection is given by $\pi^{J}(w, u, \xi):=(w, u)$. The Cauchy-Riemann operator is the section $\bar{\partial}^{J}: \mathcal{B} \longrightarrow \mathcal{E}^{J}$ given by

$$
\bar{\partial}^{J}(w, u):=\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right)_{J(\mathbf{u}), j}^{0,1} \in \mathcal{E}_{(w, u)}^{J} .
$$

With this definition, $\left(\bar{\partial}^{J}\right)^{-1}(0)=\hat{\mathcal{M}}\left(X, H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$.
Definition 4.47. Define the universal bundle, $\pi: \mathcal{E} \longrightarrow \mathcal{B} \times \mathcal{J}^{\varepsilon}$, and the universal Cauchy-Riemann operator, $\bar{\partial}: \mathcal{B} \times \mathcal{J}^{\varepsilon} \longrightarrow \mathcal{E}$, by

$$
\begin{aligned}
& \mathcal{E}:=\left\{(w, u, J, \xi) \mid(w, u) \in \mathcal{B}, J \in \mathcal{J}^{\varepsilon}, \xi \in \mathcal{E}_{(w, u)}^{J}\right\}, \\
& \pi: \mathcal{E} \longrightarrow \mathcal{B} \times \mathcal{J}^{\varepsilon}, \quad \pi(w, u, J, \xi):=(w, u, J), \\
& \bar{\partial}: \mathcal{B} \times \mathcal{J}^{\varepsilon} \longrightarrow \mathcal{E}, \quad \bar{\partial}(w, u, J):=\bar{\partial}^{J}(w, u)
\end{aligned}
$$

For $(w, u, J)$ such that $\bar{\partial}(w, u, J)=0$, choose a splitting $T_{(w, u)} \mathcal{B}=T_{w} \mathcal{M} \oplus T_{u} \mathcal{F}_{w}$. The sections $\bar{\partial}^{J}$ and $\bar{\partial}$ have corresponding linearized operators, which we denote by

$$
\begin{aligned}
\mathbf{D}_{(w, u, J)} & : T_{w} \mathcal{M} \oplus T_{u} \mathcal{F}_{w} \longrightarrow \mathcal{E}_{(w, u)}^{J}, \\
\mathbf{L}_{(w, u, J)} & : T_{w} \mathcal{M} \oplus T_{u} \mathcal{F}_{w} \oplus T_{J} \mathcal{J}^{\varepsilon} \longrightarrow \mathcal{E}_{(w, u)}^{J},
\end{aligned}
$$

respectively. We can write these operators with respect to the decompositions above as block matrices

$$
\begin{align*}
\mathbf{D}_{(w, u, J)} & =\left[\begin{array}{ll}
\mathbf{D}_{(w, u, J)}^{\mathcal{M}} & \mathbf{D}_{(w, u, J)}^{\mathcal{F}}
\end{array}\right]  \tag{4.21}\\
\mathbf{L}_{(w, u, J)} & =\left[\begin{array}{lll}
\mathbf{D}_{(w, u, J)}^{\mathcal{M}} & \mathbf{D}_{(w, u, J)}^{\mathcal{F}} & \mathbf{J}_{(w, u, J)}
\end{array}\right] . \tag{4.22}
\end{align*}
$$

Let $\tau$ be a trivialization of $u^{*} T \hat{X}$ and denote also by $\tau$ the induced trivializations of $\left(\gamma^{ \pm}\right)^{*} T \hat{X}$. We can consider the Conley-Zehnder indices $\mu_{\mathrm{CZ}}^{\tau}\left(\gamma^{ \pm}\right)$of $\gamma^{ \pm}$computed with respect to $\tau$. We denote $\mu^{\tau}\left(z^{ \pm}, \gamma^{ \pm}\right):=\mu_{\mathrm{M}}\left(z^{ \pm}\right)+\mu_{\mathrm{CZ}}^{\tau}\left(\gamma^{ \pm}\right)$.
Theorem 4.48. The operators $\mathbf{D}_{(w, u, J)}^{\mathcal{F}}$ and $\mathbf{D}_{(w, u, J)}$ are Fredholm and

$$
\begin{align*}
& \operatorname{ind} \mathbf{D}_{(w, u, J)}^{\mathcal{F}}=\mu_{\mathrm{CZ}}^{\tau}\left(\gamma^{+}\right)-\mu_{\mathrm{CZ}}^{\tau}\left(\gamma^{-}\right),  \tag{4.23}\\
& \operatorname{ind} \mathbf{D}_{(w, u, J)}=\mu^{\tau}\left(z^{+}, \gamma^{+}\right)-\mu^{\tau}\left(z^{-}, \gamma^{-}\right)+1 . \tag{4.24}
\end{align*}
$$

Proof. The operator $\mathbf{D}_{(w, u, J)}^{\mathcal{F}}$ is the linearized operator in Floer theory, which is Fredholm and has index given by Equation (4.23). Therefore,

$$
0 \oplus \mathbf{D}_{(w, u, J)}^{\mathcal{F}}: T_{w} \mathcal{M} \oplus T_{u} \mathcal{F}_{w} \longrightarrow \mathcal{E}_{(w, u)}^{J}
$$

is Fredholm and

$$
\begin{equation*}
\operatorname{ind}\left(0 \oplus \mathbf{D}_{(w, u, J)}^{\mathcal{F}}\right)=\operatorname{dim} T_{w} \mathcal{M}+\operatorname{ind} \mathbf{D}_{(w, u, J)}^{\mathcal{F}} \tag{4.25}
\end{equation*}
$$

Since $\mathbf{D}_{(w, u, J)}^{\mathcal{M}} \oplus 0: T_{w} \mathcal{M} \oplus T_{w} \mathcal{F}_{w} \longrightarrow \mathcal{E}_{(w, u)}^{J}$ is compact, the operator

$$
\mathbf{D}_{(w, u, J)}=\mathbf{D}_{(w, u, J)}^{\mathcal{M}} \oplus \mathbf{D}_{(w, u, J)}^{\mathcal{F}}=\mathbf{D}_{(w, u, J)}^{\mathcal{M}} \oplus 0+0 \oplus \mathbf{D}_{(w, u, J)}^{\mathcal{F}}
$$

is Fredholm and

$$
\begin{aligned}
\operatorname{ind} \mathbf{D}_{(w, u, J)} & =\operatorname{ind}\left(\mathbf{D}_{(w, u, J)}^{\mathcal{M}} \oplus \mathbf{D}_{(w, u, J)}^{\mathcal{F}}\right) & & {[\text { by Equation }(4.21)] } \\
& =\operatorname{ind}\left(0 \oplus \mathbf{D}_{(w, u, J)}^{\mathcal{F}}\right) & & {\left[\text { since } \mathbf{D}_{(w, u, J)}^{\mathcal{M}} \text { is compact }\right] } \\
& =\operatorname{dim} T_{w} \mathcal{M}+\operatorname{ind} \mathbf{D}_{(w, u, J)}^{\mathcal{F}} & & {[\text { by Equation }(4.25)] } \\
& =\mu^{\tau}\left(z^{+}, \gamma^{+}\right)-\mu^{\tau}\left(z^{-}, \gamma^{-}\right)+1 & & {[\text { by Equations }(4.20) \text { and }(4.23)] . }
\end{aligned}
$$

Theorem 4.49. The operator $\mathbf{L}_{(w, u, J)}$ is surjective.
Proof. It suffices to prove that

$$
\mathbf{L}_{(w, u, J)}^{\mathcal{F}}:=\mathbf{D}_{(w, u, J)}^{\mathcal{F}} \oplus \mathbf{J}_{(w, u, J)}: T_{u} \mathcal{F}_{w} \oplus T_{J} \mathcal{J}^{\varepsilon} \longrightarrow \mathcal{E}_{(w, u)}^{J}
$$

is surjective. Since $\mathbf{D}_{(w, u, J)}^{\mathcal{F}}$ is Fredholm (by Theorem 4.48), its image is closed and has finite codimension. This implies that $\operatorname{im} \mathbf{L}_{(w, u, J)}^{\mathcal{F}}$ is also of finite codimension and closed. So, it suffices to show that $\operatorname{im} \mathbf{L}_{(w, u, J)}^{\mathcal{F}}$ is dense, which is equivalent to showing that the annihilator Ann $\operatorname{im} \mathbf{L}_{(w, u, J)}^{\mathcal{F}}$ is zero. Let $\eta \in \operatorname{Annim} \mathbf{L}_{(w, u, J)}^{\mathcal{F}}$, i.e.

$$
\eta \in L^{q}\left(\operatorname{Hom}_{J(\mathbf{u}), j}^{0,1}\left(T \dot{\Sigma}, u^{*} T \hat{X}\right)\right)
$$

is such that

$$
\begin{align*}
& 0=\left\langle\eta, \mathbf{D}_{(w, u, J)}^{\mathcal{F}}(\xi)\right\rangle_{L^{2}} \quad \text { for all } \quad \xi \in T_{u} \mathcal{F}_{w},  \tag{4.26}\\
& 0=\left\langle\eta, \mathbf{J}_{(w, u, J)}(Y)\right\rangle_{L^{2}} \quad \text { for all } Y \in T_{J} \mathcal{J}^{\varepsilon} . \tag{4.27}
\end{align*}
$$

By Equation (4.26), $\eta$ satisfies the Cauchy-Riemann type equation $\left(\mathbf{D}_{(w, u, J)}^{\mathcal{F}}\right)^{*} \eta=0$, and therefore $\eta$ is smooth (by elliptic regularity) and satisfies unique continuation.

We prove that $\eta=0$ in the case where $w$ is constant. In this case, $w(s)=: w_{0}$ for every $s$, we can view $\gamma^{ \pm}$as 1-periodic orbits of $H_{w_{0}}$ (after a reparametrization) and $u$ is a solution of the Floer equation:

$$
\frac{\partial u}{\partial s}(s, t)+J_{w_{0}}(t, u(s, t))\left(\frac{\partial u}{\partial t}(s, t)-X_{H_{w_{0}}}(t, u(s, t))\right)=0 .
$$

Let $R(u)$ be the set of regular points of $u$, i.e. points $z=(s, t)$ such that

$$
\begin{equation*}
\frac{\partial u}{\partial s}(s, t) \neq 0, \quad u(s, t) \neq \gamma^{ \pm}(t), \quad u(s, t) \notin u(\mathbb{R}-\{s\}, t) \tag{4.28}
\end{equation*}
$$

By [FHS95, Theorem 4.3], $R(u)$ is open. By unique continuation, it is enough to show that $\eta$ vanishes in $R(u)$. Let $z_{0}=\left(s_{0}, t_{0}\right) \in R(u)$ and assume by contradiction that $\eta\left(z_{0}\right) \neq 0$. By [MS12, Lemma 3.2.2], there exists $Y \in T_{J} \mathcal{J}$ such that

$$
\begin{equation*}
\left\langle\eta\left(z_{0}\right), Y\left(\mathbf{u}\left(z_{0}\right)\right) \circ\left(\mathrm{D} u\left(z_{0}\right)-X_{H}\left(\mathbf{u}\left(z_{0}\right)\right) \otimes \tau_{z_{0}}\right) \circ j_{z_{0}}\right\rangle>0 . \tag{4.29}
\end{equation*}
$$

Choose a neighbourhood $V=V_{\mathbb{R}} \times V_{S^{1}}$ of $z_{0}=\left(s_{0}, t_{0}\right)$ in $\dot{\Sigma}=\mathbb{R} \times S^{1}$ such that

$$
\begin{equation*}
\left.\left\langle\eta, Y(\mathbf{u}) \circ\left(\mathrm{D} u-X_{H}(\mathbf{u}) \otimes \tau\right) \circ j\right\rangle\right|_{V}>0 . \tag{4.30}
\end{equation*}
$$

Since $z_{0}$ is as in (4.28), there exists a neighbourhood $U_{\hat{X}}$ of $u\left(z_{0}\right)$ in $\hat{X}$ such that

$$
u(s, t) \in U_{\hat{X}} \Longrightarrow s \in V_{\mathbb{R}}
$$

Choose a slice $A \subset S^{1} \times S$ which contains $\left(t_{0}, w_{0}\right)$ and which is transverse to the action of $S^{1}$ on $S^{1} \times S$. Define $U_{S^{1} \times S}=S^{1} \cdot A$. For $A$ chosen small enough,

$$
\left(t, w_{0}\right) \in U_{S^{1} \times S} \Longrightarrow t \in V_{S^{1}} .
$$

Then, defining $U:=U_{S^{1} \times S} \times U_{\hat{X}}$ we have that $\mathbf{u}^{-1}(U) \subset V$. Choose an $S^{1}$-invariant function $\beta: S^{1} \times S \times \hat{X} \longrightarrow[0,1]$ such that

$$
\begin{equation*}
\operatorname{supp} \beta \subset U, \quad \beta\left(\mathbf{u}\left(z_{0}\right)\right)=1, \quad \beta Y \in T_{J} \mathcal{J}^{\varepsilon} . \tag{4.31}
\end{equation*}
$$

Here, we can achieve that $\beta Y$ is of class $C^{\varepsilon}$ by [Wen16, Theorem B.6]. Since $\mathbf{u}^{-1}(U) \subset V$ and $\operatorname{supp} \beta \subset U$, we have that $\operatorname{supp}(\beta \circ \mathbf{u}) \subset V$. Then,

$$
\begin{aligned}
0 & =\left\langle\eta, \mathbf{J}_{(w, u, J)}(\beta Y)\right\rangle_{L^{2}} & & {[\text { by Equation }(4.27)] } \\
& =\left\langle\eta, \beta(\mathbf{u}) \mathbf{J}_{(w, u, J)}(Y)\right\rangle_{L^{2}} & & {\left[\text { since } \mathbf{J}_{(w, u, J)} \text { is } C^{\infty} \text {-linear }\right] } \\
& =\left\langle\eta, \beta(\mathbf{u}) \mathbf{J}_{(w, u, J)}(Y)\right\rangle_{L^{2}(V)} & & {[\text { since } \operatorname{supp}(\beta \circ \mathbf{u}) \subset V] } \\
& >0 & & {[\text { by Equation }(4.30)], }
\end{aligned}
$$

which is the desired contradiction.
We prove that $\eta=0$ in the case where $w$ is not constant. Let $z_{0}=\left(t_{0}, s_{0}\right) \in \mathbb{R} \times S^{1}$ and assume by contradiction that $\eta\left(z_{0}\right) \neq 0$. Choose $Y$ as in (4.29) and $V$ as in (4.30). Choose a slice $A \subset S^{1} \times S$ which contains $\left(t_{0}, w(0)\right)$ and which is transverse to the action of $S^{1}$ on $S^{1} \times S$. Define $U_{S^{1} \times S}=S^{1} \cdot A$. Since $w$ is orthogonal to the infinitesimal action on $S$, for $A$ chosen small enough we have

$$
(t, w(s)) \in U_{S^{1} \times S} \Longrightarrow(s, t) \in V
$$

Defining $U=U_{S^{1} \times S} \times \hat{X}$, we have that $\mathbf{u}^{-1}(U) \subset V$. Choosing $\beta$ as in (4.31), we obtain a contradiction in the same way as in the previous case.

Remark 4.50. We recall some terminology related to the Baire category theorem (we use the terminology from [RF10, Section 10.2]). Let $X$ be a complete metric space and $E \subset X$. Then, $E$ is meagre or of the first category if $E$ is a countable union of nowhere dense subsets of $X$. We say that $E$ is nonmeagre or of the second category if $E$ is not meagre. We say that $E$ is comeagre or residual if $X \backslash E$ is meagre. Hence, a countable intersection of comeagre sets is comeagre. With this terminology, the Baire category theorem (see [RF10, Section 10.2]) says that if $E$ is comeagre then $E$ is dense. The Sard-Smale theorem (see [Sma65, Theorem 1.3]) says that if $f: M \longrightarrow N$ is a Fredholm map between separable connected Banach manifolds of class $C^{q}$, for some $q>\max \{0$, ind $f\}$, then the set of regular values of $f$ is comeagre.
Theorem 4.51. There exists a dense subset $\mathcal{J}_{\text {reg }} \subset \mathcal{J}$ with the following property. Let $J \in \mathcal{J}_{\text {reg }}$ be an almost complex structure, $\left[z^{ \pm}, \gamma^{ \pm}\right]$be equivalence classes of 1-periodic orbits of $H$, and $(w, u) \in \hat{\mathcal{M}}\left(X, H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$. Then, near $(w, u)$ the space $\hat{\mathcal{M}}\left(X, H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$is a manifold of dimension

$$
\operatorname{dim}_{(w, u)} \hat{\mathcal{M}}\left(X, H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)=\mu^{\tau}\left(z^{+}, \gamma^{+}\right)-\mu^{\tau}\left(z^{-}, \gamma^{-}\right)+1
$$

Proof. Recall that the space $\mathcal{J}^{\varepsilon}$ is defined with respect to a reference almost complex structure $J_{\text {ref }}$. We will now emphasize this fact using the notation $\mathcal{J}^{\varepsilon}\left(J_{\text {ref }}\right)$. As a first step, we show that for every $\left[z^{ \pm}, \gamma^{ \pm}\right]$and every reference almost complex structure $J_{\text {ref }}$ there exists a comeagre set $\mathcal{J}_{\text {reg }}^{\mathcal{E}}\left(J_{\text {ref }},\left[z^{ \pm}, \gamma^{ \pm}\right]\right) \subset \mathcal{J}^{\mathcal{E}}\left(J_{\text {ref }}\right)$ such that every $J \in \mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }},\left[z^{ \pm}, \gamma^{ \pm}\right]\right)$has the property in the statement of the theorem. For shortness, for every $J$ let $\hat{\mathcal{M}}\left(J,\left[z^{ \pm}, \gamma^{ \pm}\right]\right):=\hat{\mathcal{M}}\left(X, H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$. By Theorem 4.49 and the implicit function theorem [MS12, Theorem A.3.3], the universal moduli space

$$
\hat{\mathcal{M}}\left(\left[z^{ \pm}, \gamma^{ \pm}\right]\right):=\left\{(w, u, J) \mid J \in \mathcal{J}^{\varepsilon}\left(J_{\mathrm{ref}}\right),(w, u) \in \hat{\mathcal{M}}\left(J,\left[z^{ \pm}, \gamma^{ \pm}\right]\right)\right\}
$$

is a smooth Banach manifold. Consider the smooth map

$$
\pi: \hat{\mathcal{M}}\left(\left[z^{ \pm}, \gamma^{ \pm}\right]\right) \longrightarrow \mathcal{J}^{\varepsilon}\left(J_{\mathrm{ref}}\right), \quad \pi(w, u, J)=J
$$

By [MS12, Lemma A.3.6],

$$
\begin{align*}
\operatorname{ker} \mathrm{D} \pi(w, u, J) & \cong \operatorname{ker} \mathbf{D}_{(w, u, J)}  \tag{4.32}\\
\operatorname{coker} \mathrm{D} \pi(w, u, J) & \cong \operatorname{coker} \mathbf{D}_{(w, u, J)} \tag{4.33}
\end{align*}
$$

Therefore, $\mathrm{D} \pi(w, u, J)$ is Fredholm and has the same index as $\mathbf{D}_{(w, u, J)}$. By the SardSmale theorem, the set $\mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }},\left[z^{ \pm}, \gamma^{ \pm}\right]\right) \subset \mathcal{J}^{\varepsilon}\left(J_{\text {ref }}\right)$ of regular values of $\pi$ is comeagre. By Equation (4.33), $J \in \mathcal{J}^{\varepsilon}\left(J_{\text {ref }}\right)$ is a regular value of $\pi$ if and only if $\mathbf{D}_{(w, u, J)}$ is surjective for every $(w, u) \in\left(\bar{\partial}^{J}\right)^{-1}(0)$. Therefore, by the implicit function theorem, for every $J \in \mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }},\left[z^{ \pm}, \gamma^{ \pm}\right]\right)$the set $\hat{\mathcal{M}}\left(J,\left[z^{ \pm}, \gamma^{ \pm}\right]\right)=\left(\bar{\partial}^{J}\right)^{-1}(0) \subset \mathcal{B}$ is a manifold of dimension

$$
\begin{array}{ll}
\operatorname{dim}_{(w, u)} \hat{\mathcal{M}}\left(J,\left[z^{ \pm}, \gamma^{ \pm}\right]\right) & \\
\quad=\operatorname{dim} \operatorname{ker} \mathbf{D}_{(w, u, J)} & \\
=\operatorname{ind} \mathbf{D}_{(w, u, J)} & \text { [sy the implicit function theorem] } \\
=\mu^{\tau}\left(z^{+}, \gamma^{+}\right)-\mu^{\tau}\left(z^{-}, \gamma^{-}\right)+1 & \text { [by Theorem } 4.48] .
\end{array}
$$

As a second step, we show that we can switch the order of the quantifiers in the first step, i.e. that for every reference almost complex structure $J_{\text {ref }}$ there exists a comeagre set $\mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }}\right) \subset \mathcal{J}^{\varepsilon}\left(J_{\text {ref }}\right)$ such that for every $J \in \mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }}\right)$ and every $\left[z^{ \pm}, \gamma^{ \pm}\right]$, the property in the statement of the theorem statement holds. For this, define

$$
\mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }}\right):=\bigcap_{\left[z^{ \pm}, \gamma^{ \pm}\right]} \mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }},\left[z^{ \pm}, \gamma^{ \pm}\right]\right) .
$$

Since $H$ is nondegenerate, in the above expression we are taking an intersection over a finite set of data, and hence $\mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }}\right)$ is comeagre. This finishes the proof of the second step. By the Baire category theorem, $\mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }}\right) \subset \mathcal{J}^{\varepsilon}\left(J_{\text {ref }}\right)$ is dense. Finally, define

$$
\mathcal{J}_{\text {reg }}:=\bigcup_{J_{\text {ref }} \in \mathcal{J}} \mathcal{J}_{\text {reg }}^{\varepsilon}\left(J_{\text {ref }}\right) .
$$

Then $\mathcal{J}_{\text {reg }}$ is the desired set of almost complex structures.

## Chapter 5

## $S^{1}$-equivariant Floer homology

### 5.1 Categorical setup

In this section, we define categories that will allow us to express the constructions of this chapter as functors. We will define a category of complexes (see Definitions 5.3 and 5.4) and a category of modules (see Definition 5.5). Associated to these, there is a Homology functor between the two categories (Definition 5.7).

Remark 5.1. Recall that a preorder on a set $S$ is a binary relation $\leq$ which is reflexive and transitive. A preordered set $(S, \leq)$ can be seen as a category $S$ by declaring that objects of $S$ are elements of the set $S$ and that there exists a unique morphism from $a$ to $b$ if and only if $a \leq b$, for $a, b \in S$. Throughout this thesis, we will view $\mathbb{R}$ as a category in this sense.

Definition 5.2. Let $\mathbf{C}$ be a category. A filtered object in $\mathbf{C}$ is a functor $V: \mathbb{R} \longrightarrow \mathbf{C}$. A morphism of filtered objects from $V$ to $W$ is a natural transformation $\phi: V \longrightarrow W$. We denote by $\operatorname{Hom}(\mathbb{R}, \mathbf{C})$ the category of filtered objects in $\mathbf{C}$. In this case, we will use the following notation. If $a \in \mathbb{R}$, we denote by $V^{a}$ the corresponding object of $\mathbf{C}$. If $\mathbf{C}$ is abelian and $a \leq b \in \mathbb{R}$, we denote $V^{(a, b]}:=V^{b} / V^{a}:=\operatorname{coker}\left(\iota^{b, a}: V^{a} \longrightarrow V^{b}\right)$.

Definition 5.3. Denote by ${ }_{\mathbb{Q}}$ Mod the category of $\mathbb{Q}$-modules. We define a category Comp as follows. An object of Comp is a triple $(C, \partial, U)$, where $C \in \operatorname{Hom}\left(\mathbb{R},{ }_{\mathbb{Q}}\right.$ Mod $)$ is a filtered $\mathbb{Q}$-module and $\partial, U: C \longrightarrow C$ are natural transformations such that

$$
\begin{aligned}
& \partial \circ \partial=0, \\
& \partial \circ U=U \circ \partial .
\end{aligned}
$$

A morphism in Comp from $\left(C, \partial^{C}, U^{C}\right)$ to $\left(D, \partial^{D}, U^{D}\right)$ is a natural transformation $\phi: C \longrightarrow D$ for which there exists a natural transformation $T: C \longrightarrow D$ such that

$$
\begin{aligned}
\partial^{D} \circ \phi-\phi \circ \partial^{C} & =0, \\
U^{D} \circ \phi-\phi \circ U^{C} & =\partial^{D} \circ T+T \circ \partial^{C}
\end{aligned}
$$

Definition 5.4. Let $\phi, \psi:\left(C, \partial^{C}, U^{C}\right) \longrightarrow\left(D, \partial^{D}, U^{D}\right)$ be morphisms in Comp. A chain homotopy from $\phi$ to $\psi$ is a natural transformation $T: C \longrightarrow D$ such that

$$
\psi-\phi=\partial^{D} \circ T+T \circ \partial^{C} .
$$

The notion of chain homotopy defines an equivalence relation $\sim$ on each set of morphisms in Comp. We denote the quotient category (see for example [Rot88, Theorem 0.4]) by

$$
\text { hComp }:=\text { Comp } / \sim \text {. }
$$

As we will see in Section 5.3, the $S^{1}$-equivariant Floer chain complex of $X$ (with respect to a Hamiltonian $H$ and almost complex structure $J$ ) is an object

$$
F C^{S^{1}}(X, H, J) \in \text { hComp. }
$$

Definition 5.5. We define a category Mod as follows. An object of Mod is a pair $(C, U)$, where $C \in \operatorname{Hom}\left(\mathbb{R},{ }_{\mathbb{Q}}\right.$ Mod) is a filtered $\mathbb{Q}$-module and $U: C \longrightarrow C$ is a natural transformation. A morphism in Mod from $\left(C, U^{C}\right)$ to $\left(D, U^{D}\right)$ is a natural transformation $\phi: C \longrightarrow D$ such that $\phi \circ U^{C}=U^{D} \circ \phi$.

In Section 5.3, we will show that the $S^{1}$-equivariant Floer homology of $X$ (with respect to a Hamiltonian $H$ and almost complex structure $J$ ) and the $S^{1}$-equivariant symplectic homology of $X$ are objects of Mod:

$$
\begin{aligned}
F H^{S^{1}}(X, H, J) & \in \text { Mod } \\
S H^{S^{1}}(X) & \in \text { Mod. }
\end{aligned}
$$

Lemma 5.6. The category Mod is abelian, complete and cocomplete.
Proof. Recall the definition of (co)complete: a category I is small if the class of morphisms of $\mathbf{I}$ is a set. A category is (co)complete if for any $\mathbf{I}$ small and for any functor $F: \mathbf{I} \longrightarrow$ Mod, the (co)limit of $F$ exists. By [Rie16, Theorem 3.4.12], it suffices to show that Mod has products, coequalizers, coproducts and coequalizers. First, notice that ${ }_{\mathbb{Q}}$ Mod is abelian, complete and cocomplete. Therefore, the same is true for $\operatorname{Hom}\left(\mathbb{R},{ }_{\mathbb{Q}} \mathbf{M o d}\right)$. Let $f: C \longrightarrow D$ be a morphism in Mod. Then $f$ has a kernel and a cokernel in $\operatorname{Hom}\left(\mathbb{R},{ }_{\mathbb{Q}}\right.$ Mod $)$. We need to show that the kernel and the cokernel are objects of Mod, i.e. that they come equipped with a $U$ map. The $U$ maps for $\operatorname{ker} f$, coker $f$ are the unique maps (coming from the universal property of the (co)kernel) such that diagram

commutes. Let $C_{i}$, for $i \in I$, be a family of objects in Mod. Then, the product $\prod_{i \in I} C_{i}$ and the coproduct $\oplus_{i \in I} C_{i}$ exist in $\operatorname{Hom}\left(\mathbb{R}, \mathbb{Q}_{\mathbb{Q}} \mathbf{M o d}\right)$. Again, we need to show that the
product and coproduct come equipped with a $U$ map. The $U$ maps for the product and coproduct are the maps

$$
\begin{aligned}
U_{\prod_{i \in I} C_{i}} & =\prod_{i \in I} U_{C_{i}}: \prod_{i \in I} C_{i} \longrightarrow \prod_{i \in I} C_{i}, \\
U_{\bigoplus_{i \in I} C_{i}} & =\bigoplus_{i \in I} U_{C_{i}}:
\end{aligned} \bigoplus_{i \in I} C_{i} \longrightarrow \bigoplus_{i \in I} C_{i},
$$

coming from the respective universal properties.
Definition 5.7. Let $(C, \partial, U) \in$ hComp. The homology of $(C, \partial, U)$ is the object of Mod given by $H(C, \partial, U):=(H(C, \partial), H(U))$, where $H(C, \partial)=\operatorname{ker} \partial / \operatorname{im} \partial$ and $H(U)$ is the unique map such that the diagram

commutes. If $\phi:\left(C, \partial^{C}, U^{C}\right) \longrightarrow\left(D, \partial^{D}, U^{D}\right)$ is a morphism in $\mathbf{h C o m p}$, we define the induced morphism on homology, $H(\phi): H\left(C, \partial^{C}\right) \longrightarrow H\left(D, \partial^{D}\right)$, to be the unique map such that the diagram

commutes. With these definitions, homology is a functor $H: \mathbf{h C o m p} \longrightarrow$ Mod.

### 5.2 Action functional

Our goal in this section is to establish the definitions that we will need to later define the $S^{1}$-equivariant Floer Chain complex. We define suitable families of admissible Hamiltonians (Definition 5.8) and almost complex structures (Definition 5.9). The key points of this section are Definition 5.11, where we define the set of generators of the $S^{1}$-equivariant Floer chain complex, and Definition 5.13, where we define the trajectories that are counted in the differential of the $S^{1}$-equivariant Floer chain complex. We also define the action of a generator (Definition 5.14), which will induce a filtration on the $S^{1}$-equivariant Floer chain complex. We will assume that $(X, \lambda)$ is a nondegenerate Liouville domain with completion $(\hat{X}, \hat{\lambda})$. Let $\varepsilon:=\frac{1}{2} \operatorname{Spec}(\partial X, \lambda \mid \partial X)$.

We start by recalling some basic facts about $S^{2 N+1}$ and $\mathbb{C} P^{N}$. For each $N \in \mathbb{Z}_{\geq 1}$ we denote

$$
S^{2 N+1}:=\left\{\left.\left(z_{0}, \ldots, z_{N}\right) \in \mathbb{C}^{N+1}| | z_{0}\right|^{2}+\cdots+\left|z_{N}\right|^{2}=1\right\} .
$$

There is an action $S^{1} \times S^{2 N+1} \longrightarrow S^{2 N+1}$ given by $(t, z) \longmapsto e^{2 \pi i t} z$. This action is free and proper, so we can consider the quotient manifold $S^{2 N+1} / S^{1}$. The Riemannian metric
of $\mathbb{C}^{N+1}=\mathbb{R}^{2(N+1)}$ pulls back to a Riemannian metric on $S^{2 N+1}$. The action of $S^{1}$ on $S^{2 N+1}$ is by isometries, so there exists a unique Riemannian metric on $S^{2 N+1} / S^{1}$ such that the projection $S^{2 N+1} \longrightarrow S^{2 N+1} / S^{1}$ is a Riemannian submersion. The set $\mathbb{C} \backslash\{0\}$ is a group with respect to multiplication, and it acts on $\mathbb{C}^{N+1} \backslash\{0\}$ by multiplication. This action is free and proper, so we can form the quotient

$$
\mathbb{C} P^{N}:=\left(\mathbb{C}^{N+1} \backslash\{0\}\right) /(\mathbb{C} \backslash\{0\})
$$

By the universal property of the quotient, there exists a unique map $S^{2 N+1} / S^{1} \longrightarrow \mathbb{C} P^{N}$ such that the following diagram commutes:


The map $S^{2 N+1} / S^{1} \longrightarrow \mathbb{C} P^{N}$ is a diffeomorphism. Define the Fubini-Study metric on $\mathbb{C} P^{N}$ to be the unique Riemannian metric on $\mathbb{C} P^{N}$ such that $S^{2 N+1} / S^{1} \longrightarrow \mathbb{C} P^{N}$ is an isometry.

We will now consider a special family of functions on $S^{2 N+1}$ and $\mathbb{C} P^{N}$. Define a function

$$
\begin{aligned}
f_{N}: \mathbb{C} P^{N} & \longrightarrow \mathbb{R} \\
{[w] } & \longmapsto \frac{\sum_{j=0}^{N} j\left|w_{j}\right|^{2}}{\sum_{j=0}^{N}\left|w_{j}\right|^{2}} .
\end{aligned}
$$

Define $\tilde{f}_{N}$ to be the pullback of $f_{N}$ to $S^{2 N+1}$. Let $e_{0}, \ldots, e_{N}$ be the canonical basis of $\mathbb{C}^{N+1}$ (as a vector space over $\mathbb{C}$ ). Then,

$$
\begin{aligned}
\operatorname{CritPt} \tilde{f}_{N} & =\left\{e^{2 \pi i t} e_{j} \mid t \in S^{1}, j=0, \ldots, N\right\} \\
\operatorname{CritPt} f_{N} & =\left\{\left[e_{0}\right], \ldots,\left[e_{N}\right]\right\}
\end{aligned}
$$

The function $f_{N}$ is Morse, while $\tilde{f}_{N}$ is Morse-Bott. The Morse indices are given by

$$
\begin{aligned}
\mu_{\mathrm{M}}\left(\left[e_{j}\right], f_{N}\right) & =2 j, & & \text { for all } j=0, \ldots, N, \\
\mu_{\mathrm{M}}\left(z, \tilde{f}_{N}\right) & =\mu_{\mathrm{M}}\left([z], f_{N}\right), & & \text { for all } z \in \operatorname{CritPt} f_{N} .
\end{aligned}
$$

We will use the notation $\mu_{\mathrm{M}}(z):=\mu_{\mathrm{M}}\left(z, \tilde{f}_{N}\right)=\mu_{\mathrm{M}}\left([z], f_{N}\right)$.
We now study the relation between $\tilde{f}_{N^{-}}$and $\tilde{f}_{N^{+}}$for $N^{-} \geq N^{+}$. For every $k$ such that $0 \leq k \leq N^{-}-N^{+}$, define maps

$$
\begin{aligned}
\tilde{i}_{k}^{N^{-}, N^{+}}: \quad S^{2 N^{+}+1} & \longrightarrow S^{2 N^{-}+1} \\
\left(z_{0}, \ldots, z_{N^{+}}\right) & \longmapsto(\underbrace{0, \ldots, 0}_{k}, z_{0}, \ldots, z_{N^{+}}, 0, \ldots, 0) .
\end{aligned}
$$

Let $I_{k}: \mathbb{R} \longrightarrow \mathbb{R}$ be given by $I_{k}(x)=x+k$. Then, the following diagram commutes:


The vector fields $\nabla \tilde{f}_{N^{+}}$and $\nabla \tilde{f}_{N^{-}}$are $\tilde{i}_{k}^{N^{-}, N^{+}}$-related, and analogously the vector fields $\nabla f_{N^{+}}$and $\nabla f_{N^{-}}$are $i_{k}^{N^{-}, N^{+}}$-related. For $t \in \mathbb{R}$, denote by $\phi_{\tilde{f}_{N^{-}}}^{t}$ the time- $t$ gradient flow of $\tilde{f}_{N^{-}}$and analogously for $\phi_{f_{N^{+}}}^{t}$. Then, the following diagram commutes:


Definition 5.8. A parametrized Hamiltonian $H: S^{1} \times S^{2 N+1} \times \hat{X} \longrightarrow \mathbb{R}$ is admissible if it satisfies the conditions in Items (1) to (5). We denote the set of such $H$ by $\mathcal{H}(X, N)$.
(1) There exist $D \in \mathbb{R}, C \in \mathbb{R}_{>0} \backslash \operatorname{Spec}\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ and $\delta>0$ such that:
(I) on $S^{1} \times S^{2 N+1} \times X$, we have that $-\varepsilon<H<0, H$ is $S^{1}$-independent and $H$ is $C^{2}$-small (so that there are no nonconstant 1-periodic orbits);
(II) on $S^{1} \times S^{2 N+1} \times[0, \delta] \times \partial X$, we have that $-\varepsilon<H<\varepsilon$ and $H$ is $C^{2}$-close to $(t, z, r, x) \longmapsto h\left(e^{r}\right)$, where $h:\left[1, e^{\delta}\right] \longrightarrow \mathbb{R}$ is increasing and strictly convex;
(S) on $S^{1} \times S^{2 N+1} \times[\delta,+\infty) \times \partial X$, we have that $H(t, z, r, x)=C e^{r}+D$.
(2) Consider the action of $S^{1}$ on $S^{1} \times S^{2 N+1} \times \hat{X}$ given by $t^{\prime} \cdot(t, z, x)=\left(t^{\prime}+t, e^{2 \pi i t^{\prime}} z, x\right)$. Then $H$ is invariant under this action, i.e. $H\left(t^{\prime}+t, e^{2 \pi i t^{\prime}} z, x\right)=H(t, z, x)$.
(3) If $z$ is a critical point of $\tilde{f}_{N}$ then $H_{z}$ is nondegenerate.
(4) For every $(t, z, x) \in S^{1} \times S^{2 N+1} \times \hat{X}$ we have $\left\langle\nabla_{S^{2 N+1}} H(t, z, x), \nabla \tilde{f}_{N}(z)\right\rangle \leq 0$.
(5) There exists $E \geq 0$ such that $\left(\tilde{i}_{0}^{N, N-1}\right)^{*} H=\left(\tilde{i}_{1}^{N, N-1}\right)^{*} H+E$.

Definition 5.9. A parametrized almost complex structure $J: S^{1} \times S^{2 N+1} \times \hat{X} \longrightarrow$ $\operatorname{End}(T \hat{X})$ is admissible if it satisfies the conditions in Items (1) to (4). We denote the set of such $J$ by $\mathcal{J}(X, N)$.
(1) $J$ is $S^{1}$-invariant, i.e. $J\left(t^{\prime}+t, e^{2 \pi i t^{\prime}} z, x\right)=J(t, z, x)$ for every $t^{\prime} \in S^{1}$ and $(t, z, x) \in$ $S^{1} \times S^{2 N+1} \times \hat{X}$.
(2) $J$ is $\hat{\omega}$-compatible.
(3) The restriction of $J$ to $S^{1} \times S^{2 N+1} \times \mathbb{R}_{\geq 0} \times \partial X$ is cylindrical.
(4) $\left(\tilde{i}_{0}^{N, N-1}\right)^{*} J=\left(\tilde{i}_{1}^{N, N-1}\right)^{*} J$.

Definition 5.10. Denote by $\mathbf{I}_{X}$ the set of tuples

$$
(H, J) \in \coprod_{N \in \mathbb{Z}_{\geq 1}} \mathcal{H}(X, N) \times \mathcal{J}(X, N)
$$

which are regular, where "regular" means that the moduli spaces of Definition 5.13 are transversely cut out. Define a preorder $\leq$ on $\mathbf{I}_{X}$ by

$$
\left(H^{+}, J^{+}\right) \leq\left(H^{-}, J^{-}\right): \Longleftrightarrow N^{+} \leq N^{-} \text {and } H^{+} \leq\left(i_{0}^{N^{-}, N^{+}}\right)^{*} H^{-} .
$$

Definition 5.11. Let $N \in \mathbb{Z}_{\geq 1}$ and $H \in \mathcal{H}(X, N)$. Define

$$
\hat{\mathcal{P}}(H):=\left\{\begin{array}{l|l}
(z, \gamma) & \begin{array}{l}
z \in S^{2 N+1} \text { is a critical point of } \tilde{f}_{N}, \\
\gamma \in C^{\infty}\left(S^{1}, \hat{X}\right) \text { is a 1-periodic orbit of } H_{z}
\end{array}
\end{array}\right\} .
$$

There is an action of $S^{1}$ on $\hat{\mathcal{P}}(H)$ given by $t \cdot(z, \gamma):=\left(e^{2 \pi i t^{\prime}} z, \gamma(\cdot-t)\right)$. Define the quotient

$$
\mathcal{P}(H):=\hat{\mathcal{P}}(H) / S^{1} .
$$

Remark 5.12. If $(z, \gamma) \in \hat{\mathcal{P}}(H)$, then either im $\gamma$ is in region I and $\gamma$ is constant or $\operatorname{im} \gamma$ is in region II and $\gamma$ is nonconstant. In the slope region, i.e. region S , there are no 1-periodic orbits of $H$ because $C$ is not in $\operatorname{Spec}\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ and by Corollary 2.42.
Definition 5.13. Let $N \in \mathbb{Z}_{\geq 1}, H \in \mathcal{H}(X, N)$ and $J \in \mathcal{J}(X, N)$. A pair $(w, u)$, where $w: \mathbb{R} \longrightarrow S^{2 N+1}$ and $u: \mathbb{R} \times S^{1} \longrightarrow \hat{X}$ is a solution of the parametrized Floer equation if

$$
\left\{\begin{aligned}
\dot{w}(s) & =\nabla \tilde{f}_{N}(w(s)) \\
\frac{\partial u}{\partial s}(s, t) & =-J_{w(s)}^{t}(u(s, t))\left(\frac{\partial u}{\partial t}(s, t)-X_{H_{w(s)}^{t}}(u(s, t))\right)
\end{aligned}\right.
$$

For $\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right] \in \mathcal{P}(H)$, define $\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$to be the moduli space of solutions $(w, u)$ of the parametrized Floer equation such that $(w(s), u(s, \cdot))$ converges as $s \rightarrow \pm \infty$ to an element in the equivalence class $\left[z^{ \pm}, \gamma^{ \pm}\right]$. We define the following two group actions.

| $\mathbb{R}$ | acts on | $\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$ | by | $s \cdot(w, u):=(w(\cdot-s), u(\cdot-s, \cdot))$, |
| ---: | :--- | :--- | :--- | :--- |
| $S^{1}$ | acts on | $\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$ | by | $t \cdot(w, u):=\left(e^{2 \pi i t} w, u(\cdot, \cdot-t)\right)$. |

The actions of $\mathbb{R}$ and $S^{1}$ on $\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$commute, so they define an action of $\mathbb{R} \times S^{1}$ on $\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$. Finally, let

$$
\mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right):=\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right) / \mathbb{R} \times S^{1} .
$$

Definition 5.14. For $(z, \gamma) \in \hat{\mathcal{P}}(H)$, the action of $(z, \gamma)$, denoted $\mathcal{A}_{H}(z, \gamma)$, is given by

$$
\mathcal{A}_{H}(z, \gamma):=\mathcal{A}_{H_{z}}(\gamma)=\int_{S^{1}} \gamma^{*} \hat{\lambda}-\int_{S^{1}} H(t, z, \gamma(t)) \mathrm{d} t .
$$

The action functional is a map $\mathcal{A}_{H}: \hat{\mathcal{P}}(H) \longrightarrow \mathbb{R}$. Since $H$ is $S^{1}$-invariant, $\mathcal{A}_{H}$ is $S^{1}{ }_{-}$ invariant as well, and therefore there is a corresponding map $\mathcal{A}_{H}$ whose domain is $\mathcal{P}(H)$.

Lemma 5.15. The actions of 1-periodic orbits of $H$ are ordered according to

$$
0<\mathcal{A}_{H}(\mathrm{I})<\varepsilon<\mathcal{A}_{H}(\mathrm{II}) .
$$

Proof. Consider Fig. 5.1. By Lemma 2.43 and Definition 5.8, we have that $\mathcal{A}_{H}$ is constant equal to $-H$ in regions I and S and $\mathcal{A}_{H}$ is strictly increasing in region II. We remark that strictly speaking, the Hamiltonian plotted in the picture is not $H$ but instead a Hamiltonian which is $C^{2}$-close to $H$. However, it suffices to prove the statement for the Hamiltonian which approximates $H$. From this discussion, we conclude that $0<\mathcal{A}_{H}(\mathrm{I})<\varepsilon$. We show that $\mathcal{A}_{H}(\mathrm{II})>\varepsilon$.

$$
\begin{aligned}
\mathcal{A}_{H}(\mathrm{II}) & =e^{r} T(r)-H(r) & & {[\text { by Lemma 2.43] }} \\
& \geq 2 \varepsilon e^{r}-H(r) & & {\left[2 \varepsilon=\min \operatorname{Spec}\left(\partial X,\left.\lambda\right|_{\partial X}\right) \text { and } T(r) \in \operatorname{Spec}\left(\partial X,\left.\lambda\right|_{\partial X}\right)\right] } \\
& >\varepsilon\left(2 e^{r}-1\right) & & {[H(r)<\varepsilon] } \\
& >\varepsilon & & {[r>0] . }
\end{aligned}
$$



Figure 5.1: Action of a 1-periodic orbit of $H$
Remark 5.16. Denote by $\operatorname{CritPt} \mathcal{A}_{H} \subset S^{2 N+1} \times C^{\infty}\left(S^{1}, \hat{X}\right)$ the set of critical points of the action functional. Then, $\hat{\mathcal{P}}(H)=\operatorname{CritPt} \mathcal{A}_{H}$, as is usual for various Floer theories. However, if $(w, u)$ is a path in $S^{2 N+1} \times C^{\infty}\left(S^{1}, \hat{X}\right)$, it is not true that $(w, u)$ is a gradient flow line of $\mathcal{A}_{H}$ if and only if $(w, u)$ is a solution of the parametrized Floer equations.

## $5.3 \quad S^{1}$-equivariant Floer homology

Let $(X, \lambda)$ be a nondegenerate Liouville domain. In this section, we define the $S^{1}$ equivariant Floer chain complex of $(X, \lambda)$ and other related invariants, namely the $S^{1}$-equivariant Floer homology, the positive $S^{1}$-equivariant Floer homology, the $S^{1}$ equivariant symplectic homology and the positive $S^{1}$-equivariant symplectic homology. The presentation we will give will be based on [GH18]. Other references discussing $S^{1}$ equivariant symplectic homology are [Gut14, Gut17, BO13, BO10, BO16, Sei08]. The $S^{1}$-equivariant Floer complex of $X$ depends on the additional data of $(H, J) \in \mathbf{I}_{X}$. More precisely, it can be encoded in a functor $F C_{X}^{S^{1}}: \mathbf{I}_{X} \longrightarrow \mathbf{h C o m p}$. We start by defining this functor on objects. For each $I=(H, J) \in \mathbf{I}_{X}$, we need to say what is $F C_{X}^{S^{1}}(H, J):=F C^{S^{1}}(X, H, J) \in \mathbf{h C o m p}$.

Definition 5.17. We define $F C^{S^{1}}(X, H, J)$ to be the free $\mathbb{Q}$-module generated by the elements of $\mathcal{P}(H)$. Define $F C^{S^{1}, a}(X, H, J)$ to be the subspace generated by the elements $[z, \gamma]$ of $\mathcal{P}(H)$ such that $\mathcal{A}_{H}(z, \gamma) \leq a$. These modules come equipped with inclusion maps

$$
\begin{gathered}
\iota^{a}: F C^{S^{1}, a}(X, H, J) \longrightarrow F C^{S^{1}}(X, H, J), \quad \text { for } a \in \mathbb{R} \\
\iota^{b, a}: F C^{S^{1}, a}(X, H, J) \longrightarrow F C^{S^{1}, b}(X, H, J), \\
\text { for } a \leq b
\end{gathered}
$$

For $\left[z^{ \pm}, \gamma^{ \pm}\right] \in \mathcal{P}(H)$, consider the moduli space $\mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$. Near a point $(w, u) \in \mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$, this space is a manifold (see Theorem 4.51) of dimension

$$
\begin{equation*}
\operatorname{dim}_{(w, u)} \mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)=\mu^{\tau^{+}}\left(z^{+}, \gamma^{+}\right)-\mu^{\tau^{-}}\left(z^{-}, \gamma^{-}\right)-1, \tag{5.1}
\end{equation*}
$$

where

$$
\mu^{\tau^{ \pm}}\left(z^{ \pm}, \gamma^{ \pm}\right):=\mu_{\mathrm{M}}\left(z^{ \pm}\right)+\mu_{\mathrm{CZ}}^{\tau^{ \pm}}\left(\gamma^{ \pm}\right)
$$

and $\tau^{ \pm}$are symplectic trivializations of $\left(\gamma^{ \pm}\right)^{*} T \hat{X}$ which extend to a symplectic trivialization $\tau$ of $u^{*} T \hat{X}$. With $\tau^{ \pm}$chosen like this, even though each individual term on the right-hand side of Equation (5.1) depends on $\tau^{ \pm}$, the right-hand side is independent of the choice of $\tau$. Throughout this chapter, if $\mathcal{M}$ is a moduli space of solutions of the parametrized Floer equation, we will denote by $\# \mathcal{M}$ the signed count of points ( $w, u$ ) in $\mathcal{M}$ such that $\operatorname{dim}_{(w, u)} \mathcal{M}=0$.

Definition 5.18. We define $\partial: F C^{S^{1}}(X, H, J) \longrightarrow F C^{S^{1}}(X, H, J)$ by

$$
\partial\left(\left[z^{+}, \gamma^{+}\right]\right):=\sum_{\left[z^{-}, \gamma^{-}\right] \in \mathcal{P}(H)} \# \mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right) \cdot\left[z^{-}, \gamma^{-}\right],
$$

for each $\left[z^{+}, \gamma^{+}\right] \in \mathcal{P}(H)$.
By Lemma 4.37, the differential respects the action filtration, i.e. the differential $\partial$ maps $F C^{S^{1}, a}(X, H, J)$ to itself. By [BO16, Proposition 2.2], $\partial \circ \partial=0$.

Definition 5.19. We define a map $U: F C^{S^{1}}(X, H, J) \longrightarrow F C^{S^{1}}(X, H, J)$ as follows. First, recall that a critical point $z$ of $\tilde{f}_{N}$ is of the form $z=e^{2 \pi i t} e_{j}$, for $t \in S^{1}$ and $j=0, \ldots, N$. If $j \geq 1$, let $S\left(e^{2 \pi i t} e_{j}\right):=e^{2 \pi i t} e_{j-1}$. Finally, define

$$
U([z, \gamma]):= \begin{cases}{[S(z), \gamma]} & \text { if } \mu_{\mathrm{M}}(z) \geq 2 \\ 0 & \text { if } \mu_{\mathrm{M}}(z)=0\end{cases}
$$

for $[z, \gamma] \in \mathcal{P}(H)$.
The definition of $U$ is well-posed because by Definition 5.8 (5), the Hamiltonians $H_{e_{j}}$ and $H_{e_{j-1}}$ differ by a constant. Therefore, if $\gamma$ is a 1-periodic orbit of $H_{e_{j}}$ then it is also a 1-periodic orbit of $H_{e_{j-1}}$. By [GH18, Section 6.3], $U$ is a chain map, i.e. $U \circ \partial=\partial \circ U$.

Lemma 5.20. The map $U: F C^{S^{1}}(X, H, J) \longrightarrow F C^{S^{1}}(X, H, J)$ respects the filtration.
Proof. Let $[z, \gamma] \in \mathcal{P}(H)$ be such that $\mu_{\mathrm{M}}(z) \geq 2$ and $\mathcal{A}_{H}(z, \gamma) \leq a$. We wish to show that $\mathcal{A}_{H}(S(z), \gamma) \leq \mathcal{A}_{H}(z, \gamma) \leq a$. Assumption (5) of Definition 5.8 implies that $H_{S(z)}=H_{z}+E$, where $E \geq 0$. Then,

$$
\begin{aligned}
\mathcal{A}_{H}(S(z), \gamma) & =\int_{S^{1}} \gamma^{*} \hat{\lambda}-\int_{0}^{1} H(t, S(z), \gamma(t)) \mathrm{d} t & & {\left[\text { by definition of } \mathcal{A}_{H}\right] } \\
& =\int_{S^{1}} \gamma^{*} \hat{\lambda}-\int_{0}^{1} H(t, z, \gamma(t)) \mathrm{d} t-E & & {\left[\text { since } H_{S(z)}=H_{z}+E\right] } \\
& =\mathcal{A}_{H}(z, \gamma)-E & & {\left[\text { by definition of } \mathcal{A}_{H}\right] } \\
& \leq \mathcal{A}_{H}(z, \gamma) & & {[\text { since } E \geq 0] } \\
& \leq a & & {[\text { by assumption on }[z, \gamma]] . }
\end{aligned}
$$

We will now define the continuation maps. For $\left(H^{+}, J^{+}\right) \leq\left(H^{-}, J^{-}\right) \in \mathbf{I}_{X}$, we want to define a morphism $\phi^{-,+}: F C^{S^{1}}\left(X, H^{+}, J^{+}\right) \longrightarrow F C^{S^{1}}\left(X, H^{-}, J^{-}\right)$. Consider the map

$$
\begin{aligned}
\left.\tilde{i}_{k}^{N^{-}, N^{+}}: \hat{\mathcal{P}}\left(\tilde{i}_{k}^{N^{-}, N^{+}}\right)^{*} H^{-}\right) & \longrightarrow \hat{\mathcal{P}}\left(H^{-}\right) \\
(z, \gamma) & \longmapsto\left(\tilde{i}_{k}^{N^{-}, N^{+}}(z), \gamma\right) .
\end{aligned}
$$

This map fits into the commutative diagram


Definition 5.21. An admissible homotopy of parametrized Hamiltonians from $H^{-}$to $H^{+}$is a map $H: \mathbb{R} \times S^{1} \times S^{2 N^{+}+1} \times \hat{X} \longrightarrow \mathbb{R}$ which satisfies the conditions in Items (1) to (3), where $H_{s}(t, z, x)=H(s, t, z, x)$. We denote the set of such $H$ by $\mathcal{H}\left(H^{+}, H^{-}\right)$.
(1) For every $s \in \mathbb{R}$, we have that $H_{s}$ satisfies all the assumptions in Definition 5.8, with the exceptions that $C_{s}$ may be in $\operatorname{Spec}\left(\partial X,\left.\lambda\right|_{\partial X}\right)$, and it is not necessarily true that $z \in \operatorname{CritPt} \tilde{f}_{N}$ implies that $H_{s, z}$ is nondegenerate.
(2) There exists $s_{0}>0$ such that if $\pm s>s_{0}$ then $H_{s}=\left(\tilde{i}_{0}^{N^{ \pm}, N^{+}}\right)^{*} H^{ \pm}$.
(3) For every $(s, t, z, x) \in \mathbb{R} \times S^{1} \times S^{2 N^{+}+1} \times \hat{X}$ we have that $\partial_{s} H(s, t, x, z) \leq 0$.

Definition 5.22. An admissible homotopy of parametrized almost complex structures from $J^{-}$to $J^{+}$is a map $J: \mathbb{R} \times S^{1} \times S^{2 N^{+}+1} \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ which satisfies the conditions in Items (1) and (2), where $J_{s}(t, z, x)=J(s, t, z, x)$. We denote the set of such $J$ by $\mathcal{J}\left(J^{+}, J^{-}\right)$.
(1) For every $s \in \mathbb{R}$, we have that $J_{s}$ satisfies all the assumptions in Definition 5.9.
(2) There exists $s_{0}>0$ such that if $\pm s>s_{0}$ then $J_{s}=\left(\tilde{i}_{0}^{N^{ \pm}, N^{+}}\right)^{*} J^{ \pm}$.

Definition 5.23. Let $\left[z^{ \pm}, \gamma^{ \pm}\right] \in \mathcal{P}\left(\left(\tilde{i}_{0}^{N^{ \pm}, N^{+}}\right)^{*} H^{ \pm}\right)$and $(H, J)$ be a homotopy from $\left(H^{-}, J^{-}\right)$to $\left(H^{+}, J^{+}\right)$. A pair $(w, u)$, where $w: \mathbb{R} \longrightarrow S^{2 N^{+}+1}$ and $u: \mathbb{R} \times S^{1} \longrightarrow \hat{X}$ is a solution of the parametrized Floer equation (with respect to $(H, J)$ ) if

$$
\left\{\begin{aligned}
\dot{w}(s) & =\nabla \tilde{f}_{N}(w(s)) \\
\frac{\partial u}{\partial s}(s, t) & =-J_{s, w(s)}^{t}(u(s, t))\left(\frac{\partial u}{\partial t}(s, t)-X_{H_{s, w(s)}^{t}}(u(s, t))\right)
\end{aligned}\right.
$$

Define $\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$to be the moduli space of solutions $(w, u)$ of the parametrized Floer equation such that $(w(s), u(s, \cdot))$ converges as $s \rightarrow \pm \infty$ to an element in the equivalence class $\left[z^{ \pm}, \gamma^{ \pm}\right]$. Define an action of $S^{1}$ on $\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$by

$$
t \cdot(w, u)=\left(e^{2 \pi i t} w, u(\cdot, \cdot-t)\right)
$$

Finally, let $\mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right):=\hat{\mathcal{M}}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right) / S^{1}$.
Definition 5.24. The continuation map is the map

$$
\phi^{-,+}: F C^{S^{1}}\left(X, H^{+}, J^{+}\right) \longrightarrow F C^{S^{1}}\left(X, H^{-}, J^{-}\right)
$$

given as follows. Choose a regular homotopy $(H, J)$ from $\left(H^{-}, J^{-}\right)$to $\left(H^{+}, J^{+}\right)$. Then, for every $\left[z^{+}, \gamma^{+}\right] \in \mathcal{P}\left(H^{+}\right)$,

$$
\phi^{-,+}\left(\left[z^{+}, \gamma^{+}\right]\right):=\sum_{\left[z^{-}, \gamma^{-}\right] \in \mathcal{P}\left(\left(\tilde{i}_{0}^{N^{-}, N^{+}}\right)^{*} H^{-}\right)} \# \mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right) \cdot\left[\tilde{i}_{0}^{N^{-}, N^{+}}\left(z^{-}\right), \gamma^{-}\right] .
$$

Lemma 5.25. The map $\phi^{-,+}$respects the action filtrations.
Proof. Assume that $\left[z^{ \pm}, \gamma^{ \pm}\right] \in \mathcal{P}\left(\left(\tilde{i}_{0}^{N^{ \pm}, N^{+}}\right)^{*} H^{ \pm}\right)$is such that $\mathcal{A}_{H^{+}}\left(z^{+}, \gamma^{+}\right) \leq a$ and $\mathcal{M}\left(H, J,\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right)$is nonempty. We wish to show that $\mathcal{A}_{H^{-}}\left(\tilde{i}_{0}^{N^{-}, N^{+}}\left(z^{-}\right), \gamma^{-}\right) \leq a$. The proof is the following computation.

$$
\mathcal{A}_{H^{-}}\left(\tilde{i}_{0}^{N^{-}, N^{+}}\left(z^{-}\right), \gamma^{-}\right)
$$

$$
\begin{array}{ll}
=\int_{S^{1}} \gamma^{*} \hat{\lambda}-\int_{0}^{1} H^{-}\left(t, \tilde{i}_{0}^{N^{-}, N^{+}}\left(z^{-}\right), \gamma^{-}(t)\right) \mathrm{d} t & \\
=\int_{S^{1}} \gamma^{*} \hat{\lambda}-\int_{0}^{1}\left(\left(\tilde{i}_{0}^{N^{-}, N^{+}}\right)^{*} H^{-}\right)\left(t, z^{-}, \gamma^{-}(t)\right) \mathrm{d} t & \text { [definition of action functional] of } \left.\tilde{i}_{0}^{N^{-}, N^{+}}\right] \\
=\mathcal{A}_{\left(\tilde{i}_{0}^{N^{-}, N^{+}}\right)^{*} H^{-}}\left(z^{-}, \gamma^{-}\right) & \\
\leq \mathcal{A}_{H^{+}}\left(z^{+}, \gamma^{+}\right) & \text {[definition of action functional] } \\
\leq a & \\
\text { [by assumption]. }
\end{array}
$$

By [BO16, Section 2.4], the $U$ maps and the continuation maps commute. Moreover, by the usual arguments in Floer theory, we have (see also [GH18, Section 5.3]):
(1) The continuation map $\phi^{-,+}$is a chain map, i.e. $\phi^{-,+} \circ \partial^{+}=\partial^{-} \circ \phi^{-,+}$.
(2) The continuation map $\phi^{-,+}$is independent (up to chain homotopy, i.e. as a morphism in hComp) on the choice of regular homotopy $(H, J)$.
(3) The continuation maps are functorial, i.e. if $\left(H^{0}, J^{0}\right) \leq\left(H^{1}, J^{1}\right) \leq\left(H^{2}, J^{2}\right) \in \mathbf{I}_{X}$ then $\phi^{2,1} \circ \phi^{1,0}=\phi^{2,0}$.

Remark 5.26. By the determinant property of Theorem 3.3, the parity of the ConleyZehnder index of a Hamiltonian 1-periodic orbit is independent of the choice of trivialization. Therefore, $F C^{S^{1}}(X, H, J)$ has a $\mathbb{Z}_{2}$-grading given by

$$
\begin{equation*}
\operatorname{deg}([z, \gamma]):=\mu([z, \gamma]):=\mu_{\mathrm{M}}(z)+\mu_{\mathrm{CZ}}(\gamma) \tag{5.2}
\end{equation*}
$$

If $\pi_{1}(X)=0$ and $\left.c_{1}(T X)\right|_{\pi_{2}(X)}=0$, then by Lemma 3.11 we have well-defined ConleyZehnder indices in $\mathbb{Z}$. Therefore, Equation (5.2) defines a $\mathbb{Z}$-grading on $F C^{S^{1}}(X, H, J)$. With respect to this grading,

$$
\begin{aligned}
\operatorname{deg}(\partial) & =-1, \\
\operatorname{deg}(U) & =-2, \\
\operatorname{deg}\left(\phi^{-,+}\right) & =0
\end{aligned}
$$

Definition 5.27. If $(X, \lambda)$ is a nondegenerate Liouville domain, the $S^{1}$-equivariant Floer chain complex of $X$ is the functor

$$
\begin{aligned}
& F C_{X}^{S^{1}}: \mathbf{I}_{X} \\
&\left(H^{+}, J^{+}\right) \longmapsto \mathbf{h C o m p} \\
& \downarrow \longmapsto\left(F C^{S^{1}}\left(X, H^{+}, J^{+}\right), \partial^{+}, U^{+}\right) \\
&\left(H^{-}, J^{-}\right) \longmapsto\left(F \phi^{-,+}\right. \\
&\left.S^{1}\left(X, H^{-}, J^{-}\right), \partial^{-}, U^{-}\right),
\end{aligned}
$$

The $S^{1}$-equivariant Floer homology of $X$ is the functor $F H_{X}^{S^{1}}=H \circ F C_{X}^{S^{1}}$. The positive $S^{1}$-equivariant Floer homology of $X$ is the functor $F H_{X}^{S^{1},+}$ given by

$$
\begin{aligned}
F H_{X}^{S^{1},+}(H, J) & :=F H^{S^{1},(\varepsilon,+\infty)}(X, H, J) \\
& =F H^{S^{1}}(X, H, J) / F H^{S^{1}, \varepsilon}(X, H, J) .
\end{aligned}
$$

Definition 5.28. For $(X, \lambda)$ is a nondegenerate Liouville domain, the $S^{1}$-equivariant symplectic homology of $X$ is the object in Mod given by $S H^{S^{1}}(X, \lambda):=\operatorname{colim} F H_{X}^{S^{1}}$. The positive $S^{1}$-equivariant symplectic homology of $X$ is given by

$$
\begin{aligned}
S H^{S^{1},+}(X, \lambda) & :=\operatorname{colim} F H_{X}^{S^{1},+} \\
& =S H^{S^{1},(\varepsilon,+\infty)}(X, \lambda) \\
& =S H^{S^{1}}(X, \lambda) / S H^{S^{1}, \varepsilon}(X, \lambda)
\end{aligned}
$$

### 5.4 Viterbo transfer map of a Liouville embedding

Our goal is to prove that $S H^{S^{1}}$ is a contravariant functor from a suitable category of Liouville domains onto Mod. More specifically, suppose that $\left(V, \lambda_{V}\right)$ and $\left(W, \lambda_{W}\right)$ are nondegenerate Liouville domains and $\varphi:\left(V, \lambda_{V}\right) \longrightarrow\left(W, \lambda_{W}\right)$ is a 0 -codimensional strict generalized Liouville embedding. We will define a Viterbo transfer map

$$
\begin{aligned}
& \varphi_{!}: \quad S H^{S^{1}}\left(W, \lambda_{W}\right) \longrightarrow S H^{S^{1}}\left(V, \lambda_{V}\right) \\
& \varphi_{!}: S H^{S^{1},+}\left(W, \lambda_{W}\right) \longrightarrow S H^{S^{1},+}\left(V, \lambda_{V}\right)
\end{aligned}
$$

which is a morphism in Mod. We will start by definition the Viterbo transfer map in the case where $\varphi$ is a Liouville embedding instead of just a generalized Liouville embedding. Consider the completions $\hat{V}$ and $\hat{W}$ of $V$ and $W$ respectively, as well as the induced map $\hat{\varphi}: \hat{V} \longrightarrow \hat{W}$. Choose $R$ so small that $\hat{\varphi}(V \cup([0, R] \times \partial V)) \subset W$. We define

$$
\begin{aligned}
\varepsilon_{V} & :=\frac{1}{2} \min \operatorname{Spec}\left(\partial V, \lambda_{V}\right), \\
\varepsilon_{W} & :=\frac{1}{2} \min \operatorname{Spec}\left(\partial W, \lambda_{W}\right), \\
\varepsilon & :=\min \left\{\varepsilon_{V}, \varepsilon_{W}\right\}
\end{aligned}
$$

Definition 5.29. A stair parametrized Hamiltonian is a map $\bar{H}: S^{1} \times S^{2 N+1} \times \hat{W} \longrightarrow \mathbb{R}$ such that $\bar{H}$ satisfies the conditions in Items (2) to (5) from Definition 5.8 as well as the conditions in the Items below. We denote the set of such $\bar{H}$ by $\mathcal{H}(W, V, N)$.
(I) On $S^{1} \times S^{2 N+1} \times V$, we have that $\hat{\varphi}^{*} \bar{H}$ has values in $(0, \varepsilon)$, is $S^{1}$-independent and is $C^{2}$-close to a constant.
(II) On $S^{1} \times S^{2 N+1} \times\left[0, \delta_{V}\right] \times \partial V$, we have that $-\varepsilon<\hat{\varphi}^{*} \bar{H}<\varepsilon$ and $\hat{\varphi}^{*} \bar{H}$ is $C^{2}$-close to $(t, z, r, x) \longmapsto h_{\mathrm{II}}\left(e^{r}\right)$, where $h_{\mathrm{II}}:\left[1, e^{\delta_{V}}\right] \longrightarrow \mathbb{R}$ is increasing and strictly convex.
$\left(\mathrm{S}_{V}\right)$ On $S^{1} \times S^{2 N+1} \times\left[\delta_{V}, R-\delta_{V}\right] \times \partial V$, we have that $\hat{\varphi}^{*} \bar{H}(t, z, r, x)=C_{V} e^{r}+D_{V}$, for $D_{V} \in \mathbb{R}$ and $C_{V} \in \mathbb{R}_{>0} \backslash \operatorname{Spec}\left(\partial V,\left.\lambda_{V}\right|_{\partial V}\right) \cup \operatorname{Spec}\left(\partial W,\left.\lambda_{W}\right|_{\partial W}\right)$.
(III) On $S^{1} \times S^{2 N+1} \times\left[R-\delta_{V}, R\right] \times \partial V$, we have that $\hat{\varphi}^{*} \bar{H}$ is $C^{2}$-close to the function $(t, z, r, x) \longmapsto h_{\mathrm{III}}\left(e^{r}\right)$, where $h_{\mathrm{III}}:\left[e^{R-\delta_{V}}, e^{R}\right] \longrightarrow \mathbb{R}$ is increasing and strictly concave.
(IV) On $S^{1} \times S^{2 N+1} \times W \backslash \hat{\varphi}(V \cup[0, R] \times \partial V)$, the function $\bar{H}$ is $C^{2}$-close to a constant.
(V) On $S^{1} \times S^{2 N+1} \times\left[0, \delta_{W}\right] \times \partial W$, we have that $\bar{H}$ is $C^{2}$-close to $(t, z, r, x) \longmapsto h_{\mathrm{V}}\left(e^{r}\right)$, where $h:\left[1, e^{\delta_{W}}\right] \longrightarrow \mathbb{R}$ is increasing and strictly convex.
( $\mathrm{S}_{W}$ ) On $S^{1} \times S^{2 N+1} \times\left[\delta_{W},+\infty\right) \times \partial W$, we have that $\bar{H}(t, z, r, x)=C_{W} e^{r}+D_{W}$, for $D_{W} \in \mathbb{R}$ and $C_{W} \in \mathbb{R}_{>0} \backslash \operatorname{Spec}\left(\partial V,\left.\lambda_{V}\right|_{\partial V}\right) \cup \operatorname{Spec}\left(\partial W,\left.\lambda_{W}\right|_{\partial W}\right)$ such that $C_{W}<$ $e^{-\delta_{W}}\left(C_{V} e^{R-\delta_{V}}+D_{V}\right)$.

Remark 5.30. If $(z, \gamma) \in \hat{\mathcal{P}}(H)$, then either $\gamma$ is nonconstant and $\operatorname{im} \gamma$ is in region II, III or V, or $\gamma$ is constant and $\operatorname{im} \gamma$ is in region I or IV. There are no 1-periodic orbits in the slope regions $\mathrm{S}_{V}$ and $\mathrm{S}_{W}$.

Lemma 5.31. The actions of 1-periodic orbits of $\bar{H}$ are ordered according to

$$
\mathcal{A}_{\bar{H}}(\mathrm{IV})<\mathcal{A}_{\bar{H}}(\mathrm{~V})<0<\mathcal{A}_{\bar{H}}(\mathrm{I})<\varepsilon<\mathcal{A}_{\bar{H}}(\mathrm{II}) .
$$

Proof. Consider Fig. 5.2. By Lemma 2.43 and Definition 5.29, we have that $\mathcal{A}_{\bar{H}}$ is constant in regions I, $\mathrm{S}_{V}$, IV and $\mathrm{S}_{W}, \mathcal{A}_{\bar{H}}$ is strictly increasing in regions II and V, and $\mathcal{A}_{\bar{H}}$ is strictly decreasing in region III. From this reasoning, we conclude that $\mathcal{A}_{\bar{H}}(\mathrm{IV})<\mathcal{A}_{\bar{H}}(\mathrm{~V})$ and $0<\mathcal{A}_{\bar{H}}(\mathrm{I})<\varepsilon$. By the same argument as in the proof of Lemma 5.15, we conclude that $\varepsilon<\mathcal{A}_{\bar{H}}(\mathrm{II})$. We show that $\mathcal{A}_{\bar{H}}(\mathrm{~V})<0$.

$$
\begin{array}{ll}
\mathcal{A}_{\bar{H}}(\mathrm{~V}) & \\
\quad=e^{r_{W}} T\left(r_{W}\right)-H\left(r_{W}\right) & \\
\quad<e^{r_{W}} C_{W}-H\left(r_{W}\right) & {\left[T\left(\delta_{W}\right)=C_{W} \text { and } T^{\prime}=\exp \cdot h_{V}^{\prime \prime} \circ \exp >0\right]} \\
<e^{r_{W}} C_{W}-\left(C_{V} e^{R-\delta_{V}}+D_{V}\right) & {\left[H\left(r_{W}\right)>H\left(R-\delta_{V}\right)=C_{V} e^{R-\delta_{V}}+D_{V}\right]} \\
\quad<e^{\delta_{W}} C_{W}-\left(C_{V} e^{R-\delta_{V}}+D_{V}\right) & {\left[\text { since } r_{W}<\delta_{W}\right]} \\
\quad<0 &
\end{array}
$$



Figure 5.2: Action of a 1-periodic orbit of $\bar{H}$

Definition 5.32. A stair parametrized almost complex structure is a map $\bar{J}: S^{1} \times$ $S^{2 N+1} \times \hat{W} \longrightarrow \operatorname{End}(T \hat{W})$ satisfying the conditions in Items (1) to (4) below. We denote the set of such $\bar{J}$ by $\mathcal{J}(W, V, N)$.
(1) $\bar{J}$ is $S^{1}$-invariant.
(2) $\bar{J}$ is $\hat{\omega}$-compatible.
(3) $\bar{J}$ is cylindrical on $S^{1} \times S^{2 N+1} \times[0, \delta] \times \partial V$ and on $S^{1} \times S^{2 N+1} \times \mathbb{R}_{\geq 0} \times \partial W$.
(4) $\left(\tilde{\iota}_{0}^{N, N-1}\right)^{*} \bar{J}=\left(\tilde{\iota}_{1}^{N, N-1}\right)^{*} \bar{J}$.

Definition 5.33. Define sets

$$
\begin{aligned}
& \mathbf{I}_{W, V}:=\left\{\begin{array}{l|l}
(\bar{H}, \bar{J}) & \begin{array}{l}
\bar{H} \in \mathcal{H}(W, V, N) \\
(\bar{H}, \bar{J}) \text { is regular }
\end{array}
\end{array} \text { and } \bar{J} \in \mathcal{J}(W, V, N) \text { for some } N, ~ 子,\right. \\
& \mathbf{K}_{W, V}:=\left\{\begin{array}{l|l}
(H, J, \bar{H}, \bar{J}) & \begin{array}{l}
H \in \mathcal{H}(W, N), J \in \mathcal{J}(W, N), \\
\bar{H} \in \mathcal{H}(W, V, N) \text { and } \bar{J} \in \mathcal{J}(W, V, N) \text { for some } N, \\
H \leq \bar{H}, \text { and }(H, J) \text { and }(\bar{H}, \bar{J}) \text { are regular }
\end{array}
\end{array}\right\} .
\end{aligned}
$$

Define preorders on $\mathbf{I}_{W, V}$ and $\mathbf{K}_{W, V}$ by

$$
\begin{aligned}
\left(\bar{H}^{+}, \bar{J}^{+}\right) \leq\left(\bar{H}^{-}, \bar{J}^{-}\right): \Longleftrightarrow\left\{\begin{array}{l}
N^{+} \leq N^{-} \\
\bar{H}^{+} \leq\left(\tilde{i}_{0}^{N^{-}, N^{+}}\right)^{*} \bar{H}^{-},
\end{array}\right. \\
\left(H^{+}, J^{+}, \bar{H}^{+}, \bar{J}^{+}\right) \leq\left(H^{-}, J^{-}, \bar{H}^{-}, \bar{J}^{-}\right): \Longleftrightarrow\left\{\begin{array}{l}
N^{+} \leq N^{-}, \\
H^{+} \leq\left(\tilde{i_{0}} 0^{-}, N^{+}\right. \\
\bar{H}^{+} \leq\left(\tilde{i}_{0}^{N^{-}, N^{+}}\right)^{*} H^{-} \\
\bar{H}^{-}
\end{array}\right.
\end{aligned}
$$

Definition 5.34. Define a function $\pi_{W, V, N}^{\mathcal{H}}: \mathcal{H}(W, V, N) \longrightarrow \mathcal{H}(V, N)$ by $\pi_{W, V, N}^{\mathcal{H}}(\bar{H})=$ $\bar{H}_{V}$, where

$$
\bar{H}_{V}(t, z, x):= \begin{cases}\bar{H}(t, z, \hat{\varphi}(x)) & \text { if } x \in V \cup([0, R] \times \partial V), \\ C_{V} e^{r}+D_{V} & \text { if } x=(r, y) \in[R,+\infty) \times \partial V\end{cases}
$$

Define a function $\pi_{W, V, N}^{\mathcal{J}}: \mathcal{J}(W, V, N) \longrightarrow \mathcal{J}(V, N)$ by $\pi_{W, V, N}^{\mathcal{J}}(\bar{J})=\bar{J}_{V}$, where

$$
\bar{J}_{V}(t, z, x):= \begin{cases}\mathrm{D} \hat{\varphi}^{-1}(\hat{\varphi}(x)) \circ \bar{J}(t, z, \hat{\varphi}(x)) \circ \mathrm{D} \hat{\varphi}(x) & \text { if } x \in V \cup([0, R] \times \partial V), \\ \mathrm{D} \hat{\varphi}^{-1}(\hat{\varphi}(0, y)) \circ \bar{J}(t, z, \hat{\varphi}(0, y)) \circ \mathrm{D} \hat{\varphi}(0, y) & \text { if } x=(r, y) \in[0,+\infty) \times \partial V .\end{cases}
$$

Definition 5.35. Define the functors

$$
\begin{aligned}
& \pi_{W}: \mathbf{K}_{W, V} \longrightarrow \mathbf{I}_{W}, \quad \text { given by } \pi_{W}(H, J, \bar{H}, \bar{J}):=(H, J), \\
& \pi_{W, V}: \mathbf{K}_{W, V} \longrightarrow \mathbf{I}_{W, V}, \text { given by } \pi_{W}(H, J, \bar{H}, \bar{J}):=(\bar{H}, \bar{J}), \\
& \pi_{W, V}^{\mathcal{H} \times \mathcal{J}}: \mathbf{I}_{W, V} \longrightarrow \mathbf{I}_{V}, \quad \text { given by } \pi_{W, V}^{\mathcal{H} \times \mathcal{J}}(\bar{H}, \bar{J}):=\left(\pi_{W, V, N}^{\mathcal{H}}(\bar{H}), \pi_{W, V, N}^{\mathcal{J}}(\bar{J})\right)=\left(\bar{H}_{V}, \bar{J}_{V}\right), \\
& \text { for }(\bar{H}, \bar{J}) \in \mathcal{H}(W, V, N) \times \mathcal{J}(W, V, N) . \text { Let } \pi_{V}:=\pi_{W, V}^{\mathcal{H} \times \mathcal{J}} \circ \pi_{W, V}: \mathbf{K}_{W, V} \longrightarrow \mathbf{I}_{V} .
\end{aligned}
$$

Definition 5.36. Let $H^{+} \in \mathcal{H}\left(W, N^{+}\right)$be an admissible parametrized Hamiltonian and $H^{-} \in \mathcal{H}\left(W, V, N^{-}\right)$be a stair parametrized Hamiltonian. Assume that $N^{+} \leq N^{-}$and $\left(\tilde{i}_{0}^{N^{-}, N^{+}}\right) H^{+} \leq H^{-}$. An admissible homotopy of parametrized Hamiltonians from $H^{-}$ to $H^{+}$is a map $H: \mathbb{R} \times S^{1} \times S^{2 N^{+}+1} \times \hat{W} \longrightarrow \mathbb{R}$ which satisfies the conditions in Items (1) to (3) for some $s_{0}>0$, where $H_{s}(t, z, x)=H(s, t, z, x)$. We denote the set of such $H$ by $\mathcal{H}\left(H^{+}, H^{-}\right)$.
(1) For every $s \in\left(-s_{0}, s_{0}\right)$, we have that $H_{s}$ satisfies all the conditions in Definition 5.29 with the exceptions that $C_{W, s}$ and $C_{V, s}$ are possibly in $\operatorname{Spec}\left(\partial W,\left.\lambda_{W}\right|_{\partial W}\right) \cup$ $\operatorname{Spec}\left(\partial V,\left.\lambda_{V}\right|_{\partial V}\right)$ and $H_{s, z}$ is not necessarily nondegenerate for $z \in \operatorname{CritPt} \tilde{f}_{N^{+}}$.
(2) For every $s$, if $\pm s \geq s_{0}$ then $H_{s}=\left(\tilde{i}_{0}^{N^{ \pm}, N^{+}}\right)^{*} H^{ \pm}$.
(3) For every $(s, t, z, x) \in \mathbb{R} \times S^{1} \times S^{2 N^{+}+1} \times \hat{W}$ we have $\partial_{s} H(s, t, x, z) \leq 0$.

Remark 5.37. In Definition 5.36, the parameters of $H_{s}$ depend on $s$. In particular, the "constant" value that $H_{s}$ takes in regions I and IV is dependent on $s$. However, the parameter $R$ does not depend on $s$.

Definition 5.38. Let $J^{+} \in \mathcal{J}\left(W, N^{+}\right)$be an admissible parametrized almost complex structure and $J^{-} \in \mathcal{J}\left(W, V, N^{-}\right)$be a stair parametrized almost complex structure. An admissible homotopy of parametrized almost complex structures from $J^{-}$to $J^{+}$is a map $J: \mathbb{R} \times S^{1} \times S^{2 N^{+}+1} \times \hat{W} \longrightarrow \operatorname{End}(T \hat{W})$ which satisfies the conditions in Items (1) and (2) for some $s_{0}>0$, where $J_{s}(t, z, x)=J(s, t, z, x)$. We denote the set of such $J$ by $\mathcal{J}\left(J^{+}, J^{-}\right)$.
(1) For every $s \in\left(-s_{0}, s_{0}\right)$, we have that $J_{s}$ satisfies all the conditions in Definition 5.32.
(2) For every $s$, if $\pm s \geq s_{0}$ then $J_{s}=\left(\tilde{i}_{0}^{N^{ \pm}, N^{+}}\right)^{*} J^{ \pm}$.

Remark 5.39. Let $(H, J, \bar{H}, \bar{J}) \in \mathbf{K}_{W, V}$ and consider $\pi_{W}(K)=(H, J) \in \mathbf{I}_{W}$ and $\pi_{W, V}(K)=(\bar{H}, \bar{J}) \in \mathbf{I}_{W, V}$. In Section 5.3 we defined $F C^{S^{1}}(W, H, J)$, the Floer chain complex of $W$ with respect to the auxiliary data $(H, J)$, for every $(H, J) \in \mathbf{I}_{W}$. Despite the fact that $(\bar{H}, \bar{J})$ is not an element of $\mathbf{I}_{W}$, the Floer Chain complex $F C^{S^{1}}(W, \bar{H}, \bar{J})$ of $W$ with respect to the auxiliary data $(\bar{H}, \bar{J})$ is well-defined. More precisely, it is possible to replicate the results of Section 5.3 but with the category $\mathbf{I}_{W, V}$ instead of $\mathbf{I}_{W}$. Then, we can define a functor

$$
\begin{aligned}
F C_{W}^{\mathrm{I}-\mathrm{V}}: \mathbf{I}_{W, V} & \longrightarrow \mathbf{h C o m p} \\
(\bar{H}, \bar{J}) & \longmapsto F C_{W}^{\mathrm{I-V}}(\bar{H}, \bar{J}):=F C^{S^{1}}(W, \bar{H}, \bar{J}) .
\end{aligned}
$$

For every $\left(H^{+}, J^{+}, H^{-}, J^{-}\right) \in \mathbf{K}_{W, V}$, we have that $H^{+} \leq H^{-}$, and therefore we can define a continuation map $\phi^{-,+}: F C^{S^{1}}\left(W, H^{+}, J^{+}\right) \longrightarrow F C^{S^{1}}\left(W, H^{-}, J^{-}\right)$which is given by counting solutions of the Floer equation with respect to $H \in \mathcal{H}\left(H^{+}, H^{-}\right)$and $J \in$ $\mathcal{J}\left(J^{+}, J^{-}\right)$. These continuation maps assemble into a natural transformation

$$
\phi: F C_{W}^{S^{1}} \circ \pi_{W} \longrightarrow F C_{W}^{\mathrm{I}-\mathrm{V}} \circ \pi_{W, V} .
$$

Definition 5.40. We define a functor $F C_{W}^{\text {III,IV,V }}: \mathbf{I}_{W, V} \longrightarrow \mathbf{h C o m p}$ as follows. If $(\bar{H}, \bar{J}) \in \mathbf{I}_{W, V}$, then the module $F C_{W}^{\mathrm{IIIIIV}, \mathrm{V}}(\bar{H}, \bar{J}):=F C^{\mathrm{III}, \mathrm{IV}, \mathrm{V}}(W, \bar{H}, \bar{J})$ is the submodule
of $F C^{\mathrm{I}-\mathrm{V}}(W, \bar{H}, \bar{J})$ which is generated by (equivalence classes of) 1-periodic orbits $[z, \gamma]$ of $\bar{H}$ such that im $\gamma$ is in region III, IV or V. The maps

$$
\begin{array}{cc}
\partial: & F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}(W, \bar{H}, \bar{J}) \longrightarrow F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}(W, \bar{H}, \bar{J}), \\
U: \quad F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}(W, \bar{H}, \bar{J}) \longrightarrow F C^{\mathrm{II}, \mathrm{IV}, \mathrm{~V}}(W, \bar{H}, \bar{J}), \\
\phi^{-,+}: & F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}\left(W, \bar{H}^{+}, \bar{J}^{+}\right) \longrightarrow F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}\left(W, \bar{H}^{-}, \bar{J}^{-}\right) .
\end{array}
$$

are the restrictions (see Lemma 5.41) of the maps

$$
\begin{aligned}
& \partial: \quad F C^{\mathrm{I}-\mathrm{V}}(W, \bar{H}, \bar{J}) \longrightarrow F C^{\mathrm{I}-\mathrm{V}}(W, \bar{H}, \bar{J}), \\
& U: \quad F C^{\mathrm{I}-\mathrm{v}}(W, \bar{H}, \bar{J}) \longrightarrow F C^{\mathrm{I}-\mathrm{v}}(W, \bar{H}, \bar{J}), \\
& \phi^{-,+}: F C^{\mathrm{I}-\mathrm{V}}\left(W, \bar{H}^{+}, \bar{J}^{+}\right) \longrightarrow F C^{\mathrm{I}-\mathrm{V}}\left(W, \bar{H}^{-}, \bar{J}^{-}\right),
\end{aligned}
$$

This completes the definition of $F C_{W}^{\mathrm{III}, \mathrm{IV}, \mathrm{V}}$. Since $F C^{\mathrm{III}, \mathrm{IV}, \mathrm{V}}(W, \bar{H}, \bar{J})$ is a subcomplex of $F C^{\mathrm{I}-\mathrm{V}}(W, \bar{H}, \bar{J})$, we have an inclusion natural transformation $\iota: F C_{W}^{\mathrm{III}, \mathrm{IV}, \mathrm{V}} \longrightarrow F C_{W}^{\mathrm{I}-\mathrm{V}}$.
Lemma 5.41. In Definition 5.40, the maps $\partial, U$ and $\phi^{-,+}$restrict to maps on $F C_{W}^{\mathrm{IIIIV}, \mathrm{V}}$.
Proof. To show that $U$ restricts to a map on $F C_{W}^{\text {III,IV,V }}$, we simply note that by definition $U$ affects only $z$ and not $\gamma$.

We show that $\partial$ restricts to a map on $F C_{W}^{\mathrm{IIIIIV}, \mathrm{V}}$. For this, let $\left[z^{ \pm}, \gamma^{ \pm}\right] \in \mathcal{P}(\bar{H})$ be such that $\operatorname{im} \gamma^{+}$is in region III, IV or V and assume that there exists a Floer trajectory from $\left[z^{+}, \gamma^{+}\right]$to $\left[z^{-}, \gamma^{-}\right]$with respect to $(\bar{H}, \bar{J})$. We need to show that im $\gamma^{-}$is in region III, IV or V. Assume by contradiction that im $\gamma^{-}$is in region I or II. In the case where $\operatorname{im} \gamma^{+}$is in region IV or V , the computation

$$
\begin{array}{rlr}
0 & <\mathcal{A}_{\bar{H}}\left(z^{-}, \gamma^{-}\right) & \text {[by Lemma 5.31] } \\
\leq \mathcal{A}_{\bar{H}}\left(z^{+}, \gamma^{+}\right) & {[\text {by Lemma 4.37] }} \\
<0 & & {[\text { by Lemma } 5.31]}
\end{array}
$$

gives a contradiction. It remains to derive a contradiction in the case where im $\gamma^{+}$is in region III. By Corollary 2.42, $\gamma^{+}$is (approximately) of the form $\gamma^{+}(t)=\left(r^{+}, \rho^{+}(t)\right)$ for some Reeb orbit $\rho^{+}$in $\left(\partial V,\left.\lambda_{V}\right|_{\partial V}\right)$. The "no escape" lemma (Lemma 4.41) implies that the Floer trajectory is inside $\hat{\varphi}\left(V \cup\left[0, r^{+}\right] \times \partial V\right)$, while the "asymptotic behaviour" lemma (Lemma 4.40) implies that the Floer trajectory must leave $\hat{\varphi}\left(V \cup\left[0, r^{+}\right] \times \partial V\right)$. This completes the proof that $\partial$ restricts to a map on $F C_{W}^{\text {III,IV,V }}$.

To show that $\phi^{-,+}$restricts to a map on $F C_{W}^{\text {III,IV,V }}$, we would use a proof analogous to that of $\partial$. The key difference is that now the Floer trajectory would be defined with respect to homotopies of Hamiltonians and almost complex structures. This does not affect the proof because Lemmas 4.37, 4.40 and 4.41 also apply to homotopies.

Definition 5.42. Define a functor $F C_{W}^{1, I I}: \mathbf{I}_{W, V} \longrightarrow \mathbf{h C o m p}$ as follows. For $(\bar{H}, \bar{J}) \in$ $\mathbf{I}_{W, V}$, the module $F C_{W}^{\mathrm{IIII}}(\bar{H}, \bar{J}):=F C^{\mathrm{I}, \mathrm{II}}(W, \bar{H}, \bar{J})$ is given by the quotient

$$
F C^{\mathrm{I}, \mathrm{II}}(W, \bar{H}, \bar{J}):=F C^{\mathrm{I}-\mathrm{V}}(W, \bar{H}, \bar{J}) / F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}(W, \bar{H}, \bar{J})
$$

For $\left(\bar{H}^{+}, \bar{J}^{+}\right) \leq\left(\bar{H}^{-}, \bar{J}^{-}\right) \in \mathbf{I}_{W, V}$, the continuation map $\phi^{-,+}: F C^{\mathrm{I}, \mathrm{II}}\left(W, \bar{H}^{+}, \bar{J}^{+}\right) \longrightarrow$ $F C^{\text {I,II }}\left(W, \bar{H}^{-}, \bar{J}^{-}\right)$is the unique map such that the diagram

$$
\begin{gathered}
F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}\left(W, \bar{H}^{+}, \bar{J}^{+}\right) \xrightarrow[\phi^{+},+]{\iota} \underset{\iota^{+}}{\longrightarrow} F C^{\mathrm{I}-\mathrm{V}}\left(W, \bar{H}^{+}, \bar{J}^{+}\right) \xrightarrow{\pi^{+}} F C^{\mathrm{I}, \mathrm{II}}\left(W, \bar{H}^{+}, \bar{J}^{+}\right) \\
F C^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}\left(W, \bar{H}^{-}, \bar{J}^{-}\right) \underset{\iota^{-,+}}{\longrightarrow} F C^{\mathrm{I}-\mathrm{V}}\left(W, \bar{H}^{-}, \bar{J}^{-}\right) \xrightarrow[\pi^{-}]{\longrightarrow} F C^{\mathrm{I}, \mathrm{II}}\left(W, \bar{H}^{-}, \bar{J}^{-}\right)
\end{gathered}
$$

commutes. There is a projection natural transformation $\pi: F C_{W}^{\mathrm{I}-\mathrm{V}} \longrightarrow F C_{W}^{\mathrm{I}, \mathrm{II}}$.
Definition 5.43. We define a natural transformation $\eta: F C_{V}^{S^{1}} \circ \pi_{W, V}^{\mathcal{H} \times \mathcal{J}} \longrightarrow F C_{W}^{1,1 I}$ as follows. For $(\bar{H}, \bar{J}) \in \mathbf{I}_{W, V}$, the map $\eta^{\bar{H}, \bar{J}}: F C^{S^{1}}\left(V, \bar{H}_{V}, \bar{J}_{V}\right) \longrightarrow F C^{\mathrm{I}, \mathrm{II}}(W, \bar{H}, \bar{J})$ is given by $\eta^{\bar{H}, \bar{J}}([z, \gamma]):=[z, \hat{\varphi} \circ \gamma]$.
Lemma 5.44. Definition 5.43 is well posed, i.e.:
(1) $\eta^{\bar{H}, \bar{J}}$ is well-defined and it is a morphism of filtered modules.
(2) $\eta^{\bar{H}, \bar{J}}$ commutes with the $U$ map.
(3) $\eta^{\bar{H}, \bar{J}}$ is a chain map.
(4) The maps $\eta^{\bar{H}, \bar{J}}$ assemble into a natural transformation.

Proof. (1): Since $\hat{\varphi}$ is a Liouville embedding, if $[z, \gamma] \in \mathcal{P}\left(\bar{H}_{V}\right)$ then $[z, \hat{\varphi} \circ \gamma] \in \mathcal{P}(\bar{H})$ and $\mathcal{A}_{\bar{H}}(z, \hat{\varphi} \circ \gamma)=\mathcal{A}_{\bar{H}_{V}}(z, \gamma)$.
(2): We need to show that $U_{W} \circ \eta^{\bar{H}, \bar{J}}([z, \gamma])=\eta^{\bar{H}, \bar{J}} \circ U_{V}([z, \gamma])$, for $[z, \gamma] \in \mathcal{P}\left(\bar{H}_{V}\right)$. If $\mu_{\mathrm{M}}(z)=0$, then both sides of the equation are 0 . If $\mu_{\mathrm{M}}(z)>0$, then

$$
\begin{aligned}
U_{W} \circ \eta^{\bar{H}, \bar{J}}([z, \gamma]) & =U_{W}([z, \hat{\varphi} \circ \gamma]) & & {[\text { by definition of } \eta] } \\
& =[S(z), \hat{\varphi} \circ \gamma] & & {[\text { by definition of } U] } \\
& =\eta^{\bar{H}, \bar{J}}[S(z), \gamma] & & {[\text { by definition of } \eta] } \\
& =\eta^{\bar{H}, \bar{J}} \circ U_{V}([z, \gamma]) & & {[\text { by definition of } U] . }
\end{aligned}
$$

(3): We need to show that $\eta^{\bar{H}, \bar{J}} \circ \partial_{V}\left(\left[z^{+}, \gamma^{+}\right]\right)=\partial_{W} \circ \eta^{\bar{H}, \bar{J}}\left(\left[z^{+}, \gamma^{+}\right]\right)$, for every $\left[z^{+}, \gamma^{+}\right] \in$ $\mathcal{P}\left(\bar{H}_{V}\right)$. By the "no escape" lemma (Lemma 4.41), if $\left[z^{-}, \gamma^{-}\right] \in \mathcal{P}\left(\bar{H}_{V}\right)$ then the map

$$
\begin{aligned}
\mathcal{M}\left(\bar{H}_{V}, \bar{J}_{V},\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right) & \longrightarrow \mathcal{M}\left(\bar{H}, \bar{J},\left[z^{+}, \hat{\varphi} \circ \gamma^{+}\right],\left[z^{-}, \hat{\varphi} \circ \gamma^{-}\right]\right) \\
{[w, u] } & \longmapsto[w, \hat{\varphi} \circ u]
\end{aligned}
$$

is an orientation preserving diffeomorphism. Then, we compute

$$
\begin{aligned}
& \eta^{\bar{H}, \bar{J}} \circ \partial_{V}\left(\left[z^{+}, \gamma^{+}\right]\right) \\
&=\sum_{\left[z^{-}, \gamma^{-}\right] \in \mathcal{P}\left(\bar{H}_{V}\right)} \# \mathcal{M}\left(\bar{H}_{V}, \bar{J}_{V},\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right) \cdot \eta^{\bar{H}, \bar{J}}\left(\left[z^{-}, \gamma^{-}\right]\right) \\
& \quad=\sum_{\left[z^{-}, \gamma^{-}\right] \in \mathcal{P}\left(\bar{H}_{V}\right)} \# \mathcal{M}\left(\bar{H}_{V}, \bar{J}_{V},\left[z^{+}, \gamma^{+}\right],\left[z^{-}, \gamma^{-}\right]\right) \cdot\left[z^{-}, \hat{\varphi} \circ \gamma^{-}\right]
\end{aligned}
$$

$$
\begin{aligned}
& =\sum_{\left[z^{-}, \gamma^{-}\right] \in \mathcal{P}\left(\bar{H}_{V}\right)} \# \mathcal{M}\left(\bar{H}, \bar{J},\left[z^{+}, \hat{\varphi} \circ \gamma^{+}\right],\left[z^{-}, \hat{\varphi} \circ \gamma^{-}\right]\right) \cdot\left[z^{-}, \hat{\varphi} \circ \gamma^{-}\right] \\
& =\sum_{\left[z^{-}, \gamma_{W}^{-}\right] \in \mathcal{P}^{1}, 11}(\bar{H}) \\
& =\sum_{\left[z^{-}, \gamma_{W}^{-}\right] \in \mathcal{P}(\bar{H})} \# \mathcal{M}\left(\bar{H}, \bar{J},\left[z^{-}, \gamma_{W}^{-}\right],\left[z^{+}, \gamma_{W}^{+}\right]\right) \cdot\left[z^{-}, \gamma_{W}^{-}\right] \\
& =\partial_{W}\left[\left[z^{-}, \gamma_{W}^{-}\right],\left[z^{+}, \gamma_{W}^{+}\right]\right) \cdot\left[z^{-}, \gamma_{W}^{-}\right] \\
& =\partial_{W} \circ \eta^{\bar{H}, \bar{J}}\left(\left[z^{+}, \gamma^{+}\right]\right) .
\end{aligned}
$$

In this computation, in the third equality we used the orientation preserving diffeomorphism defined above, in the fourth equality we performed the variable change $\left[z^{-}, \gamma_{W}^{-}\right]:=$ $\left[z^{-}, \hat{\varphi} \circ \gamma^{-}\right] \in \mathcal{P}^{\mathrm{I}, \mathrm{II}}(\bar{H})$ and in the fifth equality we used the fact that if $\left[z^{-}, \gamma_{W}^{-}\right] \in$ $\mathcal{P}^{\text {III,IIV,V }}(\bar{H})$ then $\left[z^{-}, \gamma_{W}^{-}\right]=0$ as an element of $F C^{\mathrm{I}, \mathrm{II}}(W, \bar{H}, \bar{J})$.
(4): This proof is analogous to that of (3).

Proposition 5.45. The map $\eta: F C_{V}^{S^{1}} \circ \pi_{W, V}^{\mathcal{H} \times \mathcal{J}} \longrightarrow F C_{W}^{\mathrm{I}, \mathrm{II}}$ is a natural isomorphism.

Proof. It suffices to show that $\eta^{\bar{H}, \bar{J}}: F C^{S^{1}}\left(V, \bar{H}_{V}, \bar{J}_{V}\right) \longrightarrow F C^{\mathrm{I}, \mathrm{II}}(W, \bar{H}, \bar{J})$ admits an inverse as a map of $\mathbb{Q}$-modules. Define $\nu^{\bar{H}, \bar{J}}: F C^{\mathrm{I}-\mathrm{V}}(W, \bar{H}, \bar{J}) \longrightarrow F C^{S^{1}}\left(V, \bar{H}_{V}, \bar{J}_{V}\right)$ by

$$
\nu^{\bar{H}, \bar{J}}([z, \gamma])= \begin{cases}{\left[z, \hat{\varphi}^{-1} \circ \gamma\right]} & \text { if }[z, \gamma] \in \mathcal{P}^{\mathrm{I}, \mathrm{II}}(\bar{H}), \\ 0 & \text { if }[z, \gamma] \in \mathcal{P}^{\mathrm{III}, \mathrm{IV}, \mathrm{~V}}(\bar{H}) .\end{cases}
$$

Then, by the universal property of the quotient of $\mathbb{Q}$-modules, $\nu^{\bar{H}, \bar{J}}$ descends to a map $\nu^{\overline{\bar{H}}, \bar{J}}: F C^{\mathrm{I}, \mathrm{II}}(W, \bar{H}, \bar{J}) \longrightarrow F C^{S^{1}}\left(V, \bar{H}_{V}, \bar{J}_{V}\right)$, which is the inverse of $\eta^{\bar{H}, \bar{J}}$.

Definition 5.46. The Viterbo transfer map, $\varphi_{!}: S H^{S^{1}}\left(W, \lambda_{W}\right) \longrightarrow S H^{S^{1}}\left(V, \lambda_{V}\right)$, is given as follows. Consider the following diagram in the category of functors from $\mathbf{K}_{W, V}$ to hComp:


Passing to homology, we get a natural transformation $H \varphi: F H_{W}^{S^{1}} \circ \pi_{W} \longrightarrow F H_{V}^{S^{1}} \circ \pi_{V}$. Then, $\varphi!$ is the unique map such that the following diagram commutes:


We define the Viterbo transfer map on positive $S^{1}$-equivariant symplectic homology by declaring it to be the unique map such that the following diagram commutes:


Remark 5.47. We have the following observations about Definition 5.46.
(1) In diagram (5.4), we view colim $F H_{W}^{S^{1}} \circ \pi_{W}$ and colim $F H_{V}^{S^{1}} \circ \pi_{V}$ as constant functors, and we view $\varphi_{!}:$colim $F H_{W}^{S^{1}} \circ \pi_{W} \longrightarrow \operatorname{colim} F H_{V}^{S^{1}} \circ \pi_{V}$ as a constant natural transformation, which is just a map. Existence and uniqueness of $\varphi$ comes from the universal property of colimits.
(2) Since $\pi_{W}\left(\mathbf{K}_{W, V}\right)$ is a cofinal subset of $\mathbf{I}_{W}$, we have $S H^{S^{1}}\left(W, \lambda_{W}\right)=\operatorname{colim} F H_{W}^{S^{1}}=$ colim $F H_{W}^{S^{1}} \circ \pi_{W}$, and analogously for $V$.
(3) We are also using the fact that

$$
\begin{aligned}
S H^{S^{1},+}\left(W, \lambda_{W}\right) & =S H^{S^{1}}\left(W, \lambda_{W}\right) / S H^{S^{1}, \varepsilon_{W}}\left(W, \lambda_{W}\right) \\
& =S H^{S^{1}}\left(W, \lambda_{W}\right) / S H^{S^{1}, \varepsilon}\left(W, \lambda_{W}\right) .
\end{aligned}
$$

This is true because $S H^{S^{1}}$ is obtained as a direct limit of Floer homologies for increasing Hamiltonians, and for $(H, J) \in \mathbf{I}_{W}$ with $H$ big enough we have that $H$ restricted to the interior of $W$ takes values in $(-\varepsilon, 0) \subset\left(-\varepsilon_{W}, 0\right)$ (and analogously for $V)$.

Let Liouv ${ }_{\text {ndg }}$ be the category whose objects are nondegenerate Liouville domains and whose morphisms are 0-codimensional Liouville embeddings which are either strict or diffeomorphisms.

Theorem 5.48 ([Gut14, Theorem 3.1.16]). The following are contravariant functors:

$$
\begin{array}{rlrl}
S H^{S^{1}}: \text { Liouv }_{\text {ndg }} & \longrightarrow \operatorname{Mod} & S H^{S^{1},+}: \text { Liouv }_{\text {ndg }} & \longrightarrow \operatorname{Mod} \\
\left(V, \lambda_{V}\right) & \longmapsto S H^{S^{1}}\left(V, \lambda_{V}\right) & \left.\longmapsto \lambda_{V}\right) & \longmapsto S H^{S^{1},+}\left(V, \lambda_{V}\right) \\
\varphi & \longmapsto \uparrow \varphi_{!} & \longmapsto \uparrow \varphi_{!}^{+} \\
\left(W, \lambda_{W}\right) & \longmapsto S H^{S^{1}}\left(W, \lambda_{W}\right), & \left(W, \lambda_{W}\right) & \longmapsto S H^{S^{1},+}\left(W, \lambda_{W}\right) .
\end{array}
$$

### 5.5 Viterbo transfer map of a generalized Liouville embedding

We now define the Viterbo transfer map in the case where $\varphi:\left(V, \lambda_{V}\right) \longrightarrow\left(W, \lambda_{W}\right)$ is a generalized Liouville embedding, i.e. $\varphi^{*} \mathrm{~d} \lambda_{W}=\mathrm{d} \lambda_{V}$ and $\left.\left(\varphi^{*} \lambda_{W}-\lambda_{V}\right)\right|_{\partial V}$ is exact.

Lemma 5.49 ([GH18, Lemma 7.5]). If $\phi:\left(V, \lambda_{V}\right) \longrightarrow\left(W, \lambda_{W}\right)$ is a 0 -codimensional strict generalized Liouville embedding, then there exists a 1-form $\lambda_{W}^{\prime}$ on $W$ such that $\mathrm{d} \lambda_{W}^{\prime}=\mathrm{d} \lambda_{W}, \lambda_{W}^{\prime}=\lambda_{W}$ near $\partial W$ and $\phi^{*} \lambda_{W}^{\prime}=\lambda_{V}$.

Lemma 5.50. Let $\left(X, \lambda_{X}\right)$ and $\left(Y, \lambda_{Y}\right)$ be nondegenerate Liouville domains and assume that $\phi:\left(X, \lambda_{X}\right) \longrightarrow\left(Y, \lambda_{Y}\right)$ is a 0-codimensional strict Liouville embedding. Suppose that $\lambda_{X}^{\prime} \in \Omega^{1}(X)$ and $\lambda_{Y}^{\prime} \in \Omega^{1}(Y)$ are 1 -forms such that

$$
\begin{aligned}
\mathrm{d} \lambda_{X}^{\prime} & =\mathrm{d} \lambda_{X}, \quad \lambda_{X}^{\prime}=\lambda_{X} \text { near } \partial X, \\
\mathrm{~d} \lambda_{Y}^{\prime} & =\mathrm{d} \lambda_{Y}, \quad \lambda_{Y}^{\prime}=\lambda_{Y} \text { near } \partial Y, \\
\phi^{*} \lambda_{Y}^{\prime} & =\lambda_{X}^{\prime} .
\end{aligned}
$$

Then,

$$
\begin{aligned}
S H^{S^{1}}\left(X, \lambda_{X}\right) & =S H^{S^{1}}\left(X, \lambda_{X}^{\prime}\right) \\
S H^{S^{1},+}\left(X, \lambda_{X}\right) & =S H^{S^{1},+}\left(X, \lambda_{X}^{\prime}\right)
\end{aligned}
$$

and the diagrams

commute.
Proof. We note that the following concepts only depend on $\mathrm{d} \lambda_{X}$ and on $\lambda_{X}$ near $\partial X$ : the set of admissible Hamiltonians and admissible almost complex structures, the Hamiltonian vector field, action, the module which underlies the Floer complex (by all the previous statements), the Floer equation and the notion of Floer trajectories (also by the previous statements), the $U$ map, the differential and the continuation maps. All the statements follow immediately from the definitions given in Section 5.3, except the fact that the action actually only depends on $\mathrm{d} \lambda_{X}$ and on $\left.\lambda_{X}\right|_{\partial X}$. To prove this, it is enough to show that

$$
\begin{equation*}
\int_{S^{1}} \gamma^{*}\left(\hat{\lambda}_{X}-\hat{\lambda}_{X}^{\prime}\right)=0 \tag{5.6}
\end{equation*}
$$

Since $\hat{\lambda}_{X}-\hat{\lambda}_{X}^{\prime}$ is closed, it defines a cohomology class $\left[\hat{\lambda}_{X}-\hat{\lambda}_{X}^{\prime}\right] \in H_{\mathrm{dR}}^{1}(\hat{X})$. The orbit $\gamma$ also defines a homology class $[\gamma]:=\gamma_{*}\left[S^{1}\right] \in H_{1}(\hat{X} ; \mathbb{Z})$. Equation (5.6) can be restated as

$$
\begin{equation*}
\left[\hat{\lambda}_{X}-\hat{\lambda}_{X}^{\prime}\right]([\gamma])=0 \tag{5.7}
\end{equation*}
$$

If $\gamma$ is contractible, then Equation (5.7) holds. If $\gamma$ is noncontractible, $\gamma$ must have an associated Reeb orbit $\rho \in C^{\infty}\left(S^{1}, \partial X\right)$. Denote by $\iota: \partial X \longrightarrow \hat{X}$ the inclusion.

$$
\begin{aligned}
{\left[\hat{\lambda}_{X}-\hat{\lambda}_{X}^{\prime}\right]([\gamma]) } & =\left[\hat{\lambda}_{X}-\hat{\lambda}_{X}^{\prime}\right]\left(\iota_{*}[\rho]\right) & & {[\text { since } \gamma \text { and } \iota \circ \rho \text { are homotopic }] } \\
& =\left(\iota^{*}\left[\hat{\lambda}_{X}-\hat{\lambda}_{X}^{\prime}\right]\right)([\rho]) & & {[\text { by definition of pullback }] } \\
& =0 & & {\left[\text { since } \lambda_{X}^{\prime}=\lambda_{X} \text { near } \partial X\right] . }
\end{aligned}
$$

Since the functors and natural transformations in diagram (5.3) only depend on $\mathrm{d} \lambda_{X}, \mathrm{~d} \lambda_{Y}$ and on $\lambda_{X}, \lambda_{Y}$ near the boundaries, the diagrams (5.5) commute.

Definition 5.51 ([GH18, Definition 7.6]). If $\varphi:\left(V, \lambda_{V}\right) \longrightarrow\left(W, \lambda_{W}\right)$ is a strict generalized Liouville embedding of codimension 0 , then the Viterbo transfer map of $\varphi$ is defined as follows. Choose $\lambda_{W}^{\prime} \in \Omega^{1}(W)$ as in Lemma 5.49. Denote by $\varphi^{\prime}:\left(V, \lambda_{V}\right) \longrightarrow$ ( $W, \lambda_{W}^{\prime}$ ) the Liouville embedding which as a map of sets coincides with $\varphi$. Then, define

$$
\begin{gathered}
\varphi_{!}: \quad S H^{S^{1}}\left(W, \lambda_{W}\right)=S H^{S^{1}}\left(W, \lambda_{W}^{\prime}\right) \xrightarrow{\varphi_{!}^{\prime}} S H^{S^{1}}\left(V, \lambda_{V}\right), \\
\varphi_{!}^{+}: S H^{S^{1},+}\left(W, \lambda_{W}\right)=S H^{S^{1},+}\left(W, \lambda_{W}^{\prime}\right) \xrightarrow{\varphi_{1}^{\prime}} S H^{S^{1},+}\left(V, \lambda_{V}\right),
\end{gathered}
$$

where the equality was explained in Lemma 5.50 and the arrows are the Viterbo transfer maps of a Liouville embedding as in Definition 5.46.

Lemma 5.52. In Definition 5.51, $\varphi_{!}$and $\varphi_{!}^{+}$are independent of the choice of $\lambda_{W}^{\prime}$.
Proof. Let $\lambda_{W}^{\prime}$ and $\lambda_{W}^{\prime \prime}$ be 1-forms as in Lemma 5.49, and denote the corresponding Liouville embeddings by $\varphi^{\prime}:\left(W, \lambda_{W}^{\prime}\right) \longrightarrow\left(V, \lambda_{V}\right)$ and $\varphi^{\prime \prime}:\left(W, \lambda_{W}^{\prime \prime}\right) \longrightarrow\left(V, \lambda_{V}\right)$ (note that as set theoretic maps, $\varphi^{\prime}=\varphi^{\prime \prime}=\varphi$ ). Then, by Lemma 5.50, the following diagram commutes:


In this diagram, the top arrow is the Viterbo transfer map defined with respect to $\lambda_{W}^{\prime}$ and the bottom arrow is the Viterbo transfer map defined with respect to $\lambda_{W}^{\prime \prime}$.

Let Liouv ${ }_{\text {ndg }}^{\text {gle }}$ be the "category" whose objects are nondegenerate Liouville domains and whose morphisms are 0-codimensional generalized Liouville embeddings which are either strict or diffeomorphisms. Strictly speaking, since composition of generalized Liouville embeddings is not in general a generalized Liouville embedding, this is not a category. However, Liouv ${ }_{\text {ndg }}^{\text {gle }}$ does fit into the notion of categroid (see Definition 6.1), which is an object like a category with only partially defined compositions. One can then talk about functors between categroids.

Theorem 5.53. The assignments

$$
\begin{array}{rlrl}
S H^{S^{1}}: \text { Liouv }_{\text {ndg }}^{\text {gle }} & \longrightarrow \operatorname{Mod} & S H^{S^{1},+}: \text { Liouv }_{\text {ndg }}^{\text {gle }} & \longrightarrow \text { Mod } \\
\left(V, \lambda_{V}\right) & \longmapsto S H^{S^{1}}\left(V, \lambda_{V}\right) & & \left.\longmapsto, \lambda_{V}\right) \\
\varphi & \longmapsto S H^{S^{1},+}\left(V, \lambda_{V}\right) \\
\varphi & \longmapsto \uparrow \varphi! & \longmapsto \uparrow \varphi_{!}^{+} \\
\left(W, \lambda_{W}\right) & \longmapsto S H^{S^{1}}\left(W, \lambda_{W}\right), & \left(W, \lambda_{W}\right) & \longmapsto S H^{S^{1},+}\left(W, \lambda_{W}\right)
\end{array}
$$

are contravariant functors.
Proof. We prove the result only for $S H^{S^{1}}$, since the proof for $S H^{S^{1},+}$ is analogous. It suffices to assume that $\varphi:\left(V, \lambda_{V}\right) \longrightarrow\left(W, \lambda_{W}\right)$ and $\psi:\left(W, \lambda_{W}\right) \longrightarrow\left(Z, \lambda_{Z}\right)$ are composable strict, generalized Liouville embeddings of codimension 0 and to prove that
$(\psi \circ \varphi)!=\varphi_{!} \circ \psi!$. Here, "composable" means that the composition $\psi \circ \varphi$ is also a generalized Liouville embedding. We start by choosing

$$
\begin{aligned}
& \lambda_{W}^{\prime} \in \Omega^{1}(W) \quad \text { such that } \mathrm{d} \lambda_{W}^{\prime}=\mathrm{d} \lambda_{W}, \quad \lambda_{W}^{\prime}=\lambda_{W} \text { near } \partial W, \quad \text { and } \quad \varphi^{*} \lambda_{W}^{\prime}=\lambda_{V}, \\
& \lambda_{Z}^{\prime} \in \Omega^{1}(Z) \quad \text { such that } \quad \mathrm{d} \lambda_{Z}^{\prime}=\mathrm{d} \lambda_{Z}, \quad \lambda_{Z}^{\prime}=\lambda_{Z} \text { near } \partial Z, \quad \text { and } \quad \psi^{*} \lambda_{Z}^{\prime}=\lambda_{W} \text {, } \\
& \lambda_{Z}^{\prime \prime} \in \Omega^{1}(Z) \quad \text { such that } \quad \mathrm{d} \lambda_{Z}^{\prime \prime}=\mathrm{d} \lambda_{Z}^{\prime}, \quad \lambda_{Z}^{\prime \prime}=\lambda_{Z}^{\prime} \text { near } \partial Z, \quad \text { and } \quad \psi^{*} \lambda_{Z}^{\prime \prime}=\lambda_{W}^{\prime} .
\end{aligned}
$$

Therefore, we have Liouville embeddings

$$
\begin{aligned}
& \varphi^{\prime}:\left(V, \lambda_{V}\right) \longrightarrow\left(W, \lambda_{W}^{\prime}\right), \\
& \psi^{\prime}:\left(W, \lambda_{W}\right) \longrightarrow\left(Z, \lambda_{Z}^{\prime}\right), \\
& \psi^{\prime \prime}:\left(W, \lambda_{W}^{\prime}\right) \longrightarrow\left(Z, \lambda_{Z}^{\prime \prime}\right)
\end{aligned}
$$

We can define the Viterbo transfer maps

$$
\begin{aligned}
& \varphi_{!}: S H^{S^{1}}\left(W, \lambda_{W}\right)=S H^{S^{1}}\left(W, \lambda_{W}^{\prime}\right) \quad \xrightarrow{\varphi_{!}^{\prime}} \quad S H^{S^{1}}\left(V, \lambda_{V}\right), \\
& \psi_{!}: S H^{S^{1}}\left(Z, \lambda_{Z}\right)=S H^{S^{1}}\left(Z, \lambda_{Z}^{\prime}\right) \quad \xrightarrow{\psi_{!}^{\prime}} \\
&(\varphi \circ \psi)^{1}: S H^{S^{1}}\left(W, \lambda_{W}\right), \\
&\left(Z, \lambda_{Z}\right)=S H^{S^{1}}\left(Z, \lambda_{Z}^{\prime \prime}\right) \xrightarrow{\left(\psi^{\prime \prime} \circ \varphi^{\prime}\right)!} S H^{S^{1}}\left(V, \lambda_{V}\right) .
\end{aligned}
$$

Consider the following commutative diagram:


Here, the two small triangles and the outside arrows commute by definition of the Viterbo transfer map of a generalized Liouville embedding, the square commutes by Lemma 5.50, and $\left(\psi^{\prime \prime} \circ \varphi^{\prime}\right)!=\varphi_{!}^{\prime} \circ \psi_{!}^{\prime \prime}$ by Theorem 5.48. Therefore, $(\psi \circ \varphi)!=\varphi_{!} \circ \psi_{!}$.

## $5.6 \delta$ map

Let $(X, \lambda)$ be a nondegenerate Liouville domain. Our goal in this section is to define a map $\delta: S H^{S^{1},+}(X) \longrightarrow H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q})$. As we will see, $\delta=\alpha \circ \delta_{0}$, where $\delta_{0}: S H^{S^{1},+}(X) \longrightarrow S H^{S^{1}, \varepsilon}(X)$ is the continuation map associated to a long exact sequence in homology (see Definition 5.59) and $\alpha: S H^{S^{1}, \varepsilon}(X) \longrightarrow H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes$ $H_{\bullet}(X, \partial X ; \mathbb{Q})$ is an isomorphism which we define in several steps (see Lemmas 5.55 to 5.58). For every $(H, J) \in \mathbf{I}_{X}$, define

$$
\begin{aligned}
H^{\prime} & :=H_{e_{0}}: S^{1} \times \hat{X} \longrightarrow \mathbb{R}, \\
J^{\prime} & :=J_{e_{0}}: S^{1} \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X}),
\end{aligned}
$$

where $e_{0} \in S^{2 N+1} \subset \mathbb{C}^{N+1}$ is the first vector in the canonical basis of $\mathbb{C}^{N+1}$. We start by giving an alternative definition of the $S^{1}$-equivariant Floer chain complex.

Definition 5.54 ([GH18, Remark 5.15]). We define a chain complex $F C^{S^{1}}(X, H, J)_{\text {alt }}$ as follows. Let $u$ be a formal variable of degree 2 and consider $\mathbb{Q}\left\{1, \ldots, u^{N}\right\}$, the $\mathbb{Q}$-module of polynomials in $u$ of degree less or equal to $2 N$. As a $\mathbb{Q}$-module,

$$
F C^{S^{1}}(X, H, J)_{\mathrm{alt}}:=\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes F C\left(X, H^{\prime}, J^{\prime}\right),
$$

where $F C\left(X, H^{\prime}, J^{\prime}\right)$ is the Floer chain complex (not $S^{1}$-equivariant) of $X$ with respect to $\left(H^{\prime}, J^{\prime}\right)$, with $\mathbb{Q}$ coefficients. We will now define a differential $\partial_{\text {alt }}$ on $F C^{S^{1}}(X, H, J)_{\text {alt }}$. For every $j=0, \ldots, N$, define a map $\varphi_{j}: F C\left(X, H^{\prime}, J^{\prime}\right) \longrightarrow F C\left(X, H^{\prime}, J^{\prime}\right)$ by

$$
\varphi_{j}\left(\gamma^{+}\right):=\sum_{\gamma^{-} \in \mathcal{P}\left(H^{\prime}\right)} \# \mathcal{M}\left(H, J,\left[e_{j}, \gamma^{+}\right],\left[e_{0}, \gamma^{-}\right]\right) \cdot \gamma^{-},
$$

for every $\gamma^{+} \in \mathcal{P}\left(H^{\prime}\right)$. Note that $\varphi_{0}: F C\left(X, H^{\prime}, J^{\prime}\right) \longrightarrow F C\left(X, H^{\prime}, J^{\prime}\right)$ is the usual differential of the Floer chain complex. Finally, we define

$$
\begin{aligned}
\partial_{\mathrm{alt}}: \mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes F C\left(X, H^{\prime}, J^{\prime}\right) & \longrightarrow \mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes F C\left(X, H^{\prime}, J^{\prime}\right) \\
u^{k} \otimes \gamma & \longmapsto \sum_{j=0}^{k} u^{k-j} \otimes \varphi_{j}(\gamma) .
\end{aligned}
$$

Lemma 5.55 ([BO16, Section 2.3]). The map

$$
\begin{aligned}
F C^{S^{1}}(X, H, J) & \longrightarrow F C^{S^{1}}(X, H, J)_{\mathrm{alt}} \\
{\left[e_{j}, \gamma\right] } & \longmapsto u^{j} \otimes \gamma
\end{aligned}
$$

is an isomorphism of chain complexes.
Recall that in $X$, the Hamiltonian $H$ is assumed to be $C^{2}$-small and $S^{1}$-independent. Therefore, if $\gamma: S^{1} \longrightarrow \hat{X}$ is a 1-periodic orbit of $H^{\prime}$ and $\operatorname{im} \gamma \subset X$, then $\gamma$ is constant with value $x \in X$, where $x$ is a critical point of $H^{\prime}$. We will now assume that the Hamiltonian $H$ is chosen such that if $x^{ \pm}$are critical points of $H^{\prime}$, then

$$
\begin{equation*}
H^{\prime}\left(x^{+}\right) \leq H^{\prime}\left(x^{-}\right) \Longrightarrow \mu_{\mathrm{M}}\left(x^{+}, H^{\prime}\right) \geq \mu_{\mathrm{M}}\left(x^{-}, H^{\prime}\right) \tag{5.8}
\end{equation*}
$$

We will denote by $\left(M C\left(X, H^{\prime}\right), \partial^{M}\right)$ the Morse complex of $X$ with respect to $H^{\prime}$, defined with the following conventions. As a vector space, $M C\left(X, H^{\prime}\right)$ is the vector space over $\mathbb{Q}$ generated by the critical points of $H^{\prime}$. If $x^{ \pm}$are critical points of $H^{\prime}$, the coefficient $\left\langle\partial^{M}\left(x^{+}\right), x^{-}\right\rangle$is the count of gradient flow lines of $H^{\prime}$ from $x^{-}$to $x^{+}$. Finally, the degree of a critical point $x$ is the Morse index of $x$.

Lemma 5.56. There is a canonical isomorphism of chain complexes

$$
\left(F C^{S^{1}, \varepsilon}(X, H, J), \partial_{\mathrm{alt}}\right)=\left(\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes M C\left(X, H^{\prime}\right), \mathrm{id} \otimes \partial^{M}\right)
$$

Proof. By Remark 5.12 and Lemmas 5.15 and 5.55 , there is a canonical isomorphism of $\mathbb{Q}$-modules

$$
F C^{S^{1}, \varepsilon}(X, H, J)=\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes M C\left(X, H^{\prime}\right)
$$

We show that this isomorphism is a chain map. We claim that if $j \geq 1$ and $x^{+}, x^{-}$ are critical points of $H^{\prime}$, then $\operatorname{dim}_{(w, u)} \mathcal{M}\left(H, J,\left[e_{j}, x^{+}\right],\left[e_{0}, x^{-}\right]\right) \geq 1$. To see this, we compute

$$
\begin{aligned}
\operatorname{dim}_{(w, u)} \mathcal{M}\left(H, J,\left[e_{j}, x^{+}\right],\left[e_{0}, x^{-}\right]\right) & =\mu\left(e_{j}, x^{+}\right)-\mu\left(e_{0}, x^{-}\right)-1 \\
& =\mu_{\mathrm{M}}\left(e_{j}\right)-\mu_{\mathrm{M}}\left(e_{0}\right)+\mu_{\mathrm{M}}\left(x^{+}, H^{\prime}\right)-\mu_{\mathrm{M}}\left(x^{-}, H^{\prime}\right)-1 \\
& =2 j+\mu_{\mathrm{M}}\left(x^{+}, H^{\prime}\right)-\mu_{\mathrm{M}}\left(x^{-}, H^{\prime}\right)-1 \\
& \geq 2 j-1 \\
& \geq 1,
\end{aligned}
$$

where in the fourth line we used Lemma 4.37 and Equation (5.8). Therefore, if $j \geq 1$ and $x^{+}$is a critical point of $H^{\prime}$ then $\varphi_{j}\left(x^{+}\right)=0$. This implies that

$$
\partial_{\mathrm{alt}}\left(u^{k} \otimes x^{+}\right)=u^{k} \otimes \varphi_{0}\left(x^{+}\right),
$$

where $\varphi_{0}\left(x^{+}\right)=\partial^{M}\left(x^{+}\right)$is the Morse theory differential applied to $x^{+}$.
Lemma 5.57. There is a canonical isomorphism

$$
F H^{S^{1}, \varepsilon}(X, H, J)=\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes H_{\bullet}(X, \partial X ; \mathbb{Q}) .
$$

Proof.

$$
\begin{aligned}
F H^{S^{1}, \varepsilon}(X, H, J) & =H\left(\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes M C\left(X, H^{\prime}\right)\right) \\
& =\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes M H_{\bullet}\left(X, H^{\prime}\right) \\
& =\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes H_{\bullet}(X, \partial X ; \mathbb{Q}),
\end{aligned}
$$

where in the first equality we used Lemma 5.56, in the second equality we used the definition of the differential of $\mathbb{Q}\left\{1, \ldots, u^{N}\right\} \otimes M C\left(X, H^{\prime}\right)$, and in the third equality we used the isomorphism between Morse homology and singular homology.

Lemma 5.58. There is a canonical isomorphism

$$
\alpha: S H^{S^{1}, \varepsilon}(X) \longrightarrow H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q})
$$

Proof.

$$
\begin{aligned}
S H^{S^{1}, \varepsilon}(X) & =\underset{\lim _{N, H, J}}{\lim ^{S^{1}, \varepsilon}(X, H, J)} \\
& =\underset{N \overrightarrow{N, H, J}}{\lim }\left\{1, \ldots, u^{N}\right\} \otimes H_{\bullet}(X, \partial X ; \mathbb{Q}) \\
& =\mathbb{Q}[u] \otimes H \bullet(X, \partial X ; \mathbb{Q}) \\
& =H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H \bullet(X, \partial X ; \mathbb{Q}),
\end{aligned}
$$

where in the first equality we used the definition of $S^{1}$-equivariant symplectic homology and in the second equality we used Lemma 5.57.

Definition 5.59. We define a map $\delta: S H^{S^{1},+}(X) \longrightarrow H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q})$ as follows. For every $(H, J) \in \mathbf{I}_{X}$, consider the short exact sequence of complexes

$$
0 \longrightarrow F C^{S^{1}, \varepsilon}(X, H, J) \longrightarrow F C^{S^{1}}(X, H, J) \longrightarrow F C^{S^{1},+}(X, H, J) \longrightarrow 0
$$

There is an associated long exact sequence in homology

$$
\cdots \longrightarrow F H^{S^{1}}(X, H, J) \longrightarrow F H^{S^{1},+}(X, H, J) \xrightarrow{\delta^{H, J}} F H^{S^{1}, \varepsilon}(X, H, J) \longrightarrow \cdots
$$

Passing to the colimit, we obtain a sequence

$$
\cdots \longrightarrow S H^{S^{1}}(X) \longrightarrow S H^{S^{1},+}(X) \xrightarrow{\delta_{0}} S H^{S^{1}, \varepsilon}(X) \longrightarrow \cdots
$$

Finally, define $\delta:=\alpha \circ \delta_{0}: S H^{S^{1},+}(X) \longrightarrow H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q})$, where $\alpha$ is the isomorphism from Lemma 5.58.

Let $\varphi:\left(X, \lambda_{X}\right) \longrightarrow\left(Y, \lambda_{Y}\right)$ be a 0 -codimensional strict generalized Liouville embedding. Define $\rho: H_{\bullet}(Y, \partial Y ; \mathbb{Q}) \longrightarrow H_{\bullet}(X, \partial X ; \mathbb{Q})$ to be the unique map such that the diagram

commutes, where $\varphi_{*}$ is an isomorphism by functoriality of homology and the vertical arrow on the right is an isomorphism by excision. The map $\rho$ is such that $\rho([Y])=[X]$.
Proposition 5.60 ([GH18, Proposition 3.3]). The diagram

commutes.

## Chapter 6

## Symplectic capacities

### 6.1 Symplectic capacities

In this section we define the notion of symplectic capacity (Definition 6.3). A capacity is a function $c$ which assigns to every symplectic manifold $X$ (in a restricted subclass) a number $c(X) \in[0,+\infty]$, and which is functorial with respect to symplectic embeddings (in a restricted subclass). In the remaining sections of this chapter, we will define various capacities, namely the Lagrangian capacity (Definition 6.17), the Gutt-Hutchings capacities (Definition 6.25) and the McDuff-Siegel capacities (Definition 6.33). In this section we also deal with two small technicalities:
(1) Most of the capacities we will deal with in this thesis are functorial with respect to generalized Liouville embeddings, which do not form a category. However, they form an object which is like a category but has only partially defined composition of morphisms. We will use the nomenclature of [AK14] and call such an object a categroid (Definition 6.1).
(2) As we will see, some capacities we will consider are defined on the class of nondegenerate Liouville domains. In the last part of this section, we will see how such a capacity can be extended uniquely to a capacity of Liouville domains.

Definition 6.1 ([AK14, Definition 22]). A categroid C consists of a family of objects $\operatorname{Obj}(\mathbf{C})$ and for any pair of objects $A, B \in \mathbf{C}$ a set $\operatorname{Hom}_{\mathbf{C}}(A, B)$ such that the following holds.
(1) For any three objects $A, B, C$ there is a subset $\operatorname{Comp}_{\mathbf{C}}(A, B, C) \subset \operatorname{Hom}_{\mathbf{C}}(B, C) \times$ $\operatorname{Hom}_{\mathbf{C}}(A, B)$ of composable morphisms and an associated composition map

$$
\circ: \operatorname{Comp}_{\mathbf{C}}(A, B, C) \longrightarrow \operatorname{Hom}_{\mathbf{C}}(A, C)
$$

such that composition of composable morphisms is associative.
(2) For any object $A$ there exists an identity morphism $\operatorname{id}_{A} \in \operatorname{Hom}_{\mathbf{C}}(A, A)$ which is composable with any morphism $f \in \operatorname{Hom}_{\mathbf{C}}(A, B)$ or $g \in \operatorname{Hom}_{\mathbf{C}}(B, A)$ and satisfies

$$
\begin{aligned}
f \circ \operatorname{id}_{A} & =f \\
\operatorname{id}_{A} \circ g & =g .
\end{aligned}
$$

In this context, one has obvious definitions of subcategroids and also of functors between categroids. Denote by Symp the category of symplectic manifolds, where morphisms are 0-codimensional symplectic embeddings.

Definition 6.2. A symplectic categroid is a subcategroid $\mathbf{C}$ of $\operatorname{Symp}$ such that $(X, \omega) \in \mathbf{C}$ implies $(X, \alpha \omega) \in \mathbf{C}$ for all $\alpha>0$.

Definition 6.3. Let $\mathbf{C}$ be a symplectic categroid. A symplectic capacity is a functor $c: \mathbf{C} \longrightarrow[0,+\infty]$ satisfying
(Monotonicity) If $\left(X, \omega_{X}\right) \longrightarrow\left(Y, \omega_{Y}\right)$ is a morphism in $\mathbf{C}$ then $c\left(X, \omega_{X}\right) \leq c\left(Y, \omega_{Y}\right)$;
(Conformality) If $\alpha>0$ then $c(X, \alpha \omega)=\alpha c(X, \omega)$.
Notice that the monotonicity property is just a restatement of the fact that $c$ is a functor.
Definition 6.4. Let $c: \mathbf{C} \longrightarrow[0,+\infty]$ be a symplectic capacity with the property that $B^{2 n}(1), Z^{2 n}(1) \in \mathbf{C}$ for every $n$. We say that $c$ is nontrivial or normalized if it satisfies
(Nontriviality) $0<c\left(B^{2 n}(1)\right) \leq c\left(Z^{2 n}(1)\right)<+\infty$;
(Normalization) $0<c\left(B^{2 n}(1)\right)=1=c\left(Z^{2 n}(1)\right)<+\infty$.
Example 6.5. Let $(X, \omega)$ be a $2 n$-dimensional symplectic manifold. Recall that the symplectic volume of $X$ is given by

$$
\operatorname{vol}(X):=\int_{X} \frac{\omega^{n}}{n!}
$$

The volume capacity of $X$ is given by

$$
c_{\mathrm{vol}}(X):=\left(\frac{\operatorname{vol}(X)}{\operatorname{vol}(B)}\right)^{1 / n}
$$

where $B:=B^{2 n}(1):=\left\{\left.z \in \mathbb{C}^{n}|\pi| z\right|^{2} \leq 1\right\}$.
Example 6.6. Let $(Y, \Omega)$ be a symplectic manifold. We define the embedding capacities, denoted by $c_{(Y, \Omega)}$ and $c^{(Y, \Omega)}$, by

$$
\begin{aligned}
& c_{(Y, \Omega)}(X, \omega):=\sup \{a>0 \mid \text { there exists a symplectic embedding }(Y, a \Omega) \longrightarrow(X, \omega)\}, \\
& c^{(Y, \Omega)}(X, \omega):=\inf \{a>0 \mid \text { there exists a symplectic embedding }(X, \omega) \longrightarrow(Y, a \Omega)\},
\end{aligned}
$$

for any symplectic manifold $(X, \omega)$. Let $\omega_{0}$ denote the canonical symplectic structure of $\mathbb{C}^{n}$. In the case where $(Y, \Omega)=\left(B^{2 n}(1), \omega_{0}\right)$ or $(Y, \Omega)=\left(P^{2 n}(1), \omega_{0}\right)$, we denote

$$
\begin{aligned}
& c_{B}(X, \omega):=c_{\left(B^{2 n}(1), \omega\right)}(X, \omega)=\sup \left\{a \mid \exists \text { symplectic embedding } B^{2 n}(a) \longrightarrow X\right\}, \\
& c_{P}(X, \omega):=c_{\left(P^{2 n}(1), \omega\right)}(X, \omega)=\sup \left\{a \mid \exists \text { symplectic embedding } P^{2 n}(a) \longrightarrow X\right\} .
\end{aligned}
$$

Embedding capacities tend to be hard to compute, since they are defined as a restatement of a hard embedding problem. For example, a restatement of Gromov's nonsqueezing theorem [Gro85] is that $c_{B}$ is a normalized symplectic capacity. The capacity $c_{B}$ is also called Gromov width.

Definition 6.7 ([GH18, Section 4.2]). If $(X, \lambda)$ is a Liouville domain and $f: \partial X \longrightarrow \mathbb{R}$ is a smooth function, we define a new Liouville domain $\left(X_{f}, \lambda_{f}\right)$ as follows. Consider the completion $\hat{X}$, which has as subsets $X \subset \hat{X}$ and $\mathbb{R} \times \partial X \subset \hat{X}$. Then,

$$
X_{f}:=\hat{X} \backslash\{(\rho, y) \in \mathbb{R} \times \partial X \mid \rho>f(y)\}
$$

and $\lambda_{f}$ is the restriction of $\hat{\lambda}$ to $X_{f}$. Define $\mathcal{F}_{X}^{ \pm}$to be the set of $f^{ \pm}: \partial X \longrightarrow \mathbb{R}^{ \pm}$such that ( $X_{f^{ \pm}}, \lambda_{f^{ \pm}}$) is nondegenerate.
Definition 6.8. A Liouville categroid is a subcategroid $\mathbf{L}$ of Symp such that
(1) Every object of $\mathbf{L}$ is a Liouville domain.
(2) If $X \in \mathbf{L}$ and $f^{+} \in \mathcal{F}_{X}^{+}$then $X_{f^{+}} \in \mathbf{L}$ and the inclusion $X \longrightarrow X_{f^{+}}$is a morphism in $\mathbf{L}$ which is composable with any other morphisms $Y \longrightarrow X$ or $X_{f^{+}} \longrightarrow Z$ in $\mathbf{L}$.
(3) If $X \in \mathbf{L}$ and $f^{-} \in \mathcal{F}_{X}^{-}$then $X_{f^{-}} \in \mathbf{L}$ and the inclusion $X_{f^{-}} \longrightarrow X$ is a morphism in $\mathbf{L}$ which is composable with any other morphisms $Y \longrightarrow X_{f}$ or $X \longrightarrow Z$ in $\mathbf{L}$.
Example 6.9. Let Liouv ${ }^{\text {gle }}$ be the categroid whose objects are Liouville domains and whose morphisms are 0-codimensional generalized Liouville embeddings. Then Liouv ${ }^{\text {gle }}$ is a Liouville categroid.
Lemma 6.10. Let $\mathbf{L}$ be a Liouville categroid. Let $\mathbf{L}_{\mathrm{nd}}$ be the full subcategroid of $\mathbf{L}$ of nondegenerate Liouville domains (i.e., if $X, Y \in \mathbf{L}_{\mathrm{ndg}}$ then $\operatorname{Hom}_{\mathbf{L}_{\mathrm{ndg}}}(X, Y)=$ $\operatorname{Hom}_{\mathbf{L}}(X, Y)$ ). If $c: \mathbf{L}_{\mathrm{ndg}} \longrightarrow[0,+\infty]$ is a symplectic capacity, then there exists a unique symplectic capacity $\bar{c}: \mathbf{L} \longrightarrow[0,+\infty]$ such that the following diagram commutes:


Proof. This proof is based on [GH18, Section 4.2]. We claim that if $\varepsilon>0$ and $(X, \lambda)$ is a nondegenerate Liouville domain in $\mathbf{L}_{\text {ndg }}$, then $\left(X_{\varepsilon}, \lambda_{\varepsilon}\right)$ is nondegenerate and

$$
\begin{equation*}
c\left(X_{\varepsilon}, \lambda_{\varepsilon}\right)=e^{\varepsilon} c(X, \lambda) \tag{6.2}
\end{equation*}
$$

To see this, notice that the time $\varepsilon$ flow of the Liouville vector field $Z$ of $\hat{X}$ restricts to a Liouville embedding $\phi:\left(X, e^{\varepsilon} \lambda\right) \longrightarrow\left(X_{\varepsilon}, \lambda_{\varepsilon}\right)$ and also to a contactomorphism $\phi:\left(\partial X,\left.e^{\varepsilon} \lambda\right|_{\partial X}\right) \longrightarrow\left(\partial X_{\varepsilon},\left.\partial \lambda_{\varepsilon}\right|_{\partial X_{\varepsilon}}\right)$. This shows that $\left(X_{\varepsilon}, \lambda_{\varepsilon}\right)$ is nondegenerate. In particular, $\left(X_{\varepsilon}, \lambda_{\varepsilon}\right) \in \mathbf{L}_{\text {ndg. }}$. Finally,

$$
\begin{aligned}
c\left(X_{\varepsilon}, \lambda_{\varepsilon}\right) & =c\left(X, e^{\varepsilon} \lambda\right) \quad[\text { by functoriality of } c] \\
& =e^{\varepsilon} c(X, \lambda) \quad[\text { by conformality }] .
\end{aligned}
$$

This finishes the proof of Equation (6.2). Define functions $c^{ \pm}: \mathbf{L} \longrightarrow[0,+\infty]$ by

$$
\begin{aligned}
& c^{+}(X):=\inf _{f^{+} \in \mathcal{F}_{X}^{+}} c\left(X_{f^{+}}\right), \\
& c^{-}(X):=\sup _{f^{-} \in \mathcal{F}_{X}^{-}} c\left(X_{f^{-}}\right) .
\end{aligned}
$$

We claim that if $(X, \lambda) \in \mathbf{L}$ is a Liouville domain then

$$
\begin{equation*}
c^{-}(X)=c^{+}(X) . \tag{6.3}
\end{equation*}
$$

Monotonicity of $c$ implies $c^{-}(X) \leq c^{+}(X)$. To show the reverse inequality, it is enough to show that $c^{+}(X) \leq e^{\varepsilon} c^{-}(X)$ for every $\varepsilon>0$. For this, choose $f^{-} \in \mathcal{F}_{X}^{-}$such that $\operatorname{im} f^{-} \subset(-\varepsilon, 0)$ and define $f^{+}=f^{-}+\varepsilon$. By the previous discussion, $\left(X_{f^{+}}, \lambda_{f^{+}}\right)$is nondegenerate and $f^{+} \in \mathcal{F}_{X}^{+}$. Then,

$$
\begin{aligned}
c^{+}(X) & =\inf _{g^{+} \in \mathcal{F}_{X}^{+}} c\left(X_{g^{+}}\right) & & {\left[\text {by definition of } c^{+}\right] } \\
& \leq c\left(X_{f^{+}}\right) & & {\left[\text {since } f^{+} \in \mathcal{F}_{X}^{+}\right] } \\
& =e^{\varepsilon} c\left(X_{f^{-}}\right) & & {[\text {by Equation }(6.2)] } \\
& \leq e^{\varepsilon} \sup _{g^{-} \in \mathcal{F}_{X}^{-}} c\left(X_{g^{-}}\right) & & {\left[\text {since } f^{-} \in \mathcal{F}_{X}^{-}\right] } \\
& =e^{\varepsilon} c^{-}(X) & & {\left[\text { by definition of } c^{-}\right], }
\end{aligned}
$$

which finishes the proof of Equation (6.3). Moreover, if $(X, \lambda) \in \mathbf{L}_{\text {ndg }}$ is nondegenerate, then $c^{-}(X) \leq c(X) \leq c^{+}(X)=c^{-}(X)$, which implies

$$
c^{-}(X)=c(X)=c^{+}(X) .
$$

We now show that $c^{ \pm}$are symplectic capacities. The conformality property is immediate. To prove monotonicity, let $X \longrightarrow Y$ be a morphism in $\mathbf{L}$.

$$
\begin{aligned}
c^{-}(X) & =\sup _{f^{-} \in \mathcal{F}_{X}^{-}} c\left(X_{f^{-}}\right) & & {\left[\text {by definition of } c^{-}\right] } \\
& \leq \inf _{g^{+} \in \mathcal{F}_{Y}^{+}} c\left(Y_{g^{+}}\right) & & {\left[\text {since } X_{f^{-}} \subset X \longrightarrow Y \subset Y_{g^{+}} \text {and by monotonicity of } c\right] } \\
& =c^{+}(Y) & & {\left[\text { by definition of } c^{+}\right] . }
\end{aligned}
$$

The result follows from Equation (6.3). To prove existence, simply notice that by the above discussion, the function $\bar{c}:=c^{-}=c^{+}: \mathbf{L} \longrightarrow[0,+\infty]$ has all the desired properties.

To prove uniqueness, let $\bar{c}$ be any function as in the statement of the lemma. We wish to show that $\bar{c}:=c^{-}=c^{+}$. We start by showing that $c^{-}(X) \leq \bar{c}(X)$.

$$
\begin{array}{rlrl}
c^{-}(X) & =\sup _{f^{-} \in \mathcal{F}_{X}^{-}} c\left(X_{f^{-}}\right) & {\left[\text {by definition of } c^{-}\right]} \\
& =\sup _{f^{-} \in \mathcal{F}_{X}^{-}} \bar{c}\left(X_{f^{-}}\right) & {[\text {by assumption on } \bar{c}]} \\
& \leq \sup _{f^{-} \in \mathcal{F}_{X}^{-}} \bar{c}(X) \quad\left[\begin{array}{ll} 
\\
& =\bar{c}(X) .
\end{array} \quad .\right.
\end{array}
$$

Analogously, we can show that $c^{+}(X) \geq \bar{c}(X)$, which concludes the proof.
Lemma 6.11. For $i=0,1$, let $c_{i}: \mathbf{L}_{\mathrm{ndg}} \rightarrow[0,+\infty]$ be symplectic capacities with extensions $\bar{c}_{i}: \mathbf{L} \rightarrow[0,+\infty]$ as in Lemma 6.10. If $c_{0}(Y) \leq c_{1}(Y)$ for every nondegenerate Liouville domain $Y \in \mathbf{L}_{\mathrm{ndg}}$ then $\bar{c}_{0}(X) \leq \bar{c}_{1}(X)$ for every Liouville domain $X \in \mathbf{L}$.

Proof.

$$
\begin{array}{rlrl}
\bar{c}_{0}(X) & =\sup _{f^{-} \in \mathcal{F}_{X}^{-}} c_{0}\left(X_{f^{-}}\right) & & {\left[\text {by the definition of } \bar{c}_{0}\right. \text { in Lemma 6.10] }} \\
& \leq \sup _{f^{-} \in \mathcal{F}_{X}^{-}} c_{1}\left(X_{f^{-}}\right) & & \\
& =\bar{c}_{1}(X) & & {\left[\text { by assumption on } c_{0} \text { and } c_{1}\right]} \\
&
\end{array}
$$

By the exposition above, if $c$ is a capacity of nondegenerate Liouville domains then it can be extended to a capacity of Liouville domains. In particular, $c(X)$ is defined for any star-shaped domain $X$. However, it will be useful to us to compute capacities of the cube $P(r)$ and of the nondisjoint union of cylinders $N(r)$. These spaces are not quite star-shaped domains, because they have corners and $N(r)$ is noncompact. So we will consider a further extension of the capacity $c$. Let Star be the category of star-shaped domains, where there is a unique morphism $X \longrightarrow Y$ if and only if $X \subset Y$. Denote by Star $_{\text {ncp }}$ the category of "star-shaped domains" which are possibly noncompact or possibly have corners, with the same notion of morphisms.
Lemma 6.12. Let $c:$ Star $\longrightarrow[0,+\infty]$ be a symplectic capacity. Define a symplectic capacity $\bar{c}: \mathbf{S t a r}_{\mathrm{ncp}} \longrightarrow[0,+\infty]$ by

$$
\bar{c}(X)=\sup _{Y \subset X} c(Y),
$$

where the supremum is taken over star-shaped domains $Y \subset X$ which are compact and have smooth boundary. Then, the diagram

commutes. Moreover, $\bar{c}$ is the smallest capacity making this diagram commute.
Proof. It is immediate that $\bar{c}$ is a symplectic capacity. We show that the diagram commutes. If $X$ is a compact star-shaped domain with smooth boundary, then

$$
\begin{aligned}
c(X) & \leq \sup _{Y \subset X} c(Y) & & {[\text { since } X \text { is compact and has smooth boundary }] } \\
& \leq c(X) & & {[\text { by monotonicity }] . }
\end{aligned}
$$

If $\tilde{c}: \mathbf{S t a r}_{\mathrm{ncp}} \longrightarrow[0,+\infty]$ is another capacity making the diagram commute, then

$$
\begin{aligned}
\bar{c}(X) & =\sup _{Y \subset X} c(Y) & & {[\text { by definition of } \bar{c}] } \\
& =\sup _{Y \subset X} \tilde{c}(Y) & & {[\text { since } \tilde{c} \text { makes the diagram commute }] } \\
& \leq \tilde{c}(X) & & {[\text { by monotonicity of } \tilde{c}] . }
\end{aligned}
$$

Remark 6.13. We will always assume that every capacity of nondegenerate Liouville domains that we define is extended as in Lemmas 6.10 and 6.12 to possibly degenerate Liouville domains and to "star-shaped domains" which are possibly noncompact or possibly have corners.

### 6.2 Lagrangian capacity

Here, we define the Lagrangian capacity (Definition 6.17) and state its properties (Proposition 6.18). One of the main goals of this thesis is to study whether the Lagrangian capacity can be computed in some cases, for example for toric domains. In the end of the section, we state some easy inequalities concerning the Lagrangian capacity (Lemmas 6.19 and 6.20), known computations (Propositions 6.21 and 6.22 ) and finally the main conjecture of this thesis (Conjecture 6.24), which is inspired by all the previous results. The Lagrangian capacity is defined in terms of the minimal area of Lagrangian submanifolds, which we now define.

Definition 6.14. Let $(X, \omega)$ be a symplectic manifold. If $L$ is a Lagrangian submanifold of $X$, then we define the minimal symplectic area of $L$, denoted $A_{\text {min }}(L)$, by

$$
A_{\min }(L):=\inf \left\{\omega(\sigma) \mid \sigma \in \pi_{2}(X, L), \omega(\sigma)>0\right\} .
$$

Lemma 6.15. Let $\iota:(X, \omega) \longrightarrow\left(X^{\prime}, \omega^{\prime}\right)$ be a symplectic embedding, $L \subset X$ be an embedded Lagrangian submanifold and $L^{\prime}=\iota(L)$. In this case,
(1) $A_{\text {min }}(L) \geq A_{\text {min }}\left(L^{\prime}\right)$;
(2) $A_{\min }(L)=A_{\min }\left(L^{\prime}\right)$, provided that $\pi_{2}\left(X^{\prime}, \iota(X)\right)=0$.

Proof. (1): By definition of minimal area and since the diagram

commutes.
(2): Considering the long exact sequence of the triple $\left(X^{\prime}, \iota(X), L^{\prime}\right)$,

$$
\cdots \longrightarrow \pi_{2}\left(\iota(X), L^{\prime}\right) \longrightarrow \pi_{2}\left(X^{\prime}, L^{\prime}\right) \longrightarrow \pi_{2}\left(X^{\prime}, \iota(X)\right)=0
$$

we conclude that $\iota_{*}: \pi_{2}(X, L) \longrightarrow \pi_{2}\left(X^{\prime}, L^{\prime}\right)$ is surjective. Again, the result follows by the definition of minimal area and diagram (6.4).

Lemma 6.16. Let $(X, \lambda)$ be an exact symplectic manifold and $L \subset X$ be a Lagrangian submanifold. If $\pi_{1}(X)=0$, then

$$
A_{\min }(L)=\inf \left\{\lambda(\rho) \mid \rho \in \pi_{1}(L), \lambda(\rho)>0\right\}
$$

Proof. The diagram

commutes, where $\partial([\sigma])=\left[\left.\sigma\right|_{S^{1}}\right]$, and the top row is exact.

Definition 6.17 ([CM18, Section 1.2]). Let $(X, \omega)$ be a symplectic manifold. We define the Lagrangian capacity of $(X, \omega)$, denoted $c_{L}(X, \omega)$, by

$$
c_{L}(X, \omega):=\sup \left\{A_{\min }(L) \mid L \subset X \text { is an embedded Lagrangian torus }\right\} .
$$

Proposition 6.18 ([CM18, Section 1.2]). The Lagrangian capacity $c_{L}$ satisfies:
(Monotonicity) If $(X, \omega) \longrightarrow\left(X^{\prime}, \omega^{\prime}\right)$ is a symplectic embedding with $\pi_{2}\left(X^{\prime}, \iota(X)\right)=0$, then $c_{L}(X, \omega) \leq c_{L}\left(X^{\prime}, \omega^{\prime}\right)$.
(Conformality) If $\alpha \neq 0$, then $c_{L}(X, \alpha \omega)=|\alpha| c_{L}(X, \omega)$.
Proof. We prove monotonicity.

$$
\begin{aligned}
c_{L}(X, \omega) & =\sup _{L \subset X} A_{\min }(L) & & {\left[\text { by definition of } c_{L}\right] } \\
& \leq \sup _{L^{\prime} \subset X^{\prime}} A_{\min }\left(L^{\prime}\right) & & {[\text { by Lemma } 6.15] } \\
& =c_{L}\left(X^{\prime}, \omega^{\prime}\right) & & {\left[\text { by definition of } c_{L}\right] }
\end{aligned}
$$

We prove conformality. Note that a submanifold $L \subset X$ is Lagrangian with respect to $\omega$ if and only if it is Lagrangian with respect to $\alpha \omega$.

$$
\begin{aligned}
c_{L}(X, \alpha \omega) & =\sup _{L \subset(X, \alpha \omega)} A_{\min }(L, \alpha \omega) & & {\left[\text { by definition of } c_{L}\right] } \\
& =\sup _{L \subset(X, \omega)}|\alpha| A_{\min }(L, \omega) & & {[\text { by definition of minimal area }] } \\
& =|\alpha| c_{L}(X, \omega) & & {\left[\text { by definition of } c_{L}\right] . }
\end{aligned}
$$

Lemma 6.19. If $X$ is a star-shaped domain, then $c_{L}(X) \geq c_{P}(X)$.
Proof. Let $\iota: P(a) \longrightarrow X$ be a symplectic embedding, for some $a>0$. We want to show that $c_{L}(X) \geq a$. Define $T=\left\{\left.z \in \mathbb{C}^{n}| | z_{1}\right|^{2}=a / \pi, \ldots,\left|z_{n}\right|^{2}=a / \pi\right\} \subset \partial P(a)$ and $L=\iota(T)$. Then,

$$
\begin{aligned}
c_{L}(X) & \geq A_{\min }(L) & & {\left[\text { by definition of } c_{L}\right] } \\
& =A_{\min }(T) & & {[\text { by Lemma } 6.15] } \\
& =a & & {[\text { by Lemma } 6.16] . }
\end{aligned}
$$

Recall that if $X_{\Omega}$ is a toric domain, its diagonal is given by $\delta_{\Omega}:=\sup \{a \mid(a, \ldots, a) \in \Omega\}$ (see Definition 2.34).

Lemma 6.20. If $X_{\Omega}$ is a convex or concave toric domain, then $c_{P}\left(X_{\Omega}\right) \geq \delta_{\Omega}$.
Proof. Since $X_{\Omega}$ is a convex or concave toric domain, we have that $P\left(\delta_{\Omega}\right) \subset X_{\Omega}$. The result follows by definition of $c_{P}$.

Actually, Gutt-Hutchings show that $c_{P}\left(X_{\Omega}\right)=\delta_{\Omega}$ for any convex or concave toric domain $X_{\Omega}$ ([GH18, Theorem 1.18]). However, for our purposes we will only need the inequality in Lemma 6.20. We now consider the results by Cieliebak-Mohnke for the Lagrangian capacity of the ball and the cylinder.

Proposition 6.21 ([CM18, Corollary 1.3]). The Lagrangian capacity of the ball is

$$
c_{L}\left(B^{2 n}(1)\right)=\frac{1}{n} .
$$

Proposition 6.22 ([CM18, p. 215-216]). The Lagrangian capacity of the cylinder is

$$
c_{L}\left(Z^{2 n}(1)\right)=1
$$

By Lemmas 6.19 and 6.20 , if $X_{\Omega}$ is a convex or concave toric domain then $c_{L}\left(X_{\Omega}\right) \geq \delta_{\Omega}$. But as we have seen in Propositions 6.21 and 6.22 , if $X_{\Omega}$ is the ball or the cylinder then $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$. This motivates Conjecture 6.23 below for the Lagrangian capacity of an ellipsoid, and more generally Conjecture 6.24 below for the Lagrangian capacity of any convex or concave toric domain.

Conjecture 6.23 ([CM18, Conjecture 1.5]). The Lagrangian capacity of the ellipsoid is

$$
c_{L}\left(E\left(a_{1}, \ldots, a_{n}\right)\right)=\left(\frac{1}{a_{1}}+\cdots+\frac{1}{a_{n}}\right)^{-1}
$$

Conjecture 6.24. If $X_{\Omega}$ is a convex or concave toric domain then

$$
c_{L}\left(X_{\Omega}\right)=\delta_{\Omega} .
$$

In Theorems 6.41 and 7.65 we present our results concerning Conjecture 6.24.

### 6.3 Gutt-Hutchings capacities

In this section we will define the Gutt-Hutchings capacities (Definition 6.25) and the $S^{1}$-equivariant symplectic homology capacities (Definition 6.29), and list their properties (Theorems 6.26 and 6.30 respectively). We will also compare the two capacities (Theorem 6.31). The definition of these capacities relies on $S^{1}$-equivariant symplectic homology. In the commutative diagram below, we display the modules and maps which will play a role in this section, for a nondegenerate Liouville domain $X$.


Here, $\iota^{a}$ and $\iota^{a, \varepsilon}$ are the maps induced by the action filtration, $\delta_{0}$ and $\delta$ are the maps from Definition 5.59 and $\alpha$ is the isomorphism from Lemma 5.58. We point out that every vertex in the above diagram has a $U$ map and every map in the diagram commutes with this $U$ map. Specifically, all the $S^{1}$-equivariant symplectic homologies have the $U$ map given as in Definition 5.19 and $H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q}) \cong \mathbb{Q}[u] \otimes H_{\bullet}(X, \partial X ; \mathbb{Q})$ has
the map $U:=u^{-1} \otimes \mathrm{id}$. We will also make use of a version of diagram (6.5) in the case where $X$ is star-shaped, namely diagram (6.6) below. In this case, the modules in the diagram admit gradings and every map is considered to be a map in a specific degree. By [GH18, Proposition 3.1], $\delta$ and $\delta_{0}$ are isomorphisms.


Definition 6.25 ([GH18, Definition 4.1]). If $k \in \mathbb{Z}_{\geq 1}$ and $(X, \lambda)$ is a nondegenerate Liouville domain, the Gutt-Hutchings capacities of $X$, denoted $c_{k}^{\mathrm{GH}}(X)$, are defined as follows. Consider the map

$$
\delta \circ U^{k-1} \circ \iota^{a}: S H^{S^{1},(\varepsilon, a]}(X) \longrightarrow H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q})
$$

from diagram (6.5). Then, we define

$$
c_{k}^{\mathrm{GH}}(X):=\inf \left\{a>0 \mid[\mathrm{pt}] \otimes[X] \in \operatorname{im}\left(\delta \circ U^{k-1} \circ \iota^{a}\right)\right\}
$$

Theorem 6.26 ([GH18, Theorem 1.24]). The functions $c_{k}^{\mathrm{GH}}$ of Liouville domains satisfy the following axioms, for all equidimensional Liouville domains $\left(X, \lambda_{X}\right)$ and $\left(Y, \lambda_{Y}\right)$ :
(Monotonicity) If $X \longrightarrow Y$ is a generalized Liouville embedding then $c_{k}^{\mathrm{GH}}(X) \leq c_{k}^{\mathrm{GH}}(Y)$. (Conformality) If $\alpha>0$ then $c_{k}^{\mathrm{GH}}\left(X, \alpha \lambda_{X}\right)=\alpha c_{k}^{\mathrm{GH}}\left(X, \lambda_{X}\right)$.
(Nondecreasing) $c_{1}^{\mathrm{GH}}(X) \leq c_{2}^{\mathrm{GH}}(X) \leq \cdots \leq+\infty$.
(Reeb orbits) If $c_{k}^{\mathrm{GH}}(X)<+\infty$, then $c_{k}^{\mathrm{GH}}(X)=\mathcal{A}(\gamma)$ for some Reeb orbit $\gamma$ which is contractible in $X$.

The following lemma provides an alternative definition of $c_{k}^{\mathrm{GH}}$, in the spirit of [FHW94].
Lemma 6.27. Let $(X, \lambda)$ be a nondegenerate Liouville domain such that $\pi_{1}(X)=0$ and $\left.c_{1}(T X)\right|_{\pi_{2}(X)}=0$. Let $E \subset \mathbb{C}^{n}$ be a nondegenerate star-shaped domain and suppose that $\phi: E \longrightarrow X$ is a symplectic embedding. Consider the map

$$
S H_{n-1+2 k}^{S^{1},(\varepsilon, a]}(X) \xrightarrow{\iota^{a}} S H_{n-1+2 k}^{S^{1},+}(X) \xrightarrow{\phi_{!}} S H_{n-1+2 k}^{S^{1},+}(E)
$$

Then, $c_{k}^{\mathrm{GH}}(X)=\inf \left\{a>0 \mid \phi_{!} \circ \iota^{a}\right.$ is nonzero $\}$.
Proof. For every $a \in \mathbb{R}$ consider the following commutative diagram:


By [GH18, Proposition 3.1] and since $E$ is star-shaped, the maps $U_{E}$ and $\delta_{E}$ are isomorphisms. Since $\rho([X])=[E]$, the map $\rho$ is an isomorphism. By definition, $c_{k}^{G H}$ is the infimum over $a$ such that the top arrow is surjective. This condition is equivalent to $\phi_{!} \circ \iota_{X}^{a}$ being nonzero.

The following computation will be useful to us in the proofs of Theorems 6.41 and 7.65.
Lemma 6.28 ([GH18, Lemma 1.19]). $c_{k}^{\mathrm{GH}}\left(N^{2 n}(\delta)\right)=\delta(k+n-1)$.
We now consider other capacities which can be defined using $S^{1}$-equivariant symplectic homology.
Definition 6.29 ([Iri21, Section 2.5]). If $k \in \mathbb{Z}_{\geq 1}$ and $(X, \lambda)$ is a nondegenerate Liouville domain, the $S^{1}$-equivariant symplectic homology capacities of $X$, denoted $c_{k}^{S^{1}}(X)$, are defined as follows. Consider the map

$$
\iota^{a, \varepsilon} \circ \alpha^{-1}: H_{\bullet}\left(B S^{1} ; \mathbb{Q}\right) \otimes H_{\bullet}(X, \partial X ; \mathbb{Q}) \longrightarrow S H^{S^{1}, a}(X)
$$

from diagram (6.5). Then, we define

$$
c_{k}^{S^{1}}(X):=\inf \left\{a>0 \mid \iota^{a, \varepsilon} \circ \alpha^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right)=0\right\} .
$$

Theorem 6.30. The functions $c_{k}^{S^{1}}$ of Liouville domains satisfy the following axioms, for all Liouville domains $\left(X, \lambda_{X}\right)$ and $\left(Y, \lambda_{Y}\right)$ of the same dimension:
(Monotonicity) If $X \longrightarrow Y$ is a generalized Liouville embedding then $c_{k}^{S^{1}}(X) \leq c_{k}^{S^{1}}(Y)$. (Conformality) If $\mu>0$ then $c_{k}^{S^{1}}\left(X, \mu \lambda_{X}\right)=\mu c_{k}^{S^{1}}\left(X, \lambda_{X}\right)$.
(Nondecreasing) $c_{1}^{S^{1}}(X) \leq c_{2}^{S^{1}}(X) \leq \cdots \leq+\infty$.
Proof. We prove monotonicity. Consider the following commutative diagram:


If $\iota_{Y}^{a, \varepsilon} \circ \alpha_{Y}^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[Y]\right)=0$, then

$$
\begin{aligned}
\iota_{X}^{a, \varepsilon} & \circ \alpha_{X}^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right) & & \\
& =\iota_{X}^{a, \varepsilon} \circ \alpha_{X}^{-1} \circ(\mathrm{id} \otimes \rho)\left(\left[\mathbb{C} P^{k-1}\right] \otimes[Y]\right) & & {[\text { since } \rho([Y])=[X]] } \\
& =\phi_{!} \circ \iota_{Y}^{a, \varepsilon} \circ \alpha_{Y}^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[Y]\right) & & {[\text { by diagram }(6.7)] } \\
& =0 & & {[\text { by assumption }] . }
\end{aligned}
$$

To prove conformality, choose $\varepsilon>0$ such that $\varepsilon, \mu \varepsilon<\min \operatorname{Spec}\left(\partial X,\left.\lambda\right|_{\partial X}\right)$. Since the diagram

commutes (by [GH18, Proposition 3.1]), the result follows.
To prove the nondecreasing property, note that if $\iota^{a, \varepsilon} \circ \alpha^{-1}\left(\left[\mathbb{C} P^{k}\right] \otimes[X]\right)=0$, then

$$
\begin{array}{rlrl}
\iota^{a, \varepsilon} & \circ \alpha^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right) & & \\
& =\iota^{a, \varepsilon} \circ \alpha^{-1} \circ U\left(\left[\mathbb{C} P^{k}\right] \otimes[X]\right) & & {\left[\text { since } U\left(\left[\mathbb{C} P^{k}\right] \otimes[X]\right)=\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right]} \\
& =U^{a} \circ \iota^{a, \varepsilon} \circ \alpha^{-1}\left(\left[\mathbb{C} P^{k}\right] \otimes[X]\right) & {\left[\text { since } \iota^{a, \varepsilon} \text { and } \alpha \text { commute with } U\right]} \\
=0 & & {[\text { by assumption }] .}
\end{array}
$$

Theorem 6.31. If $(X, \lambda)$ is a Liouville domain, then
(1) $c_{k}^{\mathrm{GH}}(X) \leq c_{k}^{S^{1}}(X)$;
(2) $c_{k}^{\mathrm{GH}}(X)=c_{k}^{S^{1}}(X)$ provided that $X$ is star-shaped.

Proof. By Lemma 6.11, we may assume that $X$ is nondegenerate. Since

$$
\begin{aligned}
\iota^{a, \varepsilon} & \circ \alpha^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right)=0 & & \\
& \Longleftrightarrow \alpha^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right) \in \operatorname{ker} \iota^{a, \varepsilon} & & \text { [by definition of kernel }] \\
& \Longleftrightarrow \alpha^{-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right) \in \operatorname{im} \delta_{0}^{a} & & \text { [since the top row of }(6.5) \text { is exact }] \\
& \Longleftrightarrow\left[\mathbb{C} P^{k-1}\right] \otimes[X] \in \operatorname{im}\left(\alpha \circ \delta_{0}^{a}\right) & & \text { [by definition of image }] \\
& \Longleftrightarrow\left[\mathbb{C} P^{k-1}\right] \otimes[X] \in \operatorname{im}\left(\delta \circ \iota^{a}\right) & & \text { [since diagram }(6.5) \text { commutes }] \\
& \Longleftrightarrow[\mathrm{pt}] \otimes[X] \in \operatorname{im}\left(U^{k-1} \circ \delta \circ \iota^{a}\right) & & {\left[\text { since } U^{k-1}\left(\left[\mathbb{C} P^{k-1}\right] \otimes[X]\right)=[\mathrm{pt}] \otimes[X]\right] } \\
& \Longleftrightarrow \operatorname{im}\left(\delta \circ U^{k-1} \circ \iota^{a}\right) & & {[\text { since } \delta \text { and } U \text { commute }], }
\end{aligned}
$$

we have that $c_{k}^{\mathrm{GH}}(X) \leq c_{k}^{S^{1}}(X)$. If $X$ is a star-shaped domain, we can view the maps of the computation above as being the maps in diagram (6.6), i.e. they are defined in a specific degree. In this case, $U^{k-1}: H_{2 k-2}\left(B S^{1}\right) \otimes H_{2 n}(X, \partial X) \longrightarrow H_{0}\left(B S^{1}\right) \otimes H_{2 n}(X, \partial X)$ is an isomorphism, and therefore the implication in the previous computation is actually an equivalence.

Remark 6.32. The capacities $c_{k}^{\mathrm{GH}}$ and $c_{k}^{S^{1}}$ are defined in terms of a certain homology class being in the kernel or in the image of a map with domain or target the $S^{1}$-equivariant symplectic homology. Other authors have constructed capacities in an analogous manner, for example Viterbo [Vit92, Definition 2.1] and [Vit99, Section 5.3], Schwarz [Sch00, Definition 2.6] and Ginzburg-Shon [GS18, Section 3.1].

### 6.4 McDuff-Siegel capacities

We now define the McDuff-Siegel capacities. These will assist us in our goal of proving Conjecture 6.24 (at least in particular cases) because they can be compared with the Lagrangian capacity (Theorem 6.40) and with the Gutt-Hutchings capacities (Proposition 6.37).

Definition 6.33 ([MS22, Definition 3.3.1]). Let $(X, \lambda)$ be a nondegenerate Liouville domain. For $\ell, k \in \mathbb{Z}_{\geq 1}$, we define the McDuff-Siegel capacities of $X$, denoted
$\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X)$, as follows. Choose $x \in \operatorname{int} X$ and $D$ a symplectic divisor at $x$. Then,

$$
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X):=\sup _{J \in \mathcal{J}(X, D)} \inf _{\Gamma_{1}, \ldots, \Gamma_{p}} \sum_{i=1}^{p} \mathcal{A}\left(\Gamma_{i}\right),
$$

where the infimum is over tuples of Reeb orbits $\Gamma_{1}, \ldots, \Gamma_{p}$ such that there exist integers $k_{1}, \ldots, k_{p} \geq 1$ with

$$
\begin{equation*}
\sum_{i=1}^{p} \# \Gamma_{i} \leq \ell, \quad \sum_{i=1}^{p} k_{i} \geq k, \quad \prod_{i=1}^{p} \mathcal{M}_{X}^{J}\left(\Gamma_{i}\right)\left\langle\mathcal{T}^{\left(k_{i}\right)} x\right\rangle \neq \varnothing \tag{6.8}
\end{equation*}
$$

The following theorem shows that the definition of $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$ we give in Definition 6.33 and the one given in [MS22, Definition 3.3.1] are equal.

Theorem 6.34 ([MS22, Remark 3.1.2]). If $(X, \lambda)$ is a nondegenerate Liouville domain, $\ell, k \in \mathbb{Z}_{\geq 1}, x \in \operatorname{int} X$ and $D$ is a symplectic divisor through $x$, then

$$
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X)=\sup _{J \in \mathcal{J}(X, D)} \inf _{\Gamma} \mathcal{A}(\Gamma),
$$

where the infimum is taken over tuples of Reeb orbits $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ such that $p \leq \ell$ and $\overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle \neq \varnothing$.

Proof. ( $\geq$ ): Let $\Gamma_{1}, \ldots, \Gamma_{p}$ and $k_{1}, \ldots, k_{p}$ be as in (6.8). We wish to show that there exists a tuple of Reeb orbits $\Gamma$ such that

$$
\# \Gamma \leq \ell, \quad \mathcal{A}(\Gamma) \leq \sum_{i=1}^{p} \mathcal{A}\left(\Gamma_{i}\right), \quad \overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle \neq \varnothing
$$

By Remark 4.25, the tuple $\Gamma=\Gamma_{1} \cup \cdots \cup \Gamma_{p}$ is as desired.
$(\leq)$ : Let $\Gamma^{+}$be a tuple of Reeb orbits such that $\# \Gamma^{+} \leq \ell$ and $\overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle \neq \varnothing$. We wish to show that there exist tuples of Reeb orbits $\Gamma_{1}^{-}, \ldots, \Gamma_{p}^{-}$and numbers $k_{1}, \ldots, k_{p}$ satisfying (6.8) and

$$
\sum_{i=1}^{p} \mathcal{A}\left(\Gamma_{i}\right) \leq \mathcal{A}(\Gamma) .
$$

Choose $F=\left(F^{1}, \ldots, F^{N}\right) \in \overline{\mathcal{M}}_{X}^{J}\left(\Gamma^{+}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ and let $C$ be the component of $F$ which inherits the constraint $\left\langle\mathcal{T}^{(k)} x\right\rangle$.
We prove the result in the case where $C$ is nonconstant. In this case, $C \in \mathcal{M}_{X}^{J}\left(\Gamma^{-}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ for some tuple of Reeb orbits $\Gamma^{-}$. By Lemma 4.13, $\mathcal{A}\left(\Gamma^{-}\right) \leq \mathcal{A}\left(\Gamma^{+}\right)$. We show that $\# \Gamma^{-} \leq \# \Gamma^{+} \leq \ell$. Let $\mathbf{n}$ be the set of nodal points of $C$. Since the graph of $F$ is a tree, for every $\gamma \in \Gamma^{+}$there exists a unique $f(\gamma) \in \Gamma^{-} \cup \mathbf{n}$ such that the subtree of $F$ emanating from $C$ at $f(\gamma)$ is positively asymptotic to $\gamma$. By the maximum principle (Lemma 4.10), $f: \Gamma^{+} \longrightarrow \Gamma^{-} \cup \mathbf{n}$ is surjective, and therefore $\# \Gamma^{-} \leq \# \Gamma^{+} \leq \ell$.

We prove the result in the case where $C$ is constant. Let $C_{1}, \ldots, C_{p}$ be the nonconstant components near $C$ as in Remark 4.25. There exist tuples of Reeb orbits $\Gamma_{1}^{-}, \ldots, \Gamma_{p}^{-}$and $k_{1}, \ldots, k_{p} \in \mathbb{Z}_{\geq 1}$ such that

$$
\sum_{i=1}^{p} \mathcal{A}\left(\Gamma_{i}^{-}\right) \leq \mathcal{A}\left(\Gamma^{+}\right), \quad \sum_{i=1}^{p} k_{i} \geq k, \quad C_{i} \in \mathcal{M}_{X}^{J}\left(\Gamma_{i}^{-}\right)\left\langle\mathcal{T}^{\left(k_{i}\right)} x\right\rangle \neq \varnothing
$$

By a reasoning similar to the previous case, $\sum_{i=1}^{p} \# \Gamma_{i}^{-} \leq \# \Gamma^{+} \leq \ell$.

Remark 6.35. If $(X, \lambda)$ is a nondegenerate Liouville domain, $k \in \mathbb{Z}_{\geq 1}, x \in \operatorname{int} X$ and $D$ is a symplectic divisor through $x$, then

$$
\tilde{\mathfrak{g}}_{k}^{\leq 1}(X)=\sup _{J \in \mathcal{J}(X, D)} \inf _{\gamma} \mathcal{A}(\gamma),
$$

where the infimum is over Reeb orbits $\gamma$ such that $\mathcal{M}_{X}^{J}(\gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle \neq \varnothing$.
Theorem 6.36 ([MS22, Theorem 3.3.2]). The functions $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$ are independent of the choices of $x$ and $D$ and satisfy the following properties, for all nondegenerate Liouville domains $\left(X, \lambda_{X}\right)$ and $\left(Y, \lambda_{Y}\right)$ of the same dimension:
(Monotonicity) If $X \longrightarrow Y$ is a generalized Liouville embedding then $\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X) \leq \tilde{\mathfrak{g}}_{k}^{\leq \ell}(Y)$.
(Conformality) If $\alpha>0$ then $\tilde{\mathfrak{g}}_{k}^{\leq \ell}\left(X, \alpha \lambda_{X}\right)=\alpha \tilde{\mathfrak{g}}_{k}^{\leq \ell}\left(X, \lambda_{X}\right)$.
(Nondecreasing) $\tilde{\mathfrak{g}}_{1}^{\leq \ell}(X) \leq \tilde{\mathfrak{g}}_{2}^{\leq \ell}(X) \leq \cdots \leq+\infty$.
We now state a result comparing the McDuff-Siegel capacities and the Gutt-Hutchings capacities. We will later apply this result to show that $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$ for every 4dimensional convex toric domain $X_{\Omega}$ (Theorem 6.41).

Proposition 6.37 ([MS22, Proposition 5.6.1]). If $X_{\Omega}$ is a 4-dimensional convex toric domain then

$$
\tilde{\mathfrak{g}}_{k}^{\leq 1}\left(X_{\Omega}\right)=c_{k}^{\mathrm{GH}}\left(X_{\Omega}\right)
$$

Finally, we state two stabilization results which we will use in Section 7.7.
Lemma 6.38 ([MS22, Lemma 3.6.2]). Let $(X, \lambda)$ be a Liouville domain. For any $c, \varepsilon \in$ $\mathbb{R}_{>0}$, there is a subdomain with smooth boundary $\tilde{X} \subset X \times B^{2}(c)$ such that:
(1) The Liouville vector field $Z_{\tilde{X}}=Z_{X}+Z_{B^{2}(c)}$ is outwardly transverse along $\partial \tilde{X}$.
(2) $X \times\{0\} \subset \tilde{X}$ and the Reeb vector field of $\partial \tilde{X}$ is tangent to $\partial X \times\{0\}$.
(3) Any Reeb orbit of the contact form $\left.\left(\lambda+\lambda_{0}\right)\right|_{\partial \tilde{X}}$ (where $\left.\lambda_{0}=1 / 2(x \mathrm{~d} y-y \mathrm{~d} x)\right)$ with action less than $c-\varepsilon$ is entirely contained in $\partial X \times\{0\}$ and has normal ConleyZehnder index equal to 1.
Lemma 6.39 ([MS22, Lemma 3.6.3]). Let $X$ be a Liouville domain, and let $\tilde{X}$ be a smoothing of $X \times B^{2}(c)$ as in Lemma 6.38.
(1) Let $J \in \mathcal{J}(\tilde{X})$ be a cylindrical almost complex structure on the completion of $\tilde{X}$ for which $\hat{X} \times\{0\}$ is J-holomorphic. Let $C$ be an asymptotically cylindrical $J$-holomorphic curve in $\hat{X}$, all of whose asymptotic Reeb orbits are nondegenerate and lie in $\partial X \times\{0\}$ with normal Conley-Zehnder index 1. Then $C$ is either disjoint from the slice $\hat{X} \times\{0\}$ or entirely contained in it.
(2) Let $J \in \mathcal{J}(\partial \tilde{X})$ be a cylindrical almost complex structure on the symplectization of $\partial \tilde{X}$ for which $\mathbb{R} \times \partial X \times\{0\}$ is J-holomorphic. Let $C$ be an asymptotically cylindrical J-holomorphic curve in $\mathbb{R} \times \partial \tilde{X}$, all of whose asymptotic Reeb orbits are nondegenerate and lie in $\partial X \times\{0\}$ with normal Conley-Zehnder index 1. Then $C$ is either disjoint from the slice $\mathbb{R} \times \partial X \times\{0\}$ or entirely contained in it. Moreover, only the latter is possible if $C$ has at least one negative puncture.

### 6.5 Computations not requiring contact homology

We now state and prove one of our main theorems, which is going to be a key step in proving that $c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}$. The proof uses techniques similar to those used in the proof of [CM18, Theorem 1.1].

Theorem 6.40. If $(X, \lambda)$ is a Liouville domain then

$$
c_{L}(X) \leq \inf _{k} \frac{\tilde{\mathfrak{a}}_{k}^{\leq 1}(X)}{k} .
$$

Proof. By Lemma 6.11, we may assume that $X$ is nondegenerate. Let $k \in \mathbb{Z}_{\geq 1}$ and $L \subset \operatorname{int} X$ be an embedded Lagrangian torus. We wish to show that for every $\varepsilon>0$ there exists $\sigma \in \pi_{2}(X, L)$ such that $0<\omega(\sigma) \leq \tilde{\mathfrak{g}}_{k}^{\leq 1}(X) / k+\varepsilon$. Define

$$
\begin{aligned}
a & :=\tilde{\mathfrak{g}}_{k}^{\leq 1}(X), \\
K_{1} & :=\ln (2), \\
K_{2} & :=\ln (1+a / \varepsilon k), \\
K & :=\max \left\{K_{1}, K_{2}\right\}, \\
\delta & :=e^{-K}, \\
\ell_{0} & :=a / \delta .
\end{aligned}
$$

By Lemma 3.30 and the Lagrangian neighbourhood theorem, there exists a Riemannian metric $g$ on $L$ and a symplectic embedding $\phi: D^{*} L \longrightarrow X$ such that $\phi\left(D^{*} L\right) \subset \operatorname{int} X$, $\left.\phi\right|_{L}=\operatorname{id}_{L}$ and such that if $\gamma$ is a closed geodesic in $L$ with length $\ell(\gamma) \leq \ell_{0}$ then $\gamma$ is noncontractible, nondegenerate and satisfies $0 \leq \mu_{\mathrm{M}}(\gamma) \leq n-1$.
Let $D_{\delta}^{*} L$ be the codisk bundle of radius $\delta$. Notice that $\delta$ has been chosen in such a way that the symplectic embedding $\phi: D^{*} L \longrightarrow X$ can be seen as an embedding like that of Lemma 4.14. We will now use the notation of Section 4.3. Define symplectic cobordisms

$$
\begin{aligned}
& \left(X^{+}, \omega^{+}\right):=\left(X \backslash \phi\left(D_{\delta}^{*} L\right), \omega\right), \\
& \left(X^{-}, \omega^{-}\right):=\left(D_{\delta}^{*} L, \mathrm{~d} \lambda_{T^{*} L}\right),
\end{aligned}
$$

which have the common contact boundary

$$
(M, \alpha):=\left(S_{\delta}^{*} L, \lambda_{T^{*} L}\right) .
$$

Here, it is implicit that we are considering the restriction of the form $\lambda_{T^{*} L}$ on $T^{*} L$ to $D_{\delta}^{*} L$ or $S_{\delta}^{*} L$. Then, $(X, \omega)=\left(X^{-}, \omega^{-}\right) \odot\left(X^{+}, \omega^{+}\right)$. Recall that there are piecewise smooth 2-forms $\tilde{\omega} \in \Omega^{2}(\hat{X})$ and $\tilde{\omega}^{ \pm} \in \Omega^{2}\left(\hat{X}^{ \pm}\right)$which are given as in Definition 4.12. Choose $x \in \operatorname{int} \phi\left(D_{\delta}^{*} L\right)$ and let $D \subset \phi\left(D_{\delta}^{*} L\right)$ be a symplectic divisor through $x$. Choose also generic almost complex structures

$$
\begin{aligned}
J_{M} & \in \mathcal{J}(M) \\
J^{+} & \in \mathcal{J}_{J_{M}}\left(X^{+}\right), \\
J^{-} & \in \mathcal{J}^{J_{M}}\left(X^{-}, D\right),
\end{aligned}
$$

and denote by $J_{\partial X} \in \mathcal{J}(\partial X)$ the "restriction" of $J^{+}$to $\mathbb{R} \times \partial X$. Let $\left(J_{t}\right)_{t} \subset \mathcal{J}(X, D)$ be the corresponding neck stretching family of almost complex structures. Since $a=$ $\tilde{\mathfrak{g}}_{k}^{\leq 1}(X)$ and by Remark 6.35, for every $t$ there exists a Reeb orbit $\gamma_{t}$ in $\partial X=\partial^{+} X^{+}$ and a $J_{t}$-holomorphic curve $u_{t} \in \mathcal{M}_{X}^{J_{t}}\left(\gamma_{t}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle$ such that $\mathcal{A}\left(\gamma_{t}\right) \leq a$. Since $\partial X$ has nondegenerate Reeb orbits, there are only finitely many Reeb orbits in $\partial X$ with action less than $a$. Therefore, possibly after passing to a subsequence, we may assume that $\gamma_{t}=: \gamma_{0}$ is independent of $t$.

The curves $u_{t}$ satisfy the energy bound $E_{\tilde{\omega}}\left(u_{t}\right) \leq a$. By the SFT compactness theorem, the sequence $\left(u_{t}\right)_{t}$ converges to a holomorphic building

$$
F=\left(F^{1}, \ldots, F^{L_{0}-1}, F^{L_{0}}, F^{L_{0}+1}, \ldots, F^{N}\right) \in \overline{\mathcal{M}}_{X}^{\left(J_{t}\right)_{t}}\left(\gamma_{0}\right)\left\langle\mathcal{T}^{(k)} x\right\rangle
$$

where

$$
\begin{aligned}
&\left(X^{\nu}, \omega^{\nu}, \tilde{\omega}^{\nu}, J^{\nu}\right):= \begin{cases}\left(T^{*} L, \mathrm{~d} \lambda_{T^{*} L}, \tilde{\omega}^{-}, J^{-}\right) & \text {if } \nu=1, \\
\left(\mathbb{R} \times M, \mathrm{~d}\left(e^{r} \alpha\right), \mathrm{d} \alpha, J_{M}\right) & \text { if } \nu=2, \ldots, L_{0}-1, \\
\left(\hat{X} \backslash L, \hat{\omega}, \tilde{\omega}^{+}, J^{+}\right) & \text {if } \nu=L_{0}, \\
\left(\mathbb{R} \times \partial X, \mathrm{~d}\left(\left.e^{r} \lambda\right|_{\partial X}\right),\left.\mathrm{d} \lambda\right|_{\partial X}, J_{\partial X}\right) & \text { if } \nu=L_{0}+1, \ldots, N,\end{cases} \\
&\left(X^{*}, \omega^{*}, \tilde{\omega}^{*}, J^{*}\right):=\coprod_{\nu=1}^{N}\left(X^{\nu}, \omega^{\nu}, \tilde{\omega}^{\nu}, J^{\nu}\right),
\end{aligned}
$$

and $F^{\nu}$ is a $J^{\nu}$-holomorphic curve in $X^{\nu}$ with asymptotic Reeb orbits $\Gamma_{\nu}^{ \pm}$(see Fig. 6.1). The holomorphic building $F$ satisfies the energy bound

$$
\begin{equation*}
E_{\tilde{\omega}^{*}}(F):=\sum_{\nu=1}^{N} E_{\tilde{\omega}^{\nu}}\left(F^{\nu}\right) \leq a . \tag{6.9}
\end{equation*}
$$

Moreover, by Lemma 4.27, $F$ has no nodes. Let $C$ be the component of $F$ in $X^{-}$which carries the tangency constraint $\left\langle\mathcal{T}^{(k)} x\right\rangle$. Then, $C$ is positively asymptotic to Reeb orbits $\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ of $M$. For $\mu=1, \ldots, p$, let $C_{\mu}$ be the subtree emanating from $C$ at $\gamma_{\mu}$. For exactly one $\mu=1, \ldots, p$, the top level of the subtree $C_{\mu}$ is positively asymptotic to $\gamma_{0}$, and we may assume without loss of generality that this is true for $\mu=1$. By the


Figure 6.1: The holomorphic building $F=\left(F^{1}, \ldots, F^{N}\right)$ in the case $L_{0}=N=p=3$
maximum principle, $C_{\mu}$ has a component in $X^{L_{0}}=\hat{X} \backslash L$ for every $\mu=2, \ldots, p$. Also by the maximum principle, there do not exist components of $C_{\mu}$ in $X^{L_{0}}=\hat{X} \backslash L$ which intersect $\mathbb{R}_{\geq 0} \times \partial X$ or components of $C_{\mu}$ in the top symplectization layers $X^{L_{0}+1}, \ldots, X^{N}$, for every $\mu=2, \ldots, p$.

We claim that if $\gamma$ is a Reeb orbit in $M$ which is an asymptote of $F^{\nu}$ for some $\nu=$ $2, \ldots, L_{0}-1$, then $\mathcal{A}(\gamma) \leq a$. To see this, notice that

$$
\begin{aligned}
a & \geq E_{\tilde{\omega}^{*}}(F) & & {[\text { by Equation (6.9)] }} \\
& \geq E_{\tilde{\omega}^{N}}\left(F^{N}\right) & & {[\text { by monotonicity of } E] } \\
& \geq\left(e^{K}-1\right) \mathcal{A}\left(\Gamma_{N}^{-}\right) & & {[\text {by Lemma 4.14] }} \\
& \geq \mathcal{A}\left(\Gamma_{N}^{-}\right) & & {\left[\text {since } K \geq K_{1}\right] } \\
& \geq \mathcal{A}\left(\Gamma_{\nu}^{-}\right) & & {[\text {by Lemma 4.13] }}
\end{aligned}
$$

for every $\nu=2, \ldots, L_{0}-1$. Every such $\gamma$ has a corresponding geodesic in $L$ (which by abuse of notation we denote also by $\gamma$ ) such that $\ell(\gamma)=\mathcal{A}(\gamma) / \delta \leq a / \delta=\ell_{0}$. Hence, by our choice of Riemannian metric, the geodesic $\gamma$ is noncontractible, nondegenerate and such that $\mu_{\mathrm{M}}(\gamma) \leq n-1$. Therefore, the Reeb orbit $\gamma$ is noncontractible, nondegenerate and such that $\mu_{\mathrm{CZ}}(\gamma) \leq n-1$.

We claim that if $D$ is a component of $C_{\mu}$ for some $\mu=2, \ldots, p$ and $D$ is a plane, then $D$ is in $X^{L_{0}}=\hat{X} \backslash L$. Assume by contradiction otherwise. Notice that since $D$ is a plane, $D$ is asymptotic to a unique Reeb orbit $\gamma$ in $M=S_{\delta}^{*} L$ with corresponding noncontractible geodesic $\gamma$ in $L$. We will derive a contradiction by defining a filling disk for $\gamma$. If $D$ is in a symplectization layer $\mathbb{R} \times S_{\delta}^{*} L$, then the map $\pi \circ D$, where $\pi: \mathbb{R} \times S_{\delta}^{*} L \longrightarrow L$ is the projection, is a filling disk for the geodesic $\gamma$. If $D$ is in the bottom level, i.e. $X^{1}=T^{*} L$,
then the map $\pi \circ D$, where $\pi: T^{*} L \longrightarrow L$ is the projection, is also a filling disk. This proves the claim.

So, summarizing our previous results, we know that for every $\mu=2, \ldots, p$ there is a holomorphic plane $D_{\mu}$ in $X^{L_{0}} \backslash\left(\mathbb{R}_{\geq 0} \times \partial X\right)=X \backslash L$. For each plane $D_{\mu}$ there is a corresponding disk in $X$ with boundary on $L$, which we denote also by $D_{\mu}$. It is enough to show that $E_{\omega}\left(D_{\mu_{0}}\right) \leq a / k+\varepsilon$ for some $\mu_{0}=2, \ldots, p$. By Lemma 4.17, $p \geq k+1 \geq 2$. By definition of average, there exists $\mu_{0}=2, \ldots, p$ such that

$$
\begin{aligned}
E_{\omega}\left(D_{\mu_{0}}\right) & \leq \frac{1}{p-1} \sum_{\mu=2}^{p} E_{\omega}\left(D_{\mu}\right) & & {[\text { by definition of average] }} \\
& =\frac{E_{\omega}\left(D_{2} \cup \cdots \cup D_{p}\right)}{p-1} & & {[\text { since energy is additive }] } \\
& \leq \frac{e^{K}}{e^{K}-1} \frac{E_{\tilde{\omega}}\left(D_{2} \cup \cdots \cup D_{p}\right)}{p-1} & & {[\text { by Lemma } 4.14] } \\
& \leq \frac{e^{K}}{e^{K}-1} \frac{a}{p-1} & & {[\text { by Equation }(6.9)] } \\
& \leq \frac{e^{K}}{e^{K}-1} \frac{a}{k} & & {[\text { since } p \geq k+1] } \\
& \leq \frac{a}{k}+\varepsilon & & {\left[\text { since } K \geq K_{2}\right] . }
\end{aligned}
$$

Theorem 6.41. If $X_{\Omega}$ is a 4-dimensional convex toric domain then

$$
c_{L}\left(X_{\Omega}\right)=\delta_{\Omega} .
$$

Proof. For every $k \in \mathbb{Z}_{\geq 1}$,

$$
\begin{aligned}
\delta_{\Omega} & \leq c_{P}\left(X_{\Omega}\right) & & {[\text { by Lemma 6.20] }} \\
& \leq c_{L}\left(X_{\Omega}\right) & & {[\text { by Lemma 6.19] }} \\
& \leq \frac{\tilde{\mathfrak{g}}_{k}^{\leq 1}\left(X_{\Omega}\right)}{k} & & {[\text { by Theorem 6.40] }} \\
& =\frac{c_{k}^{\mathrm{GH}}\left(X_{\Omega}\right)}{k} & & {[\text { by Proposition 6.37] }} \\
& \leq \frac{c_{k}^{\mathrm{GH}}\left(N\left(\delta_{\Omega}\right)\right)}{k} & & {\left[X_{\Omega} \text { is convex, hence } X_{\Omega} \subset N\left(\delta_{\Omega}\right)\right] } \\
& =\frac{\delta_{\Omega}(k+1)}{k} & & {[\text { by Lemma 6.28]. }}
\end{aligned}
$$

The result follows by taking the infimum over $k$.
The proof of Theorem 6.41 suggests the following conjecture. Notice that Conjecture 6.42 implies Conjecture 6.24.
Conjecture 6.42. If $X$ is a Liouville domain, $\pi_{1}(X)=0$ and $\left.c_{1}(T X)\right|_{\pi_{2}(X)}=0$, then

$$
c_{L}(X, \lambda) \leq \inf _{k} \frac{c_{k}^{\mathrm{GH}}(X, \lambda)}{k}
$$

Proof attempt. By Lemma 6.11, we may assume that $X$ is nondegenerate. Let $k \in \mathbb{Z}_{\geq 1}$ and $L \subset$ int $X$ be an embedded Lagrangian torus. Let also $a>c_{k}^{G H}(X)$. We wish to show that for every $\varepsilon>0$ there exists $\sigma \in \pi_{2}(X, L)$ such that $0<\omega(\sigma) \leq a / k+\varepsilon$. Start by replicating word by word the proof of Theorem 6.40 until the point where we choose $x \in \phi\left(D_{\delta}^{*} L\right)$. Instead of choosing $x$, choose a nondegenerate star-shaped domain $E \subset \mathbb{C}^{n}$ and an exact symplectic embedding $\varphi: E \longrightarrow X$ such that $\varphi(E) \subset \operatorname{int} \phi\left(D_{\delta}^{*} L\right)$. Since $a>c_{k}^{\mathrm{GH}}(X)$ and by Lemma 6.27 , the map

$$
\begin{equation*}
S H_{n-1+2 k}^{S^{1},(\varepsilon, a]}(X) \xrightarrow{\iota^{a}} S H_{n-1+2 k}^{S^{1},+}(X) \xrightarrow{\varphi!} S H_{n-1+2 k}^{S^{1},+}(E) \tag{6.10}
\end{equation*}
$$

is nonzero. Choose Hamiltonians

$$
\begin{array}{rrr}
H^{+}: S^{1} \times S^{2 N+1} \times \hat{X} \longrightarrow \mathbb{R}, & H^{+} \in \mathcal{H}(X, N), & \text { (see Definition 5.8), } \\
H^{-}: S^{1} \times S^{2 N+1} \times \hat{X} \longrightarrow \mathbb{R}, & H^{-} \in \mathcal{H}(X, E, N), & \text { (see Definition 5.29), } \\
H: \mathbb{R} \times S^{1} \times S^{2 N+1} \times \hat{X} \longrightarrow \mathbb{R}, & H \in \mathcal{H}\left(H^{+}, H^{-}\right), & \text {(see Definition 5.36). }
\end{array}
$$

Choose also an almost complex structure

$$
J: S^{1} \times S^{2 N+1} \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X}), \quad J \in \mathcal{J}(X, E, N), \quad \text { (see Definition 5.32). }
$$

The almost complex structure $J$ defines a neck stretching family of almost complex structures

$$
J_{m}: S^{1} \times S^{2 N+1} \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X}), \quad J_{m} \in \mathcal{J}(X, E, N)
$$

for $m \in \mathbb{Z}_{\geq 1}$. Since the map (6.10) is nonzero and by definition of the Viterbo transfer map, if $N, H^{ \pm}, H$ are chosen big enough (in the sense of the partial orders defined in Sections 5.3 and 5.4) then for every $m$ there exist $\left(z_{m}^{ \pm}, \gamma_{m}^{ \pm}\right) \in \hat{\mathcal{P}}\left(H^{ \pm}\right)$and a Floer trajectory $\left(w_{m}, u_{m}\right)$ with respect to $H, J_{m}$ from $\left(z_{m}^{-}, \gamma_{m}^{-}\right)$to $\left(z_{m}^{+}, \gamma_{m}^{+}\right)$, such that
(1) im $\gamma_{m}^{+}$is near $\partial X$ and $\mathcal{A}_{H^{+}}\left(z_{m}^{+}, \gamma_{m}^{+}\right) \leq a$;
(2) im $\gamma_{m}^{-}$is near $\partial E$ and $\mu\left(z_{m}^{-}, \gamma_{m}^{-}\right) \geq n-1+2 k$.

By Lemma 4.37, we have the energy bound $E\left(w_{m}, u_{m}\right) \leq a$. Possibly after passing to a subsequence, we may assume that $\left(z_{m}^{ \pm}, \gamma_{m}^{ \pm}\right)$converges to $\left(z_{0}^{ \pm}, \gamma_{0}^{ \pm}\right) \in \hat{\mathcal{P}}\left(H^{ \pm}\right)$.
Now we come to the first challenge of the proof. We would like to use an adaptation of the SFT compactness theorem to take the limit of the sequence $\left(w_{m}, u_{m}\right)_{m}$. We will assume that such a theorem can be proven, and that we get a resulting limit $F=\left(F^{1}, \ldots, F^{N}\right)$ as in the proof of Theorem 6.40, but where each $F^{\nu}=\left(w^{\nu}, u^{\nu}\right): \dot{\Sigma}^{\nu} \longrightarrow S^{2 N+1} \times X^{\nu}$ is a solution of the parametrized Floer equation (Definition 4.32). Let $C$ be the component of $F$ in $X^{-}$which is negatively asymptotic to $\left(z_{0}^{-}, \gamma_{0}^{-}\right)$.
Notice that near $X \backslash \phi\left(D_{\delta}^{*} L\right)$, the Hamiltonian $H$ is independent of $\hat{X}$. Therefore, in the intermediate symplectization levels (i.e. for $\nu=2, \ldots, L-1$ ) the map $u^{\nu}: \dot{\Sigma}^{\nu} \longrightarrow X^{\nu}$ is $J_{w^{\nu}}^{\nu}$-holomorphic, where $J_{w^{\nu}}^{\nu}: \dot{\Sigma}^{\nu} \times X^{\nu} \longrightarrow \operatorname{End}\left(T X^{\nu}\right)$ is a domain dependent almost complex structure obtained from composing an almost complex structure $J^{\nu}: \dot{\Sigma}^{\nu} \times$ $S^{2 N+1} \times X^{\nu} \longrightarrow \operatorname{End}\left(T X^{\nu}\right)$ with $w^{\nu}$. Hence, as in the proof of Theorem 6.40, the component $C$ has $p$ positive punctures asymptotic to Reeb orbits $\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ and for every $\mu=2, \ldots, p$ there is a disk $D_{\mu}$ in $X$ with boundary on $L$.

At this point, we need to show that $p \geq k+1$, which brings us to the main difficulty in the proof. In the proof of Theorem 6.40, we chose a generic almost complex structure so that $C$ would be regular. Then, the index formula for $C$ implied that $p \geq k+1$ (see Theorem 4.15 and Lemmas 4.16 and 4.17). In line with this reasoning, we wish to show that $p \geq k+1$ using the following computation:

$$
\begin{aligned}
0 & \leq \operatorname{ind}(C) \\
& =(n-3)(1-p)+\sum_{\mu=1}^{p} \mu_{\mathrm{CZ}}\left(\gamma_{\mu}\right)-\mu\left(z_{0}^{-}, \gamma_{0}^{-}\right) \\
& \leq(n-3)(1-p)+\sum_{\mu=1}^{p}(n-1)-(n-1+2 k) \\
& =2(p-k-1),
\end{aligned}
$$

where in the first line we would need to use a transversality theorem which applies to $C$, and in the second line we would need to use a Fredholm theory theorem which gives us the desired index formula for $C$. We point out a few difficulties that arise with this approach.
(1) Because of the domain dependence of the almost complex structures and Hamiltonians, it is not clear how to choose the initial almost complex structure $J: S^{1} \times$ $S^{2 N+1} \times \hat{X} \longrightarrow \operatorname{End}(T \hat{X})$ in such a way that the resulting almost complex structure $J^{1}: \dot{\Sigma}^{1} \times S^{2 N+1} \times X^{1} \longrightarrow \operatorname{End}\left(T X^{1}\right)$ is regular.
(2) We are working under the assumption that the analogue of the SFT compactness theorem which applies to solutions of the parametrized Floer equation produces a building $F$ whose symplectization levels are asymptotic to Reeb orbits. More specifically, this means that the gradient flow line in $S^{2 N+1}$ corresponding to $C$ is not asymptotic at the punctures to critical points of $\tilde{f}_{N}$. Therefore, in this case the linearized operator corresponding to the gradient flow line equation on $S^{2 N+1}$ will not be Fredholm.
(3) However, the assumption in the previous item could be wrong. Another reasonable possibility is that the analogue of the SFT compactness theorem which applies to solutions of the parametrized Floer equation produces a building $F$ whose bottom component is positively asymptotic to pairs $\left(z_{\mu}, \gamma_{\mu}\right)$, where $z_{\mu} \in S^{2 N+1}$ is a critical point of $\tilde{f}_{N}$ and $\gamma_{\mu}$ is a Reeb orbit. In this case, one would expect that the relevant operator is Fredholm. However, the Morse index of the critical points $z_{\mu}$ would appear in the index formula, and the previous computation would no longer imply that $p \geq k+1$.

Finally, we point out that if $p \geq k+1$, then by the same computation as in the proof of Theorem 6.40, we have the desired energy bound

$$
E_{\omega}\left(D_{\mu_{0}}\right) \leq \frac{a}{k}+\varepsilon
$$

for some $\mu_{0}=2, \ldots, p$. This finishes the proof attempt.

## Chapter 7

## Contact homology

### 7.1 Assumptions on virtual perturbation scheme

In this chapter, we wish to use techniques from contact homology to prove Conjecture 6.24. Consider the proof of Theorem 6.41: to prove the inequality $c_{L}\left(X_{\Omega}\right) \leq \delta_{\Omega}$, we needed to use the fact that $\tilde{\mathfrak{g}}_{k}^{\leq 1}\left(X_{\Omega}\right) \leq c_{k}^{\mathrm{GH}}\left(X_{\Omega}\right)$ (which is true if $X_{\Omega}$ is convex and 4-dimensional). Our approach here will be to consider the capacities $\mathfrak{g}_{k}^{\leq \ell}$ from [Sie20], which satisfy $\tilde{\mathfrak{g}}_{k}^{\leq 1}(X) \leq \mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)$. As we will see, $\mathfrak{g}_{k}^{\leq \ell}(X)$ is defined using the linearized contact homology of $X$, where $X$ is any nondegenerate Liouville domain.

Very briefly, the linearized contact homology chain complex, denoted $C C(X)$, is generated by the good Reeb orbits of $\partial X$, and therefore maps whose domain is $C C(X)$ should count holomorphic curves which are asymptotic to Reeb orbits. The "naive" way to define such counts of holomorphic curves would be to show that they are the elements of a moduli space which is a compact, 0 -dimensional orbifold. However, there is the possibility that a curve is multiply covered. This means that in general it is no longer possible to show that the moduli spaces are transversely cut out, and therefore we do not have access to counts of moduli spaces of holomorphic curves (or at least not in the usual sense of the notion of signed count). In the case where the Liouville domain is 4 -dimensional, there exists the possibility of using automatic transversality techniques to show that the moduli spaces are regular. This is the approach taken by Wendl [Wen10]. Nelson [Nel15], Hutchings-Nelson [HN16] and Bao-Honda [BH18] use automatic transversality to define cylindrical contact homology.

In order to define contact homology in more general contexts, one needs to replace the notion of count by a suitable notion of virtual count, which is obtained through a virtual perturbation scheme. This was done by Pardon [Par16, Par19] to define contact homology in greater generality. The theory of polyfolds by Hofer-Wysocki-Zehnder [HWZ21] can also be used to define virtual moduli counts. Alternative approaches using Kuranishi structures have been given by Ishikawa [Ish18] and Bao-Honda [BH21].

Unfortunately, linearized contact homology is not yet defined in the generality we need.
(1) In order to prove Conjecture 6.24 , we only need the capacities $\mathfrak{g}_{k}^{\ell \ell}$ for $\ell=1$. These are defined using the linearized contact homology (as a chain complex) and an
augmentation map which counts curves satisfying a tangency constraint. As far as we know, the current work on defining virtual moduli counts does not yet deal with moduli spaces of curves satisfying tangency constraints.
(2) In addition to Conjecture 6.24 , in this chapter we will also prove some properties of the capacities $\mathfrak{g}_{k}^{\leq \ell}$ for $\ell>1$. The definition of these capacities for $\ell>1$ requires the structure of an $\mathcal{L}_{\infty}$-algebra on the linearized contact homology as well as an $\mathcal{L}_{\infty}$-augmentation map counting curves which satisfy a tangency constraint.
So, during this chapter, we will work under assumption that it is possible to define a virtual perturbation scheme which makes the invariants and maps described above well-defined (this is expected to be the case).

Assumption 7.1. We assume the existence of a virtual perturbation scheme which to every compactified moduli space $\overline{\mathcal{M}}$ of asymptotically cylindrical holomorphic curves (in a symplectization or in a Liouville cobordism, possibly satisfying a tangency constraint) assigns a virtual count $\#^{\mathrm{vir}} \overline{\mathcal{M}}$. We will assume in addition that the virtual perturbation scheme has the following properties.
(1) If $\#^{\text {vir }} \overline{\mathcal{M}} \neq 0$ then $\operatorname{virdim} \overline{\mathcal{M}}=0$;
(2) If $\overline{\mathcal{M}}$ is transversely cut out then $\#^{\mathrm{vir}} \overline{\mathcal{M}}=\# \overline{\mathcal{M}}$. In particular, if $\overline{\mathcal{M}}$ is empty then $\#^{\text {vir }} \overline{\mathcal{M}}=0 ;$
(3) The virtual count of the boundary of a moduli space (defined as a sum of virtual counts of the moduli spaces that constitute the codimension one boundary strata) is zero. In particular, the expected algebraic identities $\left(\partial^{2}=0\right.$ for differentials, $\varepsilon \circ \partial=0$ for augmentations) hold, as well as independence of auxiliary choices of almost complex structure and symplectic divisor.

## $7.2 \quad \mathcal{L}_{\infty}$-algebras

In this section, we give a brief review of the algebraic definitions which will play a role. Our main reference is [Sie20, Section 2]. The key definitions are that of $\mathcal{L}_{\infty}$-algebra (Definition 7.5) and its associated bar complex (Definition 7.6). We start by defining the suspension of a graded vector space. The purpose of this definition is to define $\mathcal{L}_{\infty^{-}}$ algebras in such a way that the $\mathcal{L}_{\infty}$-relations do not have extra signs (these extra signs are "absorbed" by the degree shift in the suspension).

Definition 7.2. Let $V=\bigoplus_{k \in \mathbb{Z}} V^{k}$ be a graded vector space over a field $K$. The suspension of $V$ is the graded vector space $V[+1]=\bigoplus_{k \in \mathbb{Z}}(V[+1])^{k}$ given by $(V[+1])^{k}=V^{k+1}$. Define $s: V \longrightarrow V[+1]$ to be the linear map of degree -1 given by $s(v)=v$.
Remark 7.3. We use the Koszul sign convention, i.e. if $f, g: V \longrightarrow V$ are linear maps and $x, y \in V$ then $(f \otimes g)(x \otimes y)=(-1)^{\operatorname{deg}(x) \operatorname{deg}(g)} f(x) \otimes g(y)$.

Definition 7.4. Let $k \in \mathbb{Z}_{\geq 1}$ and denote by $\operatorname{Sym}(k)$ the symmetric group on $k$ elements. Let $V$ be a vector field over a field $K$. We define an $\operatorname{action}$ of $\operatorname{Sym}(k)$ on $\otimes_{j=1}^{k} V$ as follows. For $\sigma \in \operatorname{Sym}(k)$ and $v_{1}, \ldots, v_{k} \in V$, let

$$
\operatorname{sign}\left(\sigma, v_{1}, \ldots, v_{k}\right):=(-1)^{\operatorname{sum}\left\{\operatorname{deg}\left(v_{i}\right) \operatorname{deg}\left(v_{j}\right) \mid 1 \leq i<j \leq k, \sigma(i)>\sigma(j)\right\}},
$$

$$
\sigma \cdot\left(v_{1} \otimes \cdots \otimes v_{k}\right):=\operatorname{sign}\left(\sigma, v_{1}, \ldots, v_{k}\right) v_{\sigma(1)} \otimes \cdots \otimes v_{\sigma(k)} .
$$

Define $\odot_{j=1}^{k} V:=\bigotimes_{j=1}^{k} V / \operatorname{Sym}(k)$ and denote by $v_{1} \odot \cdots \odot v_{k}$ the equivalence class of $v_{1} \otimes \cdots \otimes v_{k}$.

We come to the main definition of this section, which encodes the algebraic structure of linearized contact homology (see Definition 7.12).
Definition 7.5. An $\mathcal{L}_{\infty}$-algebra is a graded vector space $V=\bigoplus_{k \in \mathbb{Z}} V^{k}$ together with a family $\ell=\left(\ell^{k}\right)_{k \in \mathbb{Z}_{\geq 1}}$ of maps $\ell^{k}: \bigodot_{j=1}^{k} V[+1] \longrightarrow V[+1]$ of degree 1 , satisfying the $\mathcal{L}_{\infty}$-relations, i.e.

$$
\begin{aligned}
0=\sum_{k=1}^{n} \sum_{\sigma \in \operatorname{Sh}(k, n-k)} & \operatorname{sign}\left(\sigma, s v_{1}, \ldots, s v_{n}\right) \\
& \ell^{n-k+1}\left(\ell^{k}\left(s v_{\sigma(1)} \odot \cdots \odot s v_{\sigma(k)}\right) \odot s v_{\sigma(k+1)} \odot \cdots \odot s v_{\sigma(n)}\right)
\end{aligned}
$$

for every $v_{1}, \ldots, v_{n} \in V$. Here, $\operatorname{Sh}(k, n-k) \subset \operatorname{Sym}(n)$ is the subgroup of permutations $\sigma$ such that $\sigma(1)<\cdots<\sigma(k)$ and $\sigma(k+1)<\cdots<\sigma(n)$.

The definition of $\mathcal{L}_{\infty}$-algebra can be expressed more compactly via the notion of bar complex. Indeed, the family of maps $\left(\ell^{k}\right)_{k \in \mathbb{Z}_{\geq 1}}$ satisfies the $\mathcal{L}_{\infty}$-relations if and only if the map $\hat{\ell}$ defined below is a differential, i.e. $\hat{\ell} \circ \hat{\ell}=0$.

Definition 7.6. Let $(V, \ell)$ be an $\mathcal{L}_{\infty}$-algebra. The bar complex of $(V, \ell)$ is the vector space $\mathcal{B} V=\oplus_{k=1}^{+\infty} \bigodot_{j=1}^{k} V[+1]$ together with the degree 1 differential $\hat{\ell}: \mathcal{B} V \longrightarrow \mathcal{B} V$ given by

$$
\begin{aligned}
& \hat{\ell}\left(v_{1} \odot \cdots \odot v_{n}\right) \\
& \quad=\sum_{k=1}^{n} \sum_{\sigma \in \operatorname{Sh}(k, n-k)} \operatorname{sign}\left(\sigma, v_{1}, \ldots, v_{n}\right) \ell^{k}\left(v_{\sigma(1)} \odot \cdots \odot v_{\sigma(k)}\right) \odot v_{\sigma(k+1)} \odot \cdots \odot v_{\sigma(n)} .
\end{aligned}
$$

Definition 7.7. Let $(V, \ell)$ be an $\mathcal{L}_{\infty}$-algebra. A filtration on $V$ is a family $\left(\mathcal{F}^{\leq a} V\right)_{a \in \mathbb{R}}$ of subspaces $\mathcal{F}^{\leq a} V \subset V$, satisfying the following properties:
(1) if $a \leq b$ then $\mathcal{F}^{\leq a} V \subset \mathcal{F}^{\leq b} V$;
(2) $\bigcup_{a \in \mathbb{R}} \mathcal{F}^{\leq a} V=V$;
(3) $\ell^{k}\left(\mathcal{F}^{\leq a_{1}} V[+1] \odot \cdots \odot \mathcal{F}^{\leq a_{k}} V[+1]\right) \subset \mathcal{F} \leq a_{1}+\cdots+a_{k} V[+1]$.

Definition 7.8. Let $(V, \ell)$ be an $\mathcal{L}_{\infty}$-algebra together with a filtration $(\mathcal{F} \leq a V)_{a \in \mathbb{R}}$. The induced filtration on the bar complex is the family of complexes $\left(\mathcal{F}^{\leq a} \mathcal{B} V, \hat{\ell}\right)_{a \in \mathbb{R}}$, where

$$
\mathcal{F}^{\leq a} \mathcal{B} V:=\bigoplus_{k=1}^{+\infty} \bigcup_{a_{1}+\cdots+a_{k} \leq a} \bigodot_{j=1}^{k} \mathcal{F}^{\leq a_{j}} V[+1]
$$

and $\hat{\ell}: \mathcal{F}^{\leq a} \mathcal{B} V \longrightarrow \mathcal{F}^{\leq a} \mathcal{B} V$ is the restriction of $\hat{\ell}: \mathcal{B} V \longrightarrow \mathcal{B} V$.
The linearized contact homology will have a filtration induced by the action of the Reeb orbits (see Definition 7.14). Also, the bar complex of any $\mathcal{L}_{\infty}$-algebra has a filtration by word length, which is defined below.

Definition 7.9. Let $(V, \ell)$ be an $\mathcal{L}_{\infty}$-algebra and consider its bar complex $(\mathcal{B} V, \hat{\ell})$. The word length filtration of $(\mathcal{B} V, \hat{\ell})$ is the family of complexes $(\mathcal{B} \leq m V, \hat{\ell})_{m \in \mathbb{Z}_{\geq 1}}$, where $\mathcal{B}^{\leq m} V:=\oplus_{k=1}^{m} \bigodot_{j=1}^{k} V[+1]$ and $\hat{\ell}: \mathcal{B}^{\leq m} V \longrightarrow \mathcal{B}^{\leq m} V$ is the restriction of $\hat{\ell}: \mathcal{B} V \longrightarrow \mathcal{B} V$.

### 7.3 Contact homology

In this section, we define the linearized contact homology of a nondegenerate Liouville domain $X$. This is the homology of a chain complex $C C(X)$, which is described in Definition 7.11. This complex has additional structure, namely it is also an $\mathcal{L}_{\infty}$-algebra (Definition 7.12) and it admits a filtration by action (Definition 7.14). We also define an augmentation map (Definition 7.16), which is necessary to define the capacities $\mathfrak{g}_{k}^{\leq \ell}$.
Definition 7.10. Let $(M, \alpha)$ be a contact manifold and $\gamma$ be a Reeb orbit in $M$. We say that $\gamma$ is bad if $\mu_{\mathrm{CZ}}(\gamma)-\mu_{\mathrm{CZ}}\left(\gamma_{0}\right)$ is odd, where $\gamma_{0}$ is the simple Reeb orbit that corresponds to $\gamma$. We say that $\gamma$ is good if it is not bad.
Since the parity of the Conley-Zehnder index of a Reeb orbit is independent of the choice of trivialization, the definition above is well posed.

Definition 7.11. If $(X, \lambda)$ is a nondegenerate Liouville domain, the linearized contact homology chain complex of $X$, denoted $C C(X)$, is a chain complex given as follows. First, let $C C(X)$ be the vector space over $\mathbb{Q}$ generated by the set of good Reeb orbits of $\left(\partial X,\left.\lambda\right|_{\partial X}\right)$. The differential of $C C(X)$, denoted $\partial$, is given as follows. Choose $J \in \mathcal{J}(X)$. If $\gamma$ is a good Reeb orbit of $\partial X$, we define

$$
\partial \gamma=\sum_{\eta}\langle\partial \gamma, \eta\rangle \eta
$$

where $\langle\partial \gamma, \eta\rangle$ is the virtual count (with combinatorial weights) of holomorphic curves in $\mathbb{R} \times \partial X$ with one positive asymptote $\gamma$, one negative asymptote $\eta$, and $k \geq 0$ extra negative asymptotes $\alpha_{1}, \ldots, \alpha_{k}$ (called anchors), each weighted by the count of holomorphic planes in $\hat{X}$ asymptotic to $\alpha_{j}$ (see Fig. 7.1).
By assumption on the virtual perturbation scheme, $\partial \circ \partial=0$ and $C C(X)$ is independent (up to chain homotopy equivalence) of the choice of almost complex structure $J$. In general, $C C(X)$ is not $\mathbb{Z}$-graded but only $\mathbb{Z}_{2}$-graded (see Remark 7.13). We wish to define a structure of $\mathcal{L}_{\infty}$-algebra on $C C(X)[-1]$. Notice that the definition of $\mathcal{L}_{\infty^{-}}$ structure on a vector space (Definition 7.5) also makes sense when the vector space is only $\mathbb{Z}_{2}$-graded.

Definition 7.12. We define a structure of $\mathcal{L}_{\infty}$-algebra on $C C(X)[-1]$, given by maps $\ell^{k}: \odot^{k} C C(X) \longrightarrow C C(X)$, as follows. Choose an almost complex structure $J \in \mathcal{J}(X)$. If $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{k}\right)$ is a tuple of good Reeb orbits, we define

$$
\ell^{k}\left(\gamma_{1} \odot \cdots \odot \gamma_{k}\right)=\sum_{\eta}\left\langle\ell^{k}\left(\gamma_{1} \odot \cdots \odot \gamma_{k}\right), \eta\right\rangle \eta
$$

where $\left\langle\ell^{k}\left(\gamma_{1} \odot \cdots \odot \gamma_{k}\right), \eta\right\rangle$ is the virtual count of holomorphic curves in $\mathbb{R} \times \partial X$ with positive asymptotes $\gamma_{1}, \ldots, \gamma_{k}$, one negative asymptote $\eta$, and a number of extra negative asymptotes with anchors in $\hat{X}$, such that exactly one of the components in the symplectization level is nontrivial (see Fig. 7.2).


Figure 7.1: A holomorphic curve with anchors contributing to the coefficient $\langle\partial \gamma, \eta\rangle$


Figure 7.2: A holomorphic building contributing to the coefficient $\left\langle\ell^{4}\left(\gamma_{1} \odot \cdots \odot \gamma_{4}\right), \eta\right\rangle$

By the assumptions on the virtual perturbation scheme, the maps $\ell^{k}$ satisfy the $\mathcal{L}_{\infty^{-}}$ relations and $C C(X)$ is independent (as an $\mathcal{L}_{\infty}$-algebra, up to $\mathcal{L}_{\infty}$-homotopy equivalence) of the choice of $J$. We point out that the first $\mathcal{L}_{\infty}$-operation is equal to the differential of linearized contact homology, i.e. $\ell^{1}=\partial$.
Remark 7.13. In general, the Conley-Zehnder index of a Reeb orbit is well-defined as an element in $\mathbb{Z}_{2}$. Therefore, the complex $C C(X)$ has a $\mathbb{Z}_{2}$-grading given by $\operatorname{deg}(\gamma):=$ $n-3-\mu_{\mathrm{CZ}}(\gamma)$, and with respect to this definition of degree every $\mathcal{L}_{\infty}$-operation $\ell^{k}$ has degree 1. If $\pi_{1}(X)=0$ and $2 c_{1}(T X)=0$, then by Lemma 3.16 we have well-defined Conley-Zehnder indices in $\mathbb{Z}$, which means that $C C(X)$ is $\mathbb{Z}$-graded. For some purposes, it will be enough to consider only the chain complex structure on $C C(X)$ and not the $\mathcal{L}_{\infty}$-algebra structure (namely, when we consider only the capacity $\mathfrak{g}_{k}^{\leq 1}$ instead of the higher capacities $\mathfrak{g}_{k}^{\leq \ell}$ ). In this case, to make comparisons with $S^{1}$-equivariant symplectic homology simpler, we define the grading instead by $\operatorname{deg}(\gamma):=\mu_{\mathrm{CZ}}(\gamma)$, which implies that $\partial$ has degree -1 .
Definition 7.14. For every $a \in \mathbb{R}$, we denote by $\mathcal{A}^{\leq a} C C(X)[-1]$ the submodule of $C C(X)[-1]$ generated by the good Reeb orbits $\gamma$ with action $\mathcal{A}(\gamma) \leq a$. We call this filtration the action filtration of $C C[-1]$.
In the next lemma, we check that this filtration is compatible with the $\mathcal{L}_{\infty}$-structure.
Lemma 7.15. $\ell^{k}\left(\mathcal{A}^{\leq a_{1}} C C(X) \odot \cdots \odot \mathcal{A}^{\leq a_{k}} C C(X)\right) \subset \mathcal{A}^{\leq a_{1}+\cdots+a_{k}} C C(X)$.
Proof. Let $\gamma_{1}^{+}, \ldots, \gamma_{k}^{+}, \eta$ be good Reeb orbits such that

$$
\begin{aligned}
\mathcal{A}\left(\gamma_{i}^{+}\right) & \leq a_{i}, \\
\left\langle\ell^{k}\left(\gamma_{1}^{+} \odot \cdots \odot \gamma_{k}^{+}\right), \eta\right\rangle & \neq 0 .
\end{aligned}
$$

We wish to show that $\mathcal{A}(\eta) \leq a_{1}+\cdots+a_{k}$. Since $\left\langle\ell^{k}\left(\gamma_{1}^{+} \odot \cdots \odot \gamma_{k}^{+}\right), \eta\right\rangle \neq 0$ and by assumption on the virtual perturbation scheme, there exists a tuple of Reeb orbits $\Gamma^{-}$ and a (nontrivial) punctured $J$-holomorphic sphere in $\mathbb{R} \times \partial X$ with asymptotes $\Gamma^{ \pm}$, such that $\eta \in \Gamma^{-}$and $\Gamma^{+} \subset\left(\gamma_{1}^{+}, \ldots, \gamma_{k}^{+}\right)$. Then,

$$
\begin{aligned}
\mathcal{A}(\eta) & \leq \mathcal{A}\left(\Gamma^{-}\right) & & {\left[\text {since } \eta \in \Gamma^{-}\right] } \\
& \leq \mathcal{A}\left(\Gamma^{+}\right) & & {[\text {by Lemma } 4.13] } \\
& \leq \mathcal{A}\left(\gamma_{1}^{+}, \ldots, \gamma_{k}^{+}\right) & & {\left[\text {since } \Gamma^{+} \subset\left(\gamma_{1}^{+}, \ldots, \gamma_{k}^{+}\right)\right] } \\
& \leq a_{1}+\cdots+a_{k} . & & {[\text { by definition of action of a tuple }] . }
\end{aligned}
$$

Definition 7.16. Consider the bar complex $(\mathcal{B}(C C(X)[-1]), \hat{\ell})$. For each $k \in \mathbb{Z}_{\geq 1}$, we define an augmentation $\epsilon_{k}: \mathcal{B}(C C(X)[-1]) \longrightarrow \mathbb{Q}$ as follows. Choose $x \in \operatorname{int} X$, a symplectic divisor $D$ at $x$, and an almost complex structure $J \in \mathcal{J}(X, D)$. Then, for every tuple of good Reeb orbits $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ define $\epsilon_{k}\left(\gamma_{1} \odot \cdots \odot \gamma_{p}\right)$ to be the virtual count of $J$-holomorphic planes in $\hat{X}$ which are positively asymptotic to $\Gamma$ and have contact order $k$ to $D$ at $x$ (see Fig. 7.3).
By assumption on the virtual perturbation scheme, $\epsilon_{k}$ is an augmentation, i.e. $\epsilon_{k} \circ \hat{\ell}=0$. In addition, $\epsilon_{k}$ is independent (up to chain homotopy) of the choices of $x, D, J$.


Figure 7.3: A holomorphic curve contributing to the count $\epsilon_{k}\left(\gamma_{1} \odot \gamma_{2}\right)$

### 7.4 Higher symplectic capacities

Here we define the symplectic capacities $\mathfrak{g}_{k}^{\leq \ell}$ from [Sie20]. We will prove the usual properties of symplectic capacities (see Theorem 7.19), namely monotonicity and conformality. In addition, we prove that the value of the capacities $\mathfrak{g}_{k}^{\leq \ell}$ can be represented by the action of a tuple of Reeb orbits. In Remark 7.20 we show how this property could in principle be combined with results from [GH18] to compare the capacities $\mathfrak{g}_{k}^{\leq 1}\left(X_{\Omega}\right)$ and $c_{k}^{\mathrm{GH}}\left(X_{\Omega}\right)$ when $X_{\Omega}$ is a convex or concave toric domain.

Definition 7.17 ([Sie20, Section 6.1]). Let $k, \ell \in \mathbb{Z}_{\geq 1}$ and $(X, \lambda)$ be a nondegenerate Liouville domain. The higher symplectic capacities of $X$ are given by

$$
\mathfrak{g}_{k}^{\leq \ell}(X):=\inf \left\{a>0 \mid \epsilon_{k}: H\left(\mathcal{A}^{\leq a} \mathcal{B}^{\leq \ell}(C C(X)[-1])\right) \longrightarrow \mathbb{Q} \text { is nonzero }\right\} .
$$

The capacities $\mathfrak{g}_{k}^{\leq \ell}$ will be useful to us because they have similarities with the McDuffSiegel capacities $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$, but also with the Gutt-Hutchings capacities $c_{k}^{G H}$ (for $\ell=1$ ). More specifically:
(1) Both $\mathfrak{g}_{k}^{\leq \ell}$ and $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$ are related to the energy of holomorphic curves in $X$ which are asymptotic to a word of $p \leq \ell$ Reeb orbits and satisfy a tangency constraint. In Theorem 7.63, we will actually show that $\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X) \leq \mathfrak{g}_{k}^{\leq \ell}(X)$. The capacities $\mathfrak{g}_{k}^{\leq \ell}$ can be thought of as the SFT counterparts of $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$, or alternatively the capacities $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$ can be thought of as the counterparts of $\mathfrak{g}_{k}^{\leq \ell}$ whose definition does not require the holomorphic curves to be regular.
(2) Both $\mathfrak{g}_{k}^{\leq 1}$ and $c_{k}^{\text {GH }}$ are defined in terms of a map in homology being nonzero. In the case of $\mathfrak{g}_{k}^{\leq 1}$, we consider the linearized contact homology, and in the case of $c_{k}^{\mathrm{GH}}$ the invariant in question is $S^{1}$-equivariant symplectic homology. Taking into consideration the Bourgeois-Oancea isomorphism (see [BO16]) between linearized contact homology and positive $S^{1}$-equivariant symplectic homology, one can think of $\mathfrak{g}_{k}^{\leq 1}$ and $c_{k}^{\mathrm{GH}}$ as restatements of one another under this isomorphism. This is the idea behind the proof of Theorem 7.64, where we show that $\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)$.

Remark 7.18. In the case where $X$ is only an exact symplectic manifold instead of a Liouville domain, the proof of Lemma 7.15 does not work. In this case, we do not have access to an action filtration on $C C(X)$. However, it is possible to define linearized contact homology with coefficients in a Novikov ring $\Lambda_{\geq 0}$, in which case a coefficient in
$\Lambda_{\geq 0}$ encodes the energy of a holomorphic curve. This is the approach taken in [Sie20] to define the capacities $\mathfrak{g}_{k}^{\leq \ell}$. It is not obvious that the definition of $\mathfrak{g}_{k}^{\leq \ell}$ we give and the one in [Sie20] are equivalent. However, Definition 7.17 seems to be the natural analogue when we have access to an action filtration, and in addition the definition we provide will be enough for our purposes.
Theorem 7.19. The functions $\mathfrak{g}_{k}^{\leq \ell}$ satisfy the following properties, for all nondegenerate Liouville domains $\left(X, \lambda_{X}\right)$ and $\left(Y, \lambda_{Y}\right)$ of the same dimension:
(Monotonicity) If $X \longrightarrow Y$ is an exact symplectic embedding then $\mathfrak{g}_{k}^{\leq \ell}(X) \leq \mathfrak{g}_{k}^{\leq \ell}(Y)$.
(Conformality) If $\mu>0$ then $\mathfrak{g}_{k}^{\leq \ell}\left(X, \mu \lambda_{X}\right)=\mu \mathfrak{g}_{k}^{\leq \ell}\left(X, \lambda_{X}\right)$.
(Reeb orbits) If $\pi_{1}(X)=0,2 c_{1}(T X)=0$ and $\mathfrak{g}_{k}^{\leq \ell}(X)<+\infty$, then there exists a tuple $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ of Reeb orbits such that
(1) $\mathfrak{g}_{k}^{\leq \ell}(X)=\mathcal{A}(\Gamma)$;
(2) $\mu_{\mathrm{CZ}}(\Gamma)=p(n-3)+2(k+1)$;
(3) $1 \leq p \leq \ell$.

Proof. We prove monotonicity. If $\left(X, \lambda^{X}\right) \longrightarrow\left(Y, \lambda^{Y}\right)$ is an exact symplectic embedding, then it is possible to define a Viterbo transfer map $H(\mathcal{B}(C C(Y)[-1])) \longrightarrow$ $H(\mathcal{B}(C C(X)[-1]))$. This map respects the action filtration as well as the augmentation maps, i.e. the diagram

commutes. The result then follows by definition of $\tilde{\mathfrak{g}}_{k}^{\leq \ell}$.
We prove conformality. If $\gamma$ is a Reeb orbit of $\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ of action $\mathcal{A}_{\lambda}(\gamma)$ then $\gamma$ is a Reeb orbit of $\left(\partial X,\left.\mu \lambda\right|_{\partial X}\right)$ of action $\mathcal{A}_{\mu \lambda}(\gamma)=\mu \mathcal{A}_{\lambda}(\gamma)$. Therefore, there is a diagram


Again, the result follows by definition of $\mathfrak{g}_{k}^{\leq \ell}$.
We prove the Reeb orbits property. Choose a point $x \in \operatorname{int} X$, a symplectic divisor $D$ through $x$ and an almost complex structure $J \in \mathcal{J}(X, D)$. Consider the bar complex $\mathcal{B}^{\leq \ell}(C C(X)[-1])$, computed with respect to $J$. By assumption and definition of $\mathfrak{g}_{k}^{\leq \ell}$,

$$
\begin{aligned}
+\infty & >\mathfrak{g}_{k}^{\leq \ell}(X) \\
& =\inf \left\{a>0 \mid \epsilon_{k}: H\left(\mathcal{A}^{\leq a} \mathcal{B}^{\leq \ell}(C C(X)[-1])\right) \longrightarrow \mathbb{Q} \text { is nonzero }\right\}
\end{aligned}
$$

$$
\begin{aligned}
& =\inf \left\{a>0 \mid \text { there exists } \beta \in H\left(\mathcal{A}^{\leq a} \mathcal{B}^{\leq \ell}(C C(X)[-1])\right) \text { such that } \epsilon_{k}(\beta) \neq 0\right\} \\
& =\inf \left\{\mathcal{A}(\beta) \mid \beta \in H\left(\mathcal{B}^{\leq \ell}(C C(X)[-1])\right) \text { such that } \epsilon_{k}(\beta) \neq 0\right\}
\end{aligned}
$$

where $\mathcal{A}(\beta)$ is given as in Remark 3.17. Since the action spectrum of $\left(\partial X,\left.\lambda\right|_{\partial X}\right)$ is a discrete subset of $\mathbb{R}$, we conclude that in the above expression the infimum is a minimum. More precisely, there exists $\beta \in H\left(\mathcal{B}^{\leq \ell}(C C(X)[-1])\right)$ such that $\epsilon_{k}(\beta) \neq 0$ and $\mathfrak{g}_{k}^{\leq \ell}(X)=$ $\mathcal{A}(\beta)$. The element $\beta$ can be written as a finite linear combination of words of Reeb orbits $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$, where every word has length $p \leq \ell$ and Conley-Zehnder index equal to $p(n-3)+2(k+1)$. Here, the statement about the Conley-Zehnder index follows from the computation

$$
\begin{aligned}
0 & =\operatorname{virdim} \overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle \\
& =(n-3)(2-p)+\mu_{\mathrm{CZ}}(\Gamma)-2 n-2 k+4 \\
& =\mu_{\mathrm{CZ}}(\Gamma)-p(n-3)-2(k+1) .
\end{aligned}
$$

One of the words in this linear combination is such that $\mathcal{A}(\Gamma)=\mathcal{A}(\beta)=\mathfrak{g}_{k}^{\leq \ell}(X)$.
Remark 7.20. In [GH18, Theorem 1.6] (respectively [GH18, Theorem 1.14]) GuttHutchings give formulas for $c_{k}^{G H}$ of a convex (respectively concave) toric domain. However, the given proofs only depend on specific properties of the Gutt-Hutchings capacity and not on the definition of the capacity itself. These properties are monotonicity, conformality, a Reeb orbits property similar to the one of Theorem 7.19, and finally that the capacity be finite on star-shaped domains. If we showed that $\mathfrak{g}_{k}^{\leq 1}$ is finite on star-shaped domains, we would conclude that $\mathfrak{g}_{k}^{\leq 1}=c_{k}^{\mathrm{GH}}$ on convex or concave toric domains, because in this case both capacities would be given by the formulas in the previously mentioned theorems. Showing that $\mathfrak{g}_{k}^{\leq 1}$ is finite boils down to showing that the augmentation map is nonzero, which we will do in Section 7.7. However, in Theorem 7.64 we will use this information in combination with the Bourgeois-Oancea isomorphism to conclude that $\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)$ for any nondegenerate Liouville domain $X$. Therefore, the proof suggested above will not be necessary, although it is a proof of $\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)$ alternative to that of Theorem 7.64 when $X$ is a convex or concave toric domain.

### 7.5 Cauchy-Riemann operators on bundles

In order to show that $\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)$, we will need to show that the augmentation map of a small ellipsoid in $X$ is nonzero (see the proof of Theorem 7.64). Recall that the augmentation map counts holomorphic curves satisfying a tangency constraint. In Section 7.7, we will explicitly compute how many such holomorphic curves there are. However, a count obtained by explicit methods will not necessarily agree with the virtual count that appears in the definition of the augmentation map. By assumption on the virtual perturbation scheme, it does agree if the relevant moduli space is transversely cut out.

Therefore, in this section and the next we will describe the framework that allows us to show that this moduli space is transversely cut out. This section deals with the theory of real linear Cauchy-Riemann operators on line bundles, and our main reference is [Wen10]. The outline is as follows. First, we review the basic definitions about real
linear Cauchy-Riemann operators (Definition 7.24). By the Riemann-Roch theorem (Theorem 7.30), these operators are Fredholm and their index can be computed from a number of topological quantities associated to them. We will make special use of a criterion by Wendl (Proposition 7.31) which guarantees that a real linear CauchyRiemann operator defined on a complex line bundle is surjective. For our purposes, we will also need an adaptation of this result to the case where the operator is accompanied by an evaluation map, which we state in Lemma 7.34. We now state the assumptions for the rest of this section.

Let $(\Sigma, j)$ be a compact Riemann surface without boundary, of genus $g$, with sets of positive and negative punctures $\mathbf{z}^{ \pm}=\left\{z_{1}^{ \pm}, \ldots, z_{p^{ \pm}}^{ \pm}\right\}$. Denote $\mathbf{z}=\mathbf{z}^{+} \cup \mathbf{z}^{-}$and $\dot{\Sigma}=\Sigma \backslash \mathbf{z}$. Choose cylindrical coordinates $(s, t)$ near each puncture $z \in \mathbf{z}$ and denote $\mathcal{U}_{z} \subset \dot{\Sigma}$ the domain of the coordinates $(s, t)$.
Definition 7.21. An asymptotically Hermitian vector bundle over $\dot{\Sigma}$ is given by a complex vector bundle $(E, J) \longrightarrow \dot{\Sigma}$ and for each $z \in \mathbf{z}$ a Hermitian vector bundle $\left(E_{z}, J_{z}, \omega_{z}\right) \longrightarrow S^{1}$ together with a complex vector bundle isomorphism $\Phi_{z}: \pi_{z}^{*} E_{z} \longrightarrow$ $\iota_{z}^{*} E$, where $\iota_{z}: \mathcal{U}_{z} \longrightarrow \dot{\Sigma}$ is the inclusion and $\pi_{z}: \mathcal{U}_{z} \longrightarrow S^{1}$ is given by $\pi_{z}(w)=t(w)$ :


From now until the end of this section, we will assume that $E$ is an asymptotically Hermitian vector bundle over $\dot{\Sigma}$ of complex rank $n$.

Definition 7.22. An asymptotic trivialization of an asymptotically Hermitian vector bundle $E$ is a family $\tau=\left(\tau_{z}\right)_{z \in \mathbf{z}}$ of unitary trivializations $\tau_{z}$ of $\left(E_{z}, J_{z}, \omega_{z}\right)$. By Definition 7.21, every such $\tau_{z}$ defines a complex trivialization of $\iota_{z}^{*} E$. If $\tau$ is an asymptotic trivialization, we will typically denote each $\tau_{z}$ also by $\tau$.
Definition 7.23. Let $E$ be an asymptotically Hermitian vector bundle over $\dot{\Sigma}$, together with an asymptotic trivialization $\tau$. If $\eta$ is a section of $E$ and $z$ is a puncture, denote by $\eta_{z}: Z^{ \pm} \longrightarrow \mathbb{R}^{2 n}$ the map $\eta$ written with respect to the trivialization $\tau$ and cylindrical coordinates near $z$. The Sobolev space of sections of $E$ is

$$
W^{k, p}(E):=\left\{\eta \in W_{\mathrm{loc}}^{k, p}(E) \mid \eta_{z} \in W^{k, p}\left(Z^{ \pm}, \mathbb{R}^{2 n}\right) \text { for every } z \in \mathbf{z}^{ \pm}\right\}
$$

If $\delta>0$, the weighted Sobolev space of sections of $E$ is

$$
W^{k, p, \delta}(E):=\left\{\eta \in W_{\mathrm{loc}}^{k, p}(E) \mid e^{ \pm \delta s} \eta_{z} \in W^{k, p}\left(Z^{ \pm}, \mathbb{R}^{2 n}\right) \text { for every } z \in \mathbf{z}^{ \pm}\right\}
$$

Definition 7.24. A real linear Cauchy-Riemann operator is a map

$$
\mathbf{D}: W^{1, p}(\dot{\Sigma}, E) \longrightarrow L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}(T \dot{\Sigma}, E)\right)
$$

such that $\mathbf{D}$ is linear as a map of vector spaces over $\mathbb{R}$ and $\mathbf{D}$ satisfies the Leibniz rule, i.e. if $v \in W^{1, p}(\dot{\Sigma}, E)$ and $f \in C^{\infty}(\dot{\Sigma}, \mathbb{R})$ then $\mathbf{D}(f v)=f \mathbf{D} v+v \otimes \bar{\partial} f$.

We now consider the asymptotic operators of $\mathbf{D}$. Their relevance comes from the fact that the Fredholm index of $\mathbf{D}$ is determined by the asymptotic operators at the punctures.

Definition 7.25. An asymptotic operator at $z \in \mathbf{z}$ is a bounded linear operator $\mathbf{A}: H^{1}\left(E_{z}\right) \longrightarrow L^{2}\left(E_{z}\right)$ such that when written with respect to a unitary trivialization of $E_{z}, \mathbf{A}$ takes the form

$$
\begin{aligned}
H^{1}\left(S^{1}, \mathbb{R}^{2 n}\right) & \longrightarrow L^{2}\left(S^{1}, \mathbb{R}^{2 n}\right) \\
\eta & \longmapsto-J_{0} \dot{\eta}-S \eta,
\end{aligned}
$$

where $S: S^{1} \longrightarrow \operatorname{End}\left(\mathbb{R}^{2 n}\right)$ is a loop of symmetric $2 n \times 2 n$ matrices. We say that $\mathbf{A}$ is nondegenerate if its spectrum does not contain 0 .

Definition 7.26. Let $\mathbf{D}$ be a real linear Cauchy-Riemann operator and $\mathbf{A}$ be an asymptotic operator at $z \in \mathbf{z}$. We say that $\mathbf{D}$ is asymptotic to $\mathbf{A}$ at $z$ if the expressions for $\mathbf{D}$ and $\mathbf{A}$ with respect to an asymptotic trivialization near $z$ are of the form

$$
\begin{aligned}
(\mathbf{D} \xi)(s, t) & =\partial_{s} \xi(s, t)+J_{0} \partial_{t} \xi(s, t)+S(s, t) \xi(s, t) \\
(\mathbf{A} \eta)(t) & =-J_{0} \partial_{t} \eta(t)-S(t) \eta(t),
\end{aligned}
$$

where $S(s, t)$ converges to $S(t)$ uniformly as $s \rightarrow \pm \infty$.
Remark 7.27. Suppose that $E$ splits as a direct sum of complex vector bundles $E=$ $E_{1} \oplus E_{2}$. In this case, there are canonical inclusions

$$
\begin{aligned}
W^{1, p}\left(\dot{\Sigma}, E_{i}\right) & \subset W^{1, p}(\dot{\Sigma}, E) \\
L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}\left(T \dot{\Sigma}, E_{i}\right)\right) & \subset L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}(T \dot{\Sigma}, E)\right)
\end{aligned}
$$

for $i=1,2$, and we have the following decompositions:

$$
\begin{aligned}
W^{1, p}(\dot{\Sigma}, E) & =W^{1, p}\left(\dot{\Sigma}, E_{1}\right) \oplus W^{1, p}\left(\dot{\Sigma}, E_{2}\right) \\
L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}(T \dot{\Sigma}, E)\right) & =L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}\left(T \dot{\Sigma}, E_{1}\right)\right) \oplus L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}\left(T \dot{\Sigma}, E_{2}\right)\right)
\end{aligned}
$$

We can write $\mathbf{D}$ with respect to these decompositions as a block matrix:

$$
\mathbf{D}=\left[\begin{array}{ll}
\mathbf{D}_{11} & \mathbf{D}_{12} \\
\mathbf{D}_{21} & \mathbf{D}_{22}
\end{array}\right]
$$

By [Wen16, Exercise 7.8], the diagonal terms $\mathbf{D}_{11}$ and $\mathbf{D}_{22}$ are real linear CauchyRiemann operators, while the off diagonal terms $\mathbf{D}_{12}$ and $\mathbf{D}_{21}$ are tensorial.

Let $\mathbf{D}$ be a real linear Cauchy-Riemann operator and for every puncture $z \in \mathbf{z}$ let $\mathbf{A}_{z}$ be a nondegenerate asymptotic operator at $z$. By the Riemann-Roch theorem with punctures (Theorem 7.30), D is a Fredholm operator. We now explain how to compute the Fredholm index of $\mathbf{D}$. Choose an asymptotic trivialization $\tau$ as in Definition 7.22. First, recall that the Euler characteristic of $\dot{\Sigma}$ is given by $\chi(\dot{\Sigma})=2-2 g-\# \mathbf{z}$, where $g$ is the genus of $\Sigma$.
Definition 7.28 ([Wen16, Definition 5.1]). Let $S$ be a compact oriented surface with boundary and $(E, J)$ be a complex vector bundle over $S$. Let $\tau$ be a complex trivialization of $\left.E\right|_{\partial S}$. The relative first Chern number of $E$ with respect to $\tau$, denoted $c_{1}^{\tau}(E) \in \mathbb{Z}$, is defined by the following properties.
(1) If $E$ has complex rank 1 , then $c_{1}^{\tau}(E)$ is the signed count of zeros of a generic smooth section $\eta: S \longrightarrow E$ such that $\left.\tau \circ \eta\right|_{\partial S}: \partial S \longrightarrow \mathbb{C}$ is constant.
(2) If $E_{1}$ and $E_{2}$ are complex vector bundles over $S$ with trivializations $\tau_{1}$ and $\tau_{2}$ over $\partial S$, then $c_{1}^{\tau_{1} \oplus \tau_{2}}\left(E_{1} \oplus E_{2}\right)=c_{1}^{\tau}\left(E_{1}\right)+c_{1}^{\tau}\left(E_{2}\right)$.

The definition of relative first Chern number extends to the class of asymptotically Hermitian vector bundles over punctured surfaces.

Definition 7.29. The Conley-Zehnder index of an asymptotic operator $\mathbf{A}_{z}$ is given as follows. Let $\left(\mathbf{A}_{z} \eta\right)(t)=-J_{0} \partial_{t} \eta(t)-S(t) \eta(t)$ be the expression of $\mathbf{A}_{z}$ with respect to $\tau$. Let $\Psi:[0,1] \longrightarrow \operatorname{Sp}(2 n)$ be the unique path of symplectic matrices such that

$$
\begin{aligned}
& \Psi(0)=\mathrm{id}_{\mathbb{R}^{2 n}} \\
& \dot{\Psi}(t)=J_{0} S(t) \Psi(t) .
\end{aligned}
$$

Since $\mathbf{A}_{z}$ is nondegenerate, $\Psi$ is an element of $\mathrm{SP}(n)$. Finally, define $\mu_{\mathrm{CZ}}^{\tau}\left(\mathbf{A}_{z}\right):=\mu_{\mathrm{CZ}}(\Psi)$.
Theorem 7.30 (Riemann-Roch, [Wen16, Theorem 5.4]). The operator $\mathbf{D}$ is Fredholm and its (real) Fredholm index is given by

$$
\text { ind } \mathbf{D}=n \chi(\dot{\Sigma})+2 c_{1}^{\tau}(E)+\sum_{z \in \mathbf{z}^{+}} \mu_{\mathrm{CZ}}^{\tau}\left(\mathbf{A}_{z}\right)-\sum_{z \in \mathbf{z}^{-}} \mu_{\mathrm{CZ}}^{\tau}\left(\mathbf{A}_{z}\right) .
$$

For the rest of this section, we restrict ourselves to the case where $n=\operatorname{rank}_{\mathbb{C}} E=1$. We retain the assumption that $\mathbf{D}$ is a real linear Cauchy-Riemann operator and $\mathbf{A}_{z}$ is a nondegenerate asymptotic operator for every puncture $z \in \mathbf{z}$. Our goal is to state a criterion that guarantees surjectivity of $\mathbf{D}$. This criterion depends on other topological quantities which we now define.
For every $\lambda$ in the spectrum of $\mathbf{A}_{z}$, let $w^{\tau}(\lambda)$ be the winding number of any nontrivial section in the $\lambda$-eigenspace of $\mathbf{A}_{z}$ (computed with respect to the trivialization $\tau$ ). Define the winding numbers

$$
\begin{aligned}
& \alpha_{-}^{\tau}\left(\mathbf{A}_{z}\right):=\max \left\{w^{\tau}(\lambda) \mid \lambda<0 \text { is in the spectrum of } \mathbf{A}_{z}\right\}, \\
& \alpha_{+}^{\tau}\left(\mathbf{A}_{z}\right):=\min \left\{w^{\tau}(\lambda) \mid \lambda>0 \text { is in the spectrum of } \mathbf{A}_{z}\right\} .
\end{aligned}
$$

The parity (the reason for this name is Equation (7.1) below) and associated sets of even and odd punctures are given by

$$
\begin{aligned}
p\left(\mathbf{A}_{z}\right) & :=\alpha_{+}^{\tau}\left(\mathbf{A}_{z}\right)-\alpha_{-}^{\tau}\left(\mathbf{A}_{z}\right) \in\{0,1\}, \\
\mathbf{z}_{0} & :=\left\{z \in \mathbf{z} \mid p\left(\mathbf{A}_{z}\right)=0\right\}, \\
\mathbf{z}_{1} & :=\left\{z \in \mathbf{z} \mid p\left(\mathbf{A}_{z}\right)=1\right\} .
\end{aligned}
$$

Finally, the adjusted first Chern number is given by

$$
c_{1}\left(E, \mathbf{A}_{\mathbf{z}}\right)=c_{1}^{\tau}(E)+\sum_{z \in \mathbf{z}^{+}} \alpha_{-}^{\tau}\left(\mathbf{A}_{z}\right)-\sum_{z \in \mathbf{z}^{-}} \alpha_{-}^{\tau}\left(\mathbf{A}_{z}\right) .
$$

These quantities satisfy the following equations.

$$
\begin{align*}
\mu_{\mathrm{CZ}}^{\tau}\left(\mathbf{A}_{z}\right) & =2 \alpha_{-}^{\tau}\left(\mathbf{A}_{\mathbf{z}}\right)+p\left(\mathbf{A}_{z}\right)=2 \alpha_{+}^{\tau}\left(\mathbf{A}_{\mathbf{z}}\right)-p\left(\mathbf{A}_{z}\right),  \tag{7.1}\\
2 c_{1}\left(E, \mathbf{A}_{\mathbf{z}}\right) & =\operatorname{ind} \mathbf{D}-2-2 g+\# \mathbf{z}_{0} . \tag{7.2}
\end{align*}
$$

Proposition 7.31 ([Wen10, Proposition 2.2]).
(1) If ind $\mathbf{D} \leq 0$ and $c_{1}\left(E, \mathbf{A}_{\mathbf{z}}\right)<0$ then $\mathbf{D}$ is injective.
(2) If ind $\mathbf{D} \geq 0$ and $c_{1}\left(E, \mathbf{A}_{\mathbf{z}}\right)<$ ind $\mathbf{D}$ then $\mathbf{D}$ is surjective.

We will apply the proposition above to moduli spaces of punctured spheres which have no even punctures. The following lemma is just a restatement of the previous proposition in this simpler case.

Lemma 7.32. Assume that $g=0$ and $\# \mathbf{z}_{0}=0$. Then,
(1) If ind $\mathbf{D} \leq 0$ then $\mathbf{D}$ is injective.
(2) If ind $\mathbf{D} \geq 0$ then $\mathbf{D}$ is surjective.

Proof. By Proposition 7.31 and Equation (7.2).
We now wish to deal with the case where $\mathbf{D}$ is taken together with an evaluation map (see Lemma 7.34 below). The tools we need to prove this result are explained in the following remark.

Remark 7.33. Suppose that $\operatorname{ker} \mathbf{D} \neq\{0\}$. If $\xi \in \operatorname{ker} \mathbf{D} \backslash\{0\}$, it is possible to show that $\xi$ has only a finite number of zeros, all of positive order, i.e. if $w$ is a zero of $\xi$ then $\operatorname{ord}(\xi ; w)>0$. For every $z \in \mathbf{z}$, there is an asymptotic winding number $\operatorname{wind}_{z}^{\tau}(\xi) \in \mathbb{Z}$, which has the properties

$$
\begin{aligned}
& z \in \mathbf{z}^{+} \Longrightarrow \operatorname{wind}_{z}^{\tau}(\xi) \leq \alpha_{-}^{\tau}\left(\mathbf{A}_{z}\right) \\
& z \in \mathbf{z}^{-} \Longrightarrow \operatorname{wind}_{z}^{\tau}(\xi) \geq \alpha_{+}^{\tau}\left(\mathbf{A}_{z}\right)
\end{aligned}
$$

Define the asymptotic vanishing of $\xi$, denoted $Z_{\infty}(\xi)$, and the count of zeros, denoted $Z(\xi)$, by

$$
\begin{aligned}
Z_{\infty}(\xi) & :=\sum_{z \in \mathbf{z}^{+}}\left(\alpha_{-}^{\tau}\left(\mathbf{A}_{z}\right)-\operatorname{wind}_{z}^{\tau}(\xi)\right)+\sum_{z \in \mathbf{z}^{-}}\left(\operatorname{wind}_{z}^{\tau}(\xi)-\alpha_{+}^{\tau}\left(\mathbf{A}_{z}\right)\right) \in \mathbb{Z}_{\geq 0}, \\
Z(\xi) & :=\sum_{w \in \xi^{-1}(0)} \operatorname{ord}(\xi ; w) \in \mathbb{Z}_{\geq 0} .
\end{aligned}
$$

In this case, we have the formula (see [Wen10, Equation 2.7])

$$
\begin{equation*}
c_{1}\left(E, \mathbf{A}_{\mathbf{z}}\right)=Z(\xi)+Z_{\infty}(\xi) . \tag{7.3}
\end{equation*}
$$

Lemma 7.34. Let $w \in \dot{\Sigma}$ be a point and $\mathbf{E}: W^{1, p}(\dot{\Sigma}, E) \longrightarrow E_{w}$ be the evaluation map at $w$, i.e. $\mathbf{E}(\xi)=\xi_{w}$. Assume that $g=0$ and $\# \mathbf{z}_{0}=0$. If $\operatorname{ind} \mathbf{D}=2$ then $\mathbf{D} \oplus \mathbf{E}: W^{1, p}(\dot{\Sigma}, E) \longrightarrow L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}(T \dot{\Sigma}, E)\right) \oplus E_{w}$ is surjective.

Proof. It is enough to show that the maps

$$
\begin{aligned}
& \mathbf{D}: W^{1, p}(\dot{\Sigma}, E) \longrightarrow L^{p}\left(\dot{\Sigma}, \operatorname{Hom}^{0,1}(T \dot{\Sigma}, E)\right), \\
&\left.\mathbf{E}\right|_{\operatorname{ker} \mathbf{D}}: \operatorname{ker} \mathbf{D} \longrightarrow E_{w}
\end{aligned}
$$

are surjective. By Lemma 7.32, $\mathbf{D}$ is surjective. Since $\operatorname{dim} \operatorname{ker} \mathbf{D}=\operatorname{ind} \mathbf{D}=2$ and $\operatorname{dim}_{\mathbb{R}} E_{w}=2$, the map $\left.\mathbf{E}\right|_{\operatorname{ker} \mathbf{D}}$ is surjective if and only if it is injective. So, we show that $\operatorname{ker}\left(\left.E\right|_{\operatorname{ker} \mathbf{D}}\right)=\operatorname{ker} \mathbf{E} \cap \operatorname{ker} \mathbf{D}=\{0\}$. For this, let $\xi \in \operatorname{ker} \mathbf{E} \cap \operatorname{ker} \mathbf{D}$ and assume by contradiction that $\xi \neq 0$. Consider the quantities defined in Remark 7.33. We compute

$$
\begin{aligned}
0 & =\text { ind } \mathbf{D}-2 & & {[\text { by assumption }] } \\
& =2 c_{1}\left(E, \mathbf{A}_{\mathbf{z}}\right) & & {[\text { by Equation }(7.2)] } \\
& =2 Z(\xi)+2 Z_{\infty}(\xi) & & {[\text { by Equation }(7.3)] } \\
& \geq 0 & & {\left[\text { by definition of } Z \text { and } Z_{\infty}\right], }
\end{aligned}
$$

which implies that $Z(\xi)=0$. This gives the desired contradiction, because

$$
\begin{aligned}
0 & =Z(\xi) & & \text { [by the previous computation] } \\
& =\sum_{z \in \xi^{-1}(0)} \operatorname{ord}(\xi ; z) & & {[\text { by definition of } Z] } \\
& \geq \operatorname{ord}(\xi ; w) & & {\left[\text { since } \xi_{w}=\mathbf{E}(\xi)=0\right] } \\
& >0 & & {[\text { by Remark } 7.33] . }
\end{aligned}
$$

### 7.6 Cauchy-Riemann operators as sections

In this section, we phrase the notion of a map $u: \dot{\Sigma} \longrightarrow \hat{X}$ being holomorphic in terms of $u$ being in the zero set of a section $\bar{\partial}: \mathcal{T} \times \mathcal{B} \longrightarrow \mathcal{E}$ (see Definitions 7.40 and 7.41). The goal of this point of view is that we can then think of moduli spaces of holomorphic curves in $\hat{X}$ as the zero set of the section $\bar{\partial}$. To see if such a moduli space is regular near $(j, u)$, one needs to consider the linearization $\mathbf{L}_{(j, u)}$ of $\bar{\partial}$ at $(j, u)$ (see Definition 7.42), and prove that it is surjective. We will see that a suitable restriction of $\mathbf{L}_{(j, u)}$ is a real linear Cauchy-Riemann operator (Lemma 7.45), and therefore we can use the theory from the last section to show that $\mathbf{L}_{(j, u)}$ is surjective in some particular cases (Lemmas 7.46 and 7.49).

Definition 7.35. Let $(\Sigma, j)$ be a Riemann surface and $z \in \Sigma$ be a puncture. An asymptotic marker at $z$ is a half-line $v \in\left(T_{z} \Sigma \backslash\{0\}\right) / \mathbb{R}_{>0}$.
Definition 7.36. Let $(X, \omega, \lambda)$ be a symplectic cobordism, $J \in \mathcal{J}(X)$ be a cylindrical almost complex structure on $\hat{X}$, and $\Gamma^{ \pm}=\left(\gamma_{1}^{ \pm}, \ldots, \gamma_{p^{ \pm}}^{ \pm}\right)$be tuples of Reeb orbits on $\partial^{ \pm} X$. Let $\mathcal{M}_{X}^{\Phi, J}\left(\Gamma^{+}, \Gamma^{-}\right)$be the moduli space of (equivalence classes of) tuples

$$
(\Sigma, j, \mathbf{z}, \mathbf{v}, u), \quad \mathbf{z}=\mathbf{z}^{+} \cup \mathbf{z}^{-}, \quad \mathbf{v}=\mathbf{v}^{+} \cup \mathbf{v}^{-}
$$

where $(\Sigma, j, \mathbf{z}, u)$ is as in Definition 4.7 and $\mathbf{v}^{ \pm}=\left\{v_{1}^{ \pm}, \ldots, v_{p^{ \pm}}^{ \pm}\right\}$is a set of asymptotic markers on $\mathbf{z}^{ \pm}=\left\{z_{1}^{ \pm}, \ldots, z_{p^{ \pm}}^{ \pm}\right\}$such that

$$
\lim _{t \rightarrow 0^{+}} u(c(t))=\left( \pm \infty, \gamma_{i}^{ \pm}(0)\right)
$$

for every $i=1, \ldots, p^{ \pm}$and every path $c$ in $\Sigma$ with $c(t)=z_{i}^{ \pm}$and $\dot{c}(0)=v_{i}^{ \pm}$. Two such tuples $\left(\Sigma_{0}, j_{0}, \mathbf{z}_{0}, \mathbf{v}_{0}, u_{0}\right)$ and $\left(\Sigma_{1}, j_{1}, \mathbf{z}_{1}, \mathbf{v}_{1}, u_{1}\right)$ are equivalent if there exists a biholomorphism $\phi: \Sigma_{0} \longrightarrow \Sigma_{1}$ such that

$$
u_{1} \circ \phi=u_{0},
$$

$$
\begin{aligned}
\phi\left(z_{0, i}^{ \pm}\right) & =z_{1, i}^{ \pm}, \\
\mathrm{D} \phi\left(z_{0, i}^{ \pm}\right) v_{0, i}^{ \pm} & =v_{1, i}^{ \pm} .
\end{aligned}
$$

Remark 7.37. Consider the sphere $S^{2}$, without any specified almost complex structure. Let $\mathbf{z}^{ \pm}=\left\{z_{1}^{ \pm}, \ldots, z_{p^{ \pm}}^{ \pm}\right\} \subset S^{2}$ be sets of punctures and $\mathbf{v}^{ \pm}=\left\{v_{1}^{ \pm}, \ldots, v_{p^{ \pm}}^{ \pm}\right\}$be corresponding sets of asymptotic markers. Then,

$$
\mathcal{M}_{X}^{\S, J}\left(\Gamma^{+}, \Gamma^{-}\right) \cong\left\{\begin{array}{l|l}
(j, u) & \begin{array}{l}
j \text { is an almost complex structure on } S^{2} \\
u:\left(\dot{S}^{2}, j\right) \longrightarrow(\hat{X}, J) \text { is as in Definition } 4.7
\end{array}
\end{array}\right\} / \sim,
$$

where two tuples $\left(j_{0}, u_{0}\right)$ and $\left(j_{1}, u_{1}\right)$ are equivalent if there exists a biholomorphism $\phi:\left(S^{2}, j_{0}\right) \longrightarrow\left(S^{2}, j_{1}\right)$ such that

$$
\begin{aligned}
u_{1} \circ \phi & =u_{0}, \\
\phi\left(z_{i}^{ \pm}\right) & =z_{i}^{ \pm}, \\
\mathrm{D} \phi\left(z_{i}^{ \pm}\right) v_{i}^{ \pm} & =v_{i}^{ \pm} .
\end{aligned}
$$

Remark 7.38. There is a surjective map $\pi^{\$}: \mathcal{M}_{X}^{\S, J}\left(\Gamma^{+}, \Gamma^{-}\right) \longrightarrow \mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$given by forgetting the asymptotic markers. By [Wen16, Proposition 11.1], for every $u \in$ $\mathcal{M}_{X}^{J}\left(\Gamma^{+}, \Gamma^{-}\right)$the preimage $\left(\pi^{\S}\right)^{-1}(u)$ contains exactly

$$
\frac{\prod_{\gamma \in \Gamma^{+} \cup \Gamma^{-}} m(\gamma)}{|\operatorname{Aut}(u)|}
$$

elements, where $m(\gamma)$ is the multiplicity of the Reeb orbit $\gamma$ and $\operatorname{Aut}(u)$ is the automorphism group of $u=(\Sigma, j, \mathbf{z}, u)$, i.e. an element of $\operatorname{Aut}(u)$ is a biholomorphism $\phi: \Sigma \longrightarrow \Sigma$ such that $u \circ \phi=u$ and $\phi\left(z_{i}^{ \pm}\right)=z_{i}^{ \pm}$for every $i$.

We will work with the following assumptions. Let $\Sigma=S^{2}$, (without any specified almost complex structure). Let $\mathbf{z}=\left\{z_{1}, \ldots, z_{p}\right\} \subset \Sigma$ be a set of punctures and $\mathbf{v}=\left\{v_{1}, \ldots, v_{p}\right\}$ be a corresponding set of asymptotic markers. Assume also that we have a set $\mathbf{j}=$ $\left\{j_{1}, \ldots, j_{p}\right\}$, where $j_{i}$ is an almost complex structure defined on a neighbourhood of $z_{i}$ for every $i=1, \ldots, p$. For every $i$, there are cylindrical coordinates $(s, t)$ on $\dot{\Sigma}$ near $z_{i}$ as in Definition 4.1, with the additional property that $v_{i}$ agrees with the direction $t=0$. We will also assume that $\mathcal{T} \subset \mathcal{J}(\Sigma)$ is a Teichmüller slice as in [Wen10, Section 3.1], where $\mathcal{J}(\Sigma)$ denotes the set of almost complex structures on $\Sigma=S^{2}$. Finally, let ( $X, \lambda$ ) be a nondegenerate Liouville domain of dimension $2 n$ and $J \in \mathcal{J}(X)$ be an admissible almost complex structure on $\hat{X}$.

Definition 7.39. Let $\gamma$ be an unparametrized simple Reeb orbit of $\partial X$. An admissible parametrization near $\gamma$ is a diffeomorphism $\phi: S^{1} \times D^{2 n-2} \longrightarrow O$, where $O \subset \partial X$ is an open neighbourhood of $\gamma$ and

$$
D^{2 n-2}:=\left\{\left(z^{1}, \ldots, z^{n-1}\right) \in \mathbb{C}^{n-1}| | z^{1}\left|<1, \ldots,\left|z^{n-1}\right|<1\right\}\right.
$$

is the polydisk, such that $t \longmapsto \phi(t, 0)$ is a parametrization of $\gamma$. In this case, we denote by $(\vartheta, \zeta)=\phi^{-1}: O \longrightarrow S^{1} \times D^{2 n-2}$ the coordinates near $\gamma$.

Let $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ be a tuple of (unparametrized) Reeb orbits in $\partial X$. Denote by $m_{i}$ the multiplicity of $\gamma_{i}$ and by $T_{i}$ the period of the simple Reeb orbit underlying $\gamma_{i}$ (so, the period of $\gamma_{i}$ is $m_{i} T_{i}$ ). For every $i=1, \ldots, p$, choose once and for all an admissible parametrization $\phi_{i}: S^{1} \times D^{2 n-2} \longrightarrow O_{i}$ near the simple Reeb orbit underlying $\gamma_{i}$.

Definition 7.40. We define a vector bundle $\pi: \mathcal{E} \longrightarrow \mathcal{T} \times \mathcal{B}$ as follows. Let $\mathcal{B}$ be the set of maps $u: \dot{\Sigma} \longrightarrow \hat{X}$ of class $W_{\text {loc }}^{k, p}$ satisfying the following property for every puncture $z_{i}$. Write $u$ with respect to the cylindrical coordinates $(s, t)$ defined from $\left(z_{i}, v_{i}\right)$. First, we require that $u(s, t) \in \mathbb{R}_{\geq 0} \times O_{i}$ for $s$ big enough. Write $u$ with respect to the coordinates $(\vartheta, \zeta)$ near $\gamma$ on the target and cylindrical coordinates $(s, t)$ on the domain:

$$
\begin{aligned}
u(s, t) & =\left(\pi_{\mathbb{R}} \circ u(s, t), \pi_{\partial X} \circ u(s, t)\right) \\
& =\left(\pi_{\mathbb{R}} \circ u(s, t), \vartheta(s, t), \zeta(s, t)\right) .
\end{aligned}
$$

Finally, we require that there exists $a \in \mathbb{R}$ such that the map

$$
(s, t) \longmapsto\left(\pi_{\mathbb{R}} \circ u(s, t), \vartheta(s, t), \zeta(s, t)\right)-\left(m_{i} T_{i} s+a, m_{i} T_{i} t, 0\right)
$$

is of class $W^{k, p, \delta}$. The fibre, total space, projection and zero section are defined by

$$
\begin{aligned}
\mathcal{E}_{(j, u)} & :=W^{k-1, p, \delta}\left(\operatorname{Hom}^{0,1}\left((T \dot{\Sigma}, j),\left(u^{*} T \hat{X}, J\right)\right)\right), \quad \text { for every }(j, u) \in \mathcal{T} \times \mathcal{B}, \\
\mathcal{E} & :=\coprod_{(j, u) \in \mathcal{T} \times \mathcal{B}} \mathcal{E}_{(j, u)}=\left\{(j, u, \xi) \mid(j, u) \in \mathcal{T} \times \mathcal{B}, \xi \in \mathcal{E}_{(j, u)}\right\} \\
\pi(j, u, \eta) & :=(j, u), \\
z(j, u) & :=(j, u, 0) .
\end{aligned}
$$

Definition 7.41. The Cauchy-Riemann operators are the sections

$$
\begin{aligned}
\bar{\partial}_{j}: \mathcal{B} \longrightarrow \mathcal{E}, & \bar{\partial}_{j}(u) & :=\frac{1}{2}(T u+J \circ T u \circ j) \in \mathcal{E}_{(j, u)}, \\
\bar{\partial}: \mathcal{T} \times \mathcal{B} \longrightarrow \mathcal{E}, & \bar{\partial}(j, u) & :=\bar{\partial}_{j}(u) .
\end{aligned}
$$

Definition 7.42. Let $(j, u) \in \mathcal{T} \times \mathcal{B}$ be such that $\bar{\partial}(j, u)=0$. Define the vertical projection

$$
P_{(j, u)}: T_{(j, u, 0)} \mathcal{E} \longrightarrow \mathcal{E}_{(j, u)}, \quad P_{(j, u)}(\eta):=\eta-\mathrm{D}(z \circ \pi)(j, u, 0) \eta .
$$

The linearized Cauchy-Riemann operators are the linear maps

$$
\begin{aligned}
\mathbf{D}_{(j, u)} & :=P_{(j, u)} \circ \mathrm{D}\left(\bar{\partial}_{j}\right)(u): T_{u} \mathcal{B} \longrightarrow \mathcal{E}_{(j, u)}, \\
\mathbf{L}_{(j, u)} & :=P_{(j, u)} \circ \mathrm{D}(\bar{\partial})(j, u): T_{j} \mathcal{T} \oplus T_{u} \mathcal{B} \longrightarrow \mathcal{E}_{(j, u)}
\end{aligned}
$$

Define also the restriction

$$
\mathbf{F}_{(j, u)}:=\left.\mathbf{L}_{(j, u)}\right|_{T_{j}} \mathcal{T}: T_{j} \mathcal{T} \longrightarrow \mathcal{E}_{(j, u)}
$$

Remark 7.43. Choose a smooth function $\beta: \mathbb{R} \longrightarrow[0,1]$ such that $\beta(s)=0$ if $s<0$, $\beta(s)=1$ if $s>1$ and $0 \leq \beta^{\prime}(s) \leq 2$. Consider the Liouville vector field $\hat{Z}^{X} \in \mathfrak{X}(\hat{X})$ and
the Reeb vector field $R^{\partial X} \in \mathfrak{X}(\partial X)$. For every puncture $z$, let $(s, t)$ be the cylindrical coordinates near $z$ and define sections

$$
\left.\begin{array}{rl}
\hat{Z}_{z}^{X} & \in \Gamma\left(u^{*} T \hat{X}\right), \quad \hat{Z}_{z}^{X}(s, t) \\
R_{z}^{\partial X} \in \Gamma(s) \hat{Z}^{X}(u(s, t)) \\
& \in \Gamma\left(u^{*} T \hat{X}\right), \quad R_{z}^{\partial X}(s, t)
\end{array}\right)=\beta(s) R^{\partial X}(u(s, t)) .
$$

Denote $V=\bigoplus_{i=1}^{p} \operatorname{span}\left\{\hat{Z}_{z_{i}}^{X}, R_{z_{i}}^{\partial X}\right\}$. Then, the tangent space of $\mathcal{B}$ is given by

$$
T_{u} \mathcal{B}=V \oplus W^{k, p, \delta}\left(\dot{\Sigma}, u^{*} T \hat{X}\right)
$$

Definition 7.44. Let $(j, u) \in \mathcal{T} \times \mathcal{B}$ be such that $\bar{\partial}(j, u)=0$ and consider the linearized Cauchy-Riemann operator $\mathbf{D}_{(j, u)}$. Choose a smooth function $f: \dot{\Sigma} \longrightarrow \mathbb{R}$ such that $f(s, t)=\delta s$ on every cylindrical end of $\dot{\Sigma}$. Define the restriction of $\mathbf{D}_{(j, u)}$, denoted $\mathbf{D}_{\delta}$, and the conjugation of $\mathbf{D}_{(j, u)}$, denoted $\mathbf{D}_{0}$, to be the unique maps such that the diagram

commutes.
Lemma 7.45. The maps $\mathbf{D}_{\delta}$ and $\mathbf{D}_{0}$ are real linear Cauchy-Riemann operators.
Proof. By [MS12, Proposition 3.1.1], the map $\mathbf{D}_{\delta}$ is given by the equation

$$
\mathbf{D}_{\delta} \xi=\frac{1}{2}(\nabla \xi+J(u) \nabla \xi \circ j)-\frac{1}{2} J(u)\left(\nabla_{\xi} J\right)(u) \partial(u),
$$

where $\nabla$ is the Levi-Civita connection on $\hat{X}$ associated to the Riemannian metric determined by $J$ and $\mathrm{d} \hat{\lambda}$. Since $\nabla: \mathfrak{X}(\Sigma) \times \Gamma\left(u^{*} T \hat{X}\right) \longrightarrow \Gamma\left(u^{*} T \hat{X}\right)$ satisfies the Leibniz rule with respect to the $\Gamma\left(u^{*} T \hat{X}\right)$ argument, $\mathbf{D}_{\delta}$ is a real linear Cauchy-Riemann operator. We show that $\mathbf{D}_{0}$ satisfies the Leibniz rule.

$$
\begin{aligned}
\mathbf{D}_{0}(g \xi) & =e^{f} \mathbf{D}_{\delta}\left(e^{-f} g \xi\right) & & {\left[\text { by definition of } \mathbf{D}_{\delta}\right] } \\
& =g e^{f} \mathbf{D}_{\delta}\left(e^{-f} \xi\right)+\xi \otimes \bar{\partial} g & & {\left[\mathbf{D}_{\delta} \text { obeys the Leibniz rule }\right] } \\
& =g \mathbf{D}_{0}(\xi)+\xi \otimes \bar{\partial} g & & {\left[\text { by definition of } \mathbf{D}_{\delta}\right] . }
\end{aligned}
$$

Lemma 7.46. If $n=1$ then $\mathbf{L}_{(j, u)}$ is surjective.
Proof. Let $\tau_{1}$ be a global complex trivialization of $u^{*} T \hat{X}$ extending to an asymptotic unitary trivialization near the punctures. Let $\tau_{2}$ be the unitary trivialization of $u^{*} T \hat{X}$ near the punctures which is induced from the decomposition $T_{(r, x)}(\mathbb{R} \times \partial X)=\left\langle\partial_{r}\right\rangle \oplus\left\langle R_{x}^{\partial X}\right\rangle$. It is shown in the proof of [Wen16, Lemma 7.10] that the operator $\mathbf{D}_{0}$ is asymptotic at $z_{i}$ to $-J \partial_{t}+\delta$, which is nondegenerate and has Conley-Zehnder index $\mu_{\mathrm{CZ}}^{\tau_{2}}\left(-J \partial_{t}+\delta\right)=-1$.

Therefore, every $z_{i}$ is an odd puncture and $\# \mathbf{z}_{0}=0$. We show that $c_{1}^{\tau_{2}}\left(u^{*} T \hat{X}\right)=\sum_{i=1}^{p} m_{i}$, where $m_{i}$ is the multiplicity of the asymptotic Reeb orbit $\gamma_{i}$ :

$$
\begin{aligned}
c_{1}^{\tau_{2}}\left(u^{*} T \hat{X}\right) & =c_{1}^{\tau_{1}}\left(u^{*} T \hat{X}\right)+\sum_{i=1}^{p} \operatorname{deg}\left(\left.\tau_{1}\right|_{E_{z_{i}}} \circ\left(\left.\tau_{2}\right|_{E_{z_{i}}}\right)^{-1}\right) & & {[\text { by [Wen16, Exercise 5.3]] }} \\
& =\sum_{i=1}^{p} \operatorname{deg}\left(\tau_{1} \mid E_{E_{z_{i}}} \circ\left(\left.\tau_{2}\right|_{E_{z_{i}}}\right)^{-1}\right) & & \text { [by Definition 7.28] } \\
& =\sum_{i=1}^{p} m_{i} & &
\end{aligned}
$$

where in the last equality we have used the fact that if $(s, t)$ are the cylindrical coordinates near $z_{i}$, then for $s$ large enough the map $\left.t \longmapsto \tau_{1}\right|_{u(s, t)} \circ\left(\left.\tau_{2}\right|_{u(s, t)}\right)^{-1}$ winds around the origin $m_{i}$ times. We show that ind $\mathbf{D}_{0} \geq 2$.

$$
\begin{aligned}
\operatorname{ind} \mathbf{D}_{0} & =n \chi(\dot{\Sigma})+2 c_{1}^{\tau_{2}}\left(u^{*} T \hat{X}\right)+\sum_{i=1}^{p} \mu_{\mathrm{CZ}}^{\tau_{2}}\left(-J \partial_{t}+\delta\right) & & {[\text { by Theorem } 7.30] } \\
& =2+2 \sum_{i=1}^{p}\left(m_{i}-1\right) & & {[\text { since } n=1 \text { and } g=0] } \\
& \geq 2 & & {\left[\text { since } m_{i} \geq 1 \text { for every } i\right] . }
\end{aligned}
$$

By Lemma 7.32, this implies that $\mathbf{D}_{0}$ is surjective. By Definition 7.44, the operator $\mathbf{D}_{(j, u)}$ is also surjective. Therefore, $\mathbf{L}_{(j, u)}=\mathbf{F}_{(j, u)}+\mathbf{D}_{(j, u)}$ is also surjective.

From now until the end of this section, let $\left(X, \lambda^{X}\right)$ be a Liouville domain of dimension $2 n$ and $\left(Y, \lambda^{Y}\right)$ be a Liouville domain of dimension $2 n+2$ such that
(1) $X \subset Y$ and $\partial X \subset \partial Y$;
(2) the inclusion $\iota: X \longrightarrow Y$ is a Liouville embedding;
(3) if $x \in X$ then $Z_{x}^{X}=Z_{x}^{Y}$;
(4) if $x \in \partial X$ then $R_{x}^{\partial X}=R_{x}^{\partial Y}$.

In this case, we have an inclusion of completions $\hat{X} \subset \hat{Y}$ as sets. By assumption, $Z^{X}$ is $\iota-$ related to $Z^{Y}$, which implies that there is a map $\hat{\imath}: \hat{X} \longrightarrow \hat{Y}$ on the level of completions. Since in this case $\hat{X} \subset \hat{Y}$ and by Definition 2.51, $\hat{\imath}$ is the inclusion. Assume that $J^{X} \in \mathcal{J}(X)$ and $J^{Y} \in \mathcal{J}(Y)$ are almost complex structures on $\hat{X}$ and $\hat{Y}$ respectively, such that $\hat{\imath}: \hat{X} \longrightarrow \hat{Y}$ is holomorphic. As before, let $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ be a tuple of unparametrized Reeb orbits in $\partial X$. Notice that each $\gamma_{i}$ can also be seen as a Reeb orbit in $\partial Y$. For every $i=1, \ldots, p$, choose once and for all admissible parametrizations $\phi_{i}^{X}: S^{1} \times D^{2 n-2} \longrightarrow O_{i}^{X}$ and $\phi_{i}^{Y}: S^{1} \times D^{2 n} \longrightarrow O_{i}^{Y}$ near $\gamma_{i}$ with the property that the diagram

commutes. We will consider the bundle of Definition 7.40 as well as the Cauchy-Riemann operator and its linearization for both $X$ and $Y$. We will use the notation

$$
\begin{array}{lll}
\pi^{X}: \mathcal{E} X \longrightarrow \mathcal{T} \times \mathcal{B} X, & \bar{\partial}^{X}: \mathcal{T} \times \mathcal{B} X \longrightarrow \mathcal{E} X, & \mathbf{L}_{(j, u)}^{X}: T_{j} \mathcal{T} \oplus T_{u} \mathcal{B} X \longrightarrow \mathcal{E}_{(j, u)} X, \\
\pi^{Y}: \mathcal{E} Y \longrightarrow \mathcal{T} \times \mathcal{B} Y, & \bar{\partial}^{Y}: \mathcal{T} \times \mathcal{B} Y \longrightarrow \mathcal{E} Y, & \mathbf{L}_{(j, w)}^{Y}: T_{j} \mathcal{T} \oplus T_{w} \mathcal{B} Y \longrightarrow \mathcal{E}_{(j, w)} Y
\end{array}
$$

to distinguish the bundles and maps for $X$ and $Y$. Define maps

$$
\begin{aligned}
\mathcal{B} \iota: \mathcal{B} X \longrightarrow \mathcal{B} Y, & \mathcal{B} \iota(u):=\hat{\imath} \circ u, \\
\mathcal{E} \iota: \mathcal{E} X \longrightarrow \mathcal{E} Y, & \mathcal{E} \iota(j, u, \eta):=(j, \hat{\iota} \circ u, T \hat{\iota} \circ \eta) .
\end{aligned}
$$

Then, the diagrams

commute. By the chain rule, the diagram

is also commutative whenever $\bar{\partial}^{X}(j, u)=0$.
Remark 7.47. Consider the formula for the tangent space of $\mathcal{B} X$ from Remark 7.43. By the assumptions on the Liouville domains $X$ and $Y$, we have that $V^{X}=V^{Y}$. Also, the diagrams


commute, where for shortness we are using the notation

$$
\Omega_{j}^{k, p}(E)=W^{k, p}\left(\operatorname{Hom}^{0,1}((T \dot{\Sigma}, j),(E, J))\right)
$$

for any complex vector bundle $(E, J) \longrightarrow \dot{\Sigma}$. In both diagrams, the middle term of every row is the direct sum of the left and right terms. In addition, the vertical maps in the middle of both diagrams are block diagonal when written with respect to these decompositions.

Definition 7.48. Let $z_{0} \in \dot{\Sigma}$. Define the evaluation map

$$
\begin{aligned}
\mathrm{ev}^{X}: \mathcal{B} X & \longrightarrow \hat{X} \\
u & \longmapsto u\left(z_{0}\right)
\end{aligned}
$$

as well as its derivative $\mathbf{E}_{u}^{X}:=\mathrm{D}\left(\mathrm{ev}^{X}\right)(u): T_{u} \mathcal{B} X \longrightarrow T_{u\left(z_{0}\right)} \hat{X}$.
In the following lemma, we show that if a holomorphic curve $u$ in $X$ is regular (in $X$ ) then the corresponding holomorphic curve $\hat{\iota} \circ u$ in $Y$ is also regular. See also [MS22, Proposition A.1] for a similar result.

Lemma 7.49. Let $u \in \mathcal{B} X$ be holomorphic and denote $\hat{\iota} \circ u \in \mathcal{B} Y$ simply by $u$. Assume that the normal Conley-Zehnder index of every asymptotic Reeb orbit $\gamma_{i}$ is 1.
(1) If $\mathbf{L}_{(j, u)}^{X}$ is surjective then so is $\mathbf{L}_{(j, u)}^{Y}$.
(2) If $\mathbf{L}_{(j, u)}^{X} \oplus \mathbf{E}_{u}^{X}$ is surjective then so is $\mathbf{L}_{(j, u)}^{Y} \oplus \mathbf{E}_{u}^{Y}$.

Proof. Consider the decomposition $T_{x} \hat{Y}=T_{x} \hat{X} \oplus\left(T_{x} \hat{X}\right)^{\perp}$ for $x \in \hat{X}$. Let $\tau$ be a global complex trivialization of $u^{*} T \hat{Y}$, extending to an asymptotic unitary trivialization near the punctures, and such that $\tau$ restricts to a trivialization of $u^{*} T \hat{X}$ and $u^{*}(T \hat{X})^{\perp}$. By Remark 7.47, there are splittings

$$
\begin{aligned}
T_{u} \mathcal{B} Y & =T_{u} \mathcal{B} X \oplus T_{u}^{\perp} \mathcal{B} X \\
\mathcal{E}_{(j, u)} Y & =\mathcal{E}_{(j, u)} X \oplus \mathcal{E}_{(j, u)}^{\perp} X
\end{aligned}
$$

We can write the maps

$$
\begin{aligned}
& \mathbf{L}_{(j, u)}^{Y}: T_{j} \mathcal{T} \oplus T_{u} \mathcal{B} X \oplus T_{u}^{\perp} \mathcal{B} X \longrightarrow \mathcal{E}_{(j, u)} X \oplus \mathcal{E}_{(j, u)}^{\perp} X, \\
& \mathbf{D}_{(j, u)}^{Y}: T_{u} \mathcal{B} X \oplus T_{u}^{\perp} \mathcal{B} X \longrightarrow \mathcal{E}_{(j, u)} X \oplus \mathcal{E}_{(j, u)}^{\perp} X, \\
& \mathbf{L}_{(j, u)}^{X}: T_{j} \mathcal{T} \oplus T_{u} \mathcal{B} X \longrightarrow \mathcal{E}_{(j, u)} X, \\
& \mathbf{F}_{(j, u):}^{Y,} T_{j} \mathcal{T} \longrightarrow \mathcal{E}_{(j, u)} X \oplus \mathcal{E}_{(j, u)}^{\perp} X, \\
& \quad \mathbf{E}_{u}^{Y}: T_{u} \mathcal{B} X \oplus T_{u}^{\perp} \mathcal{B} X \longrightarrow T_{x} \hat{X} \oplus\left(T_{x} \hat{X}\right)^{\perp}
\end{aligned}
$$

as block matrices

$$
\begin{align*}
\mathbf{L}_{(j, u)}^{Y} & =\left[\begin{array}{ccc}
\mathbf{F}_{(j, u)}^{X} & \mathbf{D}_{(j, u)}^{X} & \mathbf{D}_{(j, u)}^{T N} \\
0 & 0 & \mathbf{D}_{(j, u)}^{N N}
\end{array}\right],  \tag{7.5}\\
\mathbf{D}_{(j, u)}^{Y} & =\left[\begin{array}{cc}
\mathbf{D}_{(j, u)}^{X} & \mathbf{D}_{(j, u)}^{T N} \\
0 & \mathbf{D}_{(j, u)}^{N N}
\end{array}\right],  \tag{7.6}\\
\mathbf{L}_{(j, u)}^{X} & =\left[\begin{array}{cc}
\mathbf{F}_{(j, u)}^{X} & \mathbf{D}_{(j, u)}^{X}
\end{array}\right],  \tag{7.7}\\
\mathbf{F}_{(j, u)}^{Y} & =\left[\begin{array}{cc}
\mathbf{F}_{(j, u)}^{X} \\
0
\end{array}\right],  \tag{7.8}\\
\mathbf{E}_{u}^{Y} & =\left[\begin{array}{cc}
\mathbf{E}_{u}^{X} & 0 \\
0 & \mathbf{E}_{u}^{N N}
\end{array}\right], \tag{7.9}
\end{align*}
$$

where (7.9) follows by definition of the evaluation map, (7.8) is true since $\mathbf{F}_{(j, u)}^{Y}$ is given by the formula $\mathbf{F}_{(j, u)}^{Y}(y)=\frac{1}{2}(J \circ T u \circ y)$, (7.6) follows because diagram (7.4) commutes, and (7.7) and (7.5) then follow by Definition 7.42. Let $\mathbf{D}_{\delta}^{N N}$ be the restriction and $\mathbf{D}_{0}^{N N}$ be the conjugation of $\mathbf{D}_{(j, u)}^{N N}$ (as in Definition 7.44). Denote by $\mathbf{B}_{\gamma_{i}}^{N N}$ the asymptotic operator of $\mathbf{D}_{\delta}^{N N}$ at $z_{i}$. Then the asymptotic operator of $\mathbf{D}_{0}^{N N}$ at $z_{i}$ is $\mathbf{B}_{\gamma_{i}}^{N N}+\delta$, which by assumption has Conley-Zehnder index equal to 1 . We show that ind $\mathbf{D}_{0}^{N N}=2$.

$$
\begin{aligned}
\operatorname{ind} \mathbf{D}_{0}^{N N} & =\chi(\dot{\Sigma})+2 c_{1}^{\tau}\left(u^{*} T \hat{X}\right)+\sum_{i=1}^{p} \mu_{\mathrm{CZ}}^{\tau}\left(\mathbf{B}_{\gamma_{i}}^{N N}+\delta\right) & & {[\text { by Theorem } 7.30] } \\
& =2 & & {\left[\text { since } \mu_{\mathrm{CZ}}^{\tau}\left(\mathbf{B}_{\gamma_{i}}^{N N}+\delta\right)=1\right] . }
\end{aligned}
$$

We prove (1).

$$
\begin{aligned}
\text { ind } \mathbf{D}_{0}^{N N}=2 & \Longrightarrow \mathbf{D}_{0}^{N N} \text { is surjective } \quad[\text { by Lemma } 7.32] \\
& \Longrightarrow \mathbf{D}_{\delta}^{N N} \text { is surjective } \quad\left[\mathbf{D}_{0}^{N N} \text { and } \mathbf{D}_{\delta}^{N N} \text { are conjugated }\right] \\
& \Longrightarrow \mathbf{D}_{(j, u)}^{N N} \text { is surjective }\left[\mathbf{D}_{\delta}^{Y} \text { is a restriction of } \mathbf{D}_{(j, u)}^{Y}\right] \\
& \Longrightarrow \mathbf{L}_{(j, u)}^{Y} \text { is surjective }\left[\begin{array}{l}
{[(j, u)}
\end{array} \text { is surjective by assumption }\right] .
\end{aligned}
$$

We prove (2).
ind $\mathbf{D}_{0}^{N N}=2$
$\Longrightarrow \mathbf{D}_{0}^{N N} \oplus \mathbf{E}_{u}^{N N}$ is surjective [by Lemma 7.34]
$\Longrightarrow \mathbf{D}_{\delta}^{N N} \oplus \mathbf{E}_{u}^{N N}$ is surjective $\quad\left[\mathbf{D}_{0}^{N N} \oplus \mathbf{E}_{u}^{N N}\right.$ and $\mathbf{D}_{\delta}^{N N} \oplus \mathbf{E}_{u}^{N N}$ are conjugated $]$
$\Longrightarrow \mathbf{D}_{(j, u)}^{N N} \oplus \mathbf{E}_{u}^{N N}$ is surjective $\quad\left[\mathbf{D}_{\delta}^{Y} \oplus \mathbf{E}_{u}^{Y}\right.$ is a restriction of $\left.\mathbf{D}_{(j, u)}^{Y} \oplus \mathbf{E}_{u}^{Y}\right]$
$\Longrightarrow \mathbf{L}_{(j, u)}^{Y} \oplus \mathbf{E}_{u}^{Y}$ is surjective $\quad\left[\mathbf{L}_{(j, u)}^{X} \oplus \mathbf{E}_{u}^{X}\right.$ is surjective by assumption $]$.

### 7.7 Moduli spaces of curves in ellipsoids

We now use the techniques explained in the past two sections to compute the augmentation map of an ellipsoid (Theorem 7.62). The proof of this theorem consists in an explicit count of curves in the ellipsoid satisfying a tangency constraint (Proposition 7.60) together with the fact that the moduli space of such curves is transversely
cut out (Propositions 7.57 to 7.59 ). Therefore, the explicit count agrees with the virtual count. We now state the assumptions for this section.

Let $a_{1}<\cdots<a_{n} \in \mathbb{R}_{>0}$ be rationally linearly independent and consider the ellipsoid $E\left(a_{1}, \ldots, a_{n}\right) \subset \mathbb{C}^{n}$. By [GH18, Section 2.1], $\partial E\left(a_{1}, \ldots, a_{n}\right)$ has exactly $n$ simple Reeb orbits $\gamma_{1}, \ldots, \gamma_{n}$, which satisfy

$$
\begin{align*}
\gamma_{j}(t) & =\sqrt{\frac{a_{j}}{\pi}} e^{\frac{2 \pi i t}{a_{j}}} e_{j},  \tag{7.10}\\
\mathcal{A}\left(\gamma_{j}^{m}\right) & =m a_{j}  \tag{7.11}\\
\mu_{\mathrm{CZ}}\left(\gamma_{j}^{m}\right) & =n-1+2 \sum_{i=1}^{n}\left\lfloor\frac{m a_{j}}{a_{i}}\right\rfloor, \tag{7.12}
\end{align*}
$$

where $\gamma_{j}: \mathbb{R} / a_{j} \mathbb{Z} \longrightarrow \partial E\left(a_{1}, \ldots, a_{n}\right)$ and $e_{j}$ is the $j$ th vector of the canonical basis of $\mathbb{C}^{n}$ as a vector space over $\mathbb{C}$. For simplicity, for every $\ell=1, \ldots, n$ denote $E_{\ell}=$ $E\left(a_{1}, \ldots, a_{\ell}\right) \subset \mathbb{C}^{\ell}$. Notice that $\gamma_{1}$ is a Reeb orbit of $\partial E_{1}, \ldots, \partial E_{n}$. Define maps

$$
\begin{aligned}
\iota_{\ell}: \mathbb{C}^{\ell} \longrightarrow \mathbb{C}^{\ell+1}, & \iota_{\ell}\left(z_{1}, \ldots, z_{\ell}\right):=\left(z_{1}, \ldots, z_{\ell}, 0\right) \\
h_{\ell}: \mathbb{C}^{\ell} \longrightarrow \mathbb{C}, & h_{\ell}\left(z_{1}, \ldots, z_{\ell}\right):=z_{1} .
\end{aligned}
$$

The maps $\iota_{\ell}: E_{\ell} \longrightarrow E_{\ell+1}$ are Liouville embeddings satisfying the assumptions in Section 7.6. Define also

$$
\begin{aligned}
x_{\ell} & :=0 \in \mathbb{C}^{\ell} \\
D_{\ell} & :=\left\{\left(z_{1}, \ldots, z_{\ell}\right) \in \mathbb{C}^{\ell} \mid z_{1}=0\right\}=h_{\ell}^{-1}(0)
\end{aligned}
$$

Choose an admissible almost complex structure $J_{\ell} \in \mathcal{J}\left(E_{\ell}, D_{\ell}\right)$ on $\hat{E}_{\ell}$ such that $J_{\ell}$ is the canonical almost complex structure of $\mathbb{C}^{\ell}$ near 0 . We assume that the almost complex structures are chosen in such a way that $\hat{\iota}_{\ell}: \hat{E}_{\ell} \longrightarrow \hat{E}_{\ell+1}$ is holomorphic and also such that there exists a biholomorphism $\varphi: \hat{E}_{1} \longrightarrow \mathbb{C}$ such that $\varphi(z)=z$ for $z$ near $0 \in \mathbb{C}$ (see Lemma 7.50 below). Let $m \in \mathbb{Z}_{\geq 1}$ and assume that $m a_{1}<a_{2}<\cdots<a_{n}$.
Consider the sphere $S^{2}$, without any specified almost complex structure, with a puncture $z_{1} \in S^{2}$ and an asymptotic marker $v_{1} \in\left(T_{z_{1}} S^{2} \backslash\{0\}\right) / \mathbb{R}_{>0}$, and also a marked point $z_{0} \in \dot{S}^{2}=S^{2} \backslash\left\{z_{1}\right\}$. For $k \in \mathbb{Z}_{\geq 0}$, denote

$$
\begin{aligned}
\mathcal{M}_{\mathrm{p}}^{\ell,(k)} & :=\mathcal{M}_{E_{\ell}}^{\S, J_{\ell}}\left(\gamma_{1}^{m}\right)\left\langle\mathcal{T}^{(k)} x_{\ell}\right\rangle_{\mathrm{p}} \\
& :=\left\{\begin{array}{ll}
(j, u) & \begin{array}{l}
j \text { is an almost complex structure on } S^{2}, \\
u:\left(\dot{S}^{2}, j\right) \longrightarrow\left(\hat{E}_{\ell}, J_{\ell}\right) \text { is as in Definition 4.7, } \\
u\left(z_{0}\right)=x_{\ell} \text { and } u \text { has contact order } k \text { to } D_{\ell} \text { at } x_{\ell}
\end{array}
\end{array}\right\} .
\end{aligned}
$$

Here, the subscript p means that the moduli space consists of parametrized curves, i.e. we are not quotienting by biholomorphisms. Denote the moduli spaces of regular curves and of unparametrized curves by

$$
\begin{aligned}
\mathcal{M}_{\mathrm{p}}^{\ell,(k)}, & =\mathcal{M}_{E_{\ell}}^{\S, J_{\ell}}\left(\gamma_{1}^{m}\right)\left\langle\mathcal{T}^{(k)} x_{\ell}\right\rangle_{\mathrm{p}, \text { reg }}, \\
\mathcal{M}^{\ell,(k)} & :=\mathcal{M}_{E_{\ell}}^{\S, J_{\ell}}\left(\gamma_{1}^{m}\right)\left\langle\mathcal{T}^{(k)} x_{\ell}\right\rangle:=\mathcal{M}_{\mathrm{p}}^{\ell,(k)} / \sim .
\end{aligned}
$$

Here, $\mathcal{M}^{\ell,(0)}:=\mathcal{M}_{E_{\ell}}^{\S, J_{\ell}}\left(\gamma_{1}^{m}\right)\left\langle\mathcal{T}^{(0)} x_{\ell}\right\rangle:=\mathcal{M}_{E_{\ell}}^{\S, J_{\ell}}\left(\gamma_{1}^{m}\right)$ and analogously for $\mathcal{M}_{\mathrm{p}, \mathrm{reg}}^{\ell,(0)}$ and $\mathcal{M}_{\mathrm{p}}^{\ell,(0)}$.

Lemma 7.50. For any $a>0$, there exists an almost complex structure $J$ on $\hat{B}(a)$ and a biholomorphism $\varphi: \hat{B}(a) \longrightarrow \mathbb{C}$ such that
(1) $J$ is cylindrical on $\mathbb{R}_{\geq 0} \times \partial B(a)$;
(2) $J$ is the canonical almost complex structure of $\mathbb{C}$ near $0 \in B(a) \subset \mathbb{C}$;
(3) $\varphi(z)=z$ for $z$ near $0 \in B(a) \subset \mathbb{C}$.

Proof. Choose $\rho_{0}<0$ and let $g: \mathbb{R} \longrightarrow \mathbb{R}_{>0}$ be a function such that $g(\rho)=a / 4 \pi$ for $\rho \leq \rho_{0}$ and $g(\rho)=1$ for $\rho \geq 0$. For $(\rho, w) \in \mathbb{R} \times \partial B(a)$, define

$$
\begin{aligned}
f(\rho) & :=\exp \left(\frac{\rho_{0}}{2}+\frac{2 \pi}{a} \int_{\rho_{0}}^{\rho} g(\sigma) \mathrm{d} \sigma\right), \\
J_{(\rho, w)}\left(\partial_{\rho}\right) & :=g(\rho) R_{w}^{\partial B(a)}, \\
\varphi(\rho, w) & :=f(\rho) w .
\end{aligned}
$$

Property (1) follows from the fact that $g(\rho)=1$ for $\rho \geq 0$. Consider the Liouville vector field of $\mathbb{C}$, which is denoted by $Z$ and given by $Z(w)=w / 2$. Let $\Phi: \mathbb{R} \times \partial B(a) \longrightarrow \mathbb{C}$ be the map given by $\Phi(\rho, w)=\phi_{Z}^{\rho}(w)=\exp (\rho / 2) w$. By definition of completion, $\left.\Phi\right|_{B(a) \backslash\{0\}}: B(a) \backslash\{0\} \longrightarrow \mathbb{C}$ is the inclusion. To prove property (3), it suffices to show that $\varphi(\rho, w)=\Phi(\rho, w)$ for every $(\rho, w) \in \mathbb{R}_{\leq_{\rho_{0}}} \times \partial B(a)$. For this, simply note that

$$
\begin{aligned}
f(\rho) & =\exp \left(\frac{\rho_{0}}{2}+\frac{2 \pi}{a} \int_{\rho_{0}}^{\rho} g(\sigma) \mathrm{d} \sigma\right) \quad[\text { by definition of } f] \\
& =\exp \left(\frac{\rho_{0}}{2}+\frac{2 \pi}{a}\left(\rho-\rho_{0}\right) \frac{a}{4 \pi}\right) \quad\left[\rho \leq \rho_{0} \text { implies } g(\rho)=a / 4 \pi\right] \\
& =\exp \left(\frac{\rho}{2}\right)
\end{aligned}
$$

Therefore, $\varphi(z)=z$ for $z$ near $0 \in B(a) \subset \mathbb{C}$, and in particular $\varphi$ can be extended smoothly to a map $\varphi: \hat{B}(a) \longrightarrow \mathbb{C}$. We show that $\varphi$ is holomorphic.

$$
\begin{aligned}
j \circ \mathrm{D} \varphi(\rho, w)\left(\partial_{\rho}\right) & =j\left(\left.\frac{\partial}{\partial \rho}(f(\rho)|w|) \frac{\partial}{\partial r}\right|_{\varphi(\rho, w)}\right) & & {[\text { by definition of } \varphi] } \\
& =\frac{2 \pi}{a} g(\rho) j\left(\left.f(\rho)|w| \frac{\partial}{\partial r}\right|_{\varphi(\rho, w)}\right) & & {[\text { by definition of } f] } \\
& =\frac{2 \pi}{a} g(\rho) j\left(\left.|\varphi(\rho, w)| \frac{\partial}{\partial r}\right|_{\varphi(\rho, w)}\right) & & {[\text { by definition of } \varphi] } \\
& =\left.\frac{2 \pi}{a} g(\rho) \frac{\partial}{\partial \theta}\right|_{\varphi(\rho, w)} & & {[\text { by definition of } j] } \\
& =g(\rho) \mathrm{D} \varphi(\rho, w)\left(R_{w}^{\partial B(a)}\right) & & {[\text { by [GH18, Equation }(2.2)]] } \\
& =\mathrm{D} \varphi(\rho, w) \circ J\left(\partial_{\rho}\right) & & {[\text { by definition of } J] }
\end{aligned}
$$

Where $(r, \theta)$ are the polar coordinates of $\mathbb{C}$. Since $\varphi$ is holomorphic and $\varphi$ is the identity near the origin, we conclude that $J$ is the canonical almost complex structure of $\mathbb{C}$ near the origin. In particular, $J$ can be extended smoothly to an almost complex structure on $\hat{B}(a)$, which proves (2). Finally, we show that $\varphi$ is a diffeomorphism. For this, it
suffices to show that $\Phi^{-1} \circ \varphi: \mathbb{R} \times \partial B(a) \longrightarrow \mathbb{R} \times \partial B(a)$ is a diffeomorphism. This map is given by $\Phi^{-1} \circ \varphi(\rho, w)=(2 \ln (f(\rho))$, w). Since

$$
\frac{\mathrm{d}}{\mathrm{~d} \rho}(2 \ln (f(\rho)))=2 \frac{f^{\prime}(\rho)}{f(\rho)}=\frac{4 \pi}{a} g(\rho)>0
$$

$\varphi$ is a diffeomorphism.
Lemma 7.51. Let inv: $\overline{\mathbb{C}} \longrightarrow \overline{\mathbb{C}}$ be the map given by $\operatorname{inv}(z)=1 / z$ and consider the vector $V:=\mathrm{D} \operatorname{inv}(0) \partial_{x} \in T_{\infty} \overline{\mathbb{C}}$. For every $j \in \mathcal{T}$ there exists a unique biholomorphism $\psi_{j}:\left(\overline{\mathbb{C}}, j_{0}\right) \longrightarrow\left(S^{2}, j\right)$ such that

$$
\psi_{j}(0)=z_{0}, \quad \psi_{j}(\infty)=z_{1}, \quad \mathrm{D} \psi_{j}(\infty) V=\frac{v_{1}}{\left\|v_{1}\right\|},
$$

where $\|\cdot\|$ is the norm coming from the canonical Riemannian metric on $S^{2}$ as the sphere of radius 1 in $\mathbb{R}^{3}$.

Proof. By the uniformization theorem [dB16, Theorem XII.0.1], there exists a biholomorphism $\phi:\left(S^{2}, j\right) \longrightarrow\left(\overline{\mathbb{C}}, j_{0}\right)$. Since there exists a unique Möbius transformation $\psi_{0}:\left(\overline{\mathbb{C}}, j_{0}\right) \longrightarrow\left(\overline{\mathbb{C}}, j_{0}\right)$ such that

$$
\psi_{0}(0)=\phi\left(z_{0}\right), \quad \psi_{0}(\infty)=\phi\left(z_{1}\right), \quad \mathrm{D} \psi_{0}(\infty) V=\mathrm{D} \phi\left(z_{1}\right) \frac{v_{1}}{\left\|v_{1}\right\|}
$$

the result follows.
We will denote also by $\psi_{j}$ the restriction $\psi_{j}:\left(\mathbb{C}, j_{0}\right) \longrightarrow\left(S^{2}, j\right)$.
Lemma 7.52. If $(j, u) \in \mathcal{M}^{1,(0)}$ then $\varphi \circ u \circ \psi_{j}: \mathbb{C} \longrightarrow \mathbb{C}$ is a polynomial of degree $m$.
Proof. Since $u$ is positively asymptotic to $\gamma_{1}^{m}$, the map $\varphi \circ u \circ \psi_{j}$ goes to $\infty$ as $z$ goes to $\infty$. Therefore, $\varphi \circ u \circ \psi_{j}$ is a polynomial. Again using the fact that $u$ is positively asymptotic to $\gamma_{1}^{m}$, we conclude that for $r$ big enough the path $\theta \longmapsto \varphi \circ u \circ \psi_{j}\left(r e^{i \theta}\right)$ winds around the origin $m$ times. This implies that the degree of $\varphi \circ u \circ \psi_{j}$ is $m$.

Lemma 7.53. For every $\ell=1, \ldots, n-1$, view $\gamma_{1}^{m}$ as a Reeb orbit of $\partial E_{\ell} \subset \partial E_{\ell+1}$. The normal Conley-Zehnder index of $\gamma_{1}^{m}$ is 1 .

Proof. By [GH18, Equation (2.2)], the Reeb vector field of $\partial E_{\ell+1}$ is given by

$$
R^{\partial E_{\ell+1}}=2 \pi \sum_{j=1}^{\ell+1} \frac{1}{a_{j}} \frac{\partial}{\partial \theta_{j}},
$$

where $\theta_{j}$ denotes the angular polar coordinate of the $j$ th summand of $\mathbb{C}^{\ell+1}$. Therefore, the flow of $R^{\partial E_{\ell+1}}$ is given by

$$
\begin{aligned}
& \phi_{R}^{t}: \partial E_{\ell+1} \\
&\left(z_{1}, \ldots, z_{\ell+1}\right) \longmapsto\left(E_{\ell+1}\right. \\
&\left.e^{\frac{2 i}{a_{1}}} z_{1}, \ldots, e^{\frac{2 \pi i}{a_{\ell+1}}} z_{\ell+1}\right) .
\end{aligned}
$$

The diagram
commutes. Define a path $A_{\gamma_{1}^{m}}:\left[0, m a_{1}\right] \longrightarrow \mathrm{Sp}(2)$ by $A_{\gamma_{1}^{m}}(t)=\exp \left(t J_{0} S\right)$, where

$$
S=\frac{2 \pi}{a_{\ell+1}}\left[\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right]
$$

The only eigenvalue of $S$ is $2 \pi / a_{\ell+1}$, which has multiplicity 2 . Therefore, the signature of $S$ is $\operatorname{sign} S=2$. These facts allow us to compute $\mu_{\mathrm{CZ}}^{\perp}\left(\gamma_{1}^{m}\right)$ using Proposition 3.5:

$$
\begin{array}{rlrl}
\mu_{\mathrm{CZ}}^{\perp}\left(\gamma_{1}^{m}\right) & =\mu_{\mathrm{CZ}}\left(A_{\gamma_{1}^{m}}\right) & & {\left[\text { by definition of } \mu_{\mathrm{CZ}}^{\perp}\right]} \\
& =\left(\frac{1}{2}+\left\lfloor\sqrt{\frac{2 \pi}{a_{\ell+1}} \frac{2 \pi}{a_{\ell+1}}} \frac{m a_{1}}{2 \pi}\right.\right. \\
) & \operatorname{sign} S & & {[\text { by Proposition 3.5] }} \\
& =\frac{1}{2} \operatorname{sign} S & & {\left[\text { since } m a_{1}<a_{2}<\cdots<a_{n}\right]} \\
& =1 & & {[\text { by the discussion above }]}
\end{array}
$$

Lemma 7.54. If $\ell=1, \ldots, n$ then $\gamma_{1}^{m}$ is the unique Reeb orbit of $\partial E_{\ell}$ such that $\mu_{\mathrm{CZ}}\left(\gamma_{1}^{m}\right)=\ell-1+2 m$.

Proof. First, notice that

$$
\begin{aligned}
\mu_{\mathrm{CZ}}\left(\gamma_{1}^{m}\right) & =\ell-1+2 \sum_{j=1}^{\ell}\left\lfloor\frac{m a_{1}}{a_{j}}\right\rfloor & & {[\text { by equation (7.12)] }} \\
& =\ell-1+2 m & & {\left[\text { since } m a_{1}<a_{2}<\cdots<a_{n}\right] . }
\end{aligned}
$$

Conversely, let $\gamma=\gamma_{i}^{k}$ be a Reeb orbit of $\partial E_{\ell}$ with $\mu_{\mathrm{CZ}}(\gamma)=\ell-1+2 m$. By equation (7.12), this implies that

$$
\begin{equation*}
m=\sum_{j=1}^{\ell}\left\lfloor\frac{k a_{i}}{a_{j}}\right\rfloor . \tag{7.13}
\end{equation*}
$$

We show that $i=1$. Assume by contradiction otherwise. Then

$$
\begin{aligned}
m & =\sum_{1 \leq j \leq l}\left\lfloor\frac{k a_{i}}{a_{j}}\right\rfloor & & {[\text { by equation (7.13)] }} \\
& \geq \sum_{1 \leq j \leq i}\left\lfloor\frac{k a_{i}}{a_{j}}\right\rfloor & & {[\text { since every term in the sum is } \geq 0] } \\
& =\left\lfloor\frac{k a_{i}}{a_{1}}\right\rfloor+\sum_{1<j<i}\left\lfloor\frac{k a_{i}}{a_{j}}\right\rfloor+k & & {[\text { since by assumption }, i>1] } \\
& \geq(m+i-1) k & & {\left[m a_{1}<a_{2}<\cdots<a_{i}\right] }
\end{aligned}
$$

$$
>m k \quad[\text { since by assumption }, i>1],
$$

which is a contradiction, and therefore $i=1$. We show that $k=m$, using the fact that $m \geq\left\lfloor k a_{i} / a_{1}\right\rfloor=k$.

$$
\begin{aligned}
m & =\sum_{1 \leq j \leq \ell}\left\lfloor\frac{k a_{1}}{a_{j}}\right\rfloor & & {[\text { by equation (7.13) and since } i=1] } \\
& =k+\sum_{2 \leq j \leq \ell}\left\lfloor\frac{k a_{1}}{a_{j}}\right\rfloor & & \\
& =k & & {\left[\text { since } k \leq m \text { and } k a_{1} \leq m a_{1}<a_{1}<\cdots<a_{n}\right] . }
\end{aligned}
$$

Lemma 7.55. The module $C H_{n-1+2 m}\left(E_{n}\right)$ is the free $\mathbb{Q}$-module generated by $\gamma_{1}^{m}$.
Proof. By equation (7.12), every Reeb orbit of $\partial E_{n}$ is good. We claim that the differential $\partial: C C\left(E_{n}\right) \longrightarrow C C\left(E_{n}\right)$ is zero. Assume by contradiction that there exists a Reeb orbit $\gamma$ such that $\partial \gamma \neq 0$. By definition of $\partial$, this implies that there exist Reeb orbits $\eta, \alpha_{1}, \ldots, \alpha_{p}$ such that

$$
\begin{aligned}
& 0 \neq \#^{\mathrm{vir}} \overline{\mathcal{M}}_{\partial E_{n}}^{J_{n}}\left(\gamma ; \eta, \alpha_{1}, \ldots, \alpha_{p}\right) \\
& 0 \neq \#^{\mathrm{vir}} \overline{\mathcal{M}}_{E_{n}}^{J_{n}}\left(\alpha_{j}\right), \quad \text { for } j=1, \ldots, p
\end{aligned}
$$

By assumption on the virtual perturbation scheme,

$$
\begin{aligned}
0 & =\operatorname{virdim} \overline{\mathcal{M}}_{E_{n}}^{J_{n}}\left(\alpha_{j}\right)=n-3+\mu_{\mathrm{CZ}}\left(\alpha_{j}\right) \quad \text { for every } j=1, \ldots, p, \\
0 & =\operatorname{virdim} \overline{\mathcal{M}}_{\partial E_{n}}^{J_{n}}\left(\gamma ; \eta, \alpha_{1}, \ldots, \alpha_{p}\right) \\
& =(n-3)(2-(2+p))+\mu_{\mathrm{CZ}}(\gamma)-\mu_{\mathrm{CZ}}(\eta)-\sum_{j=1}^{p} \mu_{\mathrm{CZ}}\left(\alpha_{j}\right)-1 \\
& =\mu_{\mathrm{CZ}}(\gamma)-\mu_{\mathrm{CZ}}(\eta)-1 \\
& \in 1+2 \mathbb{Z},
\end{aligned}
$$

where in the last line we used equation (7.12). This gives the desired contradiction, and we conclude that $\partial: C C\left(E_{n}\right) \longrightarrow C C\left(E_{n}\right)$ is zero. Therefore, $C H\left(E_{n}\right)=C C\left(E_{n}\right)$ is the free $\mathbb{Q}$-module generated by the Reeb orbits of $\partial E_{n}$. By Lemma $7.54, \gamma_{1}^{m}$ is the unique Reeb orbit of $\partial E_{n}$ with $\mu_{\mathrm{CZ}}\left(\gamma_{1}^{m}\right)=n-1+2 m$, from which the result follows.

Lemma 7.56. If $\ell=1, \ldots, n$ and $k \in \mathbb{Z}_{\geq 1}$ then $\mathcal{M}_{\mathrm{p}}^{\ell,(k)}=\mathcal{M}_{\mathrm{p}}^{1,(k)}$ and $\mathcal{M}^{\ell,(k)}=\mathcal{M}^{1,(k)}$.
Proof. It suffices to show that $\mathcal{M}_{\mathrm{p}}^{\ell,(k)}=\mathcal{M}_{\mathrm{p}}^{\ell+1,(k)}$ for every $\ell=1, \ldots, n-1$. The inclusion $\mathcal{M}_{\mathrm{p}}^{\ell(k)} \subset \mathcal{M}_{\mathrm{p}}^{\ell+1,(k)}$ follows from the fact that the inclusion $\hat{E}_{\ell} \hookrightarrow \hat{E}_{\ell+1}$ is holomorphic and the assumptions on the symplectic divisors. To prove that $\mathcal{M}_{\mathrm{p}}^{\ell+1,(k)} \subset \mathcal{M}_{\mathrm{p}}^{\ell,(k)}$, it suffices to assume that $(j, u) \in \mathcal{M}_{\mathrm{p}}^{\ell+1,(k)}$ and to show that the image of $u$ is contained in $\hat{E}_{\ell} \subset \hat{E}_{\ell+1}$. Since $u$ has contact order $k$ to $D_{\ell+1}$ at $x_{\ell+1}=\iota_{\ell}\left(x_{\ell}\right)$, we conclude that $u$ is not disjoint from $\hat{E}_{\ell}$. By Lemma 6.39, $u$ is contained in $\hat{E}_{\ell}$.

We now prove that the moduli spaces $\mathcal{M}^{\ell,(k)}$ are regular. The proof strategy is as follows.
(1) Proposition 7.57 deals with the moduli spaces $\mathcal{M}^{1,(0)}$. We show that the linearized Cauchy-Riemann operator is surjective using Lemma 7.46.
(2) Proposition 7.58 deals with the moduli spaces $\mathcal{M}^{\ell,(1)}$. Here, we need to consider the linearized Cauchy-Riemann operator together with an evaluation map. We show inductively that this map is surjective using Lemma 7.49.
(3) Finally, Proposition 7.59 deals with the moduli spaces $\mathcal{M}^{\ell,(k)}$. We now need to consider the jet evaluation map. We prove inductively that this map is surjective by writing it explicitly.
Proposition 7.57. The moduli spaces $\mathcal{M}_{\mathrm{p}}^{1,(0)}$ and $\mathcal{M}^{1,(0)}$ are transversely cut out.
Proof. It is enough to show that $\mathcal{M}_{\mathrm{p}}^{1,(0)}$ is transversely cut out, since this implies that $\mathcal{M}^{1,(0)}$ is transversely cut out as well. Recall that $\mathcal{M}_{\mathrm{p}}^{1,(0)}$ can be written as the zero set of the Cauchy-Riemann operator $\bar{\partial}^{1}: \mathcal{T} \times \mathcal{B} E_{1} \longrightarrow \mathcal{E} E_{1}$. It suffices to assume that $(j, u) \in\left(\bar{\partial}^{1}\right)^{-1}(0)$ and to prove that the linearization

$$
\mathbf{L}_{(j, u)}^{1}: T_{j} \mathcal{T} \oplus T_{u} \mathcal{B} E_{1} \longrightarrow \mathcal{E}_{(j, u)} E_{1}
$$

is surjective. This follows from Lemma 7.46.
Proposition 7.58. If $\ell=1, \ldots, n$ then $\mathcal{M}_{\mathrm{p}}^{\ell,(1)}$ and $\mathcal{M}^{\ell,(1)}$ are transversely cut out.
Proof. We will use the notation of Section 7.6 with $X=E_{\ell}$ and $Y=E_{\ell+1}$. We will show by induction on $\ell$ that $\mathcal{M}_{\mathrm{p}}^{\ell,(1)}$ is transversely cut out. This implies that $\mathcal{M}^{\ell,(1)}$ is transversely cut out as well.

We prove the base case. By Proposition 7.57, $\mathcal{M}_{\mathrm{p}}^{1,(0)}$ is a smooth manifold. Consider the evaluation map

$$
\begin{aligned}
\mathrm{ev}^{1}: \mathcal{M}_{\mathrm{p}}^{1,(0)} & \longrightarrow \hat{E}_{1} \\
(j, u) & \longmapsto u\left(z_{0}\right) .
\end{aligned}
$$

Notice that $\mathcal{M}_{\mathrm{p}}^{1,(1)}=\left(\mathrm{ev}^{1}\right)^{-1}\left(x_{1}\right)$. We wish to show that the linearized evaluation map $\mathbf{E}_{(j, u)}^{1}=\mathrm{D}\left(\mathrm{ev}^{1}\right)(j, u): T_{(j, u)} \mathcal{M}_{\mathrm{p}}^{1,(0)} \longrightarrow T_{u\left(z_{0}\right)} \hat{E}_{1}$ is surjective whenever $u\left(z_{0}\right)=\operatorname{ev}^{1}(j, u)=$ $x_{1}$. There are commutative diagrams

where

$$
\begin{aligned}
\mathcal{M} & :=\{f: \mathbb{C} \longrightarrow \mathbb{C} \mid f \text { is a polynomial of degree } m\}, \\
\mathcal{C} & :=\left\{\left(a_{0}, \ldots, a_{m}\right) \in \mathbb{C}^{m+1} \mid a_{m} \neq 0\right\},
\end{aligned}
$$

$$
\begin{aligned}
\Phi(j, u) & :=\varphi \circ u \circ \psi_{j}, \\
\operatorname{ev}_{\mathcal{M}}(f) & :=f(0), \\
\operatorname{ev}_{\mathcal{C}}\left(a_{0}, \ldots, a_{m}\right) & :=a_{0}, \\
\mathcal{P}\left(a_{0}, \ldots, a_{m}\right)(z) & :=a_{0}+a_{1} z+\cdots+a_{m} z^{m},
\end{aligned}
$$

and the diagram on the right is obtained by linearizing the one on the left. The map $\Phi$ is well-defined by Lemma 7.52. Since $\mathbf{E}_{\mathcal{C}}\left(a_{0}, \ldots, a_{m}\right)=a_{0}$ is surjective, $\mathbf{E}_{u}^{1}$ is surjective as well. This finishes the proof of the base case.

We prove the induction step, i.e. that if $\mathcal{M}_{p}^{\ell,(1)}$ is transversely cut out then so is $\mathcal{M}_{p}^{\ell+1,(1)}$. We prove that $\mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell,(1)} \subset \mathcal{M}_{\mathrm{p}, \mathrm{reg}}^{\ell+1,(1)}$. For this, assume that $(j, u) \in \mathcal{M}_{\mathrm{p}}^{\ell,(1)}$ is such that $\mathbf{L}_{(j, u)}^{\ell} \oplus \mathbf{E}_{u}^{\ell}: T_{j} \mathcal{T} \oplus T_{u} \mathcal{B} E_{\ell} \longrightarrow \mathcal{E}_{(j, u)} E_{\ell} \oplus T_{x_{\ell}} \hat{E}_{\ell}$ is surjective. By Lemma 7.49,

$$
\mathbf{L}_{(j, u)}^{\ell+1} \oplus \mathbf{E}_{u}^{\ell+1}: T_{j} \mathcal{T} \oplus T_{u} \mathcal{B} E_{\ell+1} \longrightarrow \mathcal{E}_{(j, u)} E_{\ell+1} \oplus T_{x_{\ell+1}} \hat{E}_{\ell+1}
$$

is also surjective, which means that $(j, u) \in \mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1,(1)}$. This concludes the proof of $\mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell,(1)} \subset \mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1,(1)}$. Finally, we show that $\mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1,(1)}=\mathcal{M}_{\mathrm{p}}^{\ell+1,(1)}$.

$$
\begin{aligned}
\mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1,(1)} & \subset \mathcal{M}_{\mathrm{p}}^{\ell+1,(1)} & & {[\text { since regular curves form a subset }] } \\
& =\mathcal{M}_{\mathrm{p}}^{\ell,(1)} & & {[\text { by Lemma } 7.56] } \\
& =\mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell,(1)} & & {[\text { by the induction hypothesis }] } \\
& \subset \mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1)} & & {[\text { proven above }] . }
\end{aligned}
$$

Proposition 7.59. If $\ell=1, \ldots, n$ and $k=1, \ldots, m$ then $\mathcal{M}_{\mathrm{p}}^{\ell,(k)}$ and $\mathcal{M}^{\ell,(k)}$ are transversely cut out.

Proof. By Proposition 7.58, $\mathcal{M}_{\mathrm{p}}^{\ell,(1)}$ is a smooth manifold. Consider the jet evaluation map

$$
\begin{aligned}
j^{\ell,(k)}: \mathcal{M}_{\mathrm{p}}^{\ell,(1)} & \longrightarrow \mathbb{C}^{k-1} \\
(j, u) & \longmapsto\left(\left(h_{\ell} \circ u \circ \psi_{j}\right)^{(1)}(0), \ldots,\left(h_{\ell} \circ u \circ \psi_{j}\right)^{(k-1)}(0)\right) .
\end{aligned}
$$

The moduli space $\mathcal{M}_{\mathrm{p}}^{\ell,(k)}$ is given by $\mathcal{M}_{\mathrm{p}}^{\ell(k)}=\left(j^{\ell,(k)}\right)^{-1}(0)$. We will prove by induction on $\ell$ that $\mathcal{M}_{\mathrm{p}}^{\ell,(k)}$ is transversely cut out. This shows that $\mathcal{M}^{\ell,(k)}$ is transversely cut out as well. Define $\mathbf{J}_{(j, u)}^{\ell,(k)}:=\mathrm{D}\left(j^{\ell,(k)}\right)(j, u): T_{(j, u)} \mathcal{M}_{\mathrm{p}}^{\ell,(1)} \longrightarrow \mathbb{C}^{k-1}$.
We prove the base case, i.e. that $\mathcal{M}_{\mathrm{p}}^{1,(k)}$ is transversely cut out. For this, it suffices to assume that $(j, u) \in \mathcal{M}_{\mathrm{p}}^{1,(1)}$ is such that $j^{1,(k)}(j, u)=0$ and to prove that $\mathbf{J}_{(j, u)}^{1,(k)}$ is surjective. There are commutative diagrams

where

$$
\mathcal{M}:=\{f: \mathbb{C} \longrightarrow \mathbb{C} \mid f \text { is a polynomial of degree } m \text { with } f(0)=0\},
$$

$$
\begin{aligned}
\mathcal{C} & :=\left\{\left(a_{1}, \ldots, a_{m}\right) \in \mathbb{C}^{m} \mid a_{m} \neq 0\right\}, \\
\Phi(j, u) & :=\varphi \circ u \circ \psi_{j}, \\
j_{\mathcal{M}}^{(k)}(f) & :=\left(f^{(1)}(0), \ldots, f^{(k-1)}(0)\right), \\
j_{\mathcal{C}}^{(k)}\left(a_{1}, \ldots, a_{m}\right) & :=\left(a_{1}, \ldots,(k-1)!a_{k-1}\right), \\
\mathcal{P}\left(a_{1}, \ldots, a_{m}\right)(z) & :=a_{1} z+\cdots+a_{m} z^{m},
\end{aligned}
$$

and the diagram on the right is obtained by linearizing the one on the left. The map $\Phi$ is well-defined by Lemma 7.52. Since $\mathbf{J}_{\mathcal{C}}^{(k)}\left(a_{1}, \ldots, a_{m}\right)=\left(a_{1}, \ldots,(k-1)!a_{k-1}\right)$ is surjective, $\mathbf{J}_{u}^{1,(k)}$ is surjective as well. This finishes the proof of the base case.
We prove the induction step, i.e. that if $\mathcal{M}_{\mathrm{p}}^{\ell(k)}$ is transversely cut out then so is $\mathcal{M}_{\mathrm{p}}^{\ell+1,(k)}$. We show that $\mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell,(k)} \subset \mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1,(k)}$. For this, it suffices to assume that $(j, u) \in \mathcal{M}_{\mathrm{p}}^{\ell(,(k)}$ is such that $\mathbf{J}_{(j, u)}^{\ell(,(k)}$ is surjective, and to prove that $\mathbf{J}_{(j, u)}^{\ell+1,(k)}$ is surjective as well. This follows because the diagrams

commute. Finally, we show that $\mathcal{M}_{\mathrm{p}, \mathrm{reg}}^{\ell+1,(k)}=\mathcal{M}_{\mathrm{p}}^{\ell+1,(k)}$.

$$
\begin{aligned}
\mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1,(k)} & \subset \mathcal{M}_{\mathrm{p}}^{\ell+1,(k)} & & {[\text { since regular curves form a subset }] } \\
& =\mathcal{M}_{\mathrm{p}}^{\ell,(k)} & & {[\text { by Lemma } 7.56] } \\
& =\mathcal{M}_{\mathrm{p}, \mathrm{reg}}^{\ell,(k)} & & {[\text { by the induction hypothesis }] } \\
& \subset \mathcal{M}_{\mathrm{p}, \text { reg }}^{\ell+1,(k)} & & {[\text { proven above }] }
\end{aligned}
$$

Proposition 7.60. If $\ell=1, \ldots, n$ then $\#^{\mathrm{vir}} \overline{\mathcal{M}}^{\ell,(m)}=\# \overline{\mathcal{M}}^{\ell,(m)}=1$.
Proof. By assumption on the perturbation scheme and Proposition 7.59, $\#^{\mathrm{vir}} \overline{\mathcal{M}}^{\ell,(m)}=$ $\# \overline{\mathcal{M}}^{\ell,(m)}$. Again by Proposition 7.59, the moduli space $\mathcal{M}^{\ell,(m)}$ is transversely cut out and

$$
\operatorname{dim} \mathcal{M}^{\ell,(m)}=(n-3)(2-1)+\mu_{\mathrm{CZ}}\left(\gamma_{1}^{m}\right)-2 \ell-2 m+4=0,
$$

where in the second equality we have used Lemma 7.54. This implies that $\mathcal{M}^{\ell,(m)}$ is compact, and in particular $\# \overline{\mathcal{M}}^{\ell,(m)}=\# \mathcal{M}^{\ell,(m)}$. By Lemma 7.56, $\# \mathcal{M}^{\ell,(m)}=\# \mathcal{M}^{1,(m)}$. It remains to show that $\# \mathcal{M}^{1,(m)}=1$. For this, notice that $\mathcal{M}^{1,(m)}$ is the set of equivalence classes of pairs $(j, u)$, where $j$ is an almost complex structure on $\Sigma=S^{2}$ and $u:(\dot{\Sigma}, j) \longrightarrow\left(\hat{E}_{1}, J_{1}\right)$ is a holomorphic map such that
(1) $u\left(z_{0}\right)=x_{1}$ and $u$ has contact order $m$ to $D_{1}$ at $x_{1}$;
(2) if $(s, t)$ are the cylindrical coordinates on $\dot{\Sigma}$ near $z_{1}$ such that $v_{1}$ agrees with the direction $t=0$, then

$$
\begin{aligned}
\lim _{s \rightarrow+\infty} \pi_{\mathbb{R}} \circ u(s, t) & =+\infty \\
\lim _{s \rightarrow+\infty} \pi_{\partial E_{1}} \circ u(s, t) & =\gamma_{1}\left(a_{1} m t\right) .
\end{aligned}
$$

Here, two pairs $\left(j_{0}, u_{0}\right)$ and $\left(j_{1}, u_{1}\right)$ are equivalent if there exists a biholomorphism $\phi:\left(\Sigma, j_{0}\right) \longrightarrow\left(\Sigma, j_{1}\right)$ such that

$$
\phi\left(z_{0}\right)=z_{0}, \quad \phi\left(z_{1}\right)=z_{1}, \quad \mathrm{D} \phi\left(z_{1}\right) v_{1}=v_{1} .
$$

We claim that any two pairs $\left(j_{0}, u_{0}\right)$ and $\left(j_{1}, u_{1}\right)$ are equivalent. By Lemma 7.52, the maps $\varphi \circ u_{0} \circ \psi_{j_{0}}$ and $\varphi \circ u_{1} \circ \psi_{j_{1}}$ are polynomials of degree $m$ :

$$
\begin{aligned}
& \varphi \circ u_{0} \circ \psi_{j_{0}}(z)=a_{0}+\cdots+a_{m} z^{m}, \\
& \varphi \circ u_{1} \circ \psi_{j_{1}}(z)=b_{0}+\cdots+b_{m} z^{m} .
\end{aligned}
$$

Since $u_{0}$ and $u_{1}$ have contact order $m$ to $D_{1}$ at $x_{1}$, for every $\nu=0, \ldots, m-1$ we have

$$
\begin{aligned}
& 0=\left(\varphi \circ u_{0} \circ \psi_{j_{0}}\right)^{(\nu)}(0)=\nu!a_{\nu}, \\
& 0=\left(\varphi \circ u_{1} \circ \psi_{j_{1}}\right)^{(\nu)}(0)=\nu!b_{\nu} .
\end{aligned}
$$

Since $u_{0}$ and $u_{1}$ have the same asymptotic behaviour, $\arg \left(a_{m}\right)=\arg \left(b_{m}\right)$. Hence, there exists $\lambda \in \mathbb{R}_{>0}$ such that $\lambda^{m} b_{m}=a_{m}$. Then,

$$
u_{1} \circ \psi_{j_{1}}(\lambda z)=u_{0} \circ \psi_{j_{0}}(z) .
$$

Therefore, $\left(j_{0}, u_{0}\right)$ and $\left(j_{1}, u_{1}\right)$ are equivalent and $\# \mathcal{M}^{1,(m)}=1$.
Remark 7.61. In [CM18, Proposition 3.4], Cieliebak and Mohnke show that the signed count of the moduli space of holomorphic curves in $\mathbb{C} P^{n}$ in the homology class [ $\mathbb{C} P^{1}$ ] which satisfy a tangency condition $\left\langle\mathcal{T}^{(n)} x\right\rangle$ equals $(n-1)$ !. It is unclear how this count relates to the one of Proposition 7.60.

Finally, we will use the results of this section to compute the augmentation map of the ellipsoid $E_{n}$.

Theorem 7.62. The augmentation map $\epsilon_{m}: C H_{n-1+2 m}\left(E_{n}\right) \longrightarrow \mathbb{Q}$ is an isomorphism.
Proof. By Proposition 7.60, Remark 7.38 and definition of the augmentation map, we have $\epsilon_{m}\left(\gamma_{1}^{m}\right) \neq 0$. By Lemma 7.55, $\epsilon_{m}$ is an isomorphism.

### 7.8 Computations using contact homology

Finally, we use the tools developed in this chapter to prove Conjecture 6.24 (see Theorem 7.65). The proof we give is the same as that of Theorem 6.41 , with the update that we will use the capacity $\mathfrak{g}_{k}^{\leq 1}$ to prove that

$$
\tilde{\mathfrak{g}}_{k}^{\leq 1}(X) \leq \mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)
$$

for any nondegenerate Liouville domain $X$. Notice that in Theorem 6.41, $\tilde{\mathfrak{g}}_{k}^{\leq 1}(X) \leq$ $c_{k}^{\mathrm{GH}}(X)$ held because by assumption $X$ was a 4 -dimensional convex toric domain. We start by showing that $\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X) \leq \mathfrak{g}_{k}^{\leq \ell}(X)$. This result has already been proven in [MS22, Section 3.4], but we include a proof for the sake of completeness.

Theorem 7.63 ([MS22, Section 3.4]). If $X$ is a Liouville domain then

$$
\tilde{\mathfrak{g}}_{k}^{\leq \ell}(X) \leq \mathfrak{g}_{k}^{\leq \ell}(X)
$$

Proof. By Lemma 6.11, we may assume that $X$ is nondegenerate. Choose a point $x \in$ int $X$ and a symplectic divisor $D$ through $x$. Let $J \in \mathcal{J}(X, D)$ be an almost complex structure on $\hat{X}$ and consider the bar complex $\mathcal{B}(C C(X)[-1])$, computed with respect to $J$. Suppose that $a>0$ is such that the augmentation map

$$
\epsilon_{k}: H\left(\mathcal{A}^{\leq a} \mathcal{B}^{\leq \ell}(C C(X)[-1])\right) \longrightarrow \mathbb{Q}
$$

is nonzero. By Theorem 6.34, it is enough to show that there exists a word of Reeb orbits $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$ such that

$$
p \leq \ell, \quad \mathcal{A}(\Gamma) \leq a, \quad \overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle \neq \varnothing
$$

Choose a homology class $\beta \in H\left(\mathcal{A}^{\leq a} \mathcal{B}^{\leq \ell}(C C(X)[-1])\right)$ such that $\epsilon_{k}(\beta) \neq 0$. The element $\beta$ can be written as a finite linear combination of Reeb orbits $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$, where every word has length $p \leq \ell$ and action $\mathcal{A}(\Gamma) \leq a$. One of the words in this linear combination, say $\Gamma=\left(\gamma_{1}, \ldots, \gamma_{p}\right)$, is such that $\#^{\operatorname{vir}} \overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle \neq 0$. By assumption on the virtual perturbation scheme, $\overline{\mathcal{M}}_{X}^{J}(\Gamma)\left\langle\mathcal{T}^{(k)} x\right\rangle$ is nonempty.

Theorem 7.64. If $X$ is a Liouville domain such that $\pi_{1}(X)=0$ and $2 c_{1}(T X)=0$ then

$$
\mathfrak{g}_{k}^{\leq 1}(X)=c_{k}^{\mathrm{GH}}(X)
$$

Proof. By Lemma 6.11, we may assume that $X$ is nondegenerate. Let $E=E\left(a_{1}, \ldots, a_{n}\right)$ be an ellipsoid as in Section 7.7 such that there exists a strict exact symplectic embedding $\phi: E \longrightarrow X$. In [BO16], Bourgeois-Oancea define an isomorphism between linearized contact homology and positive $S^{1}$-equivariant contact homology, which we will denote by $\Phi_{\text {BO }}$. This isomorphism commutes with the Viterbo transfer maps and respects the action filtration. In addition, the Viterbo transfer maps in linearized contact homology commute with the augmentation maps of Definition 7.16. Therefore, there is a commutative diagram


Here, the map $\epsilon_{k}^{E}$ is nonzero, or equivalently an isomorphism, by Theorem 7.62. Then,

$$
\begin{aligned}
c_{k}^{\mathrm{GH}}(X) & =\inf \left\{a>0 \mid \phi_{!}^{S^{1}} \circ \iota^{S^{1}, a} \neq 0\right\} & & \\
& =\inf \left\{a>0 \mid \epsilon_{k}^{X} \circ \iota^{a} \neq 0\right\} & & {[\text { since the diagram commutes }] } \\
& =\mathfrak{g}_{k}^{\leq 1}(X) & & {[\text { by Definition } 7.17] . }
\end{aligned}
$$

Theorem 7.65. Under Assumption 7.1, if $X_{\Omega}$ is a convex or concave toric domain then

$$
c_{L}\left(X_{\Omega}\right)=\delta_{\Omega}
$$

Proof. Since $X_{\Omega}$ is concave or convex, we have $X_{\Omega} \subset N\left(\delta_{\Omega}\right)$. For every $k \in \mathbb{Z}_{\geq 1}$,

$$
\begin{aligned}
\delta_{\Omega} & \leq c_{P}\left(X_{\Omega}\right) & & {[\text { by Lemma } 6.20] } \\
& \leq c_{L}\left(X_{\Omega}\right) & & {[\text { by Lemma } 6.19] } \\
& \leq \frac{\tilde{\mathfrak{g}}_{k}^{\leq 1}\left(X_{\Omega}\right)}{k} & & {[\text { by Theorem } 6.40] } \\
& \leq \frac{\mathfrak{g}_{k}^{1}\left(X_{\Omega}\right)}{k} & & {[\text { by Theorem } 7.63] } \\
& =\frac{c_{k}^{G H}\left(X_{\Omega}\right)}{k} & & {[\text { by Theorem } 7.64] } \\
& \leq \frac{c_{k}^{\mathrm{GH}}\left(N\left(\delta_{\Omega}\right)\right)}{k} & & {\left[\text { since } X_{\Omega} \subset N\left(\delta_{\Omega}\right)\right] } \\
& =\frac{\delta_{\Omega}(k+n-1)}{k} & & {[\text { by Lemma } 6.28] . }
\end{aligned}
$$

The result follows by taking the infimum over $k$.

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[^0]:    ${ }^{1}$ To be precise, the definition we give may be slightly different from the one given in [Sie20]. This is due to the fact that we use an action filtration to define $\mathfrak{g}_{k}^{\leq \ell}(X)$, while the definition given in [Sie20] uses coefficients in a Novikov ring. See Remark 7.18 for further discussion.

[^1]:    ${ }^{2}$ Strictly speaking, the cylinder is noncompact, so it is not a toric domain. We will mostly ignore this small discrepancy in nomenclature, but sometimes we will refer to spaces like the cylinder as "noncompact toric domains".
    ${ }^{3}$ In this introduction, we will be showcasing many results from the main text. The theorems appear here as they do on the main text, in particular with the same numbering. The numbers of the theorems in the introduction have hyperlinks to their corresponding location in the main text.

