

A VARIATIONAL APPROACH TO GIVENTAL'S NONLINEAR MASLOV INDEX

PETER ALBERS AND URS FRAUENFELDER

ABSTRACT. In this article we consider a variant of Rabinowitz Floer homology in order to define a homological count of discriminant points for paths of contactomorphisms. The growth rate of this count can be seen as an analogue of Givental's nonlinear Maslov index. As an application we prove a Bott-Samelson type obstruction theorem for positive loops of contactomorphisms.

1. INTRODUCTION

In [Giv89, Giv90a, Giv90b] Givental introduces his nonlinear Maslov index for the prequantization spaces $\mathbb{R}P^{2n-1}$. This concept had remarkable applications to symplectic topology, for instance concerning the orderability of contact manifolds, see [EP00], the existence of Calabi quasimorphisms, see [EP03, BS07], and existence of Legendrian chords.

Let $(\Sigma, \xi = \ker \alpha)$ be a cooriented contact manifold. Givental's nonlinear Maslov index is formally defined as the intersection number of a path of contactomorphisms with the discriminant

$$\{\varphi \in \text{Cont}(\Sigma, \xi) \mid \exists x \in \Sigma \text{ such that } \varphi(x) = x \text{ and } \varphi^* \alpha|_x = \alpha|_x\}. \quad (1.1)$$

Unfortunately, the discriminant has codimension-1 singularities, see [Giv90b]. For $\Sigma = \mathbb{R}P^{2n-1}$ Givental resolves this problem by constructing the tail or train which is a subset of the discriminant and defines an cooriented codimension-1 cycle. The nonlinear Maslov index on $\mathbb{R}P^{2n-1}$ is then the intersection number with this cycle.

It seems very difficult to extend Givental's constructions to other contact manifolds. Givental already suggested to use Floer theoretic methods in the general case. In this article we define a homological count of discriminant points for *positive* paths of contactomorphisms, see Definition 2.1. For this we use a variant of Rabinowitz Floer homology which gives us a variational characterization of the discriminant. For this we require that the contact manifold is symplectically fillable and, as examples show, our homological intersection number depends on the filling.

Using this homological intersection number we define a growth rate for positive paths of contactomorphisms. For unit cotangent bundles this is related to growth rates of geodesics. We refer to [Pat99] for the latter. As an application we prove the following theorem.

Theorem 1.1. *Let B be a closed manifold with finite fundamental group such that the rational cohomology ring has at least two generators. Then $\Sigma := S^*B$ with its standard contact structure ξ admits no closed positive loops in $\text{Cont}(\Sigma, \xi)$.*

This can be thought of as a generalization of the classical Bott-Samelson theorem to positive loops of contactomorphisms.

Key words and phrases. nonlinear Maslov index, discriminant points, Rabinowitz Floer homology.

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2. POSITIVE CONTACT ISOTOPIES

Let (Σ, ξ) be a cooriented, strongly fillable contact manifold. We fix a contact form α for ξ .

Definition 2.1. A smooth path $\{\varphi_t\}_{t \in \mathbb{R}}$ in $\text{Cont}(\Sigma)$ based at the identity is called positive resp. twisted periodic if the function $h_t : \Sigma \rightarrow \mathbb{R}$ defined by

$$h_t(\varphi_t(x)) := \alpha_{\varphi_t(x)}\left(\frac{d}{dt}\varphi_t(x)\right) \quad (2.1)$$

is positive resp. 1-periodic. We set

$$\mathcal{P} \equiv \mathcal{P}(\Sigma, \xi) := \{\{\varphi_t\}_{t \in \mathbb{R}} \mid \{\varphi_t\}_{t \in \mathbb{R}} \text{ is positive and twisted periodic}\}. \quad (2.2)$$

Remark 2.2. The above definition is independent of the chosen contact form as long as it defines the same coorientation. Moreover, φ_t is twisted periodic if and only if $\varphi_{t+1} = \varphi_t \varphi_1$ for all $t \in \mathbb{R}$. In particular, a twisted periodic path satisfies $\varphi_1^m = \varphi_m$ for all $m \in \mathbb{Z}$.

We denote by $(S\Sigma := \Sigma \times \mathbb{R}_{>0}, \omega := d(r\alpha))$, $r \in \mathbb{R}_{\geq 0}$, the symplectization of Σ .

Proposition 2.3. *The contact isotopy φ_t admits a lift to a Hamiltonian isotopy ϕ_t of $S\Sigma$ as follows:*

$$\phi_t(x, r) := \left(\varphi_t(x), \frac{r}{\rho_t(x)}\right) : S\Sigma \rightarrow S\Sigma \quad (2.3)$$

where $\rho_t(x) : \Sigma \rightarrow \mathbb{R}_{>0}$ is defined by $\varphi_t^* \alpha|_x = \rho_t(x) \alpha|_x$. Moreover, ϕ_t is generated by the Hamiltonian function $H_t : S\Sigma \rightarrow \mathbb{R}$ given by

$$H_t(x, r) = r h_t(x). \quad (2.4)$$

The proof of Proposition 2.3 can be found after Remark 2.6.

Definition 2.4. The function $H_t : S\Sigma \rightarrow \mathbb{R}$ is called the contact Hamiltonian associated to $\{\varphi_t\}$.

Following Givental [Giv89, Giv90a, Giv90b] we make the following definition.

Definition 2.5. Let $\{\varphi_t\}$ be a smooth path in $\text{Cont}(\Sigma)$. Then a pair $(x, \eta) \in \Sigma \times \mathbb{R}$ is called a discriminant point (with respect to $\{\varphi_t\}$) if

$$\begin{cases} \varphi_\eta(x) = x \\ \varphi_\eta^* \alpha|_x = \alpha|_x \end{cases} \quad (2.5)$$

Remark 2.6. We point out that for a pair (x, η) being a discriminant point is equivalent to $\phi_\eta(x, r) = (x, r)$ for any $r > 0$, see Proposition 2.3.

Proof of Proposition 2.3. We prove the stronger fact that ϕ_t preserves the 1-form $r\alpha$:

$$\phi_t^*(r\alpha)|_{(x,r)} = \frac{r}{\rho_t(x)} \cdot \varphi_t^*\alpha|_x = r\alpha|_x . \quad (2.6)$$

We set

$$Y_t(\varphi_t(x)) := \frac{d}{dt}\varphi_t(x) \quad (2.7)$$

and compute

$$\begin{aligned} X_t(\phi_t(x, r)) &:= \frac{d}{dt}\phi_t(x, r) \\ &= Y_t(\varphi_t(x)) - r \frac{\dot{\rho}_t(x)}{\rho_t^2(x)} \frac{\partial}{\partial r} . \end{aligned} \quad (2.8)$$

Since ϕ_t preserves $\lambda := r\alpha$ we use Lemma 2.7 and compute

$$H_t = \lambda(X_t) = r\alpha(Y_t) = rh_t . \quad (2.9)$$

□

Lemma 2.7. Let $\omega = d\lambda$ be an exact symplectic form and X a vector field satisfying

$$\mathcal{L}_X\lambda = 0 \quad (2.10)$$

where \mathcal{L} is the Lie derivative. Then the Hamiltonian vector field X_H of the function $H := \lambda(X)$ equals X :

$$X_H = X . \quad (2.11)$$

PROOF. From $H = i_X\lambda$ we compute using Cartan's formula

$$\begin{aligned} dH &= d(i_X\lambda) \\ &= \mathcal{L}_X\lambda - i_Xd\lambda \\ &= -i_X\omega . \end{aligned} \quad (2.12)$$

□

Remark 2.8. In particular, we have the equality

$$\lambda(X_H) = H. \quad (2.13)$$

3. THE RABINOWITZ ACTION FUNCTIONAL FOR TIME-DEPENDENT HAMILTONIANS AND A VARIATIONAL APPROACH TO DISCRIMINANT POINTS

Let $(M, \omega = d\lambda)$ be an exact symplectic manifold and $F : M \times \mathbb{R} \rightarrow \mathbb{R}$ a smooth function. We denote by $\mathcal{L} := W^{1,2}(\mathbb{R}/\mathbb{Z}, M)$ the free loop space of M and define the Rabinowitz action functional

$$\begin{aligned} \mathcal{A} : \mathcal{L} \times \mathbb{R} &\longrightarrow \mathbb{R} \\ (u, \eta) &\mapsto \mathcal{A}(u, \eta) = \int_0^1 u^*\lambda - \eta \int_0^1 F_{\eta t}(u(t))dt . \end{aligned} \quad (3.1)$$

Its critical points $(u, \eta) \in \text{Crit}\mathcal{A}$ satisfy

$$\left. \begin{aligned} \dot{u}(t) &= \eta X_{F_{\eta t}}(u(t)) \\ \int_0^1 [F_{\eta t}(u(t)) + \eta t \dot{F}_{\eta t}(u(t))] dt &= 0 \end{aligned} \right\} \quad (3.2)$$

By the first equation we have

$$\begin{aligned}
\frac{d}{dt}F_{\eta t}(u(t)) &= \eta\dot{F}_{\eta t}(u(t)) + dF_{\eta t}(u(t))[u(t)] \\
&= \eta\dot{F}_{\eta t}(u(t)) + dF_{\eta t}(u(t))[\eta X_{F_{\eta t}}(u(t))] \\
&= \eta\dot{F}_{\eta t}(u(t)) - \underbrace{\omega\left(X_{F_{\eta t}}(u(t)), \eta X_{F_{\eta t}}(u(t))\right)}_{=0}
\end{aligned} \tag{3.3}$$

Thus, the second equation becomes after integration by parts

$$\begin{aligned}
0 &= \int_0^1 \left[F_{\eta t}(u(t)) + \eta t \dot{F}_{\eta t}(u(t)) \right] dt \\
&= \int_0^1 \left[F_{\eta t}(u(t)) + t \frac{d}{dt} F_{\eta t}(u(t)) \right] dt \\
&= \int_0^1 \underbrace{\left[F_{\eta t}(u(t)) - \left(\frac{d}{dt} t \right) F_{\eta t}(u(t)) \right]}_{=0} dt + t F_{\eta t}(u(t)) \Big|_0^1 \\
&= F_{\eta}(u(1)) .
\end{aligned} \tag{3.4}$$

Thus, we proved the following lemma.

Lemma 3.1. A pair $(u, \eta) \in \mathcal{L} \times \mathbb{R}$ is a critical point of \mathcal{A} if and only if the following equations hold

$$\left. \begin{aligned} \dot{u}(t) &= \eta X_{F_{\eta t}}(u(t)) \\ F_{\eta}(u(1)) &= 0 \end{aligned} \right\} \tag{3.5}$$

Lemma 3.2. If the function F_t satisfies

$$\lambda(X_{F_t}) = F_t + \kappa \tag{3.6}$$

for some $\kappa \in \mathbb{R}$ then

$$\mathcal{A}(u, \eta) = \kappa\eta \quad \forall (u, \eta) \in \text{Crit}\mathcal{A} . \tag{3.7}$$

PROOF. Using the critical point equation for \mathcal{A} we see

$$\begin{aligned}
\mathcal{A}(u, \eta) &= \int_0^1 \lambda[\eta X_{F_{\eta t}}(u(t))] dt - \eta \int_0^1 F_{\eta t}(u(t)) dt \\
&= \int_0^1 \eta F_{\eta t}(u(t)) dt + \kappa\eta - \eta \int_0^1 F_{\eta t}(u(t)) dt \\
&= \kappa\eta .
\end{aligned} \tag{3.8}$$

□

Remark 3.3. If $F_t = rh_t(x) - \kappa$ where rh_t is the contact Hamiltonian of a positive and twisted periodic path $\{\varphi_t\} \in \mathcal{P}$ then discriminant points are in 1-1 correspondence with critical points of $\mathcal{A}_{\kappa} := \frac{1}{\kappa}\mathcal{A}$, see Proposition 2.3 and Lemma 3.1.

4. A HOMOLOGICAL MASLOV INDEX (PERIODIC CASE)

Let (Σ, ξ) be a closed, cooriented contact manifold and α a fixed contact form. We assume that there exists a compact exact symplectic manifold $(\widetilde{M}, d\widetilde{\lambda})$ with $\Sigma = \partial\widetilde{M}$ and $\alpha = \lambda|_{\Sigma}$. We attach to \widetilde{M} the positive part of the symplectization of Σ , that is,

$$M := \widetilde{M} \cup_{\Sigma} \Sigma \times \{r \geq 1\}. \quad (4.1)$$

On M we define a 1-form λ by $\widetilde{\lambda}$ on \widetilde{M} and $\lambda = r\alpha$ on $\Sigma \times \{r \geq 1\}$. In particular, $(M, \omega = d\lambda)$ is an exact symplectic manifold. We point out, that the entire symplectization $S\Sigma$ of Σ embeds into M via the flow of the Liouville vector field of λ .

Convention 4.1. In the following we only consider positive and twisted periodic path, i.e. $\{\varphi_t\} \in \mathcal{P}(\Sigma, \xi)$, see Definition 2.1.

We fix $R, \kappa > 1$ and choose a smooth function $\beta_R : \mathbb{R}_{\geq 0} \rightarrow [0, 1]$ satisfying

$$\beta_R(r) = \begin{cases} 0 & r \leq 1 \\ 1 & 2 \leq r \leq R\kappa \\ 0 & r \geq R\kappa + 1 \end{cases} \quad (4.2)$$

and

$$\begin{cases} 0 \leq \beta'_R(r) \leq 2 & 1 \leq r \leq 2 \\ -2 \leq \beta'_R(r) \leq 0 & R\kappa \leq r \leq R\kappa + 1 \end{cases} \quad (4.3)$$

Moreover, we define

$$\mathfrak{h}(r) = \begin{cases} m & r \leq 2 \\ M & r > 2 \end{cases} \quad (4.4)$$

where

$$0 < m \leq \min\{h_t(x) \mid x \in \Sigma, t \in \mathbb{R}\} \quad (4.5)$$

and

$$M \geq \max\{h_t(x) \mid x \in \Sigma, t \in \mathbb{R}\}. \quad (4.6)$$

m and M are well-defined since h_t is 1-periodic. We set

$$F_t^{\kappa, R}(z) := \begin{cases} r[\beta_R(r)h_t(x) + (1 - \beta_R(r))\mathfrak{h}(r)] - \kappa & z = (x, r) \in S\Sigma \\ -\kappa & z \in M \setminus S\Sigma \end{cases} \quad (4.7)$$

and consider the normalized Rabinowitz action functional

$$\mathcal{A}_{\kappa, R} : \mathcal{L} \times \mathbb{R} \longrightarrow \mathbb{R} \\ (u, \eta) \mapsto \mathcal{A}_{\kappa, R}(u, \eta) = \frac{1}{\kappa} \left(\int_0^1 u^* \lambda - \eta \int_0^1 F_{\eta t}^{\kappa, R}(u(t)) dt \right). \quad (4.8)$$

Obviously, the critical point equation does not change if we divide by κ , thus $(u, \eta) \in \text{Crit}\mathcal{A}_{\kappa, R}$ if and only if

$$\left. \begin{aligned} \dot{u}(t) &= \eta X_{F_{\eta t}^{\kappa, R}}(u(t)) \\ F_{\eta}^{\kappa, R}(u(1)) &= 0 \end{aligned} \right\} \quad (4.9)$$

A glimpse at Lemma 3.2 reveals the reason why we divide by κ .

Lemma 4.2. Let $(u, \eta) \in \text{Crit}\mathcal{A}_{\kappa, R}$ be a critical point. Then

$$|\mathcal{A}_{\kappa, R}(u, \eta)| \geq |\eta|. \quad (4.10)$$

PROOF. We compute

$$\begin{aligned} \lambda(X_{F_{\eta t}^{\kappa, R}}) &= dF_{\eta t}^{\kappa, R}\left(r \frac{\partial}{\partial r}\right) \\ &= F_{\eta t}^{\kappa, R} + \kappa + r^2 \beta'_R(r) [h_{\eta t}(x) - \mathfrak{h}(r)]. \end{aligned} \quad (4.11)$$

We point out that

$$\beta'_R(r) [h_{\eta t}(x) - \mathfrak{h}(r)] \geq 0 \quad (4.12)$$

holds, see (4.2) and (4.3). We estimate

$$\begin{aligned} |\mathcal{A}_{\kappa, R}(u, \eta)| &= \frac{1}{\kappa} \left| \int_0^1 \lambda(\eta X_{F_{\eta t}^{\kappa, R}}(u)) - \eta \int_0^1 F_{\eta t}^{\kappa, R}(u) dt \right| \\ &= \frac{|\eta|}{\kappa} \left| \int_0^1 \left[F_{\eta t}^{\kappa, R}(u) + \kappa + r^2 \beta'_R(r) [h_{\eta t}(x) - \mathfrak{h}(r)] - F_{\eta t}^{\kappa, R}(u) \right] dt \right| \\ &= \frac{|\eta|}{\kappa} \left| \kappa + \int_0^1 \underbrace{r^2 \beta'_R(r) [h_{\eta t}(x) - \mathfrak{h}(r)]}_{\geq 0} dt \right| \\ &\geq |\eta|. \end{aligned} \quad (4.13)$$

This finishes the proof. \square

Proposition 4.3. Given $a < b$ there exists $\kappa_0 = \kappa_0(a, b) > 0$ and $R_0 = R_0(a, b) \geq 0$ such that for all $\kappa \geq \kappa_0$ and $R \geq R_0$ the following holds. Let $(u, \eta) \in \text{Crit}\mathcal{A}_{\kappa, R}$ be a critical point with critical value between a and b

$$a < \mathcal{A}_{\kappa, R}(u, \eta) < b \quad (4.14)$$

then $u(t) = (x(t), r(t)) \in \Sigma \times (2, R\kappa)$ for all $t \in S^1$ and $\mathcal{A}_{\kappa, R}(u, \eta) = \eta$.

PROOF. By Lemma 4.2 we have

$$|\eta| \leq \max\{|a|, |b|\}. \quad (4.15)$$

We set

$$C \equiv C(a, b) := \max \left\{ \left| \eta \cdot \frac{\dot{\rho}_{\eta t}(x(t))}{\rho_{\eta t}^2(x(t))} \right| : x \in \Sigma, t \in [0, 1], |\eta| \leq \max\{|a|, |b|\} \right\}. \quad (4.16)$$

We fix $\kappa_0 > \max\{1, 3Me^C\}$, $R_0 > \max\left\{\frac{1}{m}e^C + 1, \frac{1}{M}\right\}$ and choose $\kappa \geq \kappa_0$ and $R \geq R_0$.

Step 1: $u(1) = (x(1), r(1)) \in \Sigma \times [2, R\kappa]$ and $r(1)h_{\eta}(x(1)) = \kappa$.

Proof of Step 1. We examine three cases.

Case 1: $u(1) \notin \Sigma \times [1, R\kappa + 1]$.

We first observe that if $u(1) \notin S\Sigma$ then $F_{\eta}^{\kappa, R}(u(1)) = -\kappa < 0$. Therefore, the critical point equation implies $u(1) = (x(1), r(1)) \in S\Sigma$. Since $r(1) \notin [1, R\kappa + 1]$ we have $\beta_R(r(1)) = 0$ and therefore

$$0 = F_{\eta}^{\kappa, R}(u(1)) = r(1)\mathfrak{h}(r(1)) - \kappa. \quad (4.17)$$

So either $r(1) \leq 1$ and $\kappa = r(1)m \leq m$ or $r(1) \geq R\kappa + 1$ and $\kappa = r(1)M \geq RM\kappa + M$. The former contradicts the assumption $\kappa \geq \kappa_0 > 3Me^C > m$ and the latter contradicts the assumption $RM > 1$.

Case 2: $1 \leq r(1) \leq 2$.

For simplicity we write $r = r(1)$ and $x = x(1)$. Using $M \geq h_\eta(x) \geq \mathfrak{h}(r) = m$ and $0 \leq \beta_R(r) \leq 1$ we estimate using the critical point equation

$$\begin{aligned} \kappa &= r[\beta_R(r)h_\eta(x) + (1 - \beta_R(r))\mathfrak{h}(r)] \\ &= r[\beta_R(r)(h_\eta(x) - \mathfrak{h}(r)) + \mathfrak{h}(r)] \\ &\leq r[(h_\eta(x) - \mathfrak{h}(r)) + \mathfrak{h}(r)] \\ &\leq rh_\eta(x) \\ &\leq rM \\ &\leq 2M \end{aligned} \tag{4.18}$$

This contradicts $\kappa_0 > 3Me^C > 2M$.

Case 3: $R\kappa \leq r(1) \leq R\kappa + 1$.

Again for simplicity we write $r = r(1)$ and $x = x(1)$. Using that $h_\eta(x) \leq \mathfrak{h}(r)$ and $\beta(r) \geq 0$ we estimate

$$\begin{aligned} \kappa &= r[\beta_R(r)(h_\eta(x) - \mathfrak{h}(r)) + \mathfrak{h}(r)] \\ &\geq r[(h_\eta(x) - \mathfrak{h}(r)) + \mathfrak{h}(r)] \\ &= rh_\eta(x) \\ &\geq R\kappa m . \end{aligned} \tag{4.19}$$

This contradicts the assumption $RM \geq Rm > 1$.

From the three cases we conclude that $2 \leq r(1) \leq R\kappa$. The definition of β_R and the critical point equation (see Lemma 3.1) imply

$$0 = F_\eta^{\kappa, R}(u(1)) = r(1)h_\eta(x(1)) - \kappa . \tag{4.20}$$

This proves Step 1. □

Step 2: $u(t) = (x(t), r(t)) \in \Sigma \times (2, R\kappa)$ for all $t \in S^1$.

Proof of Step 2. We set

$$I := \{t \in [0, 1] \mid u(t) \in \Sigma \times (2, R\kappa)\} \tag{4.21}$$

By Step 1 we have

$$\frac{\kappa}{M} \leq r(0) = r(1) = \frac{\kappa}{h_\eta(x(1))} \leq \frac{\kappa}{m} . \tag{4.22}$$

Then since $R \geq R_0 \geq \frac{1}{m}e^C + 1 \geq \frac{1}{m} + 1$ and $\kappa \geq \kappa_0 \geq 1$ we see

$$\frac{\kappa}{m} \leq (R - 1)\kappa \leq R\kappa - 1 . \tag{4.23}$$

Moreover, since $\kappa \geq \kappa_0 \geq 3Me^C \geq 3M$ we have

$$3 \leq r(0) = r(1) \leq R\kappa - 1 . \tag{4.24}$$

Thus, $0 \in I \neq \emptyset$. We denote by I_0 the connected component of I containing 0.

Claim: If $t \in I_0$ then $3 \leq r(t) \leq R\kappa - 1$.

Proof of the Claim. As long as $u(t) = (x(t), r(t)) \in \Sigma \times [2, R\kappa]$ the function $r(t)$ satisfies

$$\dot{r}(t) = -\eta r(t) \frac{\dot{\rho}_{\eta t}(x(t))}{\rho_{\eta t}^2(x(t))}, \quad (4.25)$$

see (2.8) together with the critical point equation. Thus, for $t \in I_0$ we can estimate

$$r(0)e^{-C} \leq r(t) \leq r(0)e^C \quad (4.26)$$

where $C \equiv C(a, b)$ is defined in (4.16). By Step 1 we have $\frac{\kappa}{M} \leq r(0) = r(1) \leq \frac{\kappa}{m}$ and we obtain

$$\frac{\kappa}{M}e^{-C} \leq r(t) \leq \frac{\kappa}{m}e^C. \quad (4.27)$$

Since $\kappa \geq \kappa_0 \geq 3Me^C$ we see

$$r(t) \geq 3. \quad (4.28)$$

Since $R \geq R_0 \geq \frac{1}{m}e^C + 1$ and $\kappa \geq \kappa_0 \geq 1$ we have

$$\begin{aligned} r(t) &\leq \kappa \frac{1}{m}e^C \\ &\leq \kappa(R - 1) \\ &\leq \kappa R - 1. \end{aligned} \quad (4.29)$$

This proves the claim. \square

By definition I_0 is open. By the Claim it is also closed. Since $I_0 \neq \emptyset$ we conclude $I_0 = I = [0, 1]$. This proves Step 2. \square

Since on $\Sigma \times (2, R\kappa - 1)$ we have $F_t^{\kappa, R}(u) = rh_t(x) - \kappa$. Thus, we get

$$\lambda(X_{F_t^{\kappa, R}}) = F_t^{\kappa, R} + \kappa. \quad (4.30)$$

Therefore, Lemma 3.2 implies

$$\mathcal{A}_{\kappa, R}(u, \eta) = \eta \quad (4.31)$$

for all critical points contained in $\Sigma \times (2, R\kappa - 1)$. This finishes the proof of the Proposition. \square

Corollary 4.4. *We fix $a < b$. If $\kappa \geq \kappa_0$ and $R \geq R_0$ where κ_0 and R_0 are the constants in Proposition 4.3 then the critical point equation and the critical value for critical points of $\mathcal{A}_{\kappa, R}$ with action values $a < \mathcal{A}_{\kappa, R} < b$ are independent of κ and R . Moreover, they are critical points of \mathcal{A} and thus correspond to discriminant points, see Remark 3.3.*

PROOF. From Proposition 4.3 we know that critical points with action values $a < \mathcal{A}_{\kappa, R} < b$ are contained in $\Sigma \times (2, R\kappa - 1)$. On $\Sigma \times (2, R\kappa - 1)$ we have $F_t^{\kappa, R}(u) = rh_t(x) - \kappa$. Thus, $F_t^{\kappa, R}(u)$ is independent of R . Therefore, the critical point equation is independent (up to a κ -shift in the r -direction of the symplectization). The critical value is independent of κ due to the normalization, see (4.8). Remark 3.3 implies the statement about critical points of \mathcal{A} and discriminant points. \square

We choose an almost complex structure J which on $\Sigma \times [1, \infty)$ is of SFT-type, see [CFO09]. We define for $\kappa > 0$ the L^2 -metric \mathbf{m}^κ on $\mathcal{L} \times \mathbb{R}$ by

$$\mathbf{m}_{(z,\eta)}^\kappa((\xi, l), (\xi', l')) := \frac{1}{\kappa} \int_0^1 \omega_{(z,\eta)}(\xi, J\xi') dt + \frac{ll'}{\kappa}. \quad (4.32)$$

Then the gradient of $\mathcal{A}_{\kappa,R}$ at $(u, \eta) \in \mathcal{L} \times \mathbb{R}$ equals

$$\nabla^\kappa \mathcal{A}_{\kappa,R}(u, \eta) = \left(\begin{array}{c} \dot{u}(t) - \eta X_{F_{\eta t}^{\kappa,R}}(u(t)) \\ \int_0^1 [F_{\eta t}^{\kappa,R}(u(t)) + \eta t \dot{F}_{\eta t}^{\kappa,R}(u(t))] dt \end{array} \right) \quad (4.33)$$

and its norm

$$\|\nabla^\kappa \mathcal{A}_{\kappa,R}(u, \eta)\|_\kappa^2 = \frac{1}{\kappa} \|\dot{u}(t) - \eta X_{F_{\eta t}^{\kappa,R}}(u(t))\|_2^2 + \frac{1}{\kappa} \left(\int_0^1 [F_{\eta t}^{\kappa,R}(u(t)) + \eta t \dot{F}_{\eta t}^{\kappa,R}(u(t))] dt \right)^2. \quad (4.34)$$

Lemma 4.2 asserts that at critical points the Lagrange multiplier η is bounded by the action. This continues to hold for almost critical points.

Lemma 4.5 (Fundamental Lemma). There exists $\epsilon > 0$ such that for all $w = (u, \eta) \in \mathcal{L} \times \mathbb{R}$ we have

$$\|\mathcal{A}_{\kappa,R}(w)\|_\kappa < \epsilon \implies |\eta| \leq \frac{1}{\epsilon} (\mathcal{A}_{\kappa,R}(w) + 1). \quad (4.35)$$

PROOF. The follows by a standard scheme, see [CF09]. \square

We point out that for r sufficiently large the Hamiltonian function equals $F_t^{\kappa,R}(x, r) = Mr - \kappa$. Thus, we can apply the techniques from [CFO09] to obtain L^∞ -bounds for the r -coordinate of solutions of the Rabinowitz-Floer equation. L^∞ -bounds for the Lagrange multiplier follow again by a standard scheme from the Fundamental Lemma 4.5. Finally, there is no bubbling-off of holomorphic spheres since the symplectic manifold M was assumed to be exact.

We recall, see Remark 3.3, that a positive and twisted periodic path $\{\varphi_t\}$ of contactomorphisms defines a Rabinowitz action functional \mathcal{A} whose critical points are in 1-1 correspondence to discriminant points. Moreover, the choice of κ_0 and R_0 guarantee that the critical points of $\mathcal{A}_{\kappa,R}$ are exactly the critical points of \mathcal{A} .

Definition 4.6. We call a path $\{\varphi_t\} \in \mathcal{P}$ non-degenerate if the Rabinowitz action functional \mathcal{A} is Morse for one (and then any) κ .

Remark 4.7. Since positive and twisted periodic path are generated by time-dependent, 1-periodic functions it is straight forward to see that they are generically non-degenerate.

Theorem 4.8. *Let $\{\varphi_t\}$ be non-degenerate. Then for $a < b$ and $\kappa \geq \kappa_0(a, b)$, $R \geq R_0(a, b)$ Rabinowitz Floer homology $\text{RFH}_a^b(\mathcal{A}_{\kappa,R})$ is well-defined and independent of κ and R up to chain complex isomorphisms. For simplicity we use $\mathbb{Z}/2$ -coefficients.*

PROOF. By the previous remarks compactness up to breaking of gradient flow lines (in the sense of Floer) is guaranteed. Thus, $\text{RFH}_a^b(\mathcal{A}_{\kappa,R})$ is defined.

Since the critical points and values are independent of κ and R a continuation argument implies that $\text{RFH}_a^b(\mathcal{A}_{\kappa,R})$ is independent of κ and R up to chain complex isomorphisms. \square

Definition 4.9. Let $\{\varphi_t\}$ be non-degenerate. Then we define the filtered Rabinowitz Floer homology of $\{\varphi_t\}$ to be

$$\mathrm{RFH}_a^b(\{\varphi_t\}) := \mathrm{RFH}_a^b(\mathcal{A}_{\kappa,R}) \quad (4.36)$$

for some $\kappa \geq \kappa_0(a,b)$, $R \geq R_0(a,b)$.

Remark 4.10. We point out that $\mathrm{RFH}_a^b(\{\varphi_t\})$ possibly depends on the filling \widetilde{M} of Σ , see Section 5. Nevertheless, we suppress this in the notation.

Definition 4.11. A path $\{\varphi_t\} \in \mathcal{P}$ is non-resonant if $\mathcal{A}\kappa$ has no integer critical values for one (and then any) $\kappa > 0$, see Remark 3.3. Then for $n, m \in \mathbb{Z}$ we define

$$\mathrm{RFH}_n^m(\{\varphi_t\}) \quad (4.37)$$

using a sufficiently small perturbation of $\{\varphi_t\}$ which is non-degenerate.

Remark 4.12. $\mathrm{RFH}_n^m(\{\varphi_t\})$ is well-defined for non-resonant $\{\varphi_t\}$ since any sufficiently small perturbation is non-resonant and non-degenerate. Moreover, during a sufficiently small perturbation no critical values crosses an integer.

The same reasoning implies the following Theorem.

Theorem 4.13. *Let $I \subset \mathbb{R}$ be some interval and $\{\varphi_{t,s}\}_{t \in \mathbb{R}, s \in I}$ be a smooth family of contactomorphisms such that for all fixed $\sigma \in I$ the path $\{\varphi_{t,\sigma}\} \in \mathcal{P}$ is non-resonant. Then*

$$\mathrm{RFH}_n^m(\{\varphi_{t,\sigma}\}) \cong \mathrm{RFH}_n^m(\{\varphi_{t,0}\}) \quad \forall \sigma \in I \quad (4.38)$$

up to canonical isomorphism.

Definition 4.14. We define the set of positive contactomorphisms by

$$\mathrm{Cont}_0^+(\Sigma) := \{\varphi \in \mathrm{Cont}_0(\Sigma) \mid \exists \{\varphi_t\} \in \mathcal{P} \text{ with } \varphi_1 = \varphi\} \quad (4.39)$$

and define

$$\{\varphi_t^0\} \sim \{\varphi_t^1\} \quad (4.40)$$

if there exists a smooth family $\{\varphi_{t,s}\}_{s,t \in [0,1]}$ with $\{\varphi_{t,\sigma}\} \in \mathcal{P}$ for all $\sigma \in [0,1]$ and $\varphi_{t,0} = \varphi_t^0$ and $\varphi_{t,1} = \varphi_t^1$ for all $t \in [0,1]$.

Then the universal cover $\widetilde{\mathrm{Cont}}_0^+(\Sigma)$ is given by \sim -equivalence classes of paths in Cont_0^+ based at the identity.

For call $\varphi \in \widetilde{\mathrm{Cont}}_0^+(\Sigma)$ non-resonant if one representative (and hence all representatives) are non-resonant.

Remark 4.15. By [EP00, Lemma 3.1.A] $\varphi \in \mathrm{Cont}_0^+$ if and only if the identity can be joint to φ through a positive segment $\{\varphi_t\}_{t \in [0,1]}$ whose generating vector field need not be periodic.

We point out that $\mathrm{Cont}_0(\Sigma)$ acts on $\mathrm{Cont}_0^+(\Sigma)$ by conjugation. Indeed, if $\{\varphi_t\}$ is a positive path with contact Hamiltonian h_t and $\psi \in \mathrm{Cont}_0$ then $\{\psi\varphi_t\psi^{-1}\}$ has contact Hamiltonian $(f h_t) \circ \psi^{-1}$ where the positive function f is defined by $\psi^* \alpha = f \alpha$.

Moreover, discriminant points of $\{\varphi_t\}$ are in 1-1 correspondence with discriminant points of $\{\psi\varphi_t\psi^{-1}\}$ via the map $(x, \eta) \mapsto (\psi(x), \eta)$. In particular, $\{\varphi_t\}$ is non-resonant if and only if $\{\psi\varphi_t\psi^{-1}\}$ is non-resonant.

The induced action of ψ on $\widetilde{\mathrm{Cont}}_0^+(\Sigma)$ is denoted by \mathfrak{C}_ψ .

Definition 4.16. Let $\varphi \in \widetilde{\text{Cont}}_0^+(\Sigma)$ be non-resonant. We define for integers $n, m \in \mathbb{Z}$

$$\text{RFH}_n^m(\varphi) := \text{RFH}_n^m(\{\varphi_t\}) \quad (4.41)$$

where $\{\varphi_t\}$ a representative of φ .

Theorem 4.13 has the following two important corollaries.

Corollary 4.17. *Let $\varphi \in \widetilde{\text{Cont}}_0^+(\Sigma)$ be non-resonant then $\text{RFH}_n^m(\varphi)$ is well-defined, i.e. independent of the choice of representative.*

Corollary 4.18. *Let $\varphi \in \widetilde{\text{Cont}}_0^+(\Sigma)$ be non-resonant and let $\psi \in \text{Cont}_0(\Sigma)$. Then for integers $n < m \in \mathbb{Z}$*

$$\text{RFH}_n^m(\mathfrak{C}_\psi(\varphi)) \cong \text{RFH}_n^m(\varphi). \quad (4.42)$$

where we recall that $\mathfrak{C}_\psi(\varphi)$ is φ conjugated by ψ .

PROOF. Let ψ_s be an isotopy connecting the identity and ψ . Then we can apply Theorem 4.13 to $\varphi_{t,s} := \psi_s \varphi_t \psi_s^{-1}$, see Remark 4.15. \square

5. DIFFEOMORPHISMS OF THE CIRCLE

We consider $\Sigma = S^1 := \mathbb{R}/\mathbb{Z}$ with contact form dx . Let $a \in \mathbb{R} \setminus \mathbb{Q}$ be an irrational and positive number. Then the maps $\varphi : S^1 \rightarrow S^1$ defined by

$$\varphi_t(x) := x + at \quad (5.1)$$

is a positive and twisted period contact isotopy which is non-resonant. A pair $(x, \eta) \in S^1 \times \mathbb{R}$ is a discriminant point if and only if $\eta a \in \mathbb{Z}$. Although $\{\varphi_t\}$ is not non-degenerate it is of Morse-Bott type. Hence we can define Rabinowitz Floer homology once we choose a filling. We consider two fillings of S^1 .

First, we fill S^1 by the standard disk. In that case S^1 is Hamiltonianly displaceable in the symplectically filled symplectization and thus Rabinowitz Floer homology vanishes. In fact, it holds that $\dim \text{RFH}_n^m(\{\varphi_t\}) \in \{0, 2\}$.

If we fill S^1 by a torus with a small disk removed we see that iterations of the Reeb orbit $\cong S^1$ lie all in different free homotopy classes and hence cannot be joint by a Floer differential. In particular, the complex is acyclic and

$$\dim \text{RFH}_n^m(\{\varphi\}) = 2 \left(\left\lfloor \frac{m}{a} \right\rfloor - \left\lfloor \frac{n}{a} \right\rfloor \right). \quad (5.2)$$

In particular, it is possible to recover the rotation number a . As remarked earlier we point out that Rabinowitz Floer homology depend on the filling.

6. A HOMOLOGICAL MASLOV INDEX (BOUNDARY VALUE CASE)

We recall the setup. Let (Σ, ξ) be a closed, cooriented contact manifold and α a fixed contact form. We assume that there exists a compact exact symplectic manifold $(\widetilde{M}, d\widetilde{\lambda})$ with $\Sigma = \partial\widetilde{M}$ and $\alpha = \lambda|_\Sigma$. We attach to \widetilde{M} the positive part of the symplectization of Σ , that is,

$$M := \widetilde{M} \cup_\Sigma \Sigma \times \{r \geq 1\}. \quad (6.1)$$

On M we define a 1-form λ by $\widetilde{\lambda}$ on \widetilde{M} and $\lambda = r\alpha$ on $\Sigma \times \{r \geq 1\}$. In particular, $(M, \omega = d\lambda)$ is an exact symplectic manifold. We point out, that the entire symplectization $S\Sigma$ of Σ embeds into M via the flow of the Liouville vector field of λ .

In addition we assume that we are given two Lagrangian submanifolds L_0, L_1 inside M with following properties for $i = 0, 1$:

- $\lambda|_{L_i} = 0$ and $L_i \pitchfork \Sigma =: \Lambda_i$ is a closed Legendrian submanifold and
- $L_i \cap (\Sigma \times \{r \geq 1\}) = \Lambda_i \times \{r \geq 1\}$.

An example is given by $M = T^*B$, $\Sigma = S^*B$, a unit cotangent bundle, and $L_i = T_{q_i}^*B$ for $q_i \in B$. We define the path space

$$\mathcal{P} := \{u : [0, 1] \rightarrow M \mid u(i) \in L_i, i = 0, 1\} . \quad (6.2)$$

For a function

$$F : M \times S^1 \rightarrow \mathbb{R} \quad (6.3)$$

we define the Rabinowitz action functional

$$\mathcal{A} : \mathcal{P} \times \mathbb{R} \rightarrow \mathbb{R} \quad (6.4)$$

by precisely the same formula as above, see (3.1). Since $\lambda|_{L_i} = 0$ there are no boundary terms and the critical point equation is unchanged. Thus, a pair $(u, \eta) \in \mathcal{P} \times \mathbb{R}$ is a critical point of \mathcal{A} if and only if the following equations hold

$$\left. \begin{aligned} \dot{u}(t) &= \eta X_{F_{\eta t}}(u(t)) \\ F_{\eta}(u(1)) &= 0 \end{aligned} \right\} \quad (6.5)$$

Again following Givental [Giv89, Giv90a, Giv90b] we make the following definition.

Definition 6.1. Let $\{\varphi_t\}$ be a smooth path in $\text{Cont}(\Sigma)$. Then a pair $(x, \eta) \in \Lambda_0 \times \mathbb{R}$ is called a Legendrian discriminant point (with respect to $\{\varphi_t\}$) if

$$\varphi_{\eta}(x) \in \Lambda_1 . \quad (6.6)$$

Using Proposition 2.3 we assign to the path $\{\varphi_t\}$ the contact Hamiltonian $H_t : S\Sigma \rightarrow \mathbb{R}$. If we set

$$F_t(x, r) := H_t(x, r) - 1 \quad (6.7)$$

then the critical points of \mathcal{A} are again in 1-1 correspondence with Legendrian discriminant points. For a positive and twisted path $\{\varphi_t\} \in \mathcal{P}(\Sigma, \xi)$ we define as in Definition 2.1

$$\text{RFH}_a^b(\{\varphi_t\}; L_0, L_1) . \quad (6.8)$$

7. ASYMPTOTICS AND OBSTRUCTIONS TO POSITIVE LOOPS IN $\text{Cont}(\Sigma)$

We assume the same setting as in section 6. We fix an element $\{\varphi_t\} \in \mathcal{P}$ and consider the maps induced by inclusion

$$i^{n,m} : \text{RFH}_0^m(\{\varphi_t\}) \rightarrow \text{RFH}_0^n(\{\varphi_t\}) . \quad (7.1)$$

Then the sequence $n \mapsto \dim(\text{im } i^{n,m})$ is non-increasing and we set

$$\mu(m) := \min_n \{\dim(\text{im } i^{n,m})\} . \quad (7.2)$$

Then, by naturality, the numbers $\mu(m)$ are non-decreasing and we consider the growth rate of $m \mapsto \mu(m)$.

The following is Theorem 1.1 from the Introduction.

Theorem 7.1. *Let B be a closed manifold with finite fundamental group such that the rational cohomology ring has at least two generators. Then $\Sigma := S^*B$ with its standard contact structure ξ admits no closed positive loops in $\text{Cont}(\Sigma, \xi)$.*

Remark 7.2. Theorem 7.1 can be seen as a complement to a result by Chernov-Nemirovski. Indeed, if the fundamental group of the manifold B is infinite then there exist no positive loops in $\text{Cont}(S^*B)$, see [CN10, Corollary 8.1].

According to Eliashberg-Kim-Polterovich [EKP06] there are never positive *contractible* loops of contactomorphism of S^*B since S^*B is orderable. Strictly speaking Eliashberg-Kim-Polterovich could not handle the case of a manifold whose fundamental group is infinite but has only finitely many conjugacy classes. This is covered by the aforementioned result by Chernov-Nemirovski.

If the fundamental group is finite but the rational cohomology rings is generated by only one element there exist examples of positive loops in $\text{Cont}(S^*B)$. For instance the geodesic flow of any P-metric gives rise to such a positive loop, see [Bes78]. Of course, these loops are not contractible by the result of Eliashberg-Kim-Polterovich.

Proof of Theorem 7.1. We argue by contradiction. Let $\{\varphi_t\}$ be a positive loop in $\text{Cont}(\Sigma, \xi)$. In particular, it is twisted periodic: $\{\varphi_t\} \in \mathcal{P}$. As above we set $L_i := T_{q_i}^*B$ for $q_i \in B$. Then for generic $q_0, q_1 \in B$ the Rabinowitz Floer homology

$$\text{RFH}_a^b(\{\varphi_t\}; L_0, L_1) \quad (7.3)$$

is well defined. Since $\{\varphi_t\}$ is a loop the number of critical points of the underlying Rabinowitz action functional growth linearly with the action value. Therefore, the growth rate of the function $m \mapsto \mu(m)$ is at most linear.

As in Definition 2.1 we assign the 1-periodic, positive function $h_t : \Sigma \rightarrow \mathbb{R}_{>0}$ to $\{\varphi_t\}$. We can homotope h_t through positive and 1-periodic functions to the function

$$k(q, p) := \frac{1}{2}|p|_g^2 \quad (7.4)$$

where g is a bumpy metric on B . The contact flow $\{\psi_t\}$ induced by k is just the geodesic flow on S_g^*B associated to g . Arguing as in [AF10, Section 5] it follows that the growth rate of the positive, twisted periodic path $\{\psi_t\}$ coincides with the growth rate of $\{\varphi_t\}$. In particular, the growth rate of $\{\psi_t\}$ is at most linear.

According to [Mer10, Theorem B] the Rabinowitz Floer homology in positive degrees of the path $\{\psi_t\}$ is isomorphic to the homology of the based loop space. It follows from Gromov's theorem [Gro78, Gro07], see also [Pat99], that if the homology of the loop space growth at most linearly in action then it also grows at most linearly in degree. Using the theory of minimal models by Sullivan [Sul75] and arguing as in the proof of the Bott-Samelson theorem in [Bes78] it follows that the based loop space of a closed manifold with finite fundamental group such that the rational cohomology ring has at least two generators grows at least quadratically.

This contradiction finishes the proof of the theorem. □

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PETER ALBERS, DEPARTMENT OF MATHEMATICS, PURDUE UNIVERSITY
E-mail address: palbers@math.purdue.edu

URS FRAUENFELDER, DEPARTMENT OF MATHEMATICS AND RESEARCH INSTITUTE OF MATHEMATICS,
 SEOUL NATIONAL UNIVERSITY
E-mail address: frauenf@snu.ac.kr